Amin Yahyaabadi

Winnipeg, Canada

☑ yahyaaba@myumanitoba.ca 🖸 GitHub in Linkedin 📞 +1 431-5577531

Education

• University of Manitoba

M.Sc., Mechanical Engineering

GPA: 4.27/4.5

• Isfahan University of Technology (IUT)

B.Sc., Mechanical Engineering GPA: 18.03/20 (3.91/4)

2014-2018 17.89/20 (3.81/4) overall

Winnipeg, Canada Sep 2018 - Sep 2021

Isfahan, Iran Sep 2013 - Feb 2018

Research Experience

• An Intelligent Drone Testbed for Control Systems and Verification

Designed an intelligent drone testbed used for validation of new satellite or drone control algorithms and hardware. Identified the dynamics of the drone intelligently with minimal measuring using Particle Swarm Optimization (PSO). Developed a custom onboard software for the drone to autonomously control the drone's motion and operations. 🚨 pdf

M.Sc. Thesis, Supervisor: Dr. P. Ferguson

AI | PSO | UAV | System Identification | Control | Pixhawk | Parrot | Matlab

• Intelligent vibration control with self-sensing piezoelectric actuator

Developed an intelligent control method for a distributed system using a self-sensing piezoelectric actuator and PSO. Modelled the dynamics of the system with a novel FEA+FDA method to test the controller.

B.Sc. Thesis, Supervisor: Dr. S. Ziaei-Rad

AI PSO GA Smart Material System Identification Control FEA Matlab

Auto Code Generation for Onboard Space Object Detection and Flight Software Applications Developed machine learning and analytical image processing algorithms for satellite's onboard detection of resident space objects (RSOs) from commercial-off-the-shelf star trackers. 🗷 pdf

M.Sc. Project with Magellan Aerospace, Supervisor: Dr. P. Ferguson

• ManitobaSat Satellite's Onboard Computer and Flight Software Leader

Designed a modular onboard computer (OBC) for ManitobaSat-1, a 3U sized CubeSat satellite. The OBC was a system on a chip that used an MRAM. Developed custom real-time flight software running on FreeRTOS to control all the satellite's operations such as attitude and determination control. 🚨 pdf

M.Sc. Project with Canadian Space Agency (CSA), Supervisor: Dr. P. Ferguson

Notable Projects

• Rhino XR-3 5 DOF Robot Arm Real-time Control via Arduino

Robotics Control C++ Matlab Arduino Selected Topics in Robot Technology, Supervisor: Dr. S. Balakrishnan

• Barrett WAM 7 DOF Robot Arm Simulation and Analysis

Robotics, Supervisor: Dr. H. Mousavi Robotics Control Matlab

• Model Predictive Control of Robot Arm using Neural Networks

Machine Learning Control Robotics Matlab Neural Networks, Supervisor: Dr. M. Kamali

• Intelligent Fuzzy PID Controller for a Bluetooth controlled DC Motor via AVR Intelligent Control, Supervisor: Dr. F. Sheikholeslam AI Fuzzy Logic Control AVR Matlab

 Parallel Image Processing using MPI and OpenCV MPI OpenCV C++ Parallel Processing

• Custom Simulated Annealing Investigation for Salesperson Problem - New Mathematical Proof of The Multidimensional Newton's Weights Optimization Algorithm Machine Learning AI SA Neural Networks Matlab $Applied\ Computational\ Intelligence,\ Supervisor:\ Dr.\ K.\ Ferens$

• Designing a Signal Processing and Measuring Instrument in Labview - Verifying The Instrument using Acoustic Analysis of a Trumpet in MSC ACTRAN

Signal Processing Acoustics Actran LabView

Mechatronics Lab 2, Supervisors: Dr. M. Danesh Engineering Acoustics, Supervisor: Dr. A. Loghmani

Mechatronic Systems, Supervisor: M. Danesh

Parallel Processing, Supervisor: Dr. I. Jeffrey

• Multilayered Composite Shell Dynamics and Crack Analysis under Impact via Abaqus

[FEM] Abaqus | Computation Mechanics Computer-Aided Engineering, Supervisor: Dr. R. Jafari

Honours and Awards

• Fellowship for Education Purposes - \$40,500, UoM, Canada.	2018-2021
\bullet Faculty of Graduate Studies Program Completion Scholarship - \$2,500, UoM, Canada.	2021
\bullet International Graduate Student Entrance Scholarship (IGSES) - $\$6,\!000,$ UoM, Canada.	2018

• Fellowship to Study at IUT for M.Sc Program without Entrance Exam, IUT, Iran. 2017

• Ranked top 10% among the students of the Mechanical Engineering Department, IUT, Iran. 2017

• Ranked top 0.3% among 260000 participants in Iranian University Entrance Exam for B.Sc. Studies. 2013

• Qualified as very good in Mathematics Alympiad Final International Round in the Netherlands. 2012

2011 • Ranked 1st in Mathematics Alympiad National Round in Iran.

 $\bullet \ \, \text{Quantitative: } 170/170 \qquad \qquad \bullet \ \, \text{Verbal: } 151/170 \qquad \qquad \bullet \ \, \text{Analytical Writing: } 3.5$

Selected Courses

• Applied Computational Intelligence: 4.5/4.5

• Selected Topics in Robot Technology: 4.5/4.5

• Mechatronics: 20/20

• Robotics: 19.5/20

• Neural Networks: 20/20

• Intelligent Control: 18/20

• Applied Vibrations: 19.6/20

• Acoustics: 19.5/20

• Machinery Dynamics: 19.3/20

• Vehicle Dynamics: 18.3/20

 \bullet Mechatronics Lab 1 and 2: 18.25/20 and 19/20

• Applied Electrical/Electronics: 19.03/20

• Dynamics: 18.5/20

 \bullet Computer-aided design: 18.1/20

• Engineering Mathematics: 20/20

• Differential Equations: 20/20

• General Mathematics: 20/20

• Advanced Dynamics (Audited)

• Parallel Processing (Audited)

Software and Programming Skills

• Programming Languages: C++, Rust, Python, Matlab, Julia, D, Go, Verilog, PLC, TypeScript, AssemblyScript

• Technical Software: Simulink, Abaqus, LabView, Xilinx SDSoc - Vivado, Simpack, MSC Adams / Car, MSC Actran, Autodesk Inventor, CATIA, Proteus, Modelsim, Maple

• Embedded Processors: Arm Cortex A9, Arm Cortex M3, Xilinx Zynq 7020 SoC/FPGA, Smart Fusion 2 SoC/FPGA, Pixhawk Flight Contrller (Px4), Parrot Mambo Flight Controller, Arduino Due /Uno, AVR Atmel STK500, Intel/AMD x86

Publications

• A. Yahyaabadi, M. Driedger,..., P. Ferguson, "ManitobaSat-1: A Novel Approach for Technology Advancement," in the Journal of IEEE Potentials, 2020, 🖹 pdf

- A. Yahyaabadi, M. Driedger,..., P. Ferguson, "ManitobaSat-1: Making Space for Innovation," in *IEEE Canadian Conference of Electrical and Computer Engineering (CCECE)*, Edmonton, Canada, 2019 🖻 pdf
- A. Yahyaabadi, P. Ferguson, "An intelligent multi-vehicle drone testbed for space systems and remote sensing verification," in *Canadian Aeronautics and Space Institute (CASI) ASTRO*, Montreal, Canada, 2019 🖹 pdf
- A. Yahyaabadi, P. Harrison, P. Ferguson, "Auto Code Generation for Onboard Space Object Detection and Other Flight Software Applications A Feasibility Study," in *Canadian Aeronautics and Space Institute* (CASI) ASTRO, Montreal, Canada, 2019 pdf

Attended Conferences

• Canadian Aeronautics and Space Institute (CASI) ASTRO Submitted two papers and presented them:

Montreal, Canada, 2019

- "An intelligent multi-vehicle drone testbed for space systems and remote sensing verification" abla pdf
- "Auto Code Generation for Onboard Space Object Detection and Flight Software Applications" 🖻 pdf
- ArcticNet (ASM) 2018

Ottawa, Canada, 2018

Presented my work by the poster and oral presentation:

- "A multi-vehicle drone testbed for space systems and remote sensing verification" ☐ Proceedings P. 198

Work Experience

- The Main Member of the Drone Testbed Lab at the University of Manitoba Sep. 2018 Sep. 2021
 - Developed "an intelligent multi-vehicle drone testbed for space systems and remote sensing verification"
 - Assisted other teams to use the testbed in different research areas such as:
 - * Using hand gestures for controlling drone movements
 - * Using artificial neural networks as the controller for the drones
- Summer Internship in Bama Co

 $Summer\ 2014/2016$

- Condition monitoring and predictive maintenance planning of machinery and vehicles in Bama Co

• Jury Membership at Isfahan Mathhouse

2013-2018

- Member of the Jury in Isfahan Mathhouse for choosing qualified participants for International Competitions (e.g., Alympiad)
- Alympiad competition participants test grader in Isfahan Mathhouse
- Teaching Assistant at the Isfahan University of Technology

Fall 2016

- Statics, instructor: Dr. S. Akbarzadeh

Voluntary Experience

- Volunteering as an Open Source Programmer
 - The leader of the ♠ Atom-Community organization that brings an integrated development environment to Atom
 - The author of the ♥ Zadeh, a library for fast fuzzy filtering and matching written in C++
 - The author of the ♠ minijson, a library for the fast minification of the JSON files written in D, C, and AVX2 and SSE4_1 SIMD.
 - The author of the ${\Large \bigcirc}$ AcuteML, an intelligent markup language for web development written in Julia
 - The leader of the 🗘 JuliaMatlab organization, an open-source alternative for Matlab written in Julia
 - The co-owner of the ♥ JuliaMusic organization that provides music research tools (e.g. ♥ MusicXML.jl) in Julia
 - Other projects available on ♥ GitHub
- Music Performances in Morrow Gospel Church

Sep. 2018/Jan. 2019

- Two Rock/Blues performances in Blues Nights events, Winnipeg, Canada

References

- Dr. P. Ferguson, Associate Professor of Mechanical Eng.

 ☑ philip.ferguson@umanitoba.ca ♀ Page ♀ Page
- Dr. S. Balakrishnan, Professor of Mechanical Eng.

 ☑ subramaniam.balakrishnan@umanitoba.ca ♀ Page ♀ Page
- Dr. S. Ziaie-Rad, Professor of Mechanical Eng.

 ✓ szrad@cc.iut.ac.ir � Page � Page
- Dr. K. Ferens, Assistant Professor of Electrical and Computer Eng.

 ☑ ken.ferens@umanitoba.ca ♀ Page ♀ Page

University of Manitoba, Canada MIT Alumni, NSERC Research Chair

University of Manitoba, Canada

Isfahan University of Technology, Iran Imperial College London Alumni

University of Manitoba, Canada