Connection Between Scooters

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1 Problem Statement

We are looking to find a optimum way(time, distance) to connect scooters to each other. For example in a case that charge level for a single scooter is not enough for completing the commute, linking between scooters makes the whole trip from start point to end point possible for commuter.

2 Index

i: origins

j: destinations

s: scooter

3 Parameters

 C_{ij} : travel time control parameter h_{ij} : commute demand from i to j

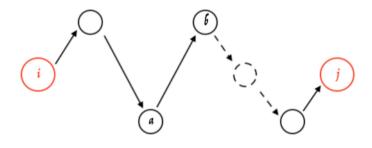


Figure 1: Connection Model

4 Variables

$$X_{i,s} = \begin{cases} 1 & \text{if scooter s is in location i} \\ 0, & \text{otherwise} \end{cases}$$

$$H_{ab} = \begin{cases} 1 & \text{if arc (a,b) is used to an trip} \\ 0, & \text{otherwise} \end{cases}$$

$$Y_{ij} = \begin{cases} 1 & \text{if there is a trip from i to j} \\ 0, & \text{otherwise} \end{cases}$$

 $P_{ab}^{ij} = \begin{cases} 1 & \text{if a paved trip between i and j uses arc (a,b) in the direction of a to b} \\ 0, & \text{otherwise} \end{cases}$

5 Model

5.1 Objective Function

$$\max \sum_{i} \sum_{j} h_{ij} \cdot Y_{ij} \tag{1}$$

5.2 Constraints

$$\sum_{ab} (P_{ab}^{ij} + P_{ba}^{ij}).c_{ab} \le C_{ij}.Y_{ij} \qquad \forall i \in I, \forall j \in J$$
 (2)

$$\sum_{a,i} P_{ai}^{ij} = Y_{ij} \qquad \forall i \in I, \forall j \in J$$
 (3)

Starting point of each interior path is equal to 1 if the a trip between i,j exists.

$$P_{ab}^{ij} + P_{ba}^{ij} \le H_{ab} \qquad \forall i \in I, \forall j \in J$$
 (4)

$$P_{ab}^{ij} \le H_{ab} \qquad \forall i \in I, \forall j \in J$$
 (5)

$$\sum_{a,k} P_{ak}^{ij} - \sum_{k,h} P_{kb}^{ij} = 0 \qquad \forall i \in I, \forall j \in J$$
 (6)

$$H_{ab} \le \sum_{s} x_{a,s} \qquad \forall a \in I$$
 (7)