Amin Yahyaabadi

Vancouver, Canada



Education

• University of Manitoba

M.Sc., Mechanical Engineering

GPA: 4.27/4.5

• Isfahan University of Technology (IUT)

B.Sc., Mechanical Engineering

GPA: 18.03/20 (3.91/4) 2014-2018 17.89/20 (3.81/4) overall

Winnipeg, Canada Sep 2018 - Sep 2021

Isfahan, Iran

Sep 2013 - Feb 2018

Work Experience

• Robotics Control Engineer,

Sanctuary AI,

Development, evaluation, and optimization of control algorithms for the general-purpose humanoid robots

2022 -

Research Experience

• An Intelligent Drone Testbed for Control Systems and Verification, University of Manitoba

2018 - 2021

Designed an intelligent drone testbed used for validation of new satellite or drone control algorithms and hardware. Identified the dynamics of the drone intelligently with minimal measuring using Particle Swarm Optimization (PSO). Developed a custom onboard software for the drone to autonomously control the drone's motion and operations. 🔁 pdf

M.Sc. Thesis, Supervisor: Dr. P. Ferguson

AI | PSO | UAV | System Identification | Control | Pixhawk | Parrot | Matlab

• Intelligent vibration control with self-sensing piezoelectric actuator, Isfahan University of Technology

2016 - 2018

Developed an intelligent control method for a distributed system using a self-sensing piezoelectric actuator and PSO. Modelled the dynamics of the system with a novel FEA+FDA method to test the controller.

B.Sc. Thesis, Supervisor: Dr. S. Ziaei-Rad

 $\fbox{AI \ [PSO] \ [GA] \ [Smart \ Material] \ [System \ Identification] \ [Control] \ [FEA] \ [Matlab]}$

• Auto Code Generation for Onboard Space Object Detection and Flight Software Applications, University of Manitoba 2018 - 2021

Developed machine learning and analytical image processing algorithms for satellite's onboard detection of resident space objects (RSOs) from commercial-off-the-shelf star trackers. 🗷 pdf

M.Sc. Project with Magellan Aerospace, Supervisor: Dr. P. Ferguson

[Machine Learning] [Image Processing] [Xilinx] [Arm Cortex] [Intel] [Matlab] [C++]

 ManitobaSat Satellite's Onboard Computer and Flight Software Leader, University of Manitoba

2018 - 2021

Designed a modular onboard computer (OBC) for ManitobaSat-1, a 3U sized CubeSat satellite. The OBC was a system on a chip that used an MRAM. Developed custom real-time flight software running on FreeRTOS to control all the satellite's operations such as attitude and determination control. 🗷 pdf

M.Sc. Project with Canadian Space Agency (CSA), Supervisor: Dr. P. Ferguson

[Mechatronics] [Control] [Smart Fusion] [Arm Cortex] [RTOS] [C++]

Notable Projects

• Rhino XR-3 5 DOF Robot Arm Real-time Control via Arduino

Robotics Control C++ Matlab Arduino

Selected Topics in Robot Technology, Supervisor: Dr. S. Balakrishnan

• Barrett WAM 7 DOF Robot Arm Simulation and Analysis Robotics Control Matlab

• Model Predictive Control of Robot Arm using Neural Networks

Robotics, Supervisor: Dr. H. Mousavi

Machine Learning Control Robotics Matlab

Neural Networks, Supervisor: Dr. M. Kamali

• Intelligent Fuzzy PID Controller for a Bluetooth controlled DC Motor via AVR

 $\fbox{AI } \fbox{Fuzzy Logic} \fbox{Control} \fbox{AVR} \fbox{Matlab}$

Intelligent Control, Supervisor: Dr. F. Sheikholeslam Mechatronic Systems, Supervisor: M. Danesh

• Parallel Image Processing using MPI and OpenCV

MPI OpenCV C++ Parallel Processing

Parallel Processing, Supervisor: Dr. I. Jeffrey

• Custom Simulated Annealing Investigation for Salesperson Problem - New Mathematical Proof of The Multidimensional Newton's Weights Optimization Algorithm

[Machine Learning] [AI] [SA] [Neural Networks] [Matlab]

Applied Computational Intelligence, Supervisor: Dr. K. Ferens

• Designing a Signal Processing and Measuring Instrument in Labview - Verifying The Instrument using Acoustic Analysis of a Trumpet in MSC ACTRAN

Signal Processing Acoustics Actran LabView

Mechatronics Lab 2, Supervisors: Dr. M. Danesh Engineering Acoustics, Supervisor: Dr. A. Loghmani

• Multilayered Composite Shell Dynamics and Crack Analysis under Impact via Abaqus

FEM | Abaqus | Computation Mechanics |

Computer-Aided Engineering, Supervisor: Dr. R. Jafari

Honours and Awards

• Fellowship for Education Purposes - \$40,500, UoM, Canada.	2018-2021
\bullet Faculty of Graduate Studies Program Completion Scholarship - \$2,500, UoM, Canada.	2021
\bullet International Graduate Student Entrance Scholarship (IGSES) - \$6,000, UoM, Canada.	2018
\bullet Fellowship to Study at IUT for M.Sc Program without Entrance Exam, IUT, Iran.	2017
\bullet Ranked top 10% among the students of the Mechanical Engineering Department, IUT, Iran.	2017
\bullet Ranked top 0.3% among 260000 participants in Iranian University Entrance Exam for B.Sc. Studies	s. 2013
\bullet Qualified as very good in Mathematics Alympiad Final International Round in the Netherlands.	2012
• Ranked 1st in Mathematics Alympiad National Round in Iran.	2011

GRE

• Quantitative: 170/170 • Verbal: 151/170 • Analytical Writing: 3.5

Selected Courses

• Applied Computational Intelligence: 4.5/4.5 • Mechatronics Lab 1 and 2 : 18.25/20 and 19/20

 Selected Topics in Robot Technology: 4.5/4.5 Applied Electrical/Electronics: 19.03/20

Robotics: 19.5/20
Computer-aided design: 18.1/20
Neural Networks: 20/20

• Intelligent Control: 18/20

• Applied Vibrations: 19.6/20 • Differential Equations: 20/20

• Acoustics: 19.5/20 • General Mathematics: 20/20

• Machinery Dynamics: 19.3/20 • Advanced Dynamics (Audited)

• Vehicle Dynamics: 18.3/20 • Parallel Processing (Audited)

Software and Programming Skills

- **Programming Languages:** C++, Rust, Python, Matlab, Julia, D, Go, Verilog, PLC, TypeScript, AssemblyScript
- Technical Software: Simulink, Abaqus, LabView, Xilinx SDSoc Vivado, Simpack, MSC Adams / Car, MSC Actran, Autodesk Inventor, CATIA, Proteus, Modelsim, Maple
- Embedded Processors: Arm Cortex A9, Arm Cortex M3, Xilinx Zynq 7020 SoC/FPGA, Smart Fusion 2 SoC/FPGA, Pixhawk Flight Contrller (Px4), Parrot Mambo Flight Controller, Arduino Due /Uno, AVR Atmel STK500, Intel/AMD x86

Publications

- A. Yahyaabadi, M. Driedger,..., P. Ferguson, "ManitobaSat-1: A Novel Approach for Technology Advancement," in the Journal of IEEE Potentials, 2020, 🗷 pdf
- A. Yahyaabadi, M. Driedger,..., P. Ferguson, "ManitobaSat-1: Making Space for Innovation," in *IEEE Canadian Conference of Electrical and Computer Engineering (CCECE)*, Edmonton, Canada, 2019 🖻 pdf
- A. Yahyaabadi, P. Ferguson, "An intelligent multi-vehicle drone testbed for space systems and remote sensing verification," in *Canadian Aeronautics and Space Institute (CASI) ASTRO*, Montreal, Canada, 2019 🖹 pdf
- A. Yahyaabadi, P. Harrison, P. Ferguson, "Auto Code Generation for Onboard Space Object Detection and Other Flight Software Applications A Feasibility Study," in *Canadian Aeronautics and Space Institute* (CASI) ASTRO, Montreal, Canada, 2019 pdf

Attended Conferences

• Canadian Aeronautics and Space Institute (CASI) ASTRO
Submitted two papers and presented them:

Montreal, Canada, 2019

- "An intelligent multi-vehicle drone testbed for space systems and remote sensing verification" ▶ pdf
- "Auto Code Generation for Onboard Space Object Detection and Flight Software Applications" ▶ pdf
- ArcticNet (ASM) 2018

 Presented my work by the poster and oral presentation:

 Ottawa, Canada, 2018
 - "A multi-vehicle drone testbed for space systems and remote sensing verification" → Proceedings P. 198

Additional Experience

- The Main Member of the Drone Testbed Lab at the University of Manitoba
- 2018 2021
- Developed "an intelligent multi-vehicle drone testbed for space systems and remote sensing verification"
- Assisted other teams to use the testbed in different research areas such as:
 - * Using hand gestures for controlling drone movements
 - * Using artificial neural networks as the controller for the drones
- Summer Internship in Bama Co

Summer 2014/2016

- Condition monitoring and predictive maintenance planning of machinery and vehicles in Bama Co
- Jury Membership at Isfahan Mathhouse

2013 - 2018

- Member of the Jury in Isfahan Mathhouse for choosing qualified participants for International Competitions (e.g., Alympiad)
- Alympiad competition participants test grader in Isfahan Mathhouse
- Teaching Assistant at the Isfahan University of Technology

Fall 2016

- Statics, instructor: Dr. S. Akbarzadeh

Voluntary Experience

- Volunteering as an Open Source Programmer
 - The leader of the ♠ Atom-Community organization that brings an integrated development environment to Atom
 - The author of the ♥ Zadeh, a library for fast fuzzy filtering and matching written in C++
 - The author of the ♠ minijson, a library for the fast minification of the JSON files written in D, C, and AVX2 and SSE4_1 SIMD.
 - The author of the **O** AcuteML, an intelligent markup language for web development written in Julia
 - The leader of the 🗘 JuliaMatlab organization, an open-source alternative for Matlab written in Julia
 - The co-owner of the ♥ JuliaMusic organization that provides music research tools (e.g. ♥ MusicXML.jl) in Julia
 - Other projects available on ♥ GitHub
- Music Performances in Morrow Gospel Church

Sep. 2018/Jan. 2019

- Two Rock/Blues performances in Blues Nights events, Winnipeg, Canada

References

• Dr. P. Ferguson, Associate Professor of Mechanical Eng.

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University of Manitoba, Canada MIT Alumni, NSERC Research Chair

• Dr. S. Balakrishnan, Professor of Mechanical Eng.

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University of Manitoba, Canada

• Dr. S. Ziaie-Rad, Professor of Mechanical Eng.

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Isfahan University of Technology, Iran Imperial College London Alumni

• Dr. K. Ferens, Assistant Professor of Electrical and Computer Eng.

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University of Manitoba, Canada