

Efficient AI with Rust Lab
Rapid Time Series Datasets Library
RWTH Aachen University
Group 1

Marius Kaufmann¹ Amir Ali Aali² Kilian Fin Braun¹

¹Masters of Computer Science

²Masters of Data Science

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Overview

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- ▶ Preprocessing of time series datasets

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 - ▶ `ForecastingDataSet`

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Data Input Format

Input 3D numpy array:

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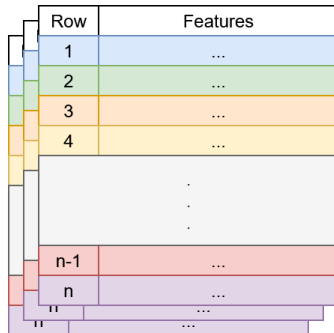
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Row	Features
1	...
2	...
3	...
4	...
.	
.	
.	
n-1	...
n	...

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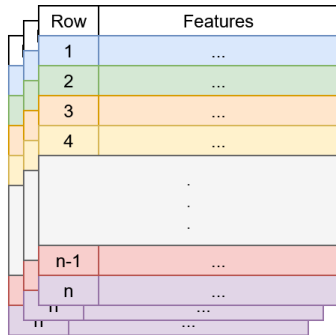
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In practice

- ▶ Forecasting datasets:
 - ▶ One instance



The diagram illustrates a 3D numpy array structure for forecasting datasets. It shows a stack of 2D arrays, each representing an instance. The first instance (top) has rows 1, 2, 3, 4, and a large block of rows (indicated by three dots), followed by rows n-1 and n. The second instance (middle) has rows 1, 2, 3, 4, and a large block of rows (indicated by three dots), followed by rows n-1 and n. The third instance (bottom) has rows 1, 2, 3, 4, and a large block of rows (indicated by three dots), followed by rows n-1 and n. The rows are color-coded: blue for row 1, green for row 2, orange for row 3, yellow for row 4, light grey for the large block, red for row n-1, and purple for row n. The columns are labeled 'Row' and 'Features'.

Row	Features
1	...
2	...
3	...
4	...
...	...
n-1	...
n	...

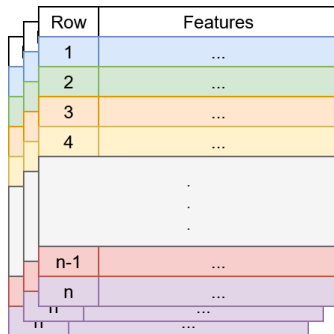
Data Input Format

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- ▶ **First dimension:** Instances
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In practice

- ▶ Forecasting datasets:
 - ▶ One instance
- ▶ Classification datasets:
 - ▶ Multiple instances

A diagram illustrating a 3D numpy array structure. It shows a stack of multiple 2D tables. The top table has two columns: 'Row' and 'Features'. The 'Row' column contains values 1, 2, 3, 4, followed by a large grey box containing three vertical dots, then n-1, n, and a double quote. The 'Features' column contains three dots for each row. The tables are color-coded: blue for row 1, green for row 2, orange for rows 3 and 4, grey for the middle section, red for row n-1, and purple for row n and the bottom section. The bottom section is partially obscured by a double quote.

Row	Features
1	...
2	...
3	...
4	...
...	...
n-1	...
n	...
"	...
"	...

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Necessary parameter when splitting:

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Splitting II (Random Split - Classification Data)

How it works:

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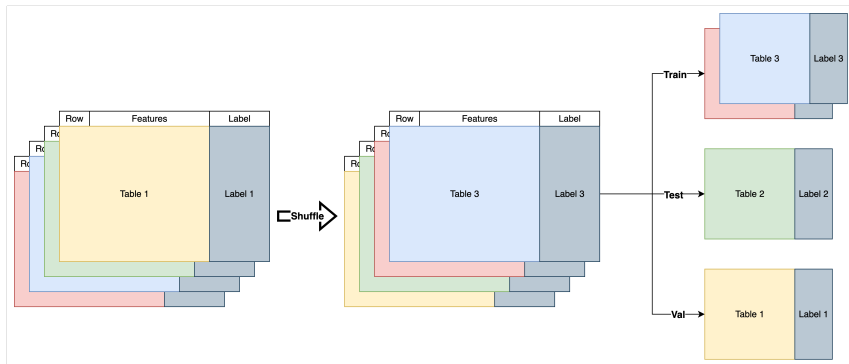
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How it works:

1. Validate the proportions of train, validation, and test sets.
2. Shuffle the instances of the dataset randomly.
3. Compute the split offsets based on the proportions.
4. Split the instances into three sets.
5. Return the three sets as separate datasets.

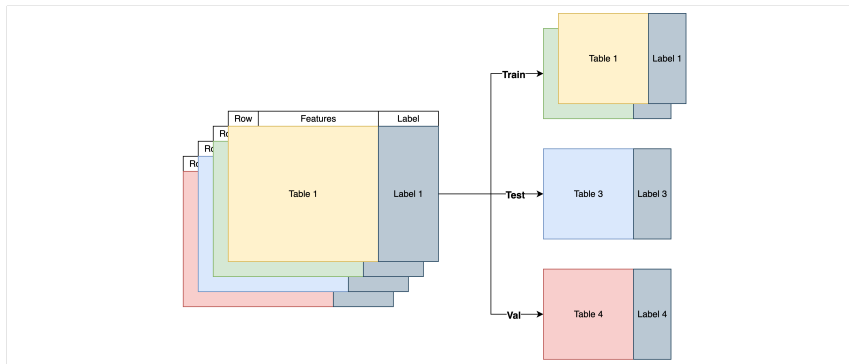
Splitting III (Random Split - Classification Data)



Random split example

Splitting IV (In-Order Split - Classification Data)

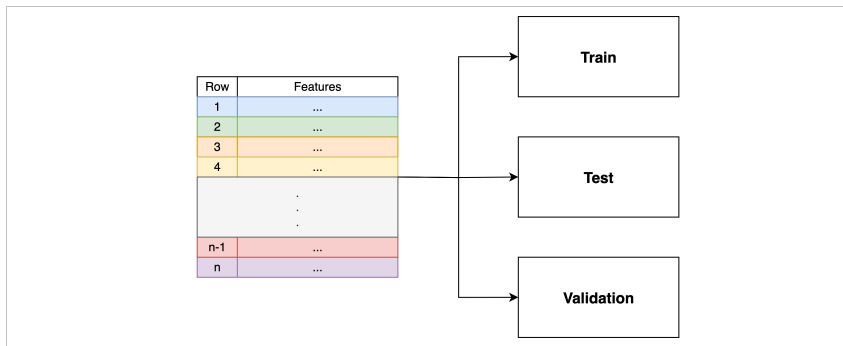
Works very similar to the random split, but it **doesn't shuffle** the dataset anymore.



In-Order split example

Splitting V (Temporal Split - Forecasting Data)

Similar to the in-order split, but this time we are dealing with forecasting data, which in most cases is only one instance and we split over **timesteps** and not instances anymore.



Temporal split example

Performance considerations

Copying

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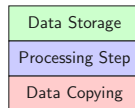
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Data-flow

Forecasting Dataset Data-Flow Classification Dataset Data-Flow

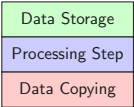
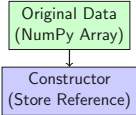
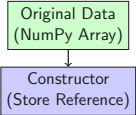
Original Data
(NumPy Array)

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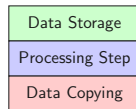
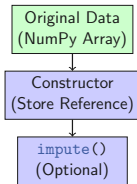
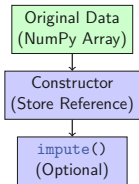
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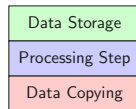
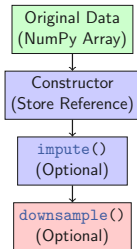
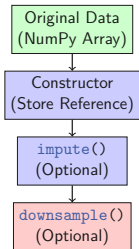
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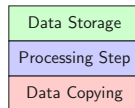
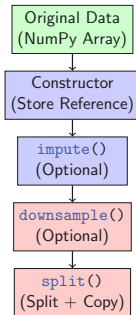
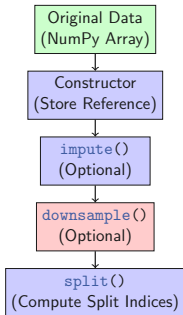
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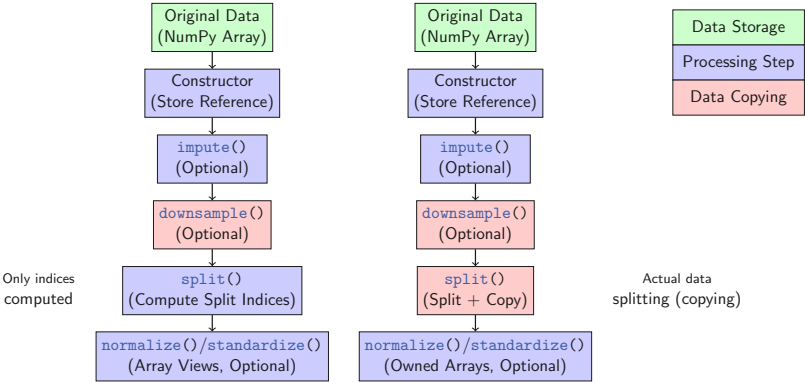
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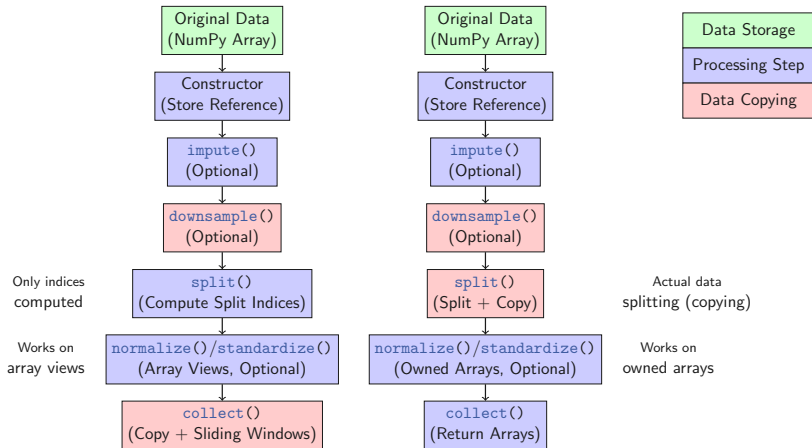
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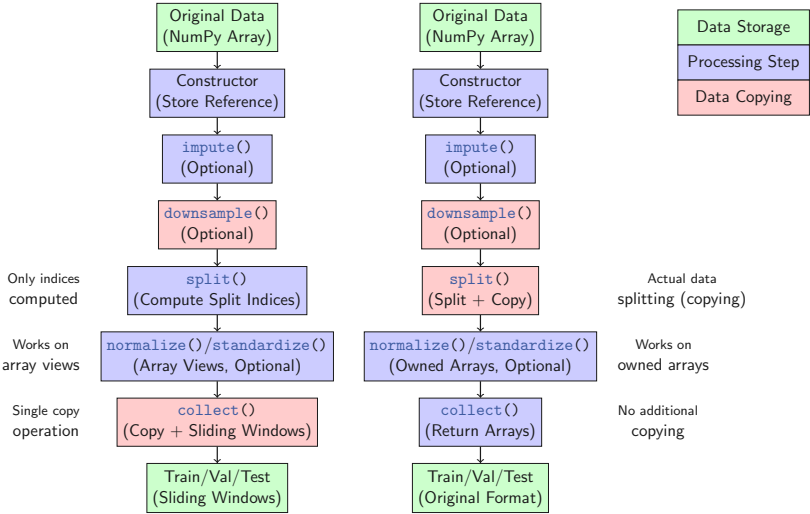
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Pipeline Design

ForecastingDataSet

```
# Create instance
fore = ForecastingDataSet(
    data, 0.7, 0.2, 0.1
)

# call the pipeline methods
fore.impute(
    ImputeStrategy.Median
)
fore.downsample(2)
fore.split()

fore.normalize()
fore.standardize()

# collect the results
fore_res = fore.collect(3, 1, 1)
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ClassificationDataSet

```
# create instance
clas = ClassificationDataSet(
    data, labels, 0.7, 0.2, 0.1
)

# call the pipeline methods
clas.impute(
    ImputeStrategy.Median
)
clas.downsample(2)
clas.split(
    SplittingStrategy.Random
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clas.normalize()
clas.standardize()

# collect the results
clas_res = clas.collect()
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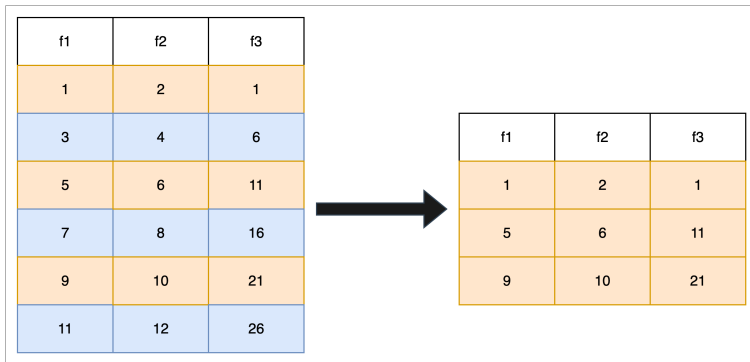
Necessary parameter when downsampling:

- ▶ Downsampling factor: How many data points to skip

Example:

- ▶ Downsampling factor of 2: Every second data point is kept

Downsampling II



Downsampling example with a factor of 2

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- ▶ Creating view only possible on continuous data.
- ▶ Downsampling does not yield a continuous data structure.

Standardization

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$$x' = \frac{x - \text{mean}}{\text{std}} \quad (1)$$

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- ▶ Apply the same min and max to the **validation** and **test** sets.

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How:

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Solution:

- ▶ Use the PyO3 testing framework.
- ▶ Mimic the Python API in Rust.
- ▶ Write unit tests in Rust that can be called from Python.

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- ▶ PyO3 provides a way to write Python bindings for Rust code.

Solution:

- ▶ Use the PyO3 testing framework.
- ▶ Mimic the Python API in Rust.
- ▶ Write unit tests in Rust that can be called from Python.
- ▶ Use the PyO3 testing framework to run the tests.

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- ▶ The coverage is not as detailed as with the standard Rust testing framework, but it is sufficient for our needs.

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Results:

- ▶ Number of all methods: 47
- ▶ Number of methods called during tests: 40
- ▶ Coverage: 85.1%

Benchmarking

Goal:

- ▶ Compare vs. PyTorch TimeSeriesDataSet

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- ▶ Measure timings and memory use

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Peak Memory:

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- ▶ **But:** Measurements show the same value (312 MB)
- ▶ Setup or measurement error.

Total setup durations I

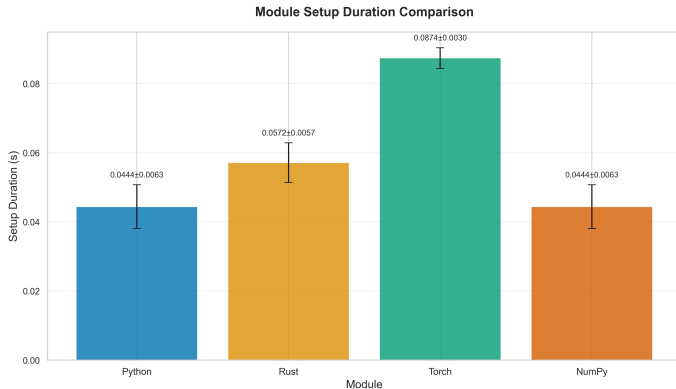
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Setup durations on GunPoint

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Explanation:

- ▶ Numpy uses vectorized operations in C

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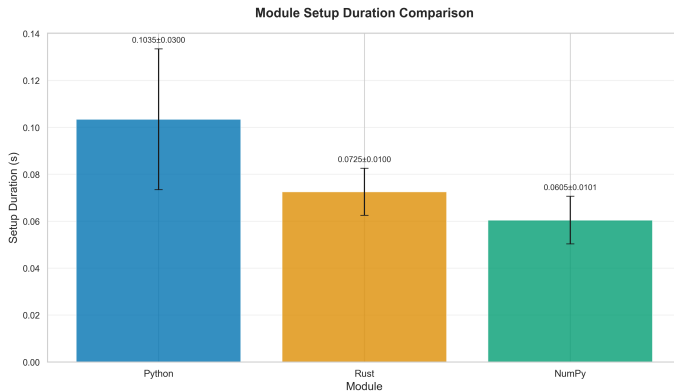
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Explanation:

- ▶ Numpy uses vectorized operations in C
- ▶ Torch overhead from Pandas

Total setup durations II

- **Goal:** Measure total setup over different parameters



Setup durations on GunPoint

Total setup durations II

- ▶ **Goal:** Measure total setup over different parameters

Explanation:

- ▶ More processing benefits Rust and Numpy

Total iteration durations

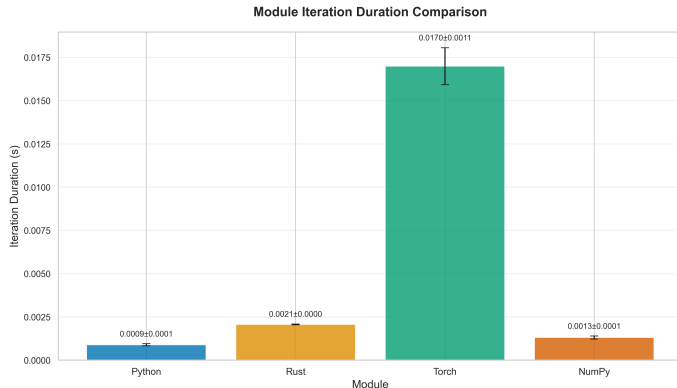
- ▶ **Goal:** Measure total data retrieval

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Iteration durations on GunPoint

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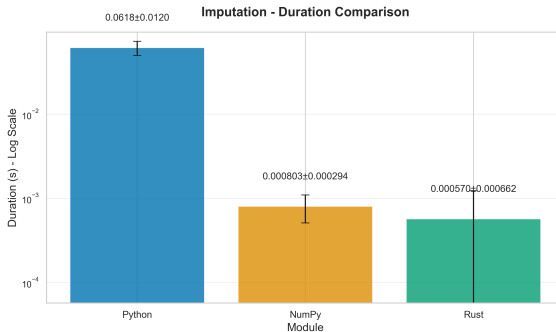
- ▶ PyTorch slowest due to deferred preprocessing during retrieval

Imputing durations

- ▶ **Goal:** Measure imputing in isolation

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Imputing durations on GunPoint

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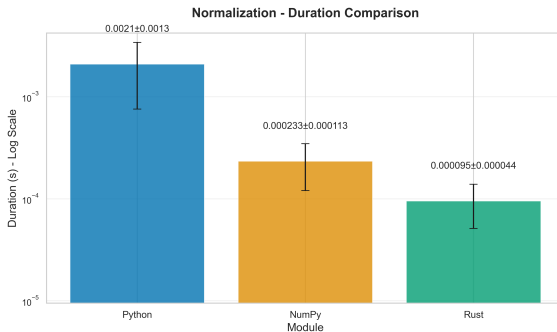
- ▶ Rust benefits from compiler
- ▶ NumPy benefits from partial vectorization

Normalization durations

- ▶ **Goal:** Measure normalization in isolation

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Normalization durations on GunPoint

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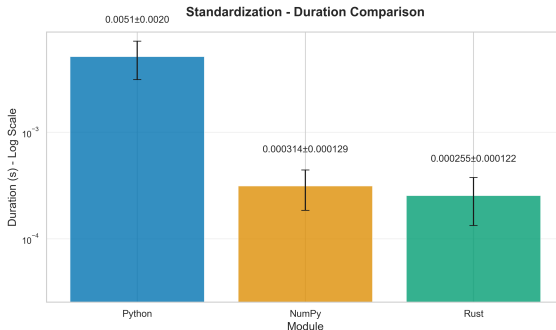
- ▶ **Again:**
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Standardization durations on GunPoint

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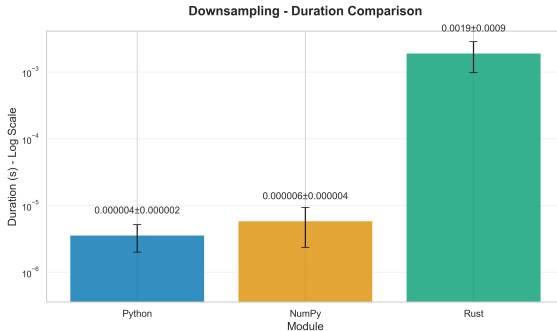
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Downsampling durations

- ▶ **Goal:** Measure downsampling in isolation

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Downsampling durations on GunPoint

Downsampling durations

- ▶ **Goal:** Measure downsampling in isolation

Explanation:

- ▶ Rust slowest due to costly data copying

Data collection durations

- ▶ **Goal:** Measure data collection in isolation

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Data collection durations on GunPoint

Data collection durations

- ▶ **Goal:** Measure data collection in isolation

Explanation:

- ▶ Rust slowest due to Python data transfer