

# Ch2: Laplace Transform Review

## Contents:

Laplace Transform

Partial-Fraction Expansion

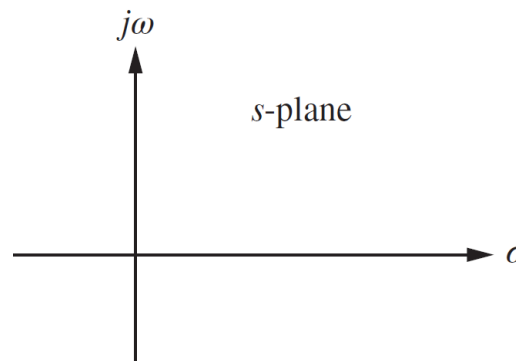
# Laplace Transform

# Laplace Transform

The definition of the unilateral (or one-sided) **Laplace Transform** is:

$$\mathcal{L}[f(t)] = F(s) = \int_{0^-}^{\infty} f(t)e^{-st} dt$$

where  $s = \sigma + j\omega$  is a **complex variable** (with real numbers  $\sigma$  and  $\omega$ ) and  $0^-$  is a value just before  $t = 0$  (which is applicable for discontinuous functions like impulse function or discontinuous initial conditions of differential equations at  $t = 0$ ).



**Note:** The Laplace Transform exists if there exists a real number  $\sigma_1$  such that:

$$\lim_{t \rightarrow \infty} |f(t)e^{-\sigma_1 t}| = 0$$

# Example

Find the Laplace transform of  $f(t) = Ae^{-at}$  ( $t \geq 0$ ).

# Inverse Laplace Transform

Finding  $f(t)$  from  $F(s)$ :

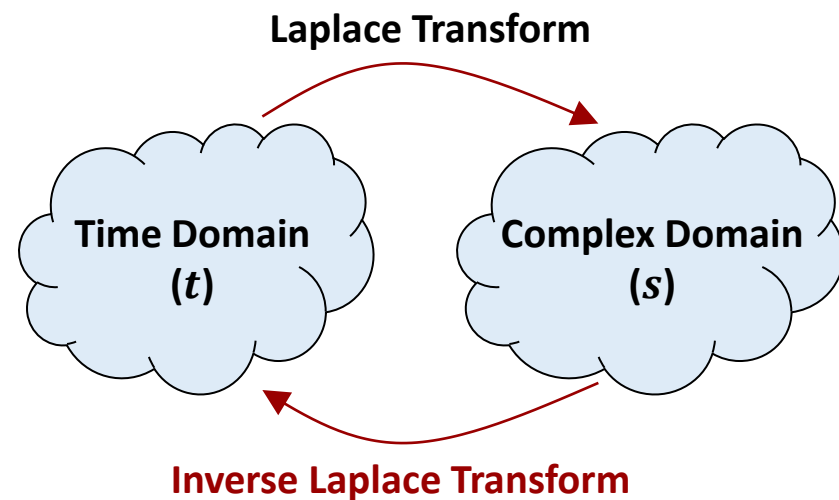
$$\mathcal{L}^{-1}[F(s)] = \frac{1}{2\pi j} \int_{\sigma-j\infty}^{\sigma+j\infty} F(s)e^{st} ds = f(t) \quad (t \geq 0)$$

where  $\sigma$ , the abscissa of convergence, is a real constant and is chosen larger than the real parts of all singular points of  $F(s)$ . Thus, the path of integration is parallel to the  $j\omega$  axis and is displaced by the amount  $\sigma$  from it. This path of integration is to the right of all singular points.

Evaluating the inversion integral appears complicated. In practice, we frequently use the **Laplace Transform Theorems** and **Partial-Fraction Expansion Method** for transforming between  $f(t)$  and  $F(s)$ .

# Laplace Transform Pairs

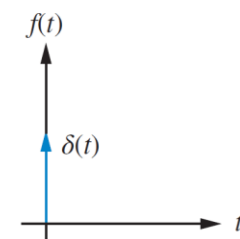
$f(t), t > 0$	$F(s)$
(impulse) $\delta(t)$	1
(step) $u(t)$	$\frac{1}{s}$
$t^n$	$\frac{n!}{s^{n+1}}$
$e^{-at}$	$\frac{1}{s+a}$
$\sin \omega t$	$\frac{\omega}{s^2 + \omega^2}$
$\cos \omega t$	$\frac{s}{s^2 + \omega^2}$



$$\delta(t) = \infty \text{ for } 0- < t < 0+$$

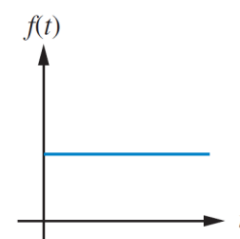
$$= 0 \text{ elsewhere}$$

$$\int_{0-}^{0+} \delta(t) dt = 1$$



$$u(t) = 1 \text{ for } t > 0$$

$$= 0 \text{ for } t < 0$$



# Laplace Transform Theorems

No.	Theorem	Name
1.	$\mathcal{L}[k_1 f_1(t) + k_2 f_2(t)] = k_1 F_1(s) + k_2 F_2(s)$	Linearity theorem
2.	$\mathcal{L}[e^{-at} f(t)] = F(s + a)$	Frequency shift theorem
3.	$\mathcal{L}[f(t - T)] = e^{-sT} F(s)$	Time shift theorem
4.	$\mathcal{L}[f(at)] = \frac{1}{a} F\left(\frac{s}{a}\right)$	Scaling theorem
5.	$\mathcal{L}\left[\frac{df}{dt}\right] = sF(s) - f(0^-)$	Differentiation theorem
6.	$\mathcal{L}\left[\frac{d^2 f}{dt^2}\right] = s^2 F(s) - sf(0^-) - f'(0^-)$	Differentiation theorem
7.	$\mathcal{L}\left[\frac{d^n f}{dt^n}\right] = s^n F(s) - \sum_{k=1}^n s^{n-k} f^{k-1}(0^-)$	Differentiation theorem
8.	$\mathcal{L}\left[\int_{0^-}^t f(\tau) d\tau\right] = \frac{F(s)}{s}$	Integration theorem

# Laplace Transform Theorems

No.	Theorem	Name
9.	$\mathcal{L}[tf(t)] = -\frac{dF(s)}{ds}$	Multiplication by time
10.	$\mathcal{L}[t^n f(t)] = (-1)^n \frac{d^n F(s)}{ds^n}, (n = 1, 2, \dots)$	Multiplication by time
11.	$\lim_{t \rightarrow \infty} f(t) = \lim_{s \rightarrow 0} sF(s)$	Final value theorem <sup>1</sup>
12.	$\lim_{t \rightarrow 0^+} f(t) = \lim_{s \rightarrow \infty} sF(s)$	Initial value theorem <sup>2</sup>
13.	$\mathcal{L}^{-1}[F_1(s)F_2(s)] = f_1(t) * f_2(t)$	Convolution Integral <sup>3</sup>

<sup>1</sup> For this theorem to yield correct finite results, all **roots** of the denominator of  $F(s)$  must have **negative real parts**, and no more than one can be at the origin.

<sup>2</sup> For this theorem to be valid,  $f(t)$  must be **continuous** or have a step discontinuity at  $t = 0$  (that is, no impulses or their derivatives at  $t = 0$ ).

<sup>3</sup>  $f_1(t) * f_2(t) = \int_0^t f_1(t - \tau)f_2(\tau)d\tau = \int_0^t f_1(\tau)f_2(t - \tau)d\tau$  and  $f_1(t)$  and  $f_2(t)$  are 0 for  $t < 0$ .



# Example

$$f(t) = 1 + 2 \sin \omega t \quad \mathcal{L}\{f(t)\} = ?$$

$$f(t) = A \sin(t - t_d) \quad \mathcal{L}\{f(t)\} = ?$$

$$f(t) = Ae^{-at} \sin \omega t \quad \mathcal{L}\{f(t)\} = ?$$

$$F(s) = \frac{1}{(s + 3)^2} \quad \mathcal{L}^{-1}\{F(s)\} = ?$$

$$F(s) = \frac{1}{s^2(s - a)} \quad \mathcal{L}^{-1}\{F(s)\} = ?$$

# Partial-Fraction Expansion

# Partial-Fraction Expansion

To find the **inverse Laplace transform** of a complicated function  $F(s) = N(s)/D(s)$ , we can **convert** the function to a sum of **simpler terms** for which we know the Laplace transform of each term using the Tables and Theorems.

If the order of  $N(s)$  is less than the order of  $D(s)$ , then a Partial-Fraction Expansion can be made. If the order of  $N(s)$  is greater than or equal to the order of  $D(s)$ , then first  $N(s)$  must be divided by  $D(s)$  successively until the result has a remainder whose numerator is of order less than its denominator (i.e.,  $F(s) = R(s) + N(s)/D(s)$ ).

$$F(s) = \frac{s^3 + 2s^2 + 6s + 7}{s^2 + s + 5} \longrightarrow F(s) = s + 1 + \frac{2}{s^2 + s + 5}$$

Based on roots of  $D(s)$  there are three cases:

**Case 1:** Roots of the Denominator of  $F(s)$  Are Real and Distinct

**Case 2:** Roots of the Denominator of  $F(s)$  Are Real and Repeated

**Case 3:** Roots of the Denominator of  $F(s)$  Are Complex or Imaginary

# Case 1: Real and Distinct Roots

$$F(s) = \frac{N(s)}{D(s)} = \frac{N(s)}{(s + p_1)(s + p_2) \cdots (s + p_i) \cdots (s + p_n)}$$

$$= \frac{K_1}{(s + p_1)} + \frac{K_2}{(s + p_2)} + \cdots + \frac{K_i}{(s + p_i)} + \cdots + \frac{K_n}{(s + p_n)}$$

**Note:** Order of  $N(s)$  is less than the order of  $D(s)$ .

$K_i$  is constant and called Residue.

$$K_i = (s + p_i)F(s) \Big|_{s \rightarrow -p_i} = \frac{(s + p_i)N(s)}{(s + p_1)(s + p_2) \cdots (s + p_i) \cdots (s + p_n)} \Big|_{s \rightarrow -p_i}, i = 1, \dots, n$$

$$\Rightarrow f(t) = \mathcal{L}^{-1}\{F(s)\} = K_1 e^{-p_1 t} + \cdots + K_i e^{-p_i t} + \cdots + K_n e^{-p_n t} \quad \text{for } t \geq 0$$

# Example

$$F(s) = \frac{2}{(s+1)(s+2)}$$

$$\mathcal{L}^{-1}\{F(s)\} = ?$$

# Case 2: Real and Repeated Roots

$$F(s) = \frac{N(s)}{D(s)} = \frac{N(s)}{(s + p_1)^r (s + p_2) \cdots (s + p_n)}$$

**Note:** Order of  $N(s)$  is less than the order of  $D(s)$ .

$$= \frac{K_1}{(s + p_1)^r} + \underbrace{\frac{K_2}{(s + p_1)^{r-1}} + \cdots + \frac{K_r}{(s + p_1)}}_{\text{(Each multiple root generates additional terms consisting of denominator factors of reduced multiplicity)}} + \frac{K_{r+1}}{(s + p_2)} + \cdots + \frac{K_n}{(s + p_n)}$$

(Each multiple root generates additional terms consisting of denominator factors of reduced multiplicity)

$$\left\{ \begin{array}{l} K_1, K_{r+1}, \dots, K_n \text{ can be found using the method explained in Case 1.} \\ K_2, \dots, K_r \text{ can be found using: } K_i = \frac{1}{(i-1)!} \left. \frac{d^{i-1} \{ (s + p_1)^r F(s) \}}{ds^{i-1}} \right|_{s \rightarrow -p_1}, i = 2, \dots, r \end{array} \right.$$

**Note:** For finding  $f(t)$ , we know  $\mathcal{L}^{-1} \left\{ \frac{1}{(s + a)^n} \right\} = e^{-at} \frac{t^{n-1}}{(n-1)!}$

# Example

$$F(s) = \frac{2}{(s+1)(s+2)^2}$$

$$\mathcal{L}^{-1}\{F(s)\} = ?$$

# Case 3: Complex or Imaginary Roots

## Method 1

$$F(s) = \frac{N(s)}{D(s)} = \frac{N(s)}{(s + p_1)(s^2 + as + b) \dots}$$

$$= \frac{K_1}{(s + p_1)} + \frac{(K_2s + K_3)}{(s^2 + as + b)} + \dots \quad (*)$$

**Note:** Order of  $N(s)$  is less than the order of  $D(s)$ .

$K_1$  can be found using the method explained in **Case 1**.

$K_2$  and  $K_3$  can be found by multiplying both sides of equation (\*) by  $D(s)$  and balancing coefficients of both sides of equation:

$$\frac{N(s)}{D(s)} = \frac{K_1}{(s + p_1)} + \frac{(K_2s + K_3)}{(s^2 + as + b)} + \dots \Rightarrow N(s) = K_1(s^2 + as + b) + (K_2s + K_3)(s + p_1) + \dots$$

**Note:** For finding  $f(t)$ , we know

$$\left\{ \begin{aligned} s^2 + as + b &= \left(s + \frac{a}{2}\right)^2 + b - \left(\frac{a}{2}\right)^2 = (s + \sigma)^2 + \omega^2, \\ \mathcal{L}^{-1} \left\{ \frac{A(s + \sigma) + B\omega}{(s + \sigma)^2 + \omega^2} \right\} &= Ae^{-\sigma t} \cos \omega t + Be^{-\sigma t} \sin \omega t \end{aligned} \right.$$



# Example

$$F(s) = \frac{3}{s(s^2 + 2s + 5)}$$

$$\mathcal{L}^{-1}\{F(s)\} = ?$$

## Case 3: Complex or Imaginary Roots Method 2

The techniques described for real roots, i.e., **Case 1** and **Case 2**, can be also used for complex and imaginary roots.

$$F(s) = \frac{N(s)}{D(s)} = \frac{N(s)}{(s + p_1)(s^2 + as + b) \dots} = \frac{K_1}{(s + p_1)} + \frac{K_2}{(s + \sigma + j\omega)} + \frac{K_3}{(s + \sigma - j\omega)} + \dots$$

- $K_1$  and  $K_2$  can be found using the method explained in **Case 1**, and  $K_3$  will be the **complex conjugate** of  $K_2$ .
- Using this general method, inverse Laplace transform of a function with Repeated Complex or Imaginary Roots can be also found using the method explained in **Case 2**.

**Note:** For finding  $f(t)$ , we know

$$\left\{ \begin{array}{l} \frac{e^{j\omega t} + e^{-j\omega t}}{2} = \cos \omega t \\ \frac{e^{j\omega t} - e^{-j\omega t}}{2j} = \sin \omega t \end{array} \right.$$

# Example

$$F(s) = \frac{3}{s(s^2 + 2s + 5)} \quad \mathcal{L}^{-1}\{F(s)\} = ?$$

$$F(s) = \frac{3}{s(s^2 + 2s + 5)} = \frac{K_1}{s} + \frac{K_2}{s + 1 + j2} + \frac{K_3}{s + 1 - j2}$$

$K_1$ ,  $K_2$ , and  $K_3$  can be found using method explained in Case 1:

$$K_1 = \frac{3}{5}, \quad K_2 = \frac{3}{s(s + 1 - j2)} \Big|_{s \rightarrow -1 - j2} = -\frac{3}{20}(2 + j1), \quad K_3 \text{ is complex conjugate of } K_2: K_3 = -\frac{3}{20}(2 - j1)$$

$$F(s) = \frac{3}{5} \frac{1}{s} - \frac{3}{20} \left( \frac{2 + j1}{s + 1 + j2} + \frac{2 - j1}{s + 1 - j2} \right)$$

$$f(t) = \frac{3}{5} - \frac{3}{20} [(2 + j1)e^{-(1+j2)t} + (2 - j1)e^{-(1-j2)t}]$$

$$f(t) = \frac{3}{5} - \frac{3}{20} e^{-t} \left[ 4 \left( \frac{e^{j2t} + e^{-j2t}}{2} \right) + 2 \left( \frac{e^{j2t} - e^{-j2t}}{2j} \right) \right] \Rightarrow f(t) = \frac{3}{5} - \frac{3}{5} e^{-t} \left( \cos 2t + \frac{1}{2} \sin 2t \right) \quad t \geq 0$$

# Example

$$G(s) = \frac{s^3 + 5s^2 + 9s + 7}{(s + 1)(s + 2)}$$

$$\mathcal{L}^{-1}\{G(s)\} = ?$$

# Example

$$\mathcal{L}^{-1} \left\{ \frac{s^2 + 2s + 3}{(s + 1)^3} \right\} = ?$$

# Example: Solving an ODE Using Laplace Transform

$$\ddot{x} + 2\dot{x} + 5x = 3, \quad \dot{x}(0) = 0, \quad x(0) = 0$$