Amin Yahyaabadi

University of Manitoba, Winnipeg, Canada

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Education

University of Manitoba

M.Sc., Mechanical Engineering

- GPA: 4.27/4.5

Isfahan University of Technology (IUT)

B.Sc., Mechanical Engineering

- GPA: 18.03/20 (3.91/4) 2014-2018 17.89/20 (3.81/4) overall Winnipeg, Canada Sep 2018 - Current

Department of Mechanical Engineering

Isfahan, Iran Sep 2013 - Feb 2018

Research Interests

- Machine Learning

- ANNs, Differential Programming, System Identification

Artificial Intelligence:

- Meta-heuristic Algorithms, Swarm Intelligence

Robotics

- UAVs, Swarms, Legged Robots, Manipulators

- Control Systems

- Adaptive, Fuzzy, Model Predictive

Publications

- A. Yahyaabadi, M. Driedger,..., P. Ferguson, "ManitobaSat-1: A Novel Approach for Technology Advancement," in the Journal of IEEE Potentials, 2020, Link
- A. Yahyaabadi, M. Driedger,..., P. Ferguson, "ManitobaSat-1: Making Space for Innovation," in *IEEE Canadian Conference of Electrical and Computer Engineering (CCECE)*, Edmonton, Canada, 2019 Link
- A. Yahyaabadi, P. Ferguson, "An intelligent multi-vehicle drone testbed for space systems and remote sensing verification," in *Canadian Aeronautics and Space Institute (CASI) ASTRO*, Montreal, Canada, 2019 Link
- A. Yahyaabadi, P. Harrison, P. Ferguson, "Auto Code Generation for Onboard Space Object Detection and Other Flight Software Applications A Feasibility Study," in Canadian Aeronautics and Space Institute (CASI) ASTRO, Montreal, Canada, 2019 Link

Research Assistance Experiences

- An intelligent multi-vehicle drone testbed for space systems and remote sensing verification
 I develop an accessible intelligent multi-vehicle drone testbed for validation of new satellite or drone control algorithms and hardware. System identification of drone's dynamics is done intelligently with minimal measuring using PSO/GA.

 (AI) PSO/GA (UAV) (System Identification) (Control) (Pixhawk) (Parrot) (Matlab) Supervisor: Dr. P. Ferguson

 M.Sc.Thesis
- Intelligent vibration control with self-sensing piezoelectric actuator

 I developed an intelligent control method for a distributed system using a self-sensing piezoelectric actuator. I modeled the dynamics of the system with a custom programmed FEA beside FDA to simulate the system and test the controller.

 AI PSO/GA Smart Material System Identification Control FEA Matlab Supervisor: Dr. S. Ziaei-Rad

 B.Sc.Thesis
- Auto Code Generation for Onboard Space Object Detection and Flight Software Applications
 We developed machine learning and analytical image processing algorithms for satellite's onboard detection of resident space objects (RSOs) from commercial-off-the-shelf star trackers using a Matlab's syntax and special guidelines, and we compared the performance of generated hardware optimized C/C++ code to handwritten code.

 Link

 Machine Learning [Image Processing] (Xilinx Arm Cortex Intel Matlab C++/C)

 Supervisor: Dr. P. Ferguson

 M.Sc. Project
- ManitobaSat Satellite's "Onboard Computer" and "Flight Software" Leader
 We design a modular onboard computer (OBC) for ManitobaSat-1, which is a 3U sized CubeSat satellite to
 expose special geological samples to space environment. OBC uses new technologies such as a "system on a
 chip" (Soc) and MRAM. We develop a custom real-time flight software using FreeRTOS to control all the
 satellite's operations such as attitude and determination control. A Link

Mechatronics Control Smart Fusion Arm Cortex RTOS C++/C

Supervisor: Dr. P. Ferguson

M.Sc. Project

Honors and Awards

Fellowship for Education Purposes - \$40,500, UoM, Canada	2018-2020
International Graduate Student Entrance Scholarship (IGSES) - \$6,000, UoM, Canada	2018
Awarded Full Fellowship to Study at IUT for M.Sc Program without Entrance Exam, IUT, Ira	n 2017
Among top 10% students in the Mechanical Engineering Department, IUT, Iran	2017
Ranked top 0.3% among 260000 participants in Iranian University Entrance Exam for B.Sc. St	udies, 2013
Qualified as very good in Mathematics Alympiad Final International Round in Netherlands	$\dots 2012$
Ranked 1st in Mathematics Alympiad National Round in Iran	2011

Notable Projects

- Rhino XR-3 5 DOF Robot Arm Real-time Control and Simulation via Arduino and Matlab

 [Robotics] [Control] [C/C++] [Matlab] [Arduino] Selected Topics in Robot Technology, Supervisor: Dr. S. Balakrishnan
- Barrett WAM 7 DOF Robot Arm Simulation and Analysis via Matlab

 Robotics Control Matlab

 Robotics, Supervisor: Dr. H. Mousavi
- Model Predictive Control of Robot Arm via Neural Networks

Machine Learning Control Robotics Matlab Neural Networks, Supervisor: Dr. M. Kamali

- Intelligent Fuzzy PID Controller for a Bluetooth controlled DC Motor via AVR
 [AI] [Fuzzy Logic] [Control] [AVR] [Matlab]
 Intelligent Control, Mechatronic Systems, Sup: F. Sheikholeslam, M. Danesh
- Custom Simulated Annealing Investigation for Salesperson Problem A New Mathematical Proof of Multidimensional Newton's Weights Optimization Algorithm

 Machine Learning
 AI
 SA
 Neural Networks
 Matlab

Applied Computational Intelligence, Sup: K. Ferens

GRE

- Quantitative: 170 Verbal: 151 Analytical Writing: 3.5

Selected Courses

- Applied Computational Intelligence: 4.5/4.5 - Vehicle Dynamics: 18.3/20

— Selected Topics in Robot Technology: 4.5/4.5 — Mechatronics Lab 1 & 2 : 18.25/20 & 19/20

- Mechatronics: 20/20 - Applied Electrical/Electronics: 19.03/20

- Robotics: 19.5/20 - Dynamics: 18.5/20

- Neural Networks: 20/20 - Computer-aided design: 18.1/20

Intelligent Control: 18/20
 Applied Vibrations: 19.6/20
 Engineering Mathematics: 20/20
 Differential Equations: 20/20

- Acoustics: 19.5/20 - General Mathematics: 20/20

- Machinery Dynamics: 19.3/20 - Advanced Dynamics (Auditing)

Software and Programming Skills

Languages	Embedded Processors	Technical Software
A Matlab	A Xilinx Zynq 7020 - Zybo Z720 SoC/FPGA	Xilinx SDSoc - Vivado
Julia	Smart Fusion 2 SoC/FPGA	Abaqus
² C++/C	Pixhawk Flight Contrller (Px4)	Simpack
Python	Parrot Mambo Flight Controller	MSC Adams
Simulink	Arm Cortex A9	MSC Adams Car
Labview	Arm Cortex M3	MSC Actran
Maple	Arduino Due/Uno	Autodesk Inventor
Verilog	AVR Atmel STK500	A CATIA
Linux	$\stackrel{\textstyle >}{\sim}$ Intel x64/x86	Proteus
\nearrow IATEX	PLC Programming	Modelsim
		Q Evmont

Attended Conferences

- Submitted two papers and presented them:
 - "An intelligent multi-vehicle drone testbed for space systems and remote sensing verification" 🔁 Link
 - "Auto Code Generation for Onboard Space Object Detection and Other Flight Software Applications" **Link**
- Presented my colleagues' works:
 - V. Parthasarathy, "A Virtual Ground Station for Automated Spacecraft Health Monitoring" [A] Link
 - J. Campos, "Industry Project Management Tools for Nanosatellites Teams" 🔁 Link
 - V. Platero, "Outreaching for the Stars with ManitobaSat-1" 口 Link

- ArcticNet (ASM) 2018

Ottawa, Canada, 2018

- Presented my work by poster and oral presentation:
 - "A multi-vehicle drone testbed for space systems and remote sensing verification" Proceedings P. 198

Work Experience

- Main Member of Drone Testbed Lab at the University of Manitoba Sep. 2018 - Current
 - Perusing my main research "An intelligent multi-vehicle drone testbed for space systems and remote sensing verification"
 - Helping other teams use my testbed in different research areas such as:
 - Using hand gestures for controlling drone movements
 - Using artificial neural networks as the controller for the drones
- Summer Internship in Bama Co

Summer 2014/2016

- Condition monitoring and predictive maintenance planning of machinery & vehicles in Bama Co
- Special Membership in Isfahan Mathhouse

- Being a member of the Jury in Isfahan Mathhouse for choosing qualified participants for International Competitions (e.g., Alympiad)
- Alympiad competition participants test grader in Isfahan Mathhouse
- Teaching Assistant at the Isfahan University of Technology

Fall 2016

• Statics, instructor: Dr. S. Akbarzadeh

Voluntary Experience

- Volunteering as an Open Source Programmer
 - Owning O Atom-Community organization that brings an integrated development environment to Atom
 - Owning O AcuteML, which is an intelligent markup language for web development written in Julia
 - Owning O JuliaMatlab organization which is an open source alternative for Matlab written in Julia
 - Owning O JuliaMusic organization which provides music research tools (e.g. O MusicXML) in Julia
 - Other projects that are available on O Github

- Music Performances in Morrow Gospel Church

Sep. 2018/Jan. 2019

• Two Blues/Folk performances in Blues Nights events, Winnipeg, Canada

References

- Dr. P. Ferguson, Associate Professor of Mechanical Eng.

- Dr. S. Balakrishnan, Professor of Mechanical Eng.

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- Dr. S. Ziaie-Rad, Professor of Mechanical Eng.

- Dr. K. Ferens, Assistant Professor of Electrical and Computer Eng.

University of Manitoba, Canada

Imperial College London Alumni

University of Manitoba, Canada MIT Alumni, NSERC Research Chair

Isfahan University of Technology, Iran

University of Manitoba, Canada