

## Week 1 notes : What is VxWork?

- a proprietary & customisable real-time operating system (RTOS)
- designed for distributed computing on CPUs with embedded systems
- used with a spectrum of hardware eg. communications & network devices

Platform : ① Intel architecture

② Power architecture

③ ARM architecture

- can be used for : ① multi-core asymmetric processing (AMP)
- ② symmetric multiprocessing (SMP)
- ③ mixed modes & multi-OS designs

- Features : ① Multitasking kernel with preemptive & round-robin scheduling & fast interrupt response
- ② Native 64-bit operating system
- ③ user-mode applications ("Real time processes") isolated from other user-mode applications via memory protection mechanisms
- ④ Human machine interface → Vector Graphics & Tilcon UI
- ⑤ Graphical user interface (GUI) :
  - \* OpenVG stack
  - \* Open GL
  - \* Tilcon UI
  - \* Frame Buffer Driver
  - \* EV Dev Interface
- ⑥ Networking features with 64-bit support

- Hardware support : ① Intel x86 family
  - ② MIPS
  - ③ Power PC
  - ④ Freescale ColdFire
  - ⑤ Intel i960
  - ⑥ SPARC
  - ⑦ Arm, StrongARM & xScale CPUs

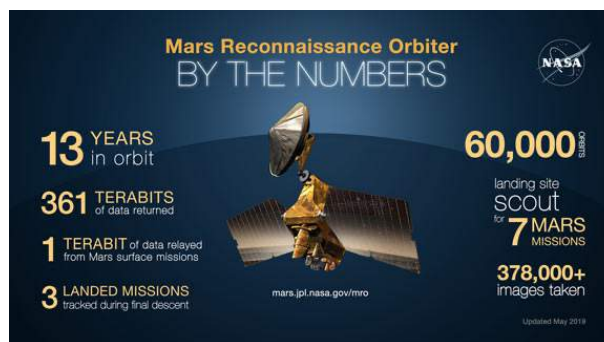
- Notable uses : ① Mars Science Laboratory Curiosity rover



- ② ASIMO Robot



- ③ Mars Reconnaissance Orbiter



④ Boeing 747



⑤ Varian Medical Systems Truebeam

