





**road bike**



Input







output



















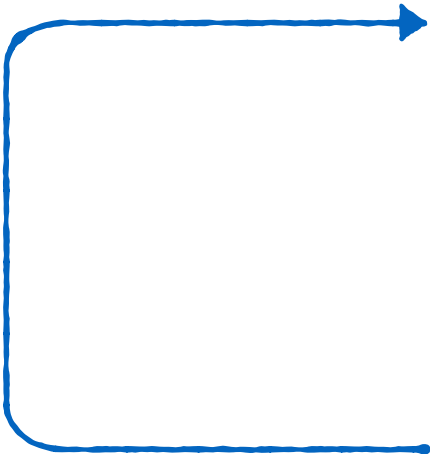




























**d**

V











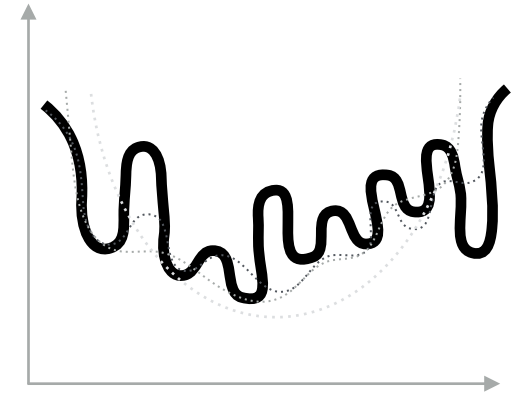
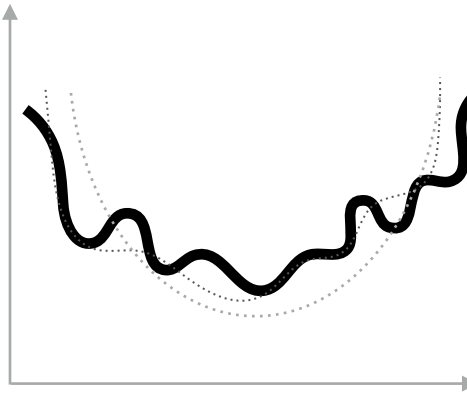
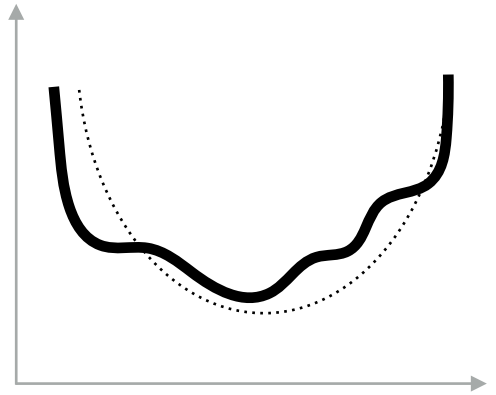
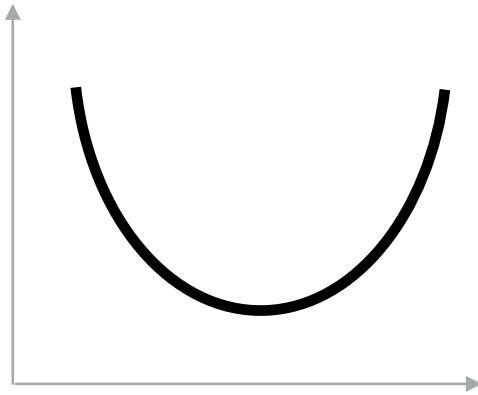


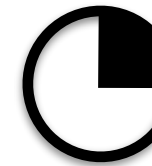




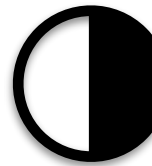
episodic  
curriculum  
learning

**taxonomic  
prediction**

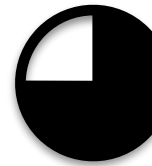




$T/4$



$2T/4$



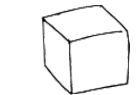
$3T/4$



$4T/4$

early  
prediction

time



**object**



**vehicle**

...



**wheeled vehicle**



vessel



**bike**



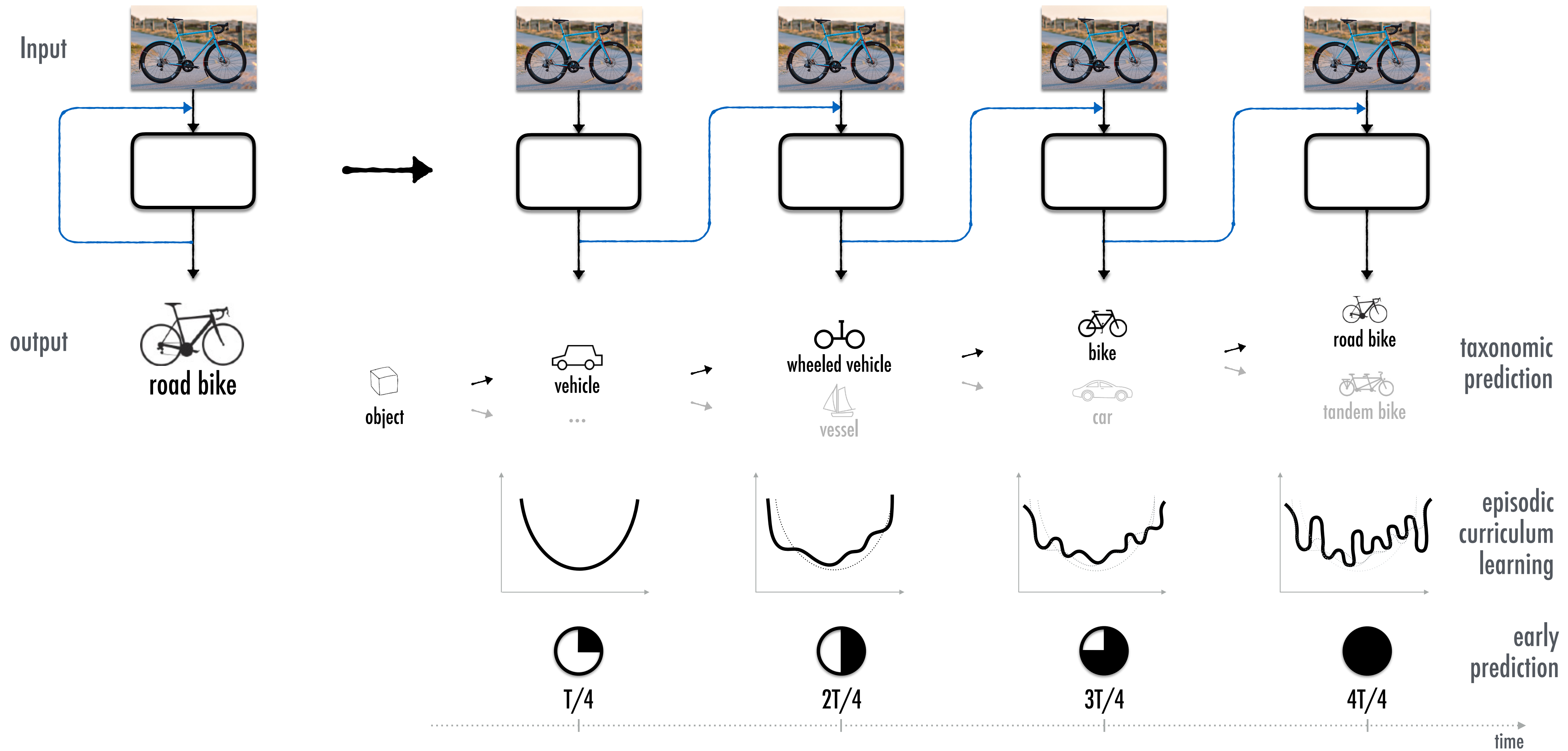
car



**road bike**



tandem bike



**Core Advantages**