## Boudjoghra, Mohamed el amine

EDUCATION	
MSc in computer vision	13 May 2024
Mohamed Bin Zayed University of Artificial Intelligence, Abu Dhabi, UAE	GPA: 3.9/4.0
Engineering degree in control systems and automation	22 June 2022
Ecole Nationale Polytechnique, Algiers, Algeria	GPA: 15.48/20
PUBLICATIONS	
Open-Yolo 3D: Towards Fast and Accurate Open-Vocabulary 3D Instance Segmentation   arXiv	
MEA Boudjoghra, A Dai, J Lahoud, H Cholakkal, RM Anwer, S Khan, FS Khan	
Continual Learning and Unknown Object Discovery in 3D Scenes via Continual Self-Distillation   ECO	CV 2024
MEA Boudjoghra, J Lahoud, H Cholakkal, RM Anwer, S Khan, FS Khan	
3D Indoor Instance Segmentation in an Open-World   NeurIPS 2023	
MEA Boudjoghra, SK. Al Khatib, J Lahoud, H Cholakkal, RM Anwer, S Khan, FS Khan	
3D Instance Segmentation via Enhanced Spatial and Semantic Supervision   ICCV 2023	
SK. Al Khatib, MEA Boudjoghra, J Lahoud, FS Khan	
State-Domain Equations and Their Quantum Computing Solution Based HHL Algorithm   MMEP	
MEA Boudjoghra, SAS Daimellah, N Zioui, Y Mahmoudi, M Tadjine	
EXPERIENCE	
Research Assistant   Mohamed Bin Zayed University of Artificial Intelligence 15 J	lune 2023 - Present
Conducting research on deep learning models for autonomous driving and 3D scene understanding.	
Graduate Assistant   Mohamed Bin Zayed University of Artificial Intelligence 1 August 2023	- 1 December 2023
Assisted PhD students in the Advanced Computer Vision course (CV801) to get hands-on experience in visio	n language models,
and object segmentation and detection.	
Intern   Core42 29 May 2	2023 - 10 July 2023
Worked on developing computer vision algorithms specifically for videos	
HONORS & AWARDS	
UAE, Abu Dhabi   Academic excellence award	2024
France, Paris   ICCV DEI award	2023
UAE, Abu Dhabi   MBZUAI fully funded scholarship	2022
Algeria, Algiers   Ranked 3rd nationally in engineering contest for higher education schools enrollment	2019
PROJECTS	
YOLOngv8: From Imbalanced to Accurate Object Detection in Long Tailed iSAID Dataset	2023
Visual Simultaneous Localization and Mapping on Lie groups	2022
Indoor localization and navigation for an autonomous drone	2019
Arduino-based autonomous robot	2019
LANGUAGES	
Arabic (Native)   English (IELTS 7)   Japanese (Intermediate)   F	rench (Advanced)