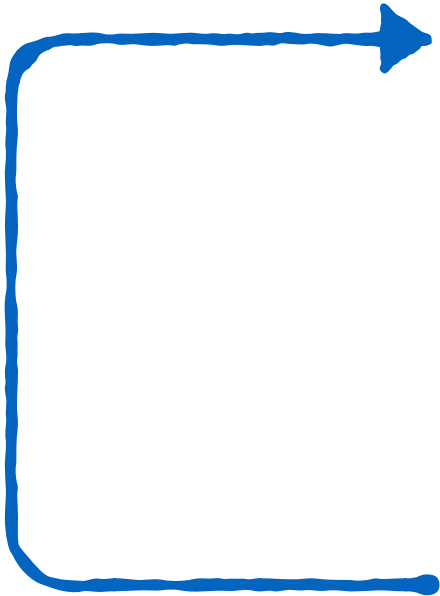


Input



output













l





K





d





U











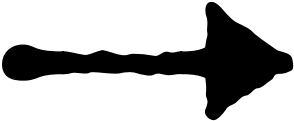


d

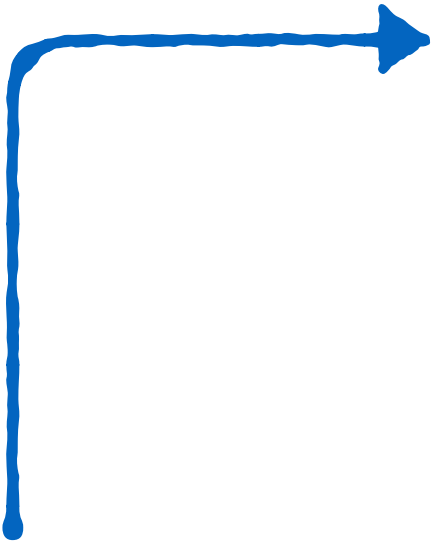




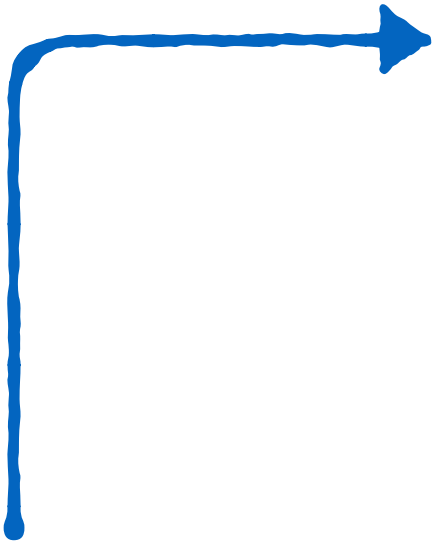
road bike



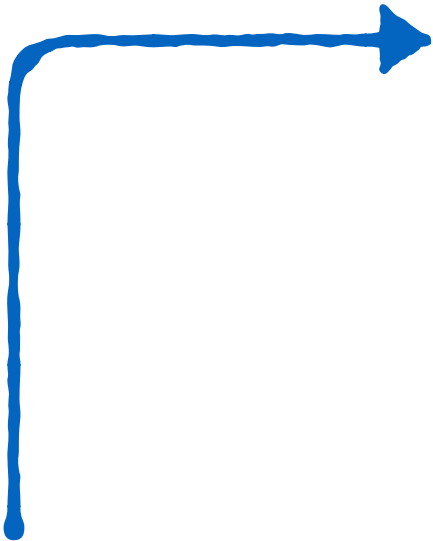




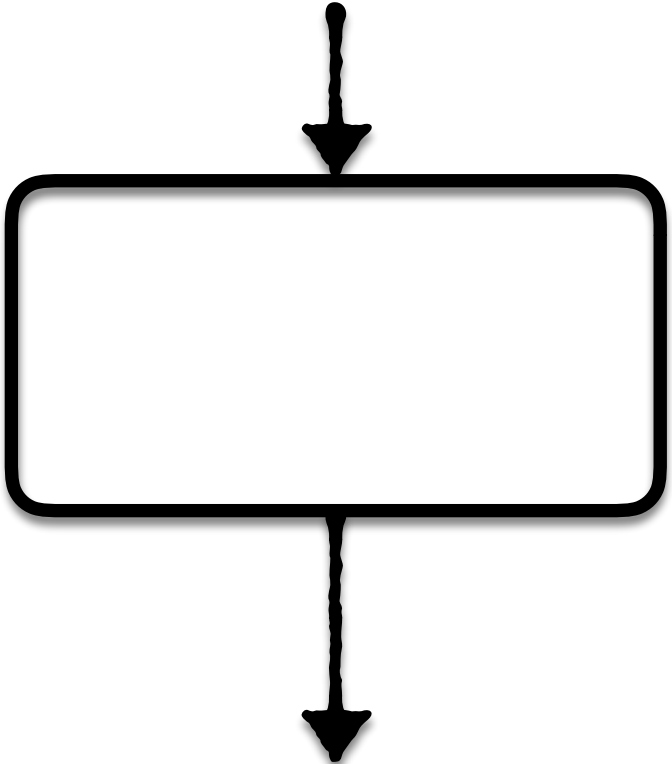






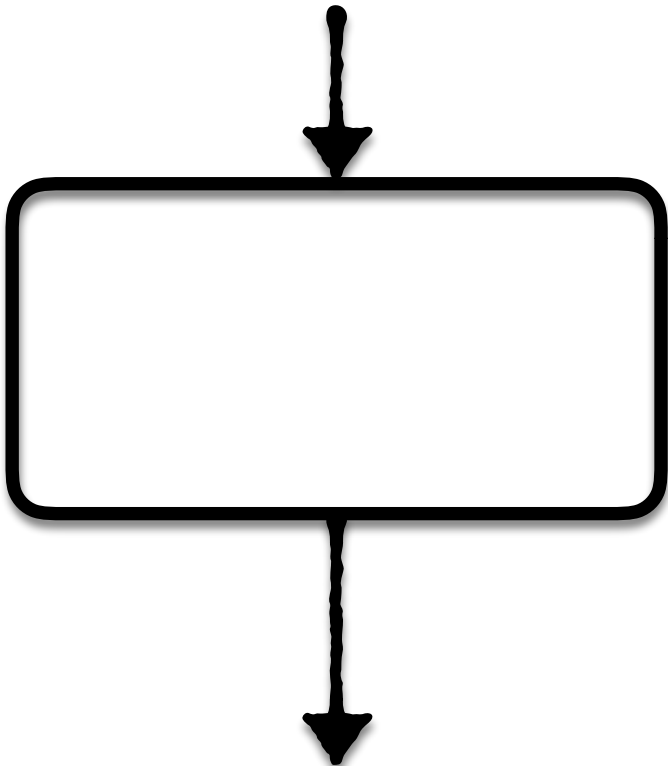


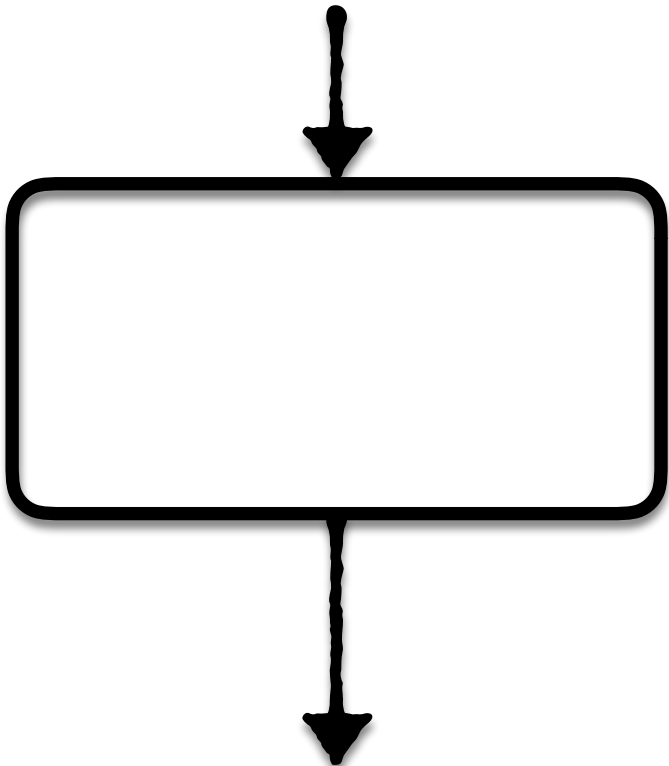


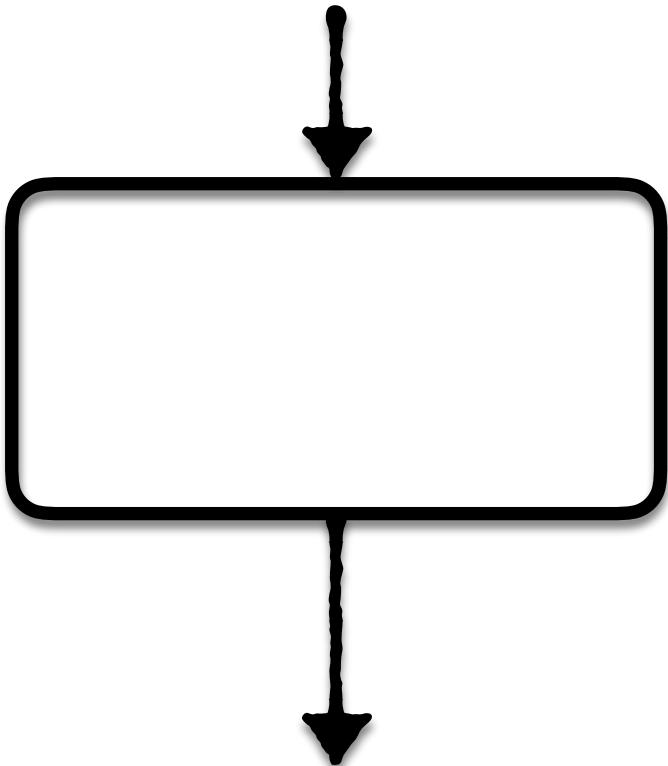


















roadbike







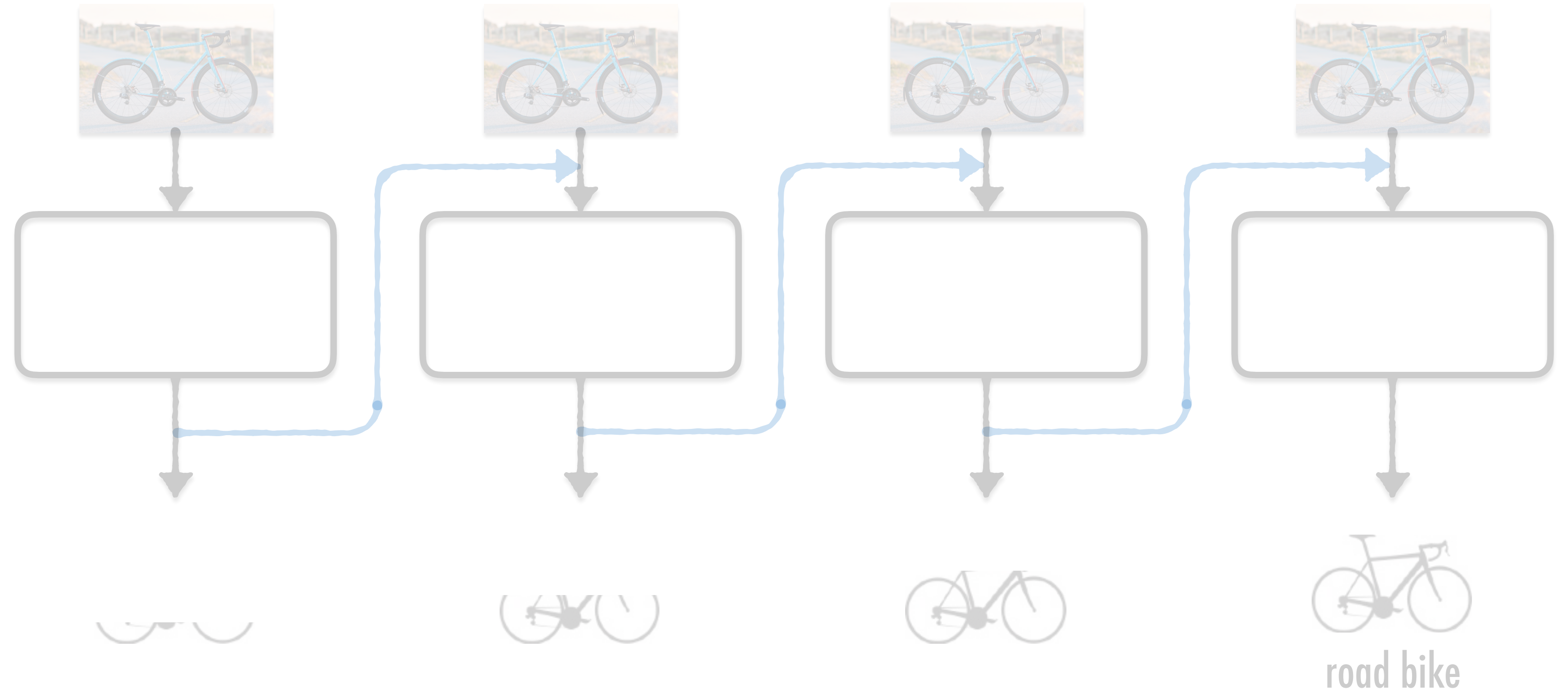
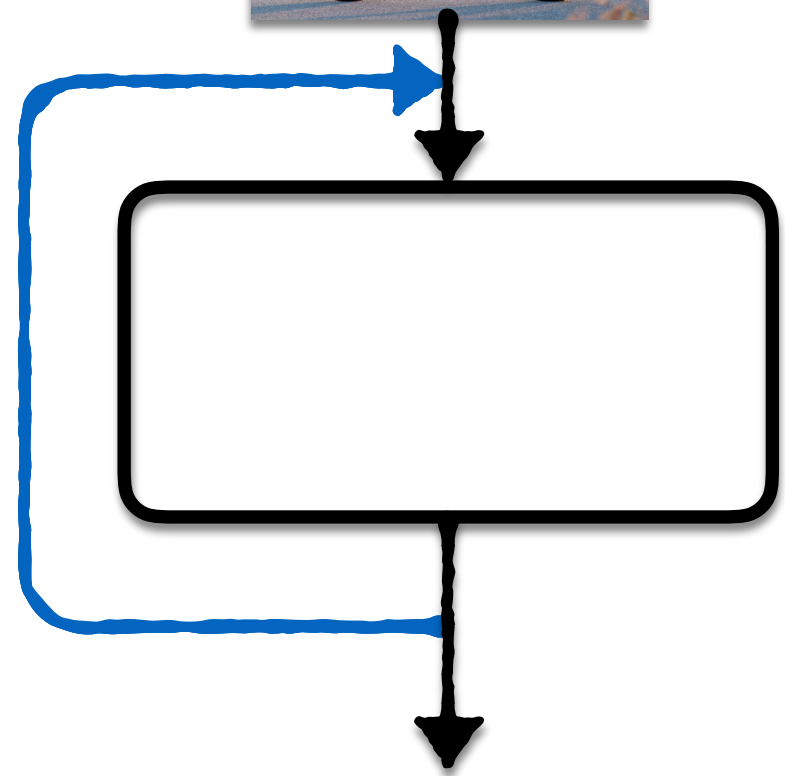






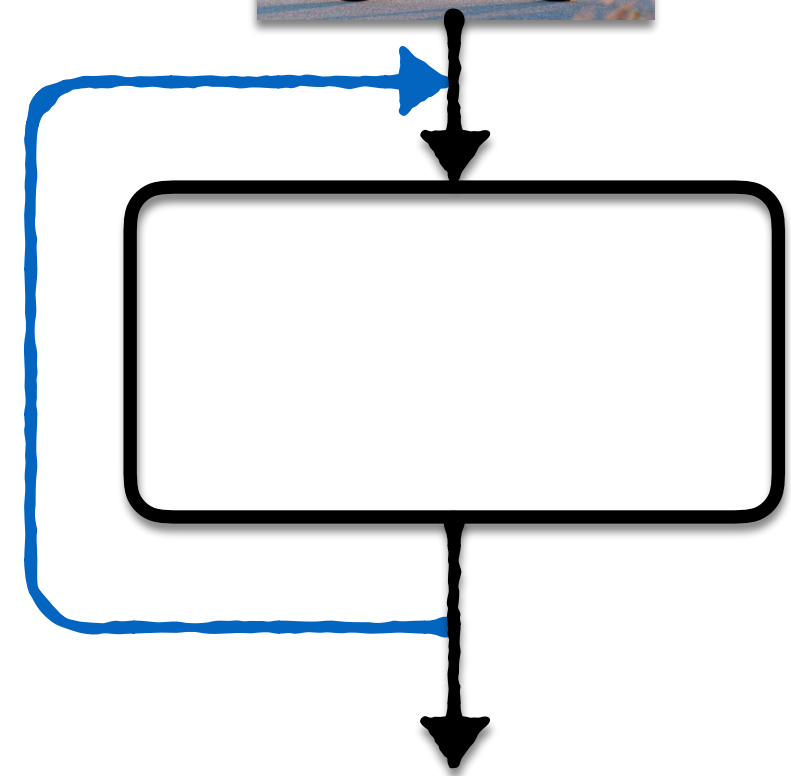
Feed back model/underlled.

Input

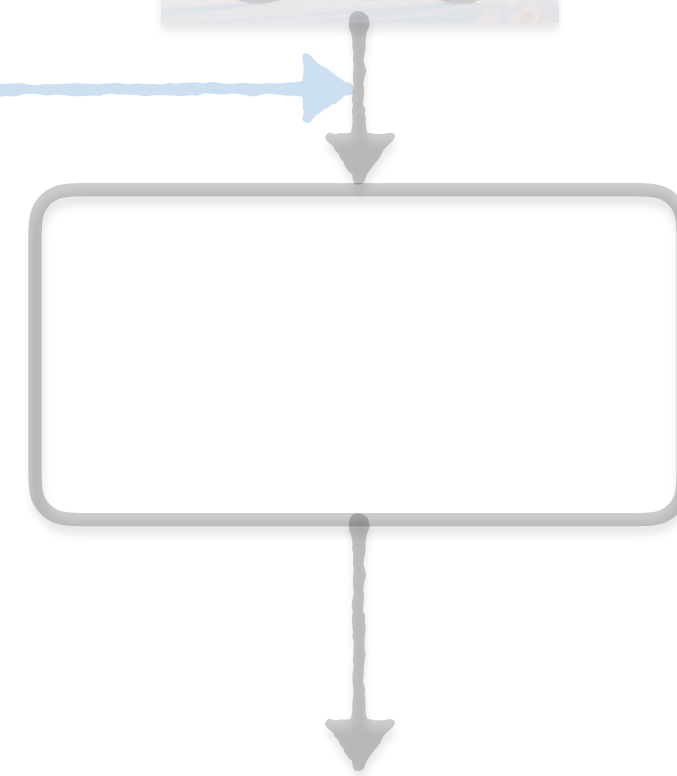
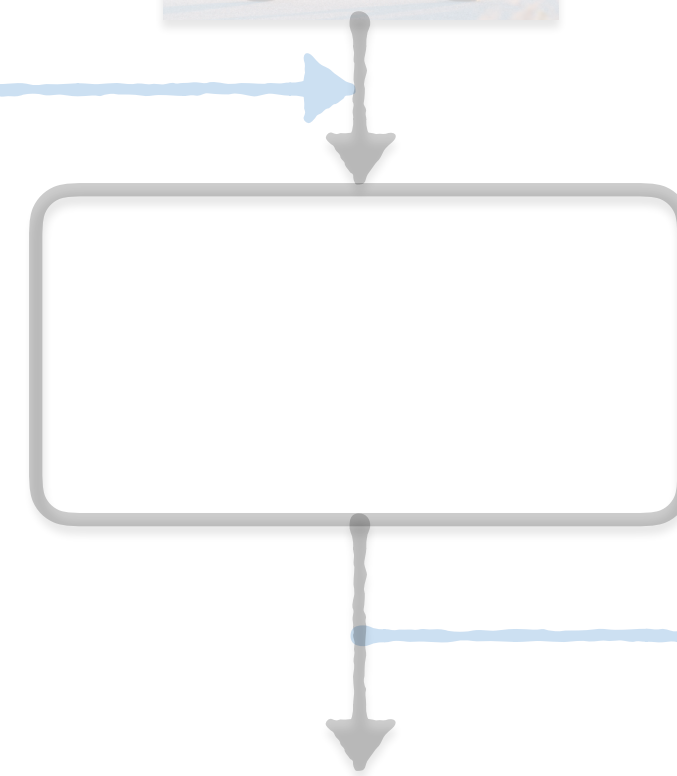
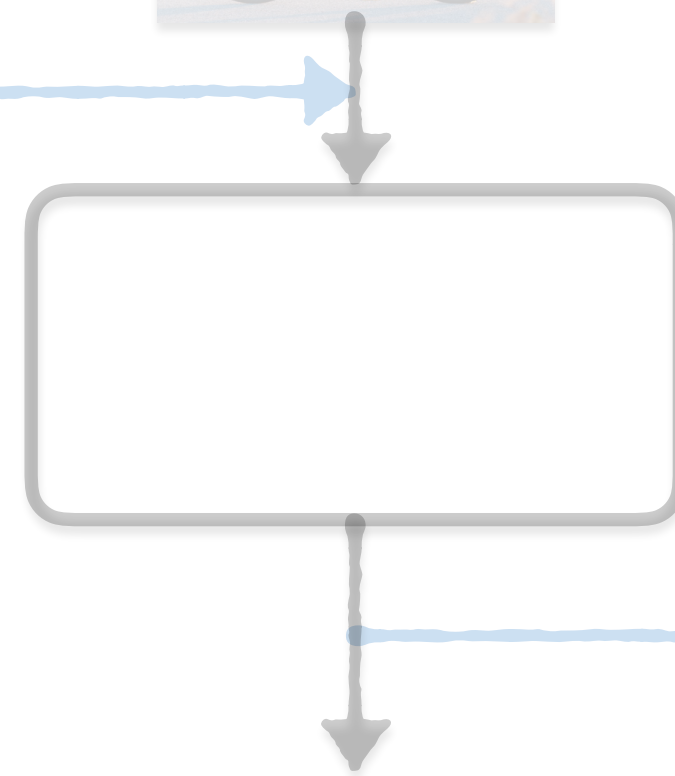
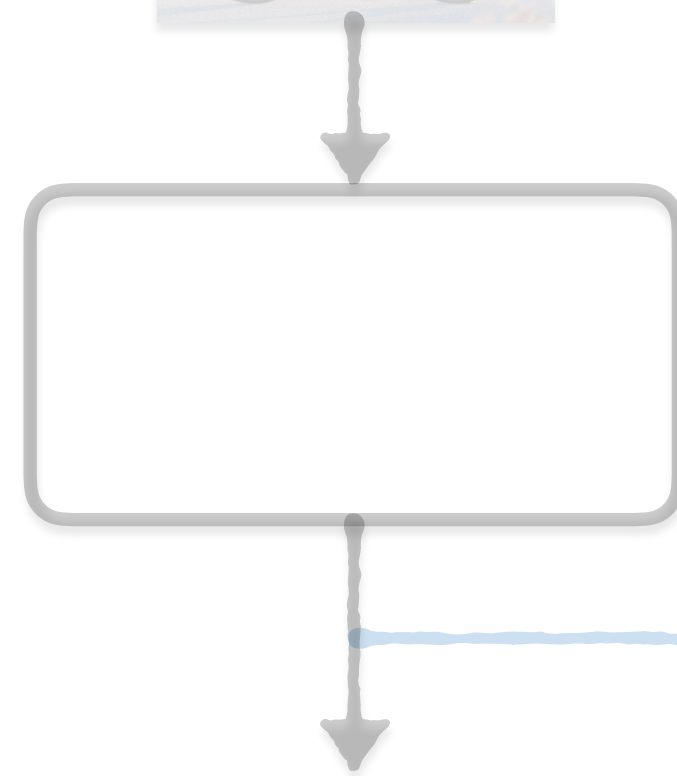


output

Input



output



road bike