

Spring 2011

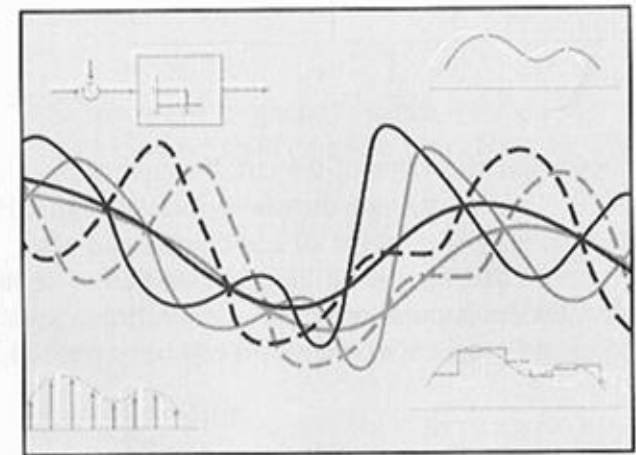
# 信號與系統 Signals and Systems

## Chapter SS-7 Sampling

Feng-Li Lian

NTU-EE

Feb11 – Jun11

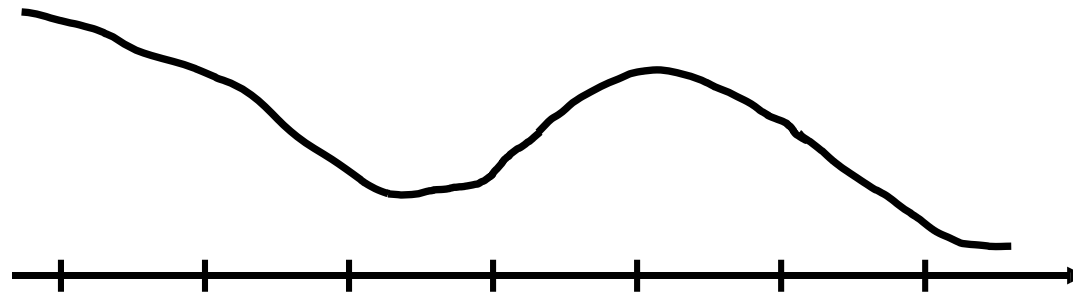


Figures and images used in these lecture notes are adopted from  
“Signals & Systems” by Alan V. Oppenheim and Alan S. Willsky, 1997

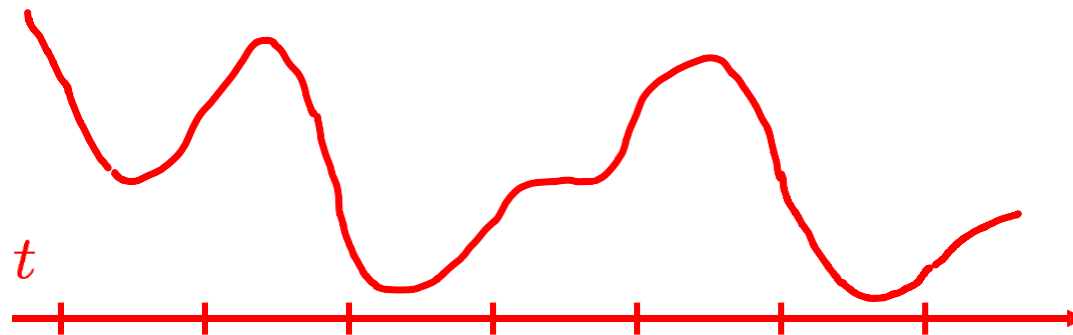
- Representation of of a Continuous-Time Signal by Its Samples: The Sampling Theorem
- Reconstruction of of a Signal from Its Samples Using Interpolation
- The Effect of Under-sampling: Aliasing
- Discrete-Time Processing of Continuous-Time Signals
- Sampling of Discrete-Time Signals

## ■ Representation of CT Signals by its Samples

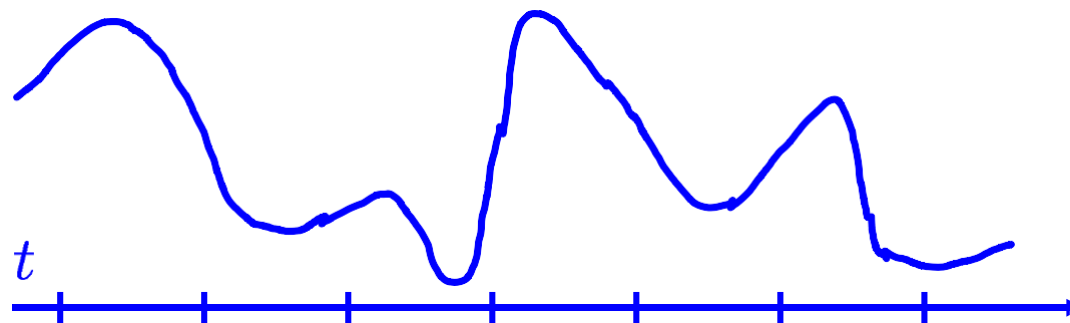
$x_1(t)$



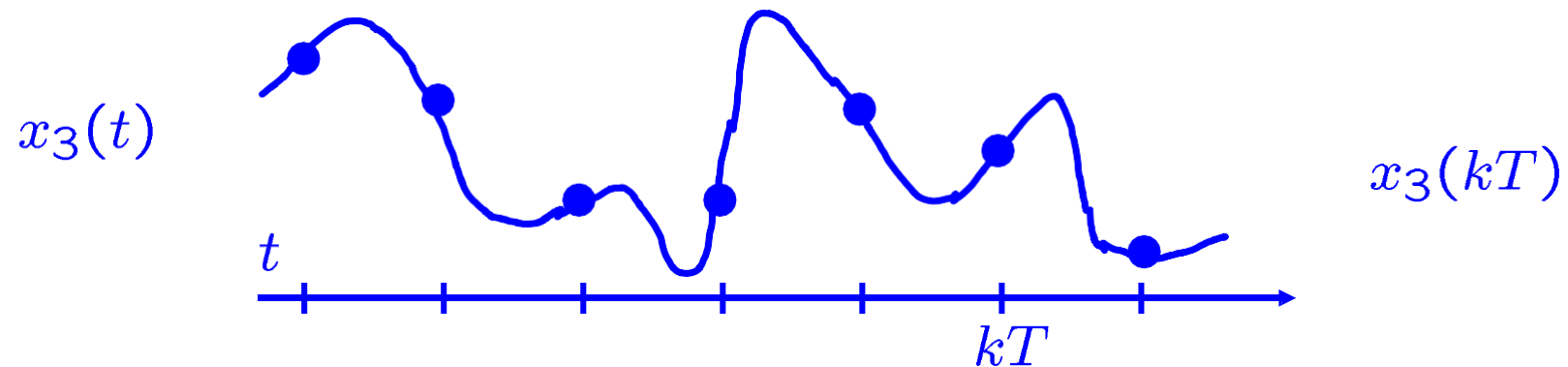
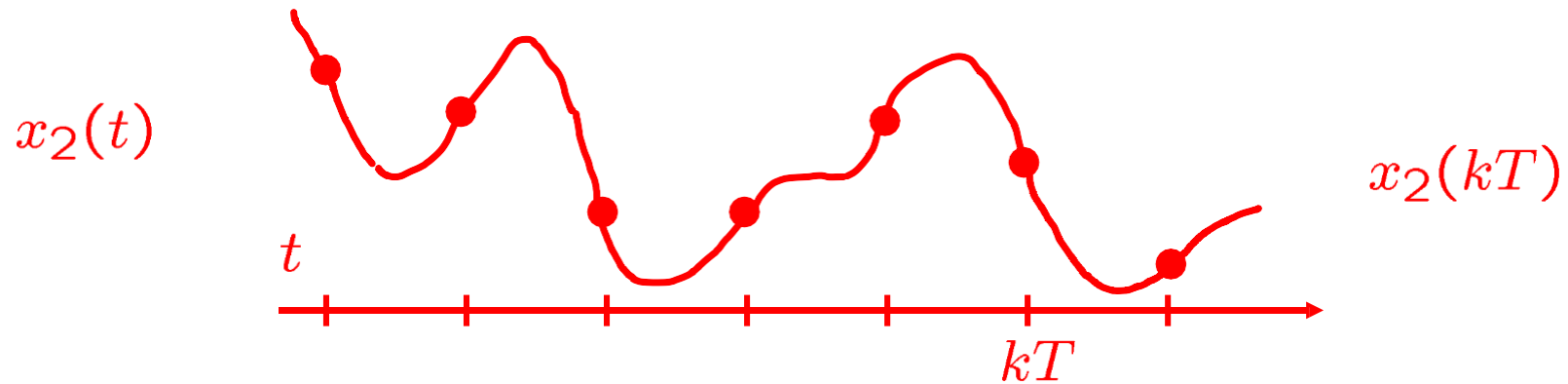
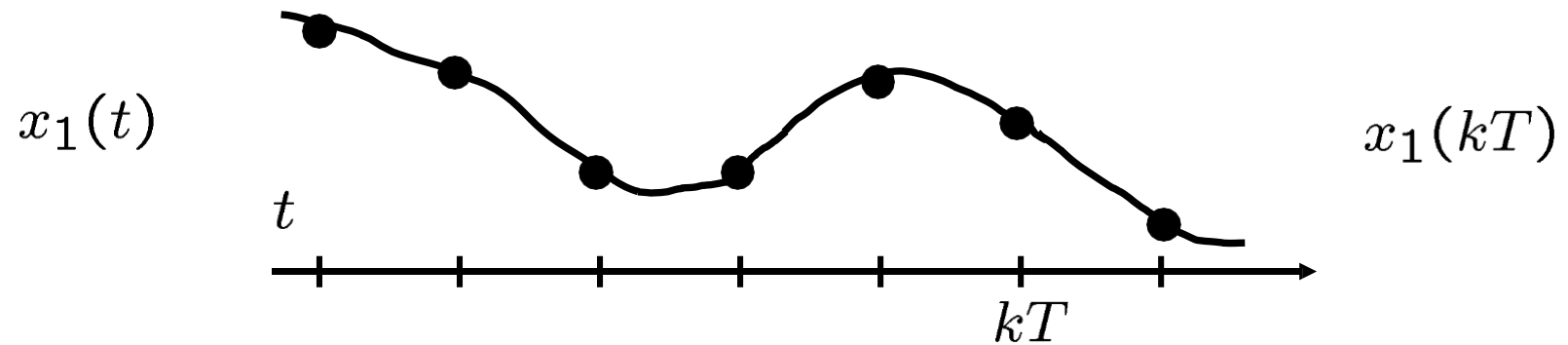
$x_2(t)$



$x_3(t)$

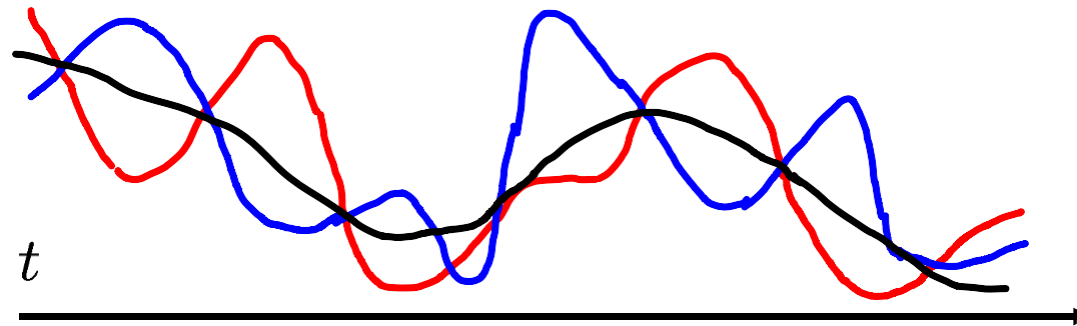


## ■ Representation of CT Signals by its Samples

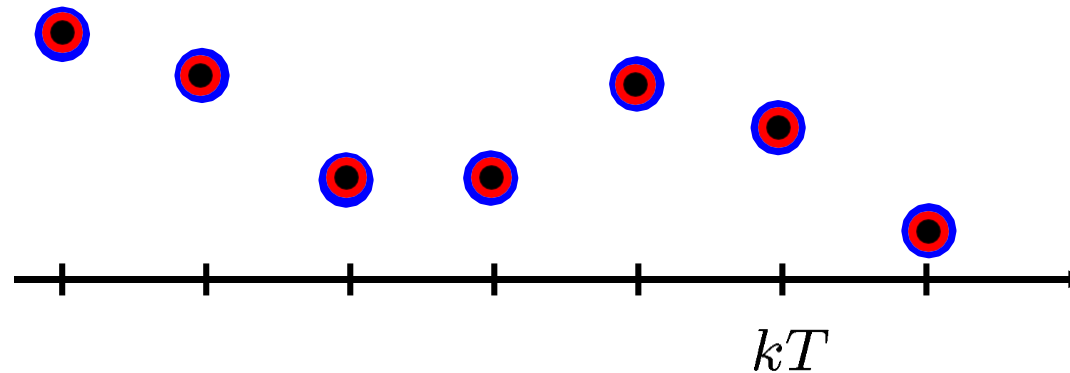


## ■ Representation of CT Signals by its Samples

$$x_1(t) \neq x_2(t) \neq x_3(t)$$



$$x_1(kT) = x_2(kT) = x_3(kT)$$



## ■ Impulse-Train Sampling:

$p(t)$  : sampling function

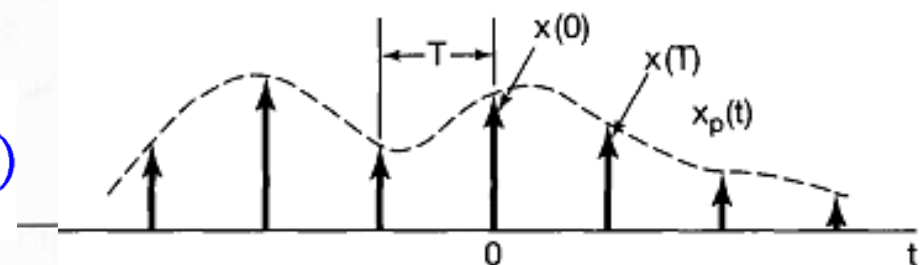
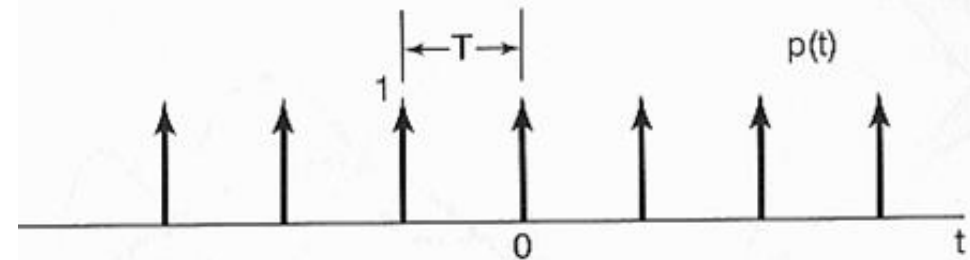
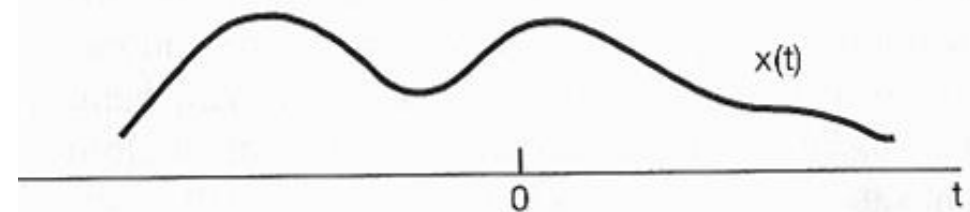
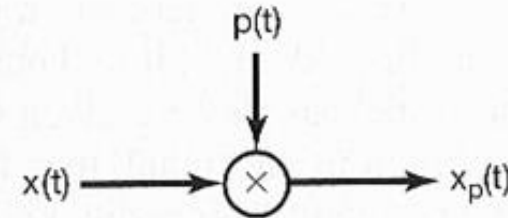
$T$  : sampling period

$w_s = \frac{2\pi}{T}$  : sampling frequency

$$\Rightarrow x_p(t) = x(t) p(t)$$

$$p(t) = \sum_{n=-\infty}^{+\infty} \delta(t - nT)$$

$$x_p(t) = \sum_{n=-\infty}^{+\infty} x(nT) \delta(t - nT)$$



## ■ Impulse-Train Sampling:

From multiplication property,

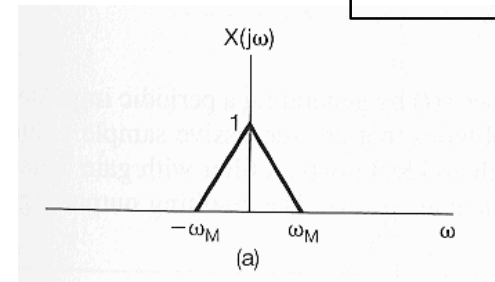
$$x_p(t) = x(t) p(t) \xleftrightarrow{\mathcal{F}} X_p(j\omega) = \frac{1}{2\pi} \int_{-\infty}^{+\infty} X(j\theta) P(j(\omega - \theta)) d\theta$$

Eq 4.70, p. 322

$$= \frac{1}{T} \sum_{k=-\infty}^{+\infty} X(j(\omega - k\omega_s))$$

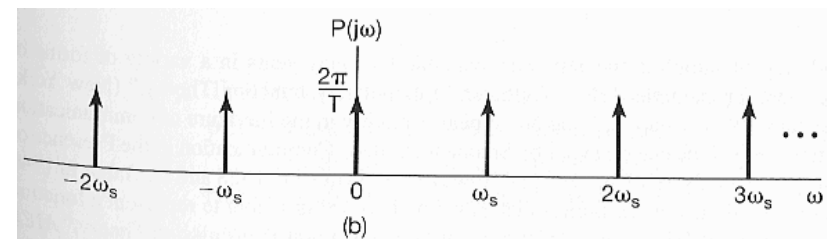
Ex 4.21, p. 323

$$x(t) \xleftrightarrow{\mathcal{F}} X(j\omega)$$



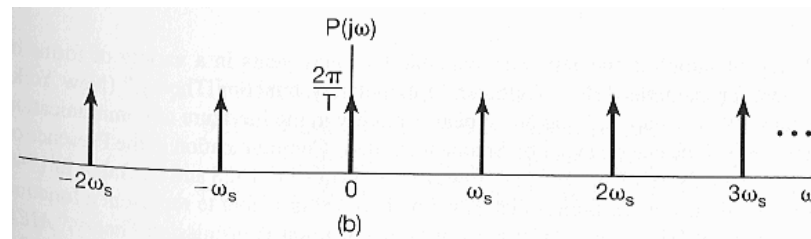
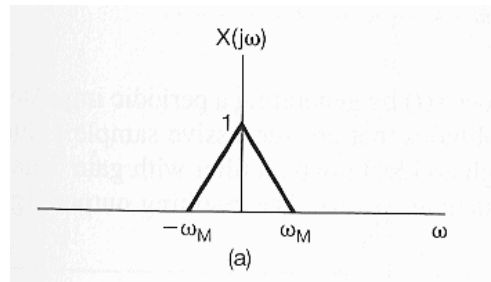
$$p(t) \xleftrightarrow{\mathcal{F}} P(j\omega) = \frac{2\pi}{T} \sum_{k=-\infty}^{+\infty} \delta(\omega - k\omega_s)$$

Ex 4.8, pp. 299-300

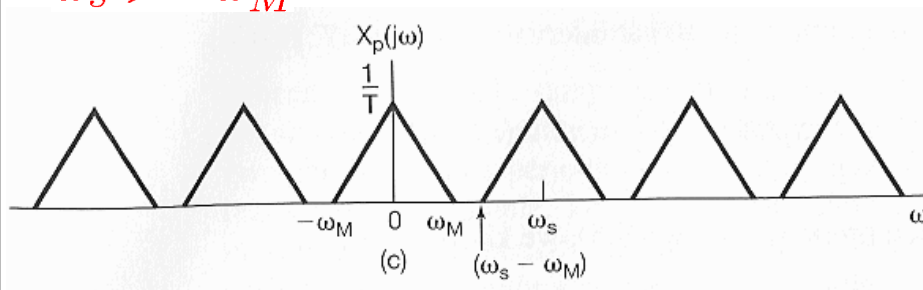


## ■ Impulse-Train Sampling:

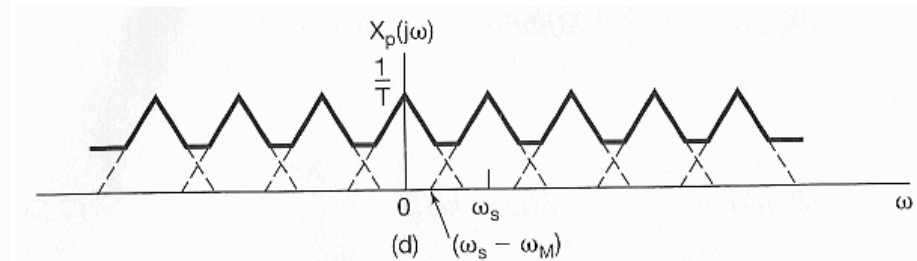
Ex 4.21, 4.22, pp. 323-4



$$\omega_s > 2\omega_M$$



$$\omega_s < 2\omega_M$$

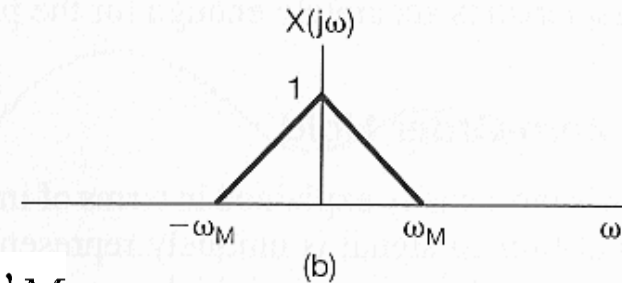




## ■ The Sampling Theorem:

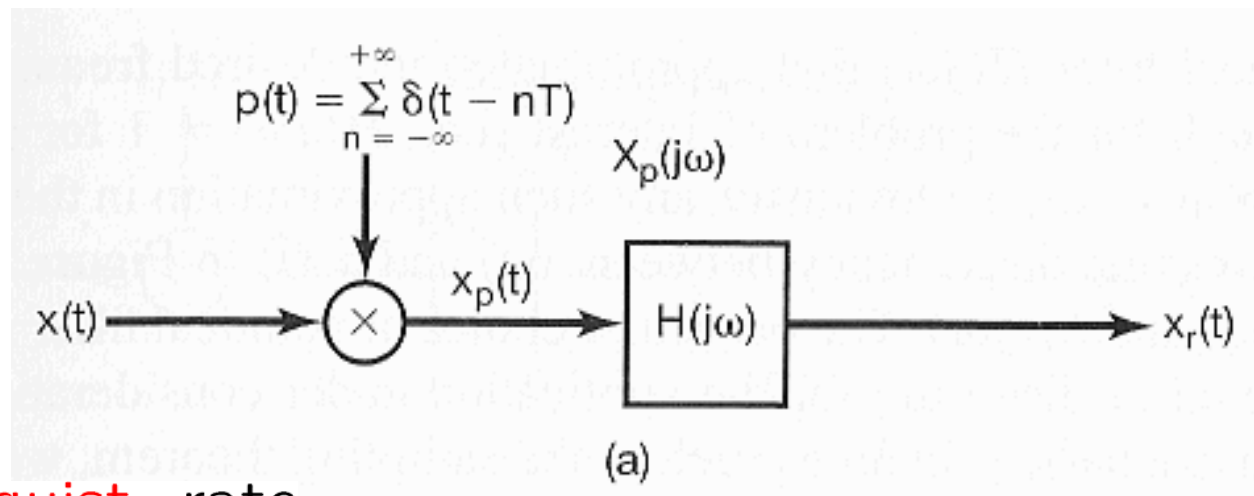
$x(t)$  : a band-limited signal

with  $X(j\omega) = 0$  for  $|\omega| > \omega_M$



if  $\omega_s > 2\omega_M$  where  $\omega_s = \frac{2\pi}{T}$

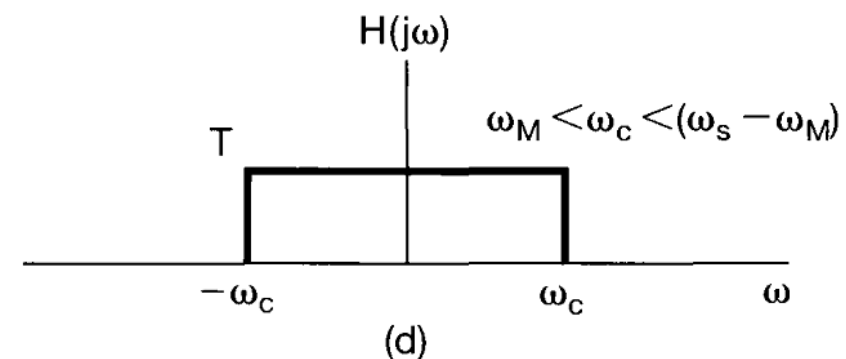
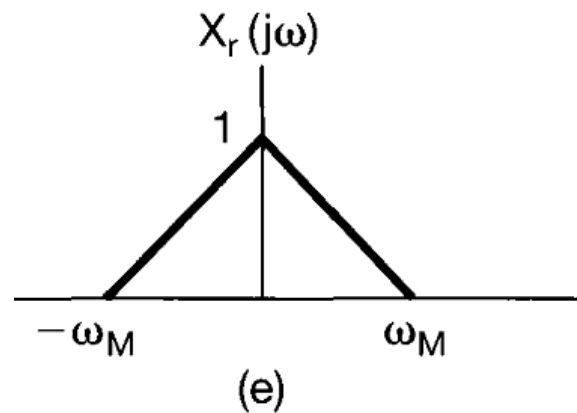
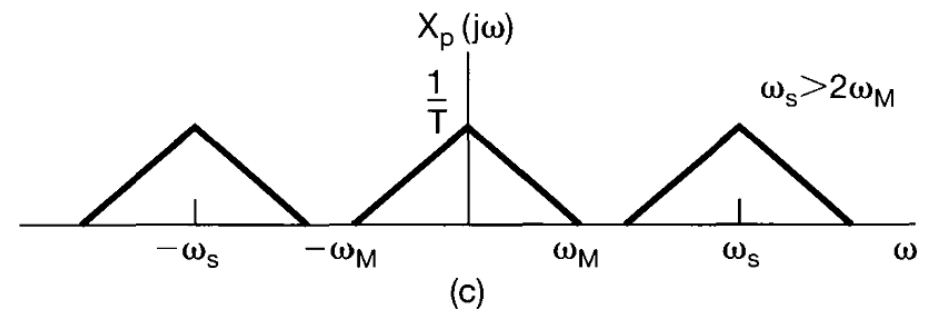
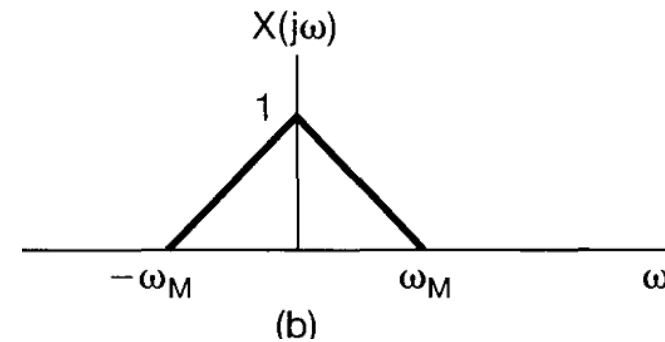
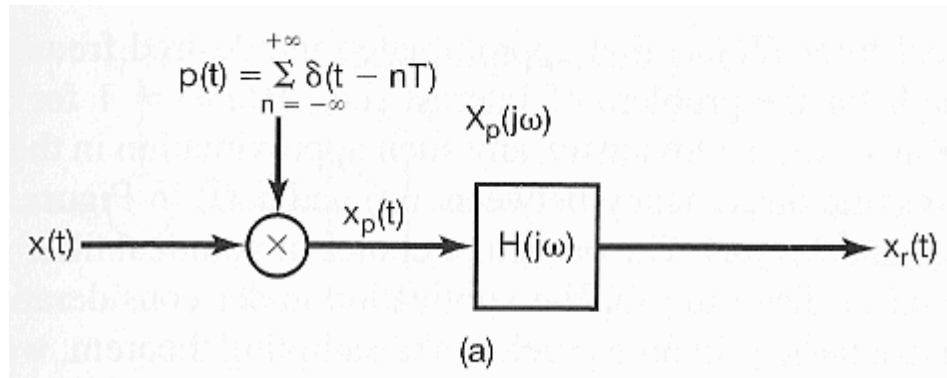
$\Rightarrow x(t)$  is uniquely determined by  $x(nT)$ ,  $n = 0, \pm 1, \pm 2, \dots$ ,



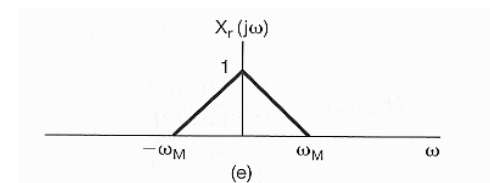
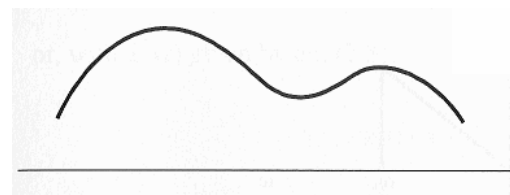
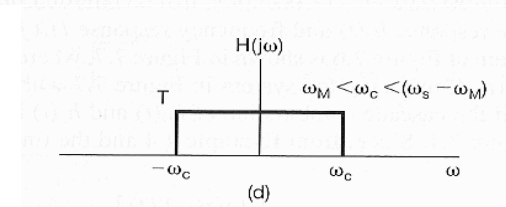
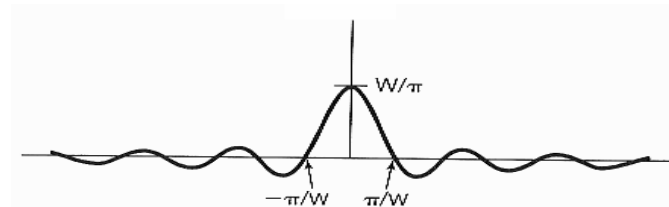
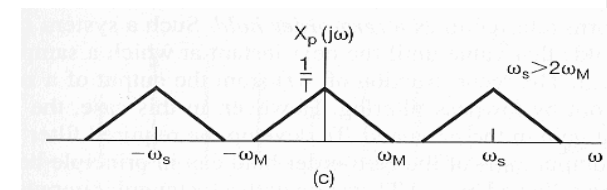
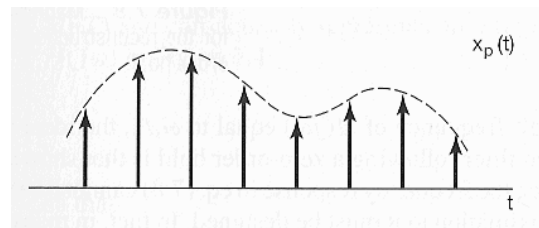
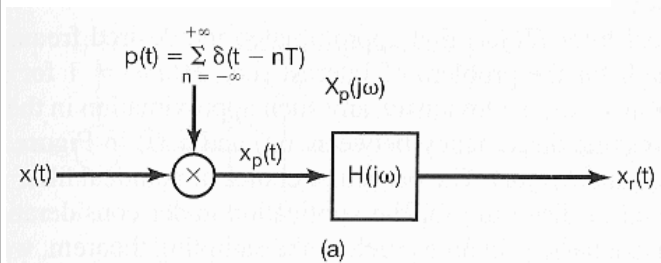
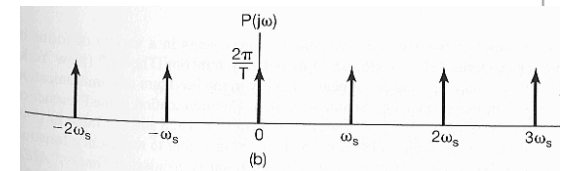
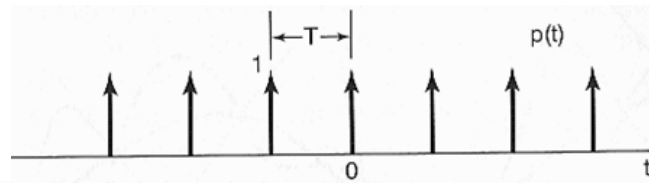
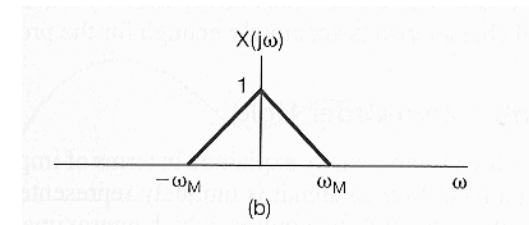
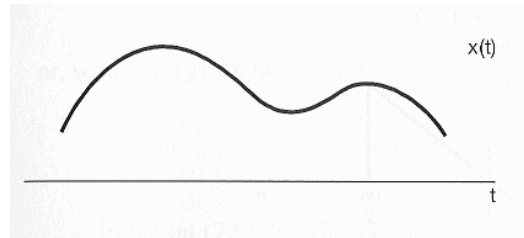
$\Rightarrow 2\omega_M$  : Nyquist rate

$\omega_M$  : Nyquist frequency

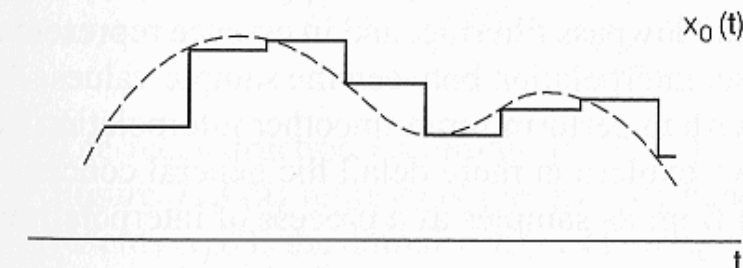
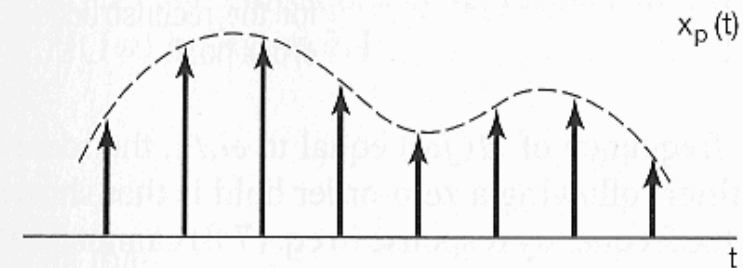
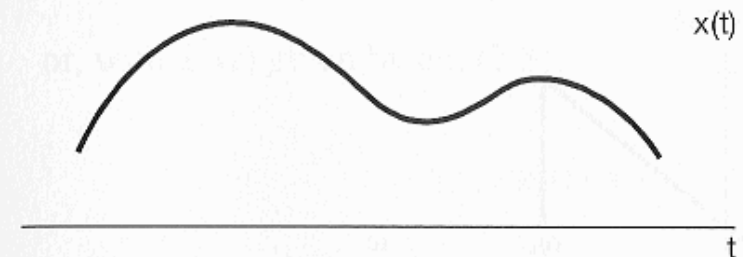
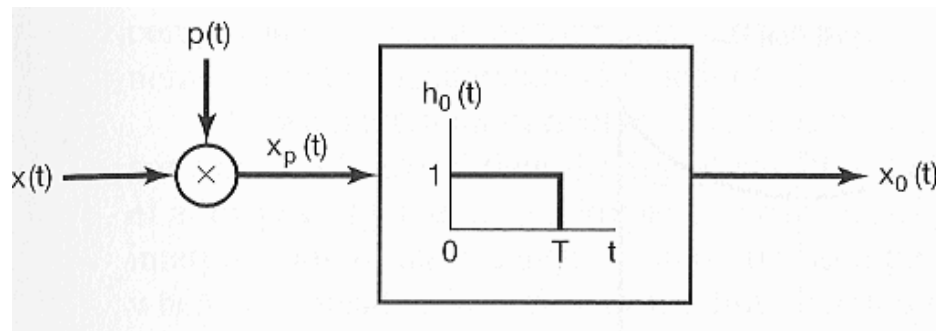
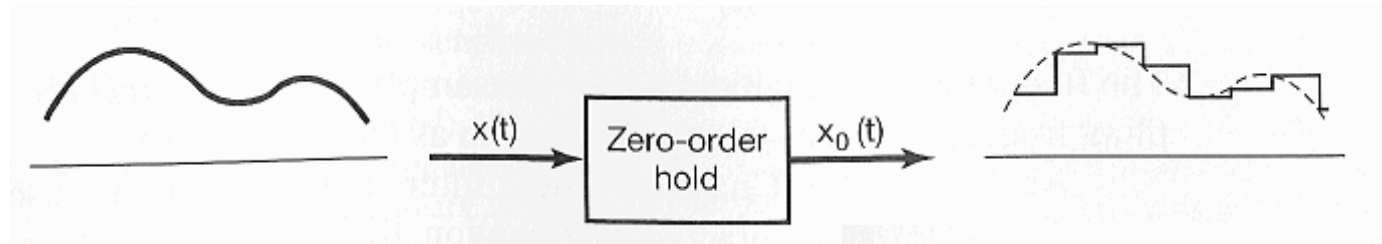
## Exact Recovery by an Ideal Lowpass Filter:



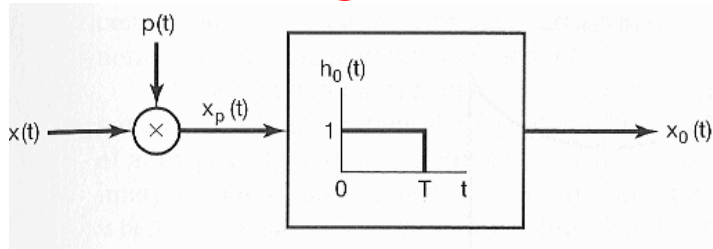
## Exact Recovery by an Ideal Lowpass Filter:



## ■ Sampling with Zero-Order Hold:



## ■ Sampling with Zero-Order Hold:

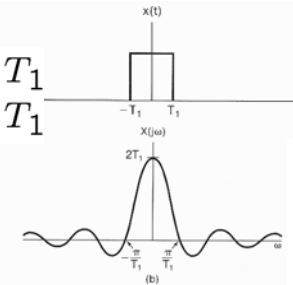


Ex 4.4, p. 293

Eq 4.27, p. 301

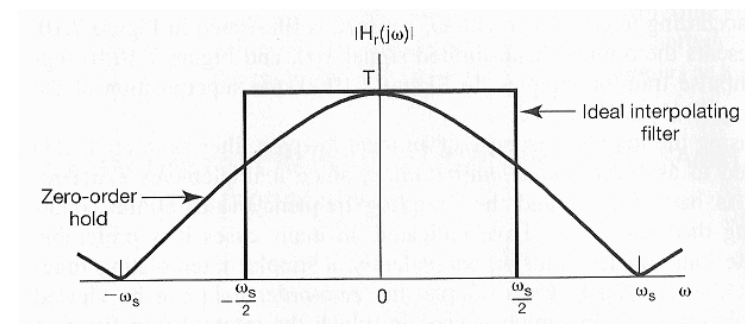
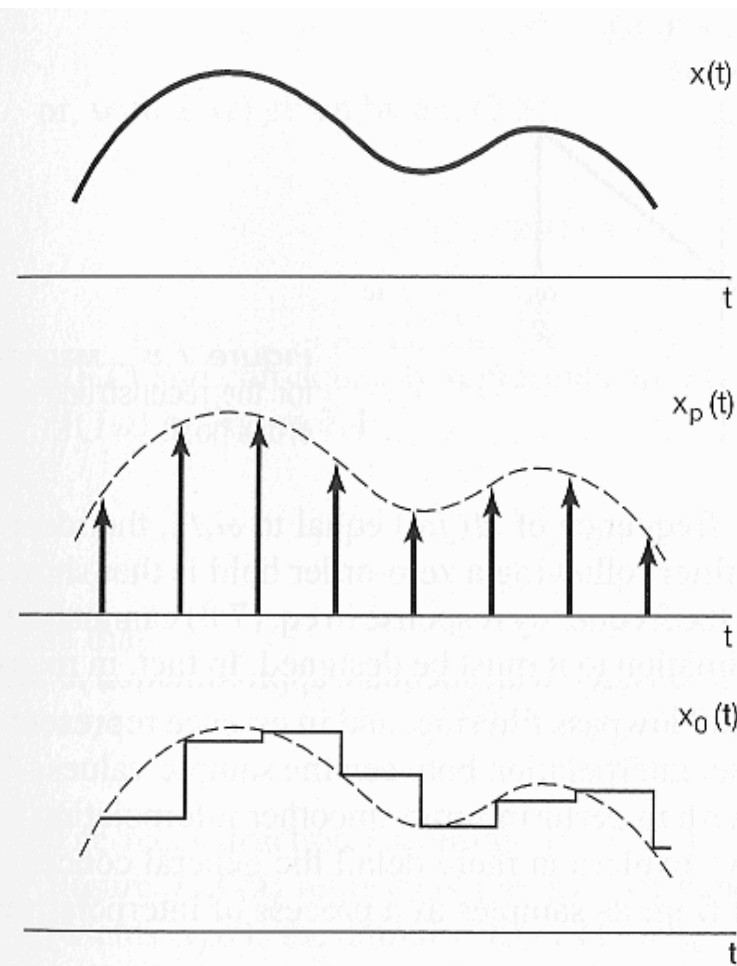
$$x(t) = \begin{cases} 1, & |t| < T_1 \\ 0, & |t| > T_1 \end{cases}$$

$$X(j\omega) = 2 \frac{\sin(\omega T_1)}{\omega}$$

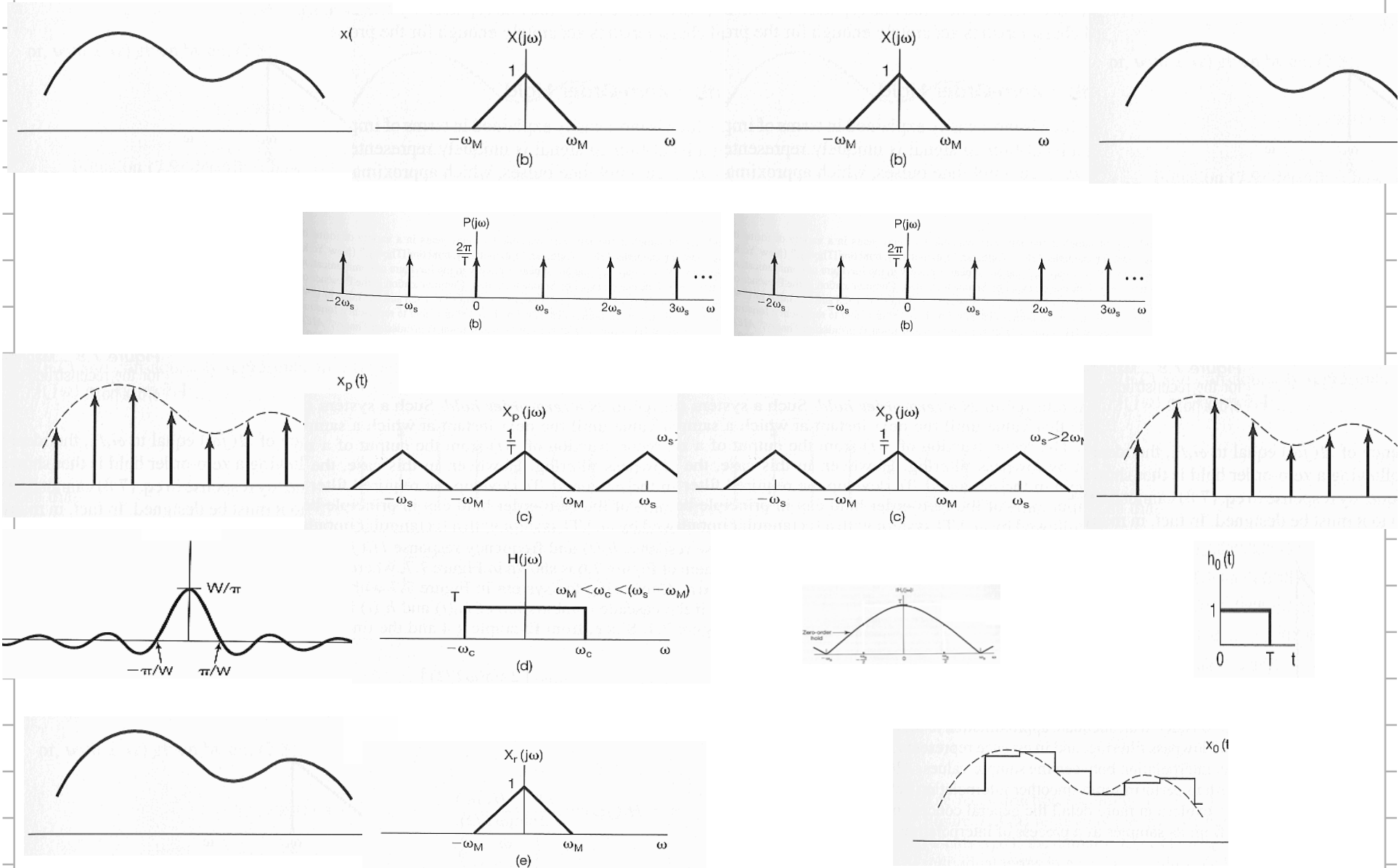


$$x(t - t_0) \xleftrightarrow{\mathcal{F}} e^{-j\omega t_0} X(j\omega)$$

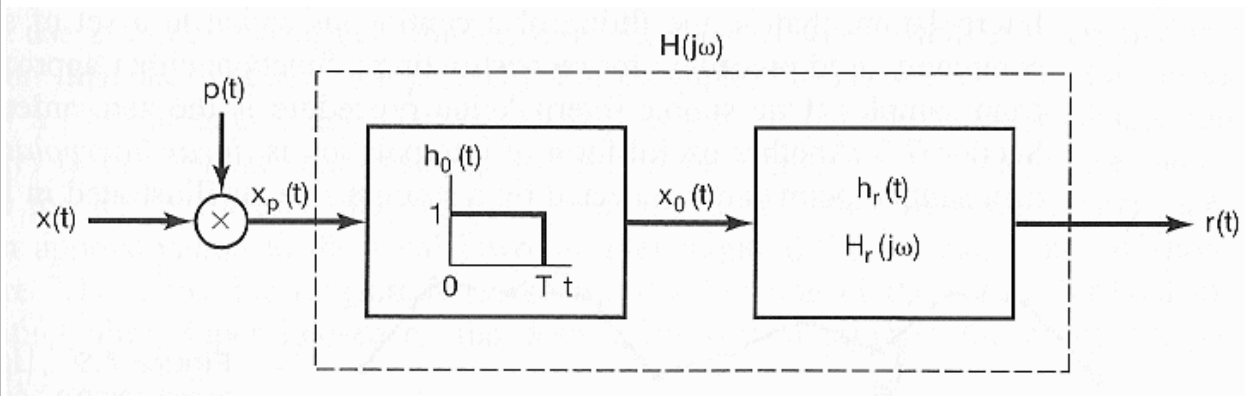
$$H_0(j\omega) = e^{-j\omega T/2} \left[ \frac{2 \sin(\omega T/2)}{\omega} \right]$$



## ■ With Ideal Lowpass Filter & with Zero-Order Hold:



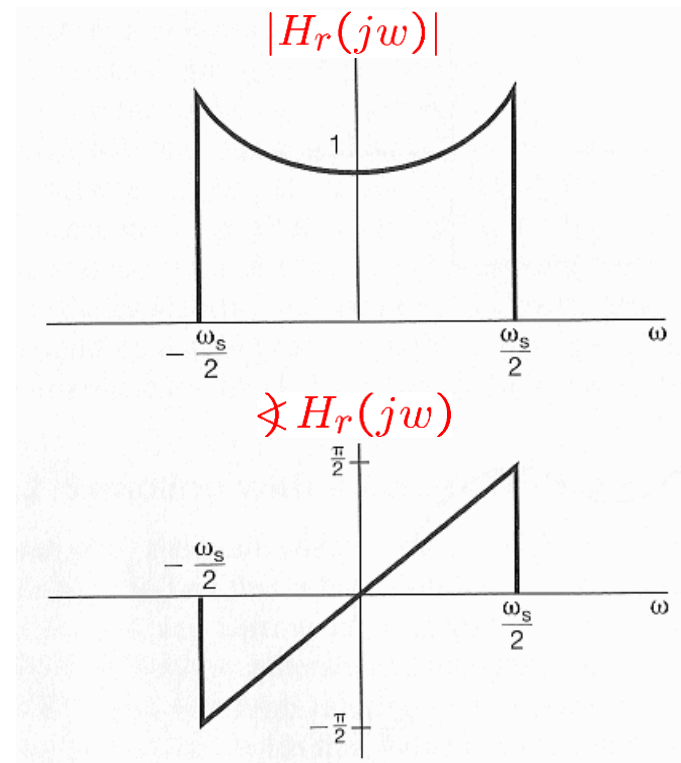
## ■ Sampling with Zero-Order Hold:



$$H_0(j\omega) = e^{-j\omega T/2} \left[ \frac{2 \sin(\omega T/2)}{\omega} \right]$$

$$H(j\omega) = H_0(j\omega) H_r(j\omega)$$

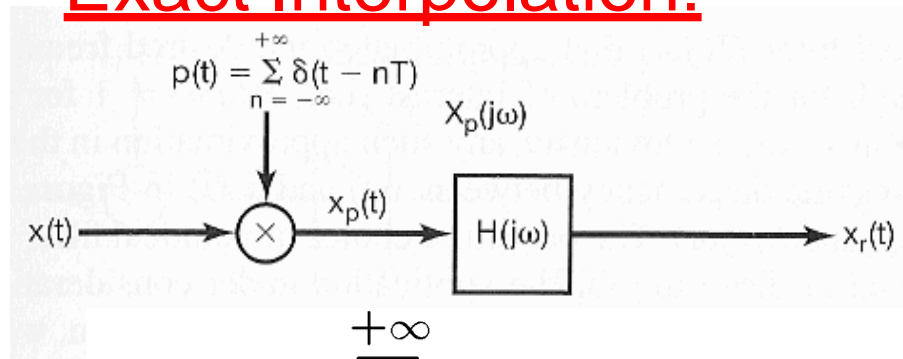
$$\Rightarrow H_r(j\omega) = \frac{e^{j\omega T/2} H(j\omega)}{\frac{2 \sin(\omega T/2)}{\omega}}$$



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## Exact Interpolation:



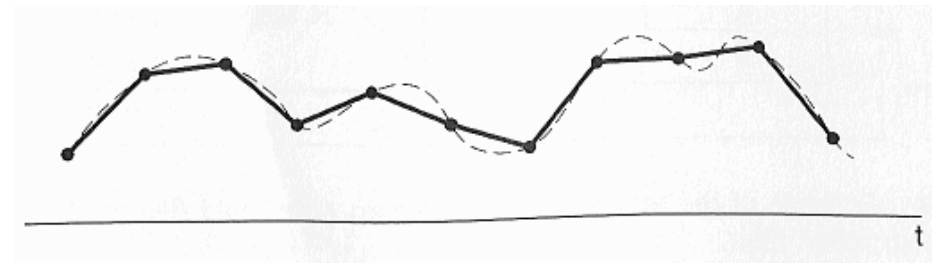
$$x_p(t) = \sum_{n=-\infty}^{+\infty} x(nT)\delta(t - nT)$$

$$x_r(t) = x_p(t) * h(t)$$

Ex 2.11, p. 110  $x(t - t_0) = x(t) * \delta(t - t_0)$

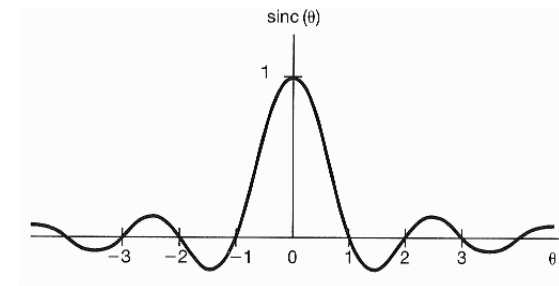
$$x_r(t) = \sum_{n=-\infty}^{+\infty} x(nT)h(t - nT)$$

$$x_r(t) = \sum_{n=-\infty}^{+\infty} x(nT) \frac{w_c T}{\pi} \frac{\sin(w_c(t - nT))}{w_c(t - nT)}$$

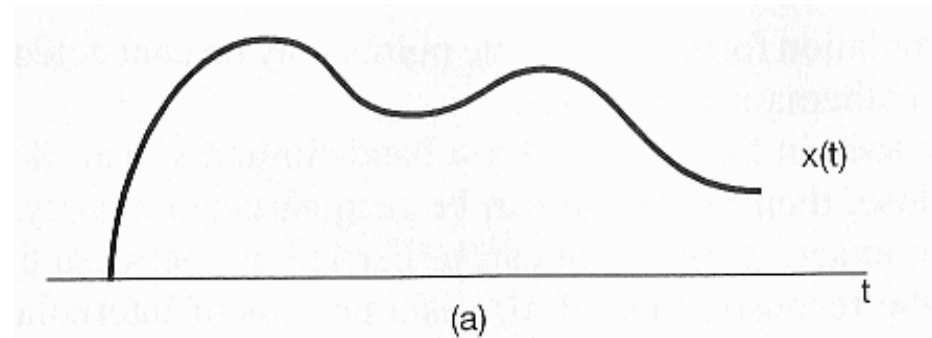
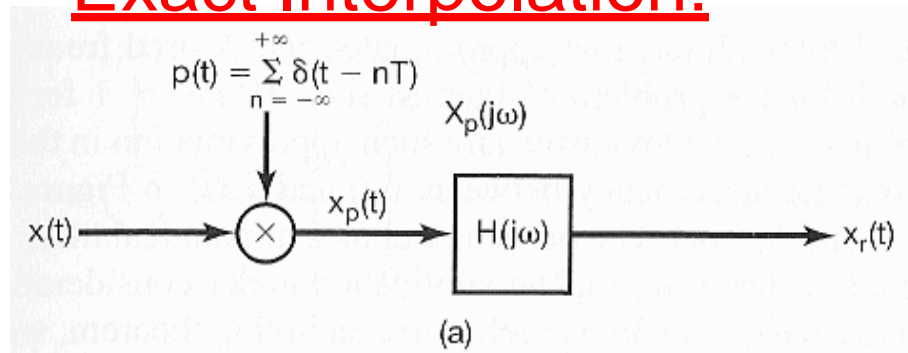


ideal lowpass filter  
with a magnitude of  $T$

$$h(t) = T \frac{w_c}{\pi} \frac{\sin(w_c t)}{w_c t}$$



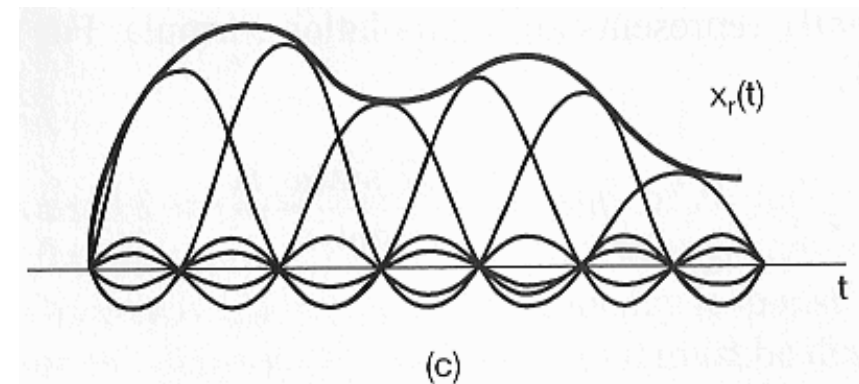
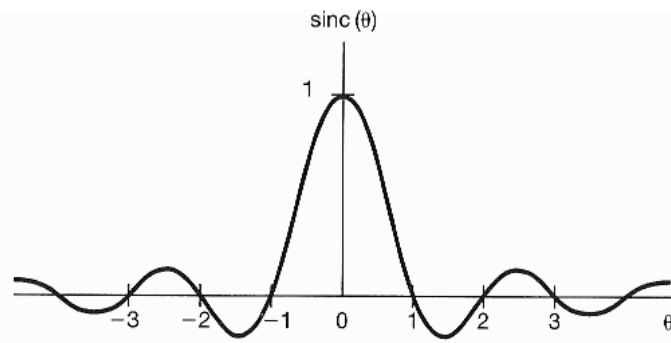
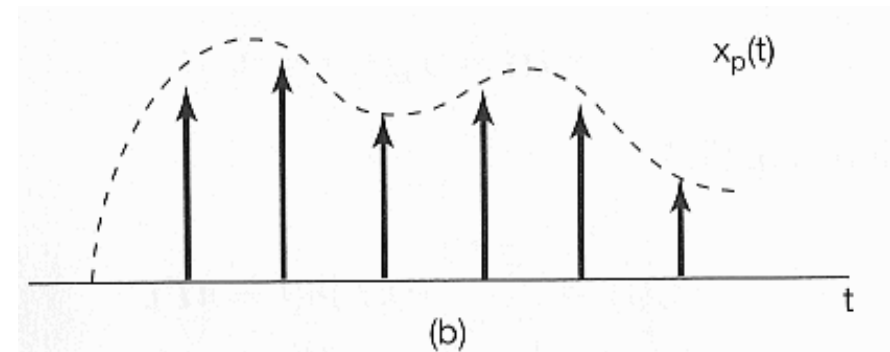
## Exact Interpolation:



$$x_r(t) = \sum_{n=-\infty}^{+\infty} x(nT) \frac{\omega_c T}{\pi} \frac{\sin(\omega_c(t - nT))}{\omega_c(t - nT)}$$

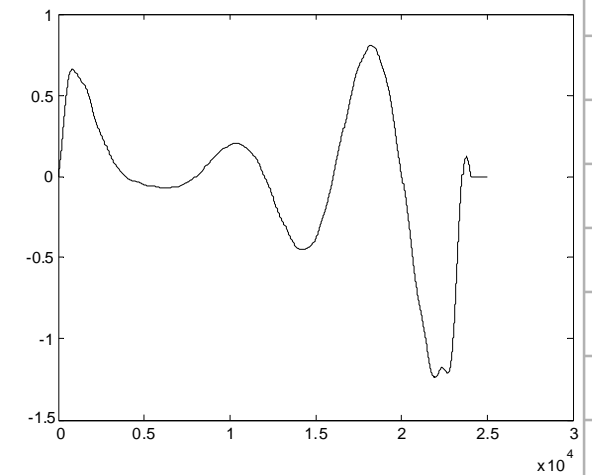
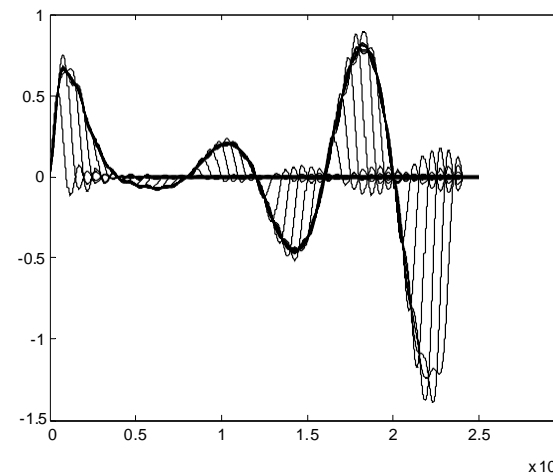
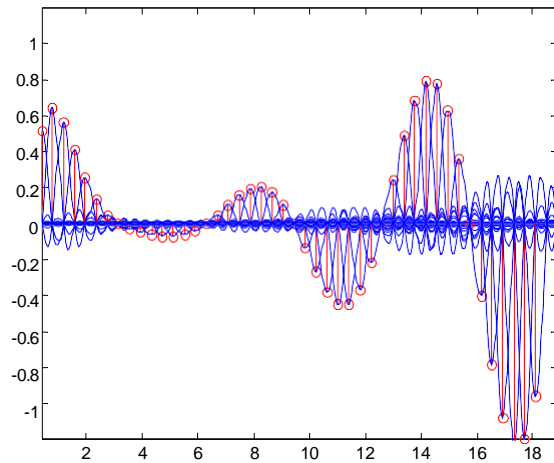
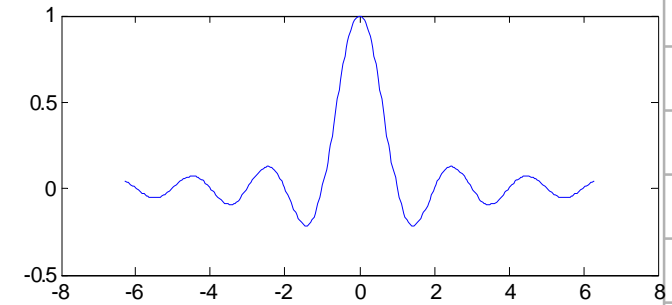
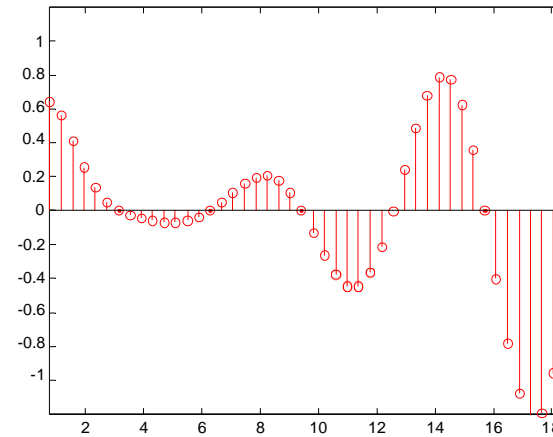
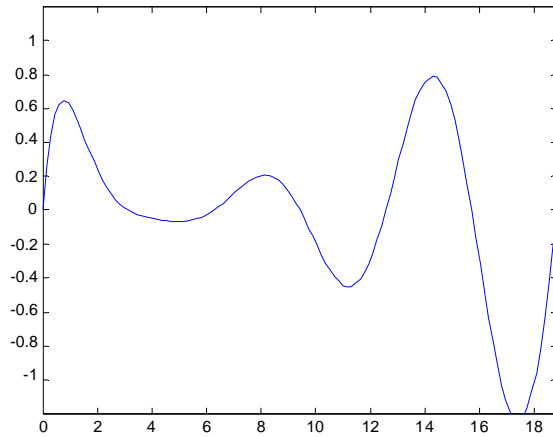
$$\frac{\omega_c}{\pi} \frac{2\pi}{\omega_s} \frac{\sin \pi(\omega_c(t - nT)/\pi)}{\pi \omega_c(t - nT)/\pi}$$

$$\frac{2\omega_c}{\omega_s} \text{sinc}(\omega_c(t - nT)/\pi)$$

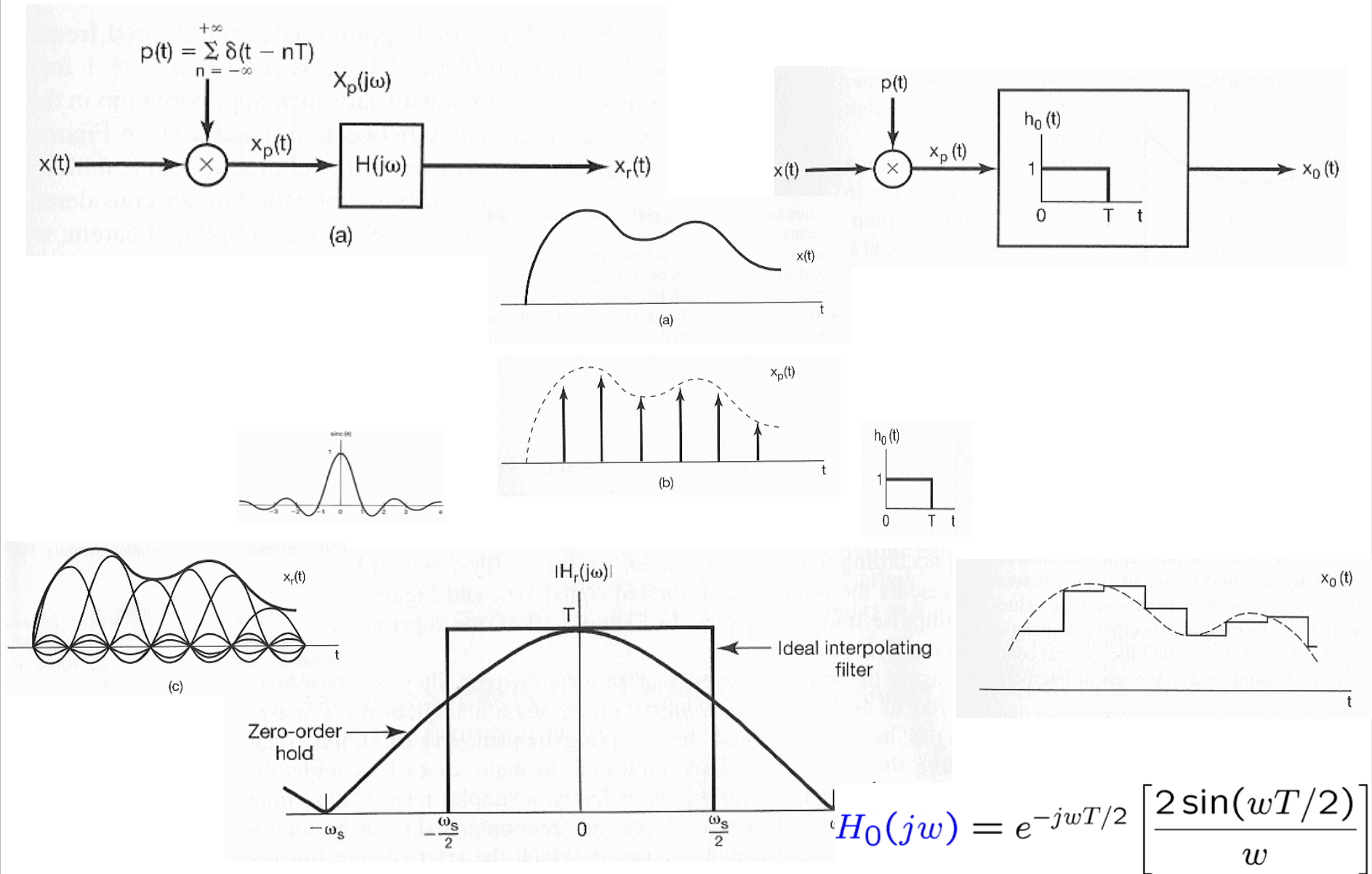


# Reconstruction of a Signal from its Samples Using Interpolation

Feng-Li Lian © 2011  
NTU EE-SS7-Sampling-21

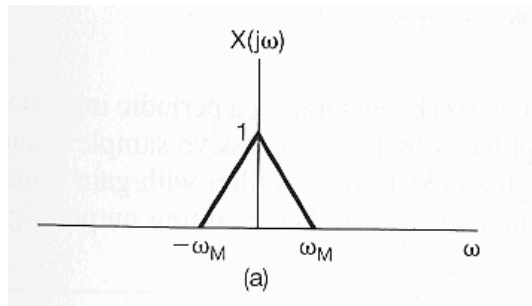


## ■ Ideal Interpolating Filter & The Zero-Order Hold:

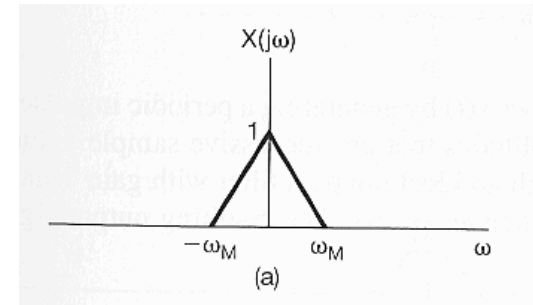


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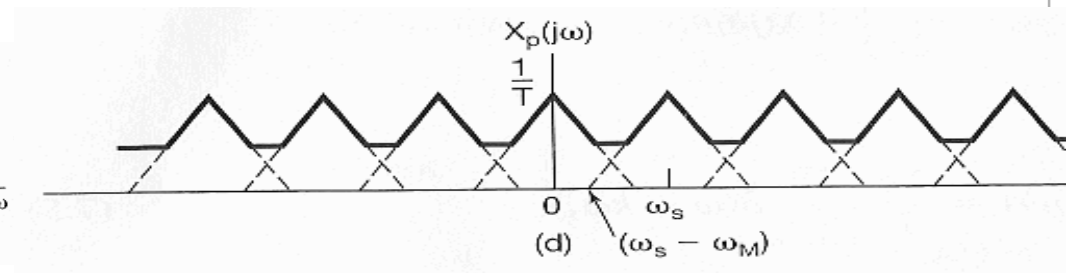
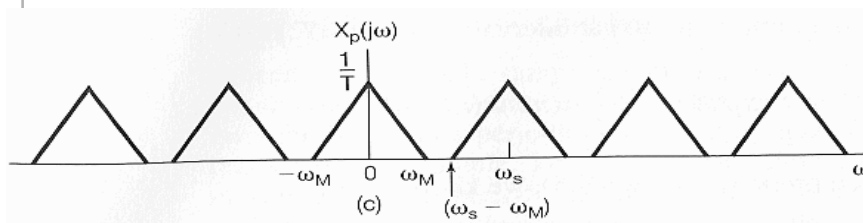
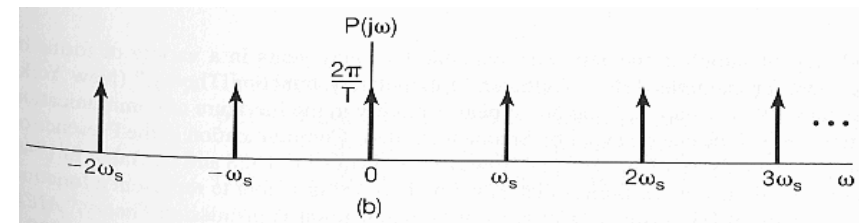
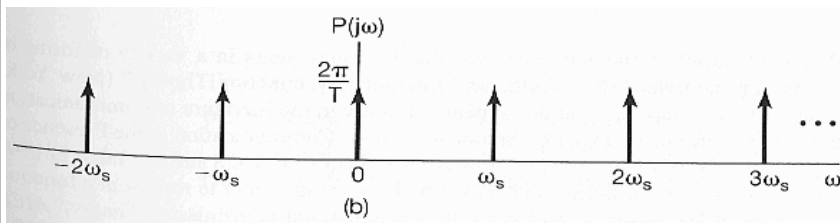
## ■ Overlapping in Frequency-Domain: Aliasing



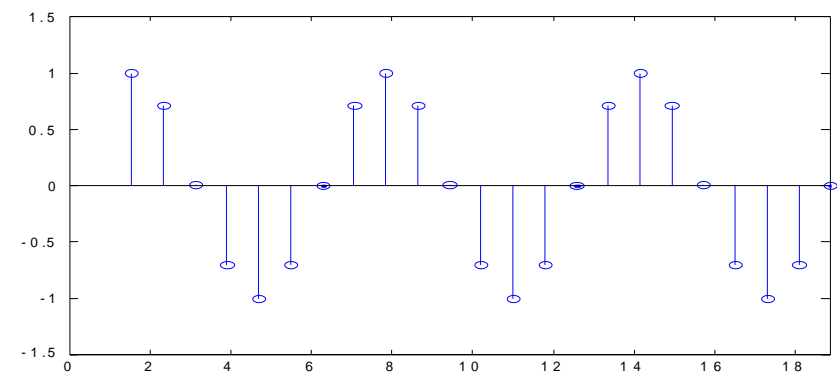
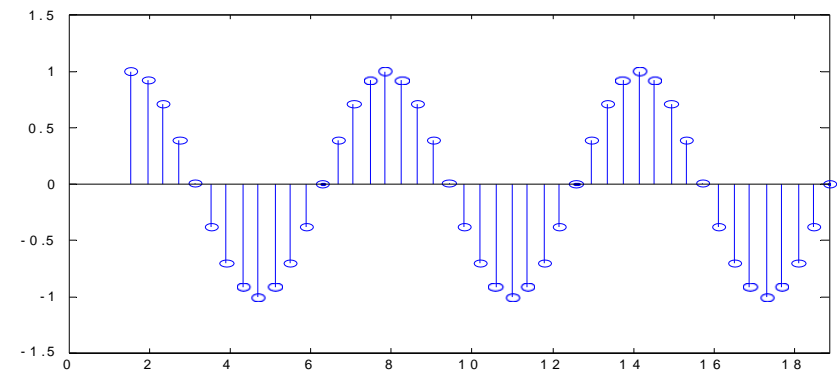
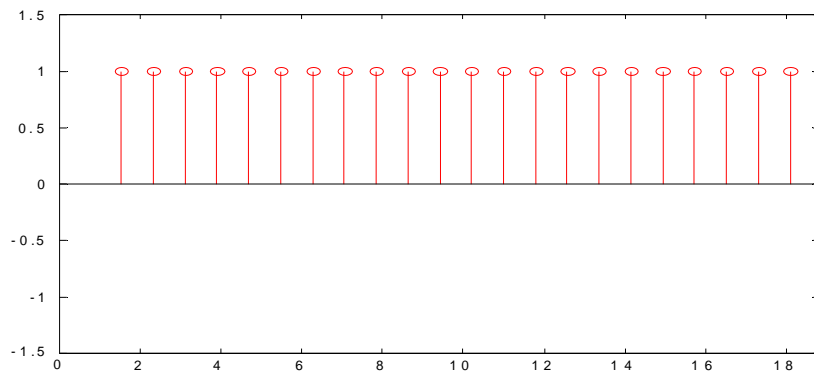
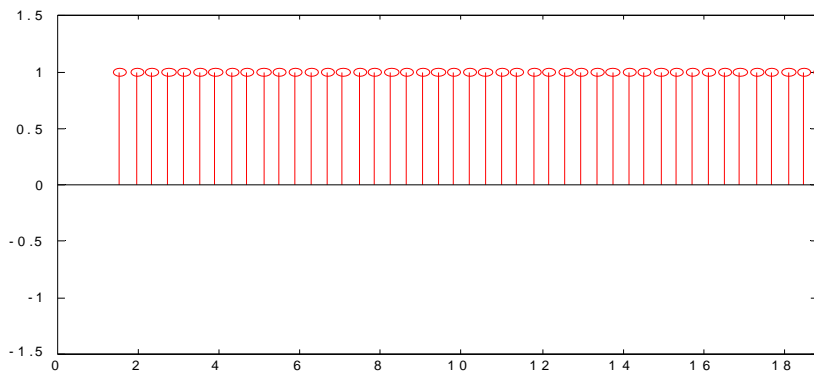
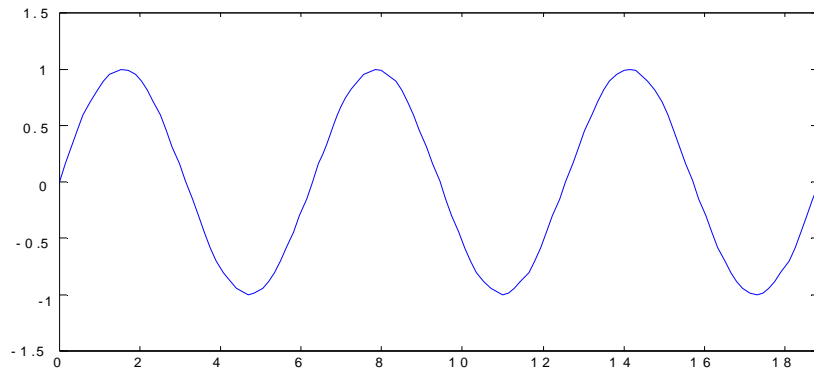
$$\omega_s > 2\omega_M$$



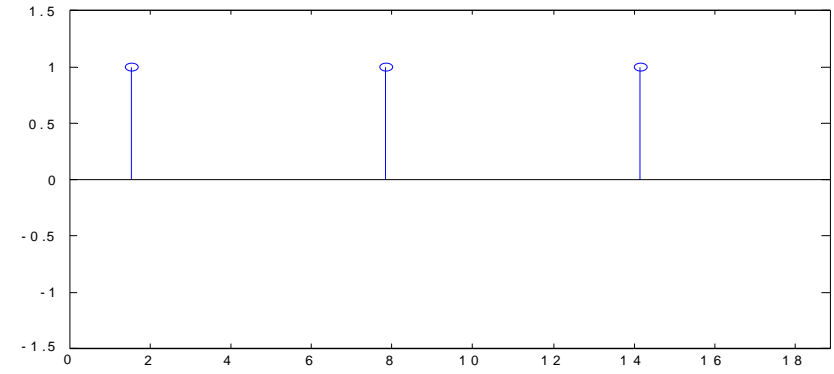
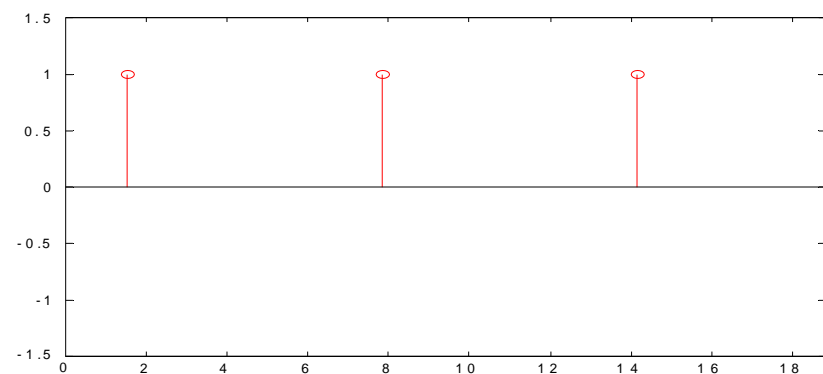
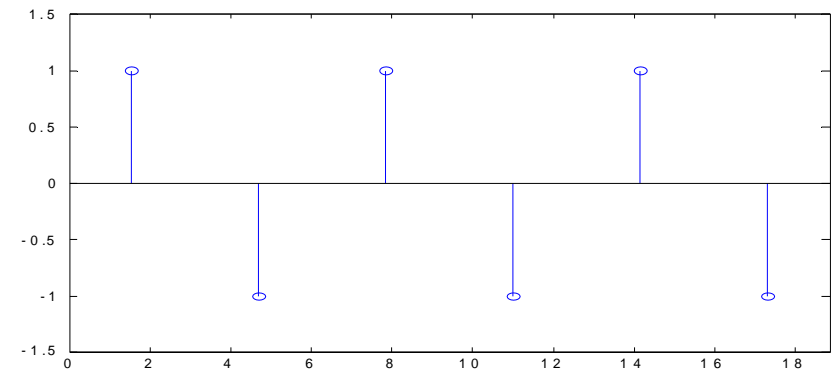
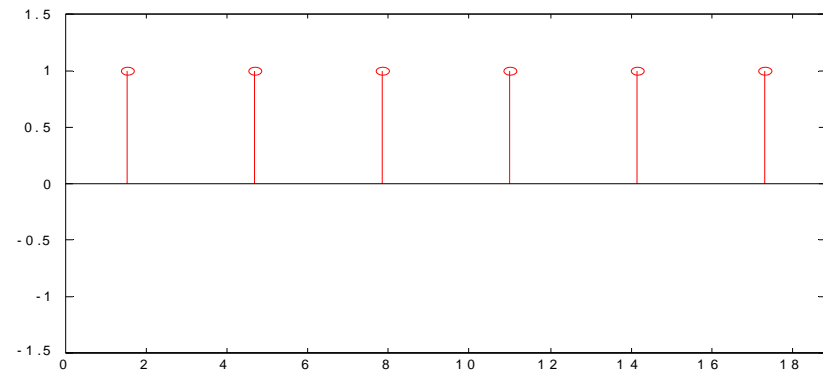
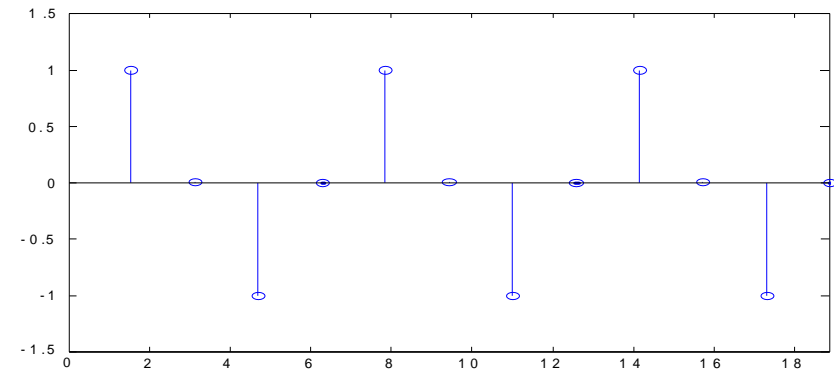
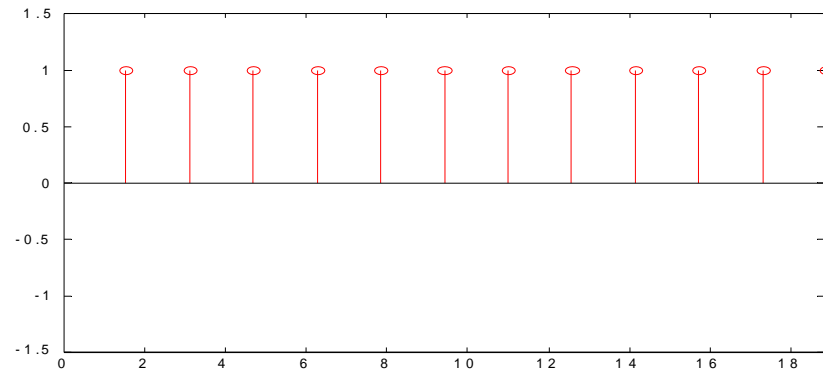
$$\omega_s < 2\omega_M$$



## ■ Overlapping in Frequency-Domain: Aliasing



## ■ Overlapping in Frequency-Domain: Aliasing

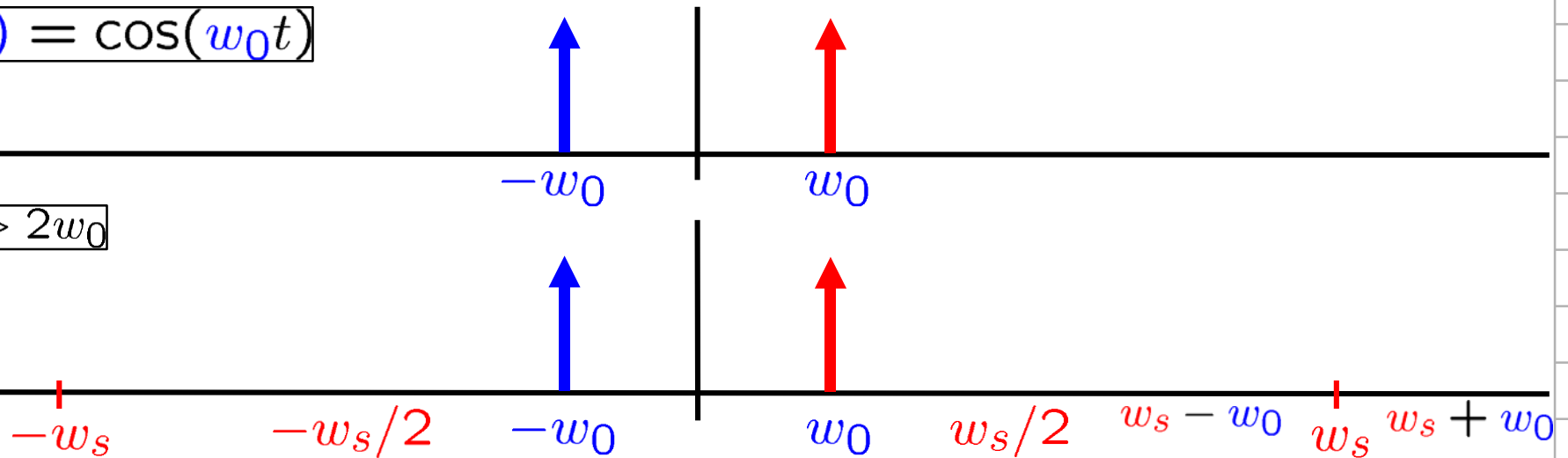




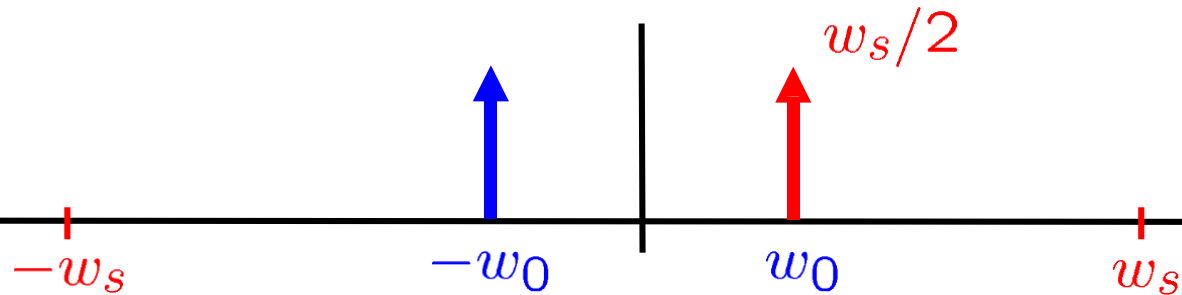
## Overlapping in Frequency-Domain: Aliasing

$$x(t) = \cos(w_0 t)$$

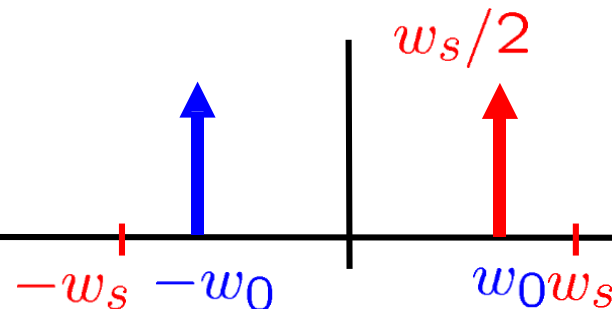
$$w_s > 2w_0$$



$$w_s > 2w_0$$



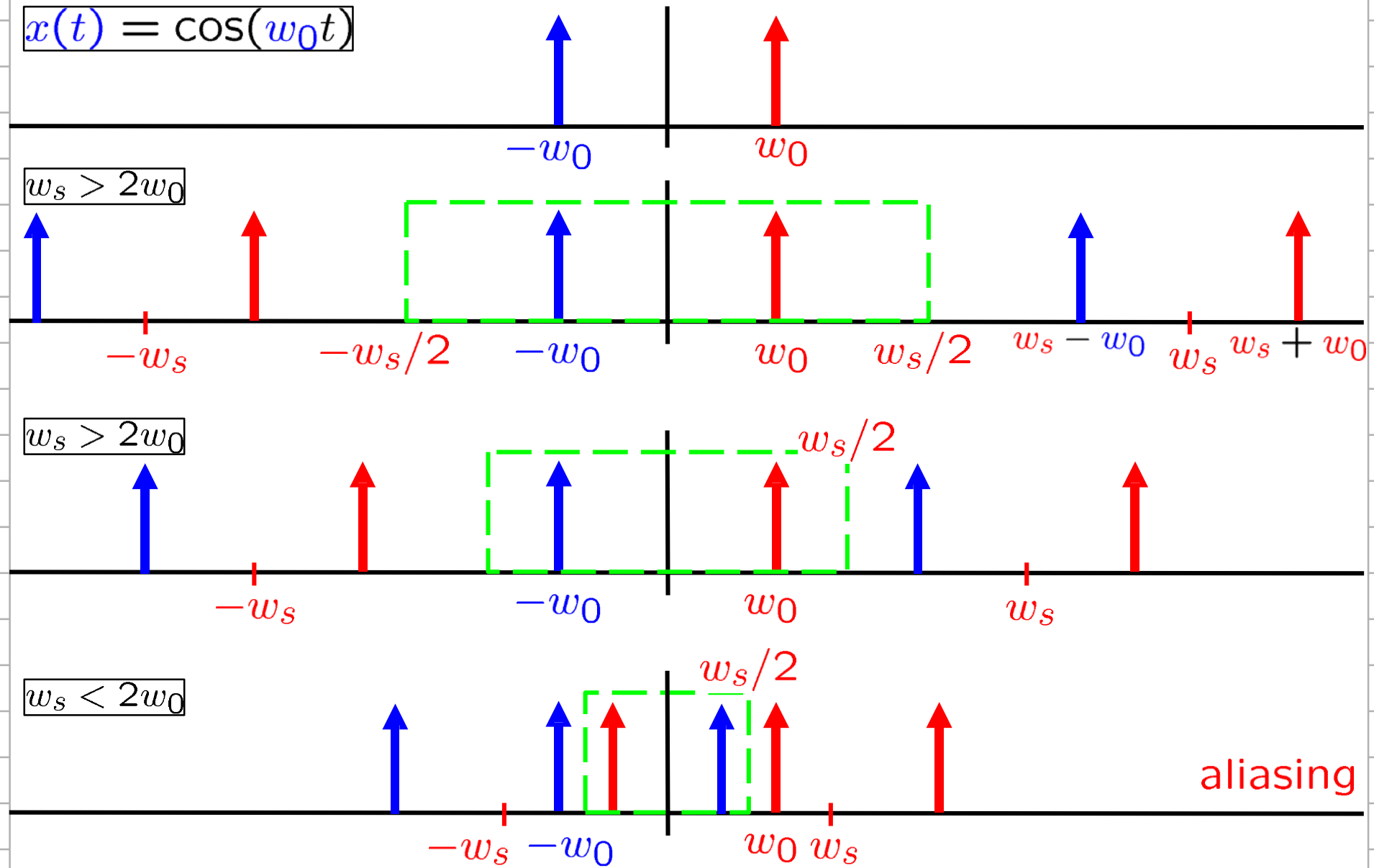
$$w_s < 2w_0$$



aliasing

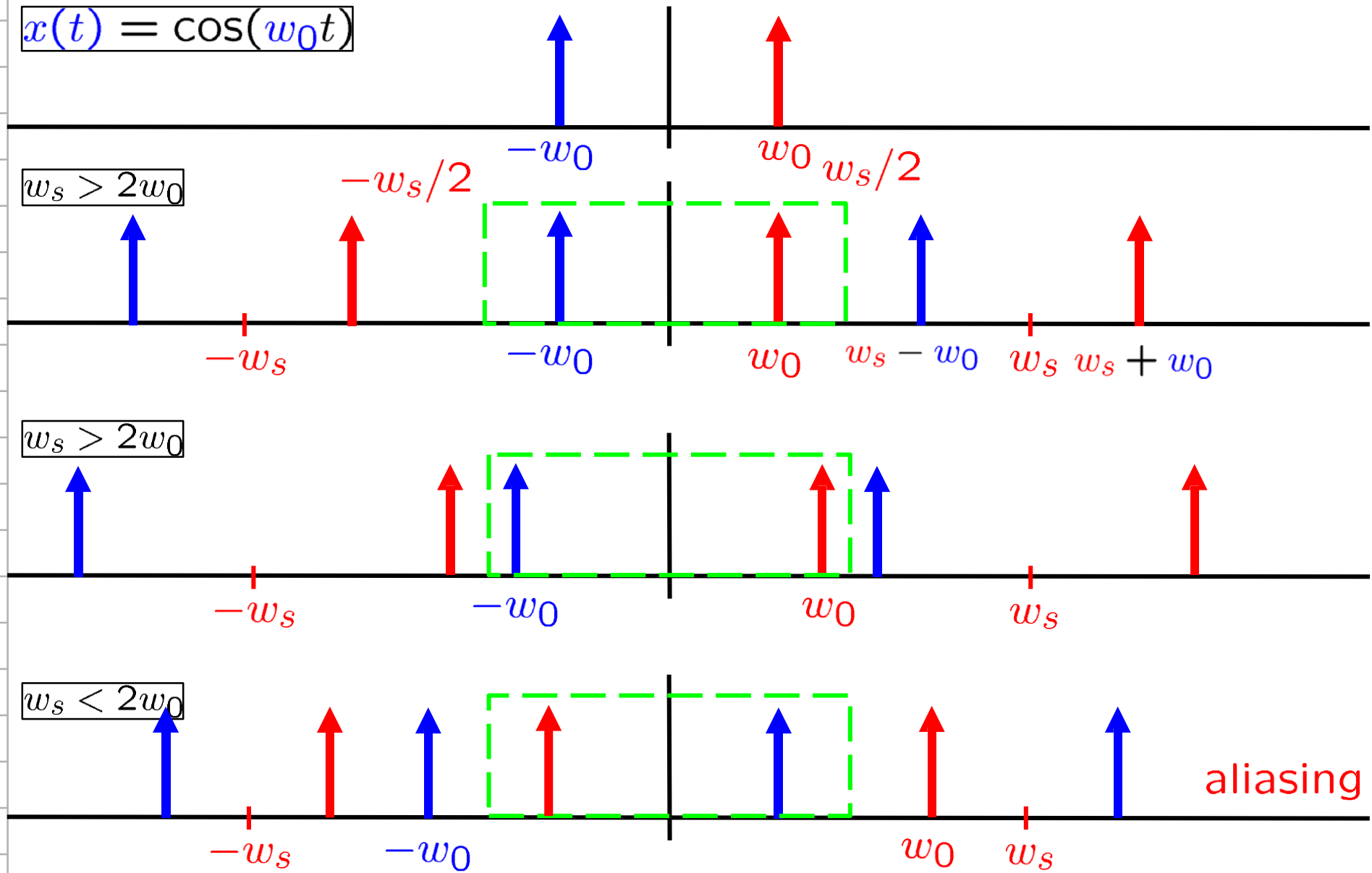
## Overlapping in Frequency-Domain: Aliasing

$$x(t) = \cos(w_0 t)$$



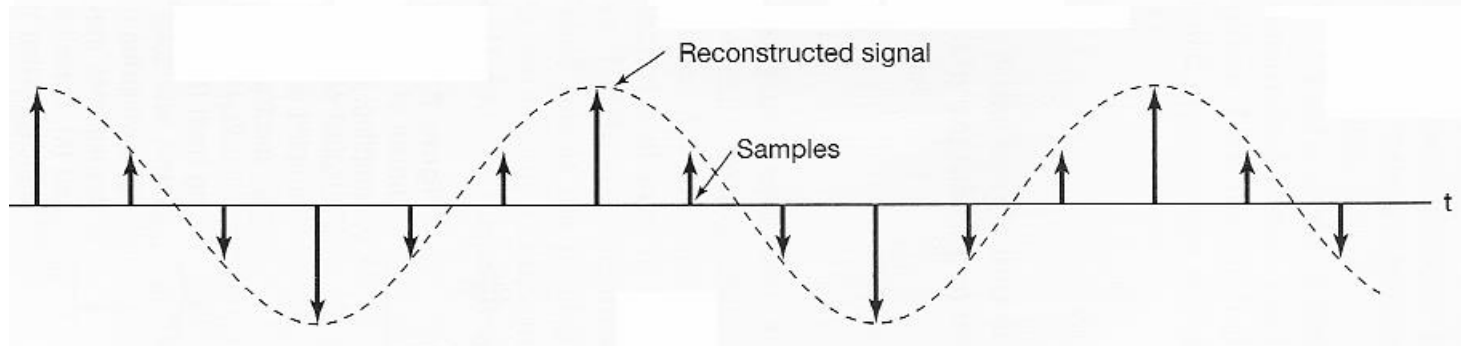
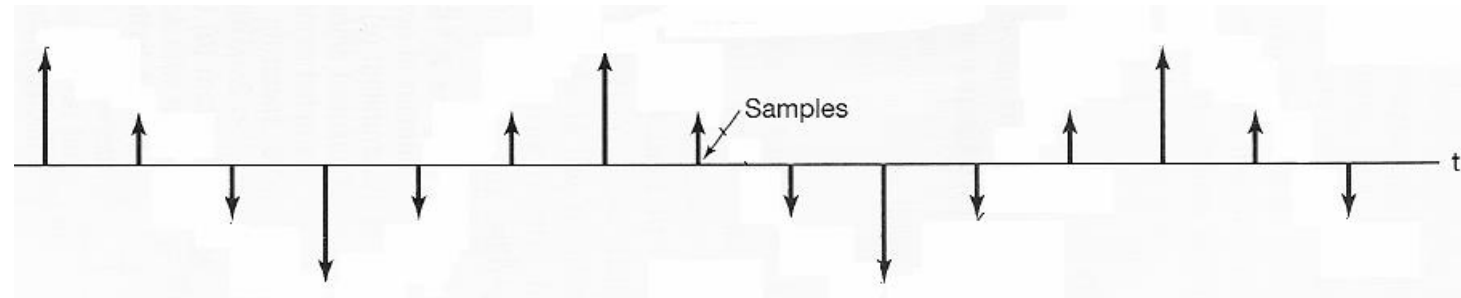
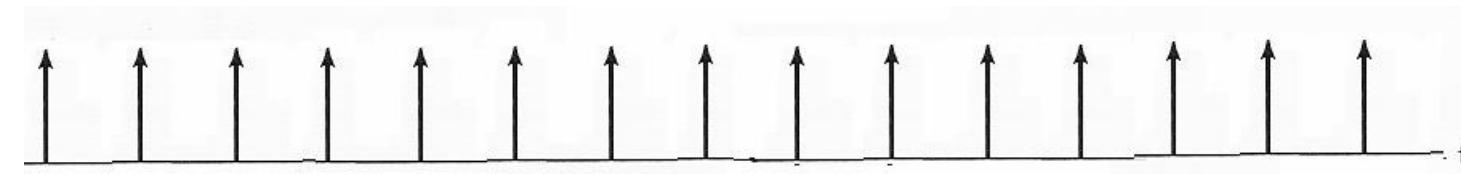
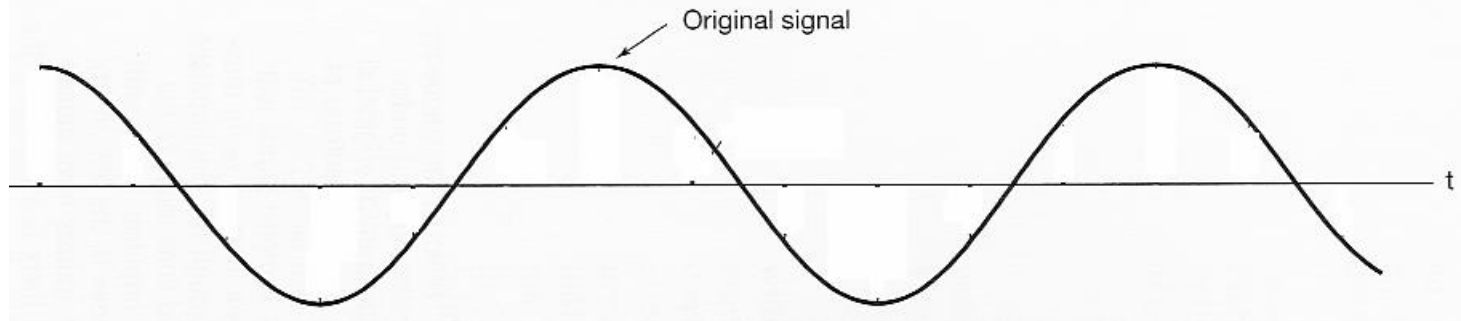
## Overlapping in Frequency-Domain: Aliasing

$$x(t) = \cos(w_0 t)$$

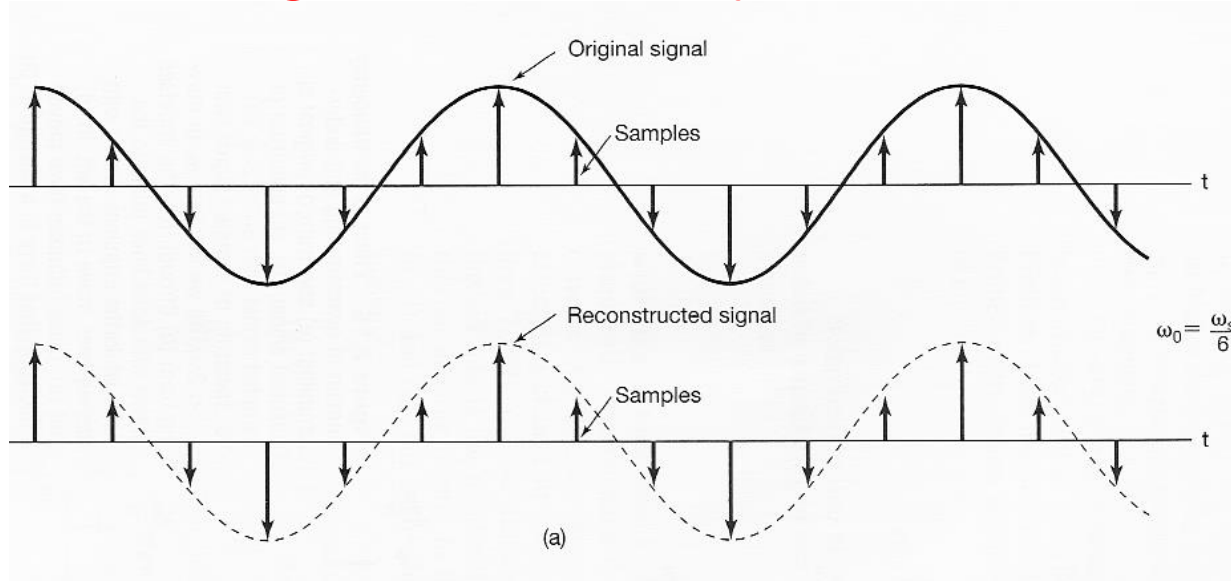


## ■ Overlapping in Frequency-Domain: Aliasing

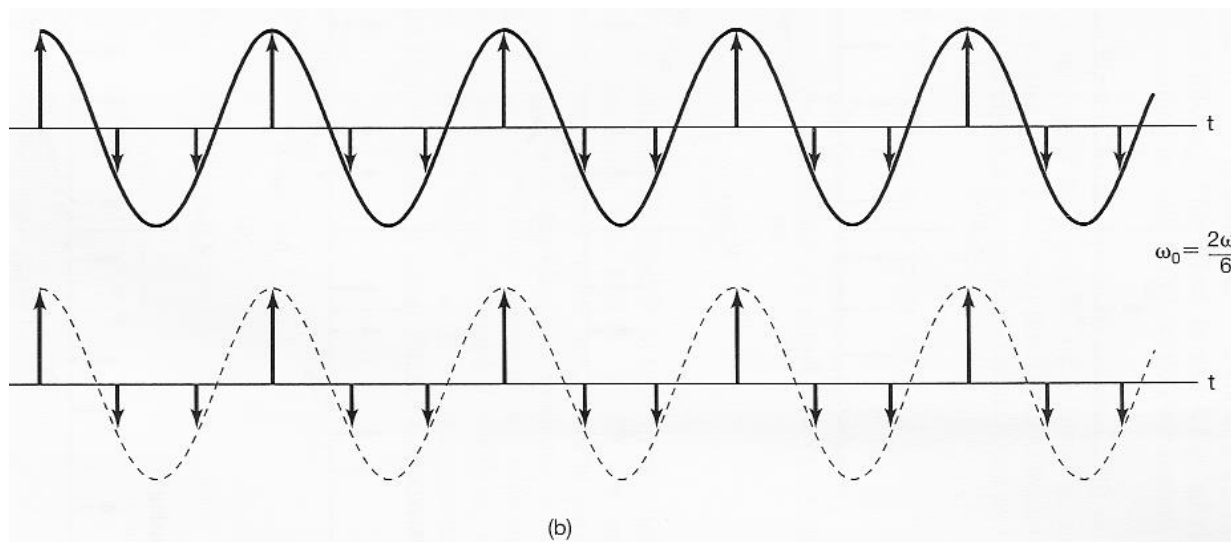
$$\omega_0 = \frac{\omega_s}{6}$$



## ■ Overlapping in Frequency-Domain: Aliasing

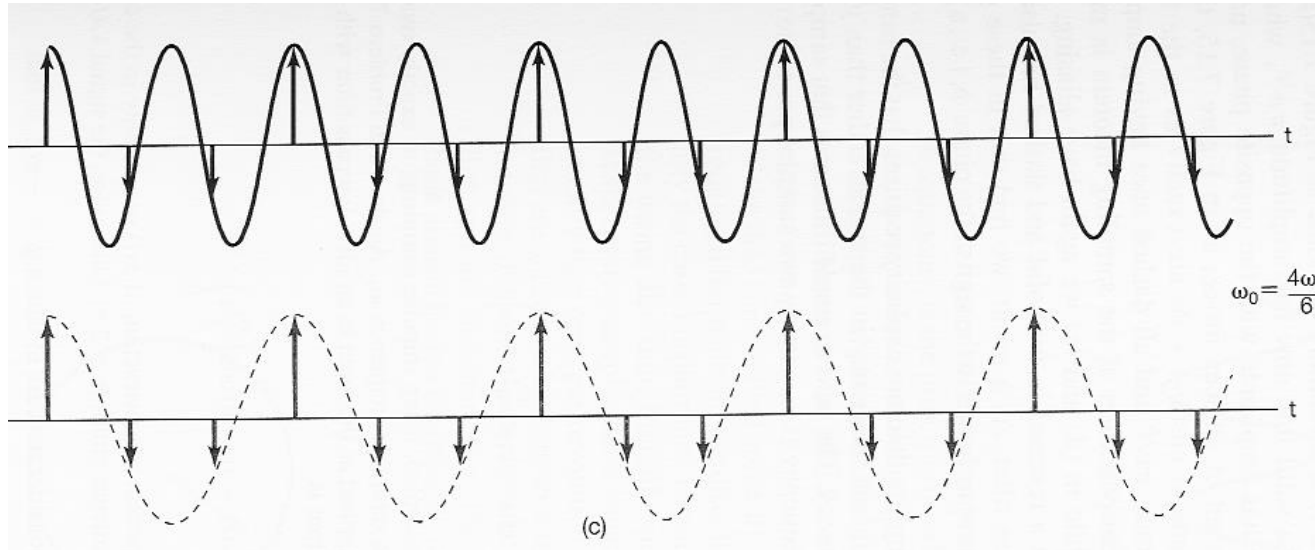


$$\omega_0 = \frac{\omega_s}{6}$$

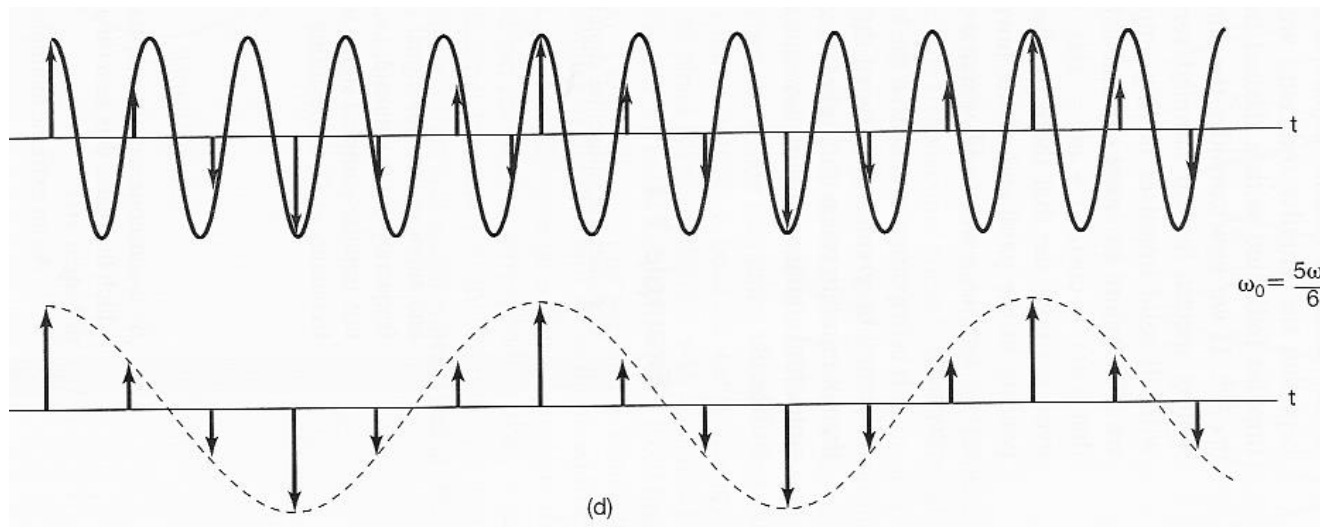


$$\omega_0 = \frac{2\omega_s}{6}$$

## Overlapping in Frequency-Domain: Aliasing



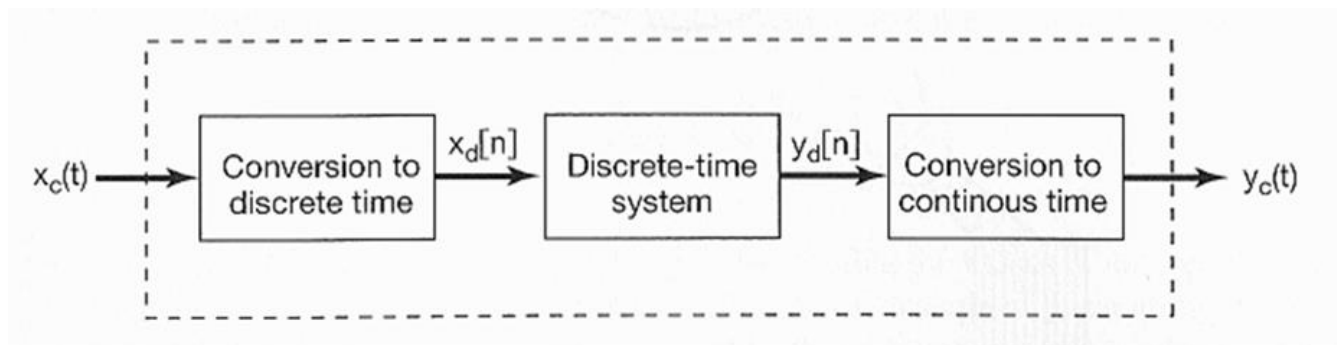
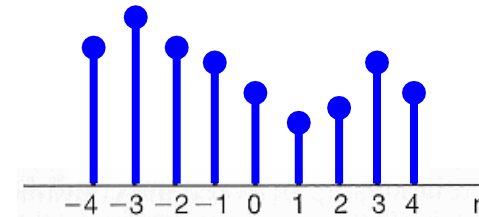
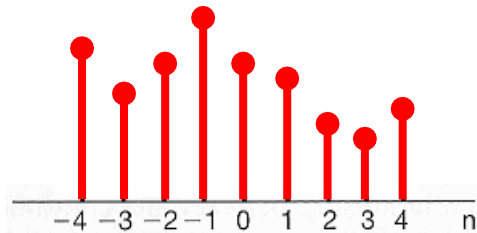
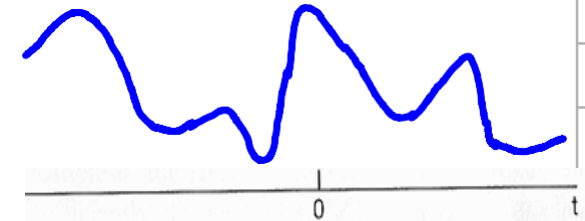
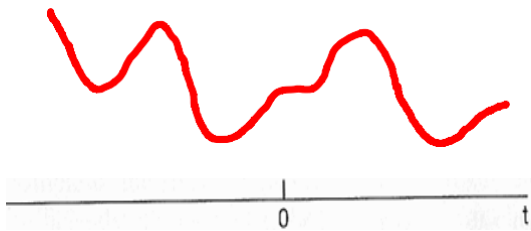
$$\omega_0 = \frac{4\omega_s}{6}$$



$$\omega_0 = \frac{5\omega_s}{6}$$

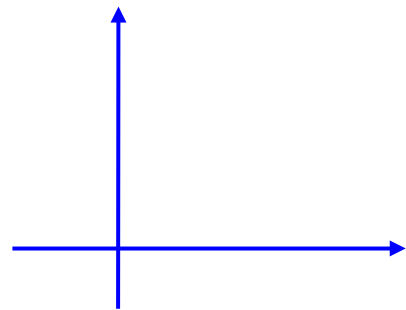
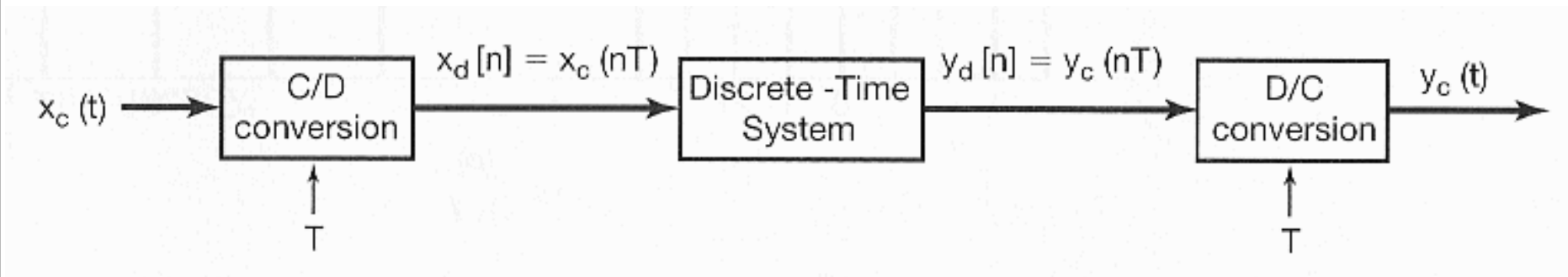
- Representation of of a Continuous-Time Signal by Its Samples: The Sampling Theorem
- Reconstruction of of a Signal from Its Samples Using Interpolation
- The Effect of Under-sampling: Aliasing
- Discrete-Time Processing of Continuous-Time Signals
- Sampling of Discrete-Time Signals

## ■ Discrete-Time Processing of CT Signals:



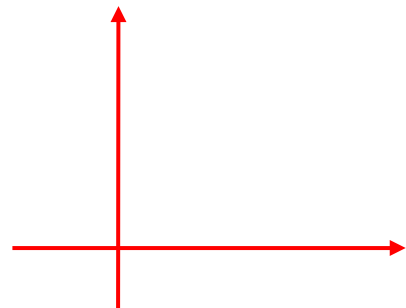


## ■ C/D or A-to-D (ADC) and D/C or D-to-A (DAC):



C/D: continuous-to-discrete-time conversion

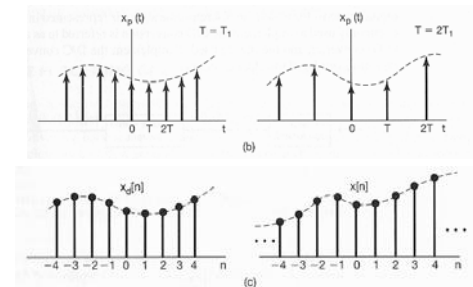
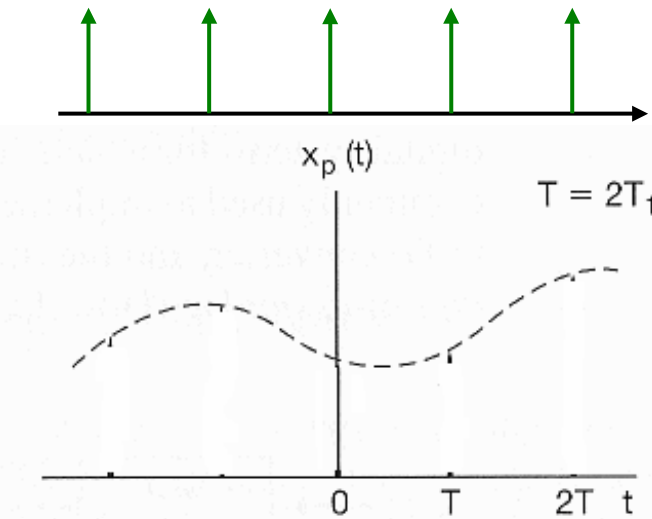
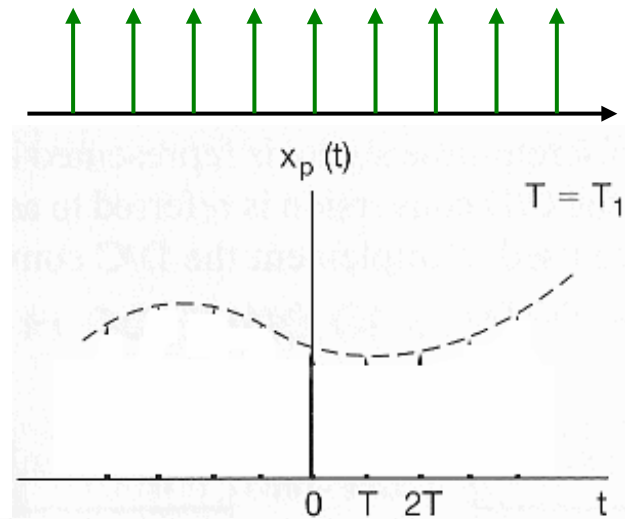
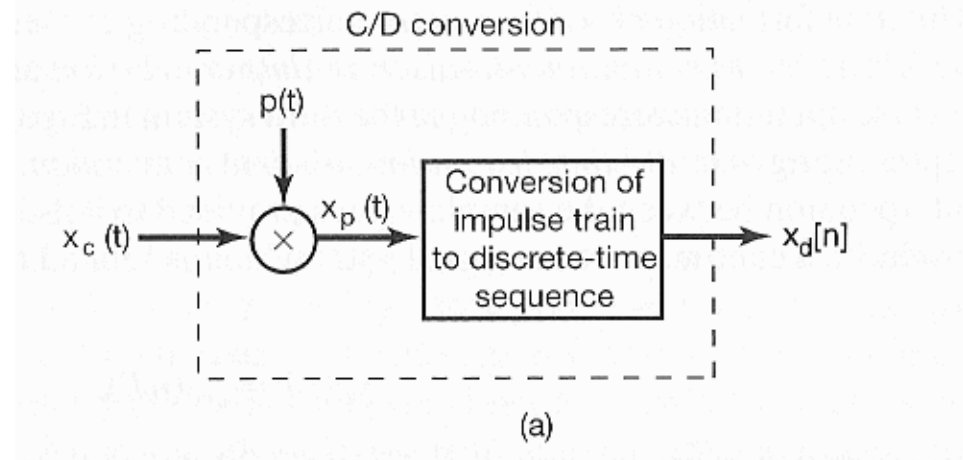
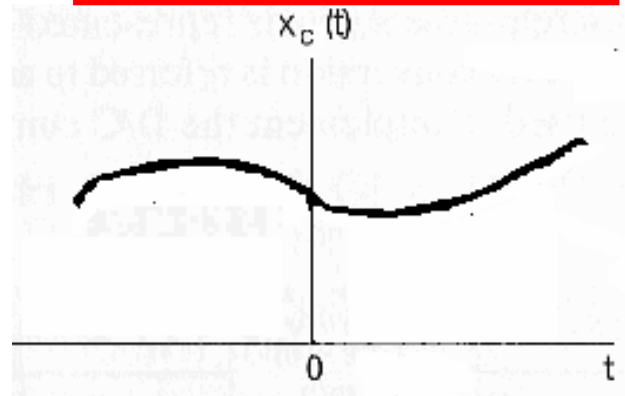
A-to-D: analog-to-digital converter



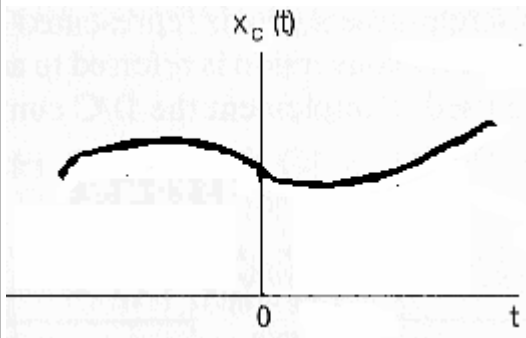
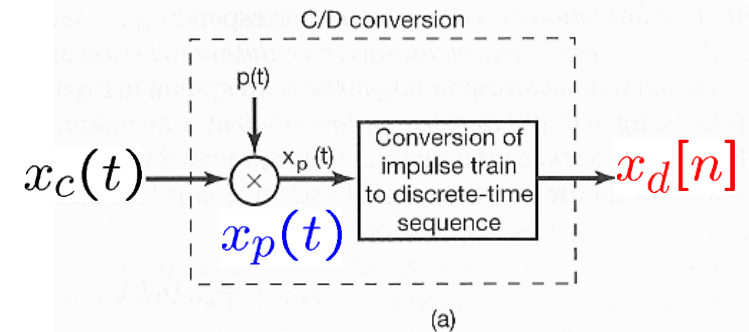
D/C: discrete-to-continuous-time conversion

D-to-A: digital-to-analog converter

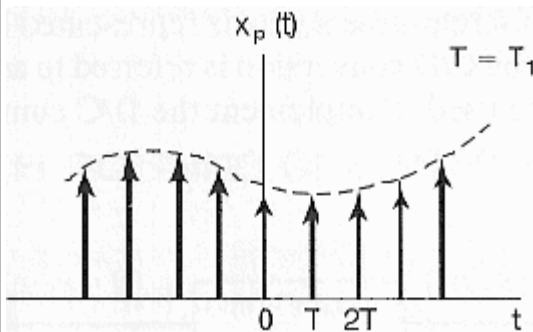
## ■ C/D Conversion:



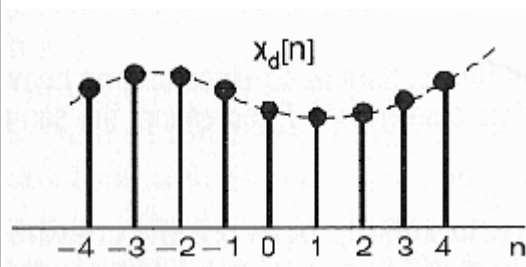
## ■ C/D Conversion:



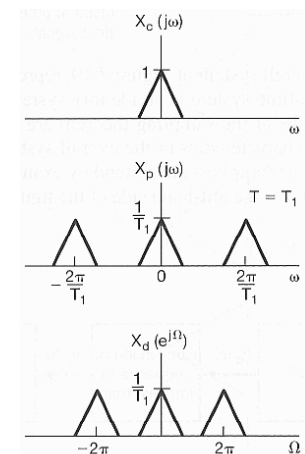
$$X_c(j\omega)$$



$$X_p(j\omega)$$



$$X_d(e^{j\Omega})$$



## ■ C/D Conversion:

$$x_p(t) = \sum_{n=-\infty}^{+\infty} x_c(nT)\delta(t - nT)$$

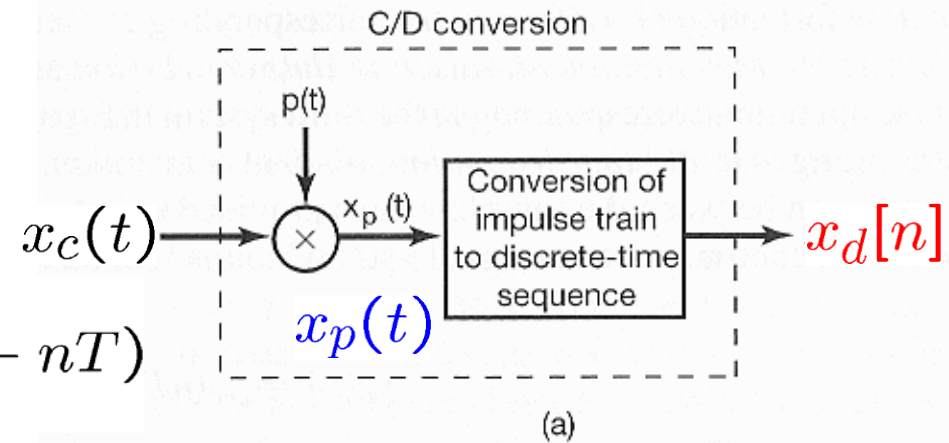


Table 4.2, p. 329

$$\delta(t - t_0) \xleftrightarrow{\mathcal{F}} e^{-j\omega t_0}$$

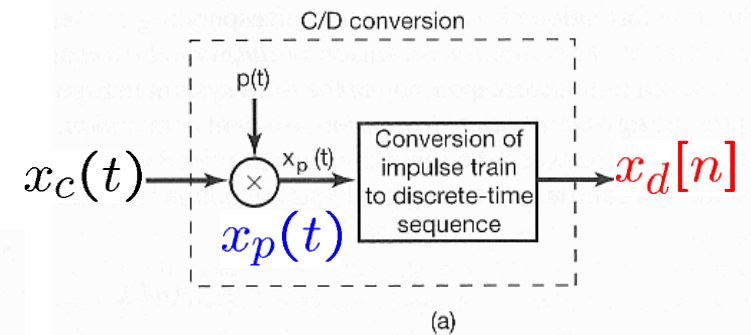
Eq 7.3, 7.6, p. 517

$$X_p(j\omega) = \sum_{n=-\infty}^{+\infty} x_c(nT)e^{-j\omega nT} = \frac{1}{T} \sum_{K=-\infty}^{+\infty} X_c(j(\omega - K\omega_s))$$

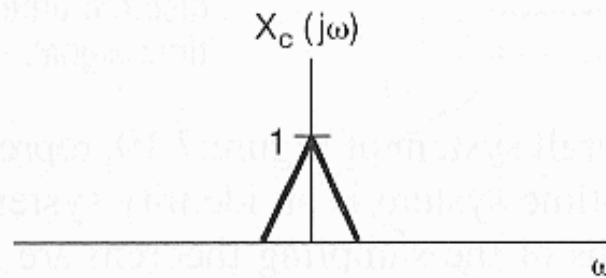
$$X_d(e^{j\Omega}) = \sum_{n=-\infty}^{+\infty} x_d[n]e^{-j\Omega n} = \sum_{n=-\infty}^{+\infty} x_c(nT)e^{-j\Omega n}$$

$$\Rightarrow X_d(e^{j\Omega}) = X_p\left(j\frac{\Omega}{T}\right) = \frac{1}{T} \sum_{K=-\infty}^{+\infty} X_c\left(j\left(\frac{\Omega}{T} - K\frac{2\pi}{T}\right)\right)$$

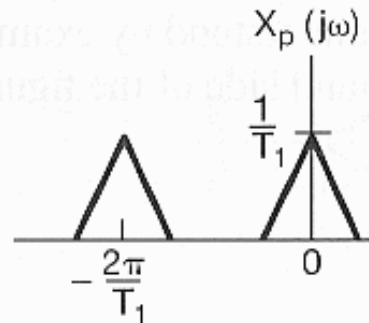
## ■ C/D Conversion:



$$X_c(j\omega)$$



$$X_p(j\omega)$$



$$X_d(e^{j\Omega})$$

