

Amin Yahyaabadi

Vancouver, Canada

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Work Experience

- **Sanctuary AI,** Vancouver, Canada
Robotics Control Engineer, 2022 - Now
Development, evaluation, and optimization of control algorithms for the general-purpose humanoid robots

Education

- **University of Manitoba** Winnipeg, Canada
M.Sc., Mechanical Engineering Sep 2018 - Sep 2021
GPA: 4.27/4.5
- **Isfahan University of Technology (IUT)** Isfahan, Iran
B.Sc., Mechanical Engineering Sep 2013 - Feb 2018
GPA: 18.03/20 (3.91/4) 2014-2018
17.89/20 (3.81/4) overall

Research Experience

- **An Intelligent Drone Testbed for Control Systems and Verification,** 2018 - 2021
University of Manitoba
Designed an intelligent drone testbed used for validation of new satellite or drone control algorithms and hardware.
Identified the dynamics of the drone intelligently with minimal measuring using Particle Swarm Optimization (PSO).
Developed a custom onboard software for the drone to autonomously control the drone's motion and operations.  [pdf](#)
M.Sc. Thesis, Supervisor: Dr. P. Ferguson

AI PSO UAV System Identification Control Pixhawk Parrot Matlab
- **Intelligent vibration control with self-sensing piezoelectric actuator,** 2016 - 2018
Isfahan University of Technology
Developed an intelligent control method for a distributed system using a self-sensing piezoelectric actuator and PSO.
Modelled the dynamics of the system with a novel FEA+FDA method to test the controller.
B.Sc. Thesis, Supervisor: Dr. S. Ziaei-Rad

AI PSO GA Smart Material System Identification Control FEA Matlab
- **Auto Code Generation for Onboard Space Object Detection and Flight Software Applications,** 2018 - 2021
University of Manitoba
Developed machine learning and analytical image processing algorithms for satellite's onboard detection of resident space objects (RSOs) from commercial-off-the-shelf star trackers.  [pdf](#)
M.Sc. Project with Magellan Aerospace, Supervisor: Dr. P. Ferguson

Machine Learning Image Processing Xilinx Arm Cortex Intel Matlab C++
- **ManitobaSat Satellite's Onboard Computer and Flight Software Leader,** 2018 - 2021
University of Manitoba
Designed a modular onboard computer (OBC) for ManitobaSat-1, a 3U sized CubeSat satellite. The OBC was a system on a chip that used an MRAM. Developed custom real-time flight software running on FreeRTOS to control all the satellite's operations such as attitude and determination control.  [pdf](#)
M.Sc. Project with Canadian Space Agency (CSA), Supervisor: Dr. P. Ferguson

Mechatronics Control Smart Fusion Arm Cortex RTOS C++

Notable Projects

- **Rhino XR-3 5 DOF Robot Arm Real-time Control via Arduino** Selected Topics in Robot Technology, Supervisor: Dr. S. Balakrishnan

Robotics Control C++ Matlab Arduino
- **Barrett WAM 7 DOF Robot Arm Simulation and Analysis** Robotics, Supervisor: Dr. H. Mousavi

Robotics Control Matlab
- **Model Predictive Control of Robot Arm using Neural Networks** Neural Networks, Supervisor: Dr. M. Kamali

Machine Learning Control Robotics Matlab
- **Intelligent Fuzzy PID Controller for a Bluetooth controlled DC Motor via AVR** Intelligent Control, Supervisor: Dr. F. Sheikholeslam

AI Fuzzy Logic Control AVR Matlab

Mechatronic Systems, Supervisor: M. Danesh
- **Parallel Image Processing using MPI and OpenCV** Parallel Processing, Supervisor: Dr. I. Jeffrey

MPI OpenCV C++ Parallel Processing
- **Custom Simulated Annealing Investigation for Salesperson Problem - New Mathematical Proof of The Multidimensional Newton's Weights Optimization Algorithm** Applied Computational Intelligence, Supervisor: Dr. K. Ferens

Machine Learning AI SA Neural Networks Matlab
- **Designing a Signal Processing and Measuring Instrument in Labview - Verifying The Instrument using Acoustic Analysis of a Trumpet in MSC ACTRAN** Mechatronics Lab 2, Supervisors: Dr. M. Danesh

Signal Processing Acoustics Actran LabView

Engineering Acoustics, Supervisor: Dr. A. Loghmani
- **Multilayered Composite Shell Dynamics and Crack Analysis under Impact via Abaqus** Computer-Aided Engineering, Supervisor: Dr. R. Jafari

FEM Abaqus Computation Mechanics

Honours and Awards

- Fellowship for Education Purposes - \$40,500, UoM, Canada. 2018-2021
- Faculty of Graduate Studies Program Completion Scholarship - \$2,500, UoM, Canada. 2021
- International Graduate Student Entrance Scholarship (IGSES) - \$6,000, UoM, Canada. 2018
- Fellowship to Study at IUT for M.Sc Program without Entrance Exam, IUT, Iran. 2017
- Ranked top 10% among the students of the Mechanical Engineering Department, IUT, Iran. 2017
- Ranked top 0.3% among 260000 participants in Iranian University Entrance Exam for B.Sc. Studies. 2013
- Qualified as very good in Mathematics Olympiad Final International Round in the Netherlands. 2012
- Ranked 1st in Mathematics Olympiad National Round in Iran. 2011

Software and Programming Skills

- **Programming Languages:** C++, Rust, Python, Matlab, Julia, D, Go, Verilog, PLC, TypeScript, AssemblyScript
- **Technical Software:** Simulink, Abaqus, LabView, Xilinx SDSoc - Vivado, Simpack, MSC Adams / Car, MSC Actran, Autodesk Inventor, CATIA, Proteus, Modelsim, Maple
- **Embedded Processors:** Arm Cortex A9, Arm Cortex M3, Xilinx Zynq 7020 SoC/FPGA, Smart Fusion 2 SoC/FPGA, Pixhawk Flight Contrller (Px4), Parrot Mambo Flight Controller, Arduino Due /Uno, AVR Atmel STK500, Intel/AMD x86

Publications

- **A. Yahyaabadi**, M. Driedger,..., P. Ferguson, "ManitobaSat-1: A Novel Approach for Technology Advancement," in *the Journal of IEEE Potentials*, 2020, [pdf](#)
- **A. Yahyaabadi**, M. Driedger,..., P. Ferguson, "ManitobaSat-1: Making Space for Innovation," in *IEEE Canadian Conference of Electrical and Computer Engineering (CCECE)*, Edmonton, Canada, 2019 [pdf](#)
- **A. Yahyaabadi**, P. Ferguson, "An intelligent multi-vehicle drone testbed for space systems and remote sensing verification," in *Canadian Aeronautics and Space Institute (CASI) ASTRO*, Montreal, Canada, 2019 [pdf](#)
- **A. Yahyaabadi**, P. Harrison, P. Ferguson, "Auto Code Generation for Onboard Space Object Detection and Other Flight Software Applications - A Feasibility Study," in *Canadian Aeronautics and Space Institute (CASI) ASTRO*, Montreal, Canada, 2019 [pdf](#)









Attended Conferences

- **Canadian Aeronautics and Space Institute (CASI) ASTRO** Montreal, Canada, 2019
Submitted two papers and presented them:
 - "An intelligent multi-vehicle drone testbed for space systems and remote sensing verification" [pdf](#)
 - "Auto Code Generation for Onboard Space Object Detection and Flight Software Applications" [pdf](#)
- **ArcticNet (ASM) 2018** Ottawa, Canada, 2018
Presented my work by the poster and oral presentation:
 - "A multi-vehicle drone testbed for space systems and remote sensing verification" [Proceedings P. 198](#)

Additional Experience

- **The Main Member of the Drone Testbed Lab at the University of Manitoba** 2018 - 2021
 - Developed "an intelligent multi-vehicle drone testbed for space systems and remote sensing verification"
 - Assisted other teams to use the testbed in different research areas such as:
 - * Using hand gestures for controlling drone movements
 - * Using artificial neural networks as the controller for the drones
- **Summer Internship in Bama Co** Summer 2014/2016
 - Condition monitoring and predictive maintenance planning of machinery and vehicles in [Bama Co](#)
- **Jury Membership at Isfahan Mathhouse** 2013 - 2018
 - Member of the Jury in [Isfahan Mathhouse](#) for choosing qualified participants for International Competitions (e.g., Olympiad)
 - Olympiad competition participants test grader in Isfahan Mathhouse
- **Teaching Assistant at the Isfahan University of Technology** Fall 2016
 - Statics, instructor: Dr. S. Akbarzadeh

Voluntary Experience

- **Volunteering as an Open Source Programmer**
 - The leader of the  [Atom-Community](#) organization that brings an integrated development environment to Atom
 - The author of the  [Zadeh](#), a library for fast fuzzy filtering and matching written in C++
 - The author of the  [minijson](#), a library for the fast minification of the JSON files written in D, C, and AVX2 and SSE4.1 SIMD.
 - The author of the  [AcuteML](#), an intelligent markup language for web development written in Julia
 - The leader of the  [JuliaMatlab](#) organization, an open-source alternative for Matlab written in Julia
 - The co-owner of the  [JuliaMusic](#) organization that provides music research tools (e.g.  [MusicXML.jl](#)) in Julia
 - Other projects available on  [GitHub](#)
- **Music Performances in Morrow Gospel Church** Sep. 2018/Jan. 2019
 - Two Rock/Blues performances in Blues Nights events, Winnipeg, Canada















GRE

- Quantitative: 170/170
- Verbal: 151/170
- Analytical Writing: 3.5

Selected Courses

- Applied Computational Intelligence: 4.5/4.5
- Selected Topics in Robot Technology: 4.5/4.5
- Mechatronics: 20/20
- Robotics: 19.5/20
- Neural Networks: 20/20
- Intelligent Control: 18/20
- Applied Vibrations: 19.6/20
- Acoustics: 19.5/20
- Machinery Dynamics: 19.3/20
- Vehicle Dynamics: 18.3/20
- Mechatronics Lab 1 and 2 : 18.25/20 and 19/20
- Applied Electrical/Electronics: 19.03/20
- Dynamics: 18.5/20
- Computer-aided design: 18.1/20
- Engineering Mathematics: 20/20
- Differential Equations: 20/20
- General Mathematics: 20/20
- Advanced Dynamics (Audited)
- Parallel Processing (Audited)

References

- **Dr. H. Khadivi**, Control Engineering Team Lead Sanctuary AI, Canada
 hatef@sanctuary.ai  [Page](#) The University of British Columbia Alumni, Canada
- **Dr. P. Ferguson**, Associate Professor of Mechanical Eng, NSERC Research Chair, University of Manitoba, Canada
 philip.ferguson@umanitoba.ca  [Page](#)  [Page](#) Massachusetts Institute of Technology (MIT) Alumni, US
- **Dr. S. Balakrishnan**, Professor of Mechanical Eng. University of Manitoba, Canada
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- **Dr. S. Ziaie-Rad**, Professor of Mechanical Eng. Isfahan University of Technology, Iran
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- **Dr. K. Ferens**, Assistant Professor of Electrical and Computer Eng. University of Manitoba, Canada
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