

Symmetric and Antisymmetric Tensors

The Dual Vector (of an Antisymmetric Tensor)

Eigenvalues / Eigenvectors of a Tensor

Symmetric Tensor: $T = T^T$

$$T_{ij} = T_{ji} \quad (1)$$

for example: $T_{12} = T_{21}$ $T_{11} = T_{11}$ $T_{32} = T_{23}$

Antisymmetric Tensor: $T = -T^T$

$$T_{ij} = -T_{ji} \quad (2)$$

for example: $T_{12} = -T_{21}$ $T_{32} = -T_{23}$ $T_{11} = T_{22} = T_{33} = 0$

* Any tensor T can be written as the sum of its symmetric and antisymmetric part.

$$T = T^S + T^A$$

where $T^S = \frac{T + T^T}{2}$ and $T^A = \frac{T - T^T}{2}$

Some Important Properties:

1. $\text{tr}(T^S T^A) = 0$

proof: $\text{tr}(T^S T^A) = \text{tr}(\underbrace{T_{ij}}_{\text{sym}} \underbrace{T_{ji}}_{\text{asym}})$ $\stackrel{(1)}{=} \text{tr}(T_{ji} (-T_{ij}))$ $\stackrel{(2)}{=}$

$$= -\text{tr}(T_{ji}T_{ij}) = -\text{tr}(T_{jj})$$

the left-hand side can be written as $\text{tr}(T_{ii})$

$$\text{tr}(T_{ii}) = -\text{tr}(T_{jj}) \Rightarrow \text{tr}(T_{ii}) = -\text{tr}(T_{ii})$$

$$2\text{tr}(T_{ii}) = 0 \Rightarrow \text{tr}(T_{ii}) = 0$$

$$2. \text{tr}(AB) = \text{tr}(A^S B^S) + \text{tr}(A^A B^A)$$

$$3. (T^A)^T = -T^A$$

The Dual vector of an Antisymmetric Tensor:

In an antisymmetric tensor: $T = -T^T$, $T_{ij} = -T_{ji}$

$$T^A = \begin{bmatrix} 0 & T_{12} & T_{13} \\ -T_{12} & 0 & T_{23} \\ -T_{13} & -T_{23} & 0 \end{bmatrix}$$

Definition of a dual vector: $Ta = t^A \times a$ (3)

$$T_{12} = e_1 \cdot T e_2 \stackrel{(3)}{=} e_1 \cdot (t^A \times e_2)$$

from Module 1.1.2 : $a \cdot (b \times c) = b \cdot (c \times a) = c \cdot (a \times b)$ (*)

$$T_{12} = e_1 \cdot (t^A \times e_2) \stackrel{(*)}{=} t^A \cdot (e_2 \times e_1) = -t^A e_3$$

$$T_{31} = e_3 \cdot T e_1 = e_3 \cdot (t^A \times e_1) \stackrel{(*)}{=} t^A \cdot (e_1 \times e_3) = -t^A e_2$$

$$T_{23} = e_2 \cdot T e_3 = e_2 \cdot (t^A \times e_3) \stackrel{(*)}{=} t^A \cdot (e_3 \times e_2) = -t^A e_1$$

$$t^A = - (T_{23} \hat{e}_1 + T_{31} \hat{e}_2 + T_{12} \hat{e}_3)$$

$$= (T_{32} \hat{e}_1 + T_{13} \hat{e}_2 + T_{21} \hat{e}_3)$$

$$t^A = -\frac{1}{2} \epsilon_{ijk} T_{jk} e_i \Rightarrow 2t^A = -\epsilon_{ijk} T_{jk} e_i$$

- the axis of rotation of a rotation matrix is parallel to the dual vector of the rotation tensor.

deformation gradient $\nabla u = \overset{\text{sym}}{E} + \overset{\text{asym}}{\Omega}$

infinitesimal strain tensor $\overset{\text{sym}}{E}$ infinitesimal rotation tensor $\overset{\text{asym}}{\Omega}$

$-\Omega dX = t^A \times dX$

direction vector t^A

cross product

dual vector of the infinitesimal tensor ($-\Omega$)

Proof: (Example 2.21.2)

R : a rotation tensor

m : a univector in the direction of axis of rotation.

We would like to prove q (dual vector of R) is parallel to m

in other words $q \times m = 0$

$$|q||m| \sin \theta = 0$$

$$(1) Rm = m \xrightarrow{\times R^T} \underbrace{R^T R}_{=I} m = R^T m \Rightarrow Im = R^T m \Rightarrow m = R^T m \quad (2)$$

$$R \text{ is a rotation tensor} \therefore R^T R = R R^T = I$$

from (1) and (2) :

$$\begin{cases} Rm = m \\ R^T m = m \end{cases} \xrightarrow[\text{both sides}]{\text{subtract}} Rm - R^T m = 0$$

$$m(R - R^T) = 0$$

$$R^A = \left(\frac{R - R^T}{2} \right) \Rightarrow 2R^A_m = 0 \quad \text{and} \quad R^A = q$$

$$2R^A_m = 2q \times m = 0 \Rightarrow q \times m = 0$$

↑
dual vector of R^A

Eigenvalues and Eigenvectors of a Tensor:

$$T a = \lambda a \leftarrow \begin{array}{l} \text{eigenvectors} \\ \text{eigenvalues} \end{array}$$

$$\underset{\substack{\uparrow \\ \text{scalar}}}{T(\alpha a)} = \alpha T a = \alpha \lambda a = \lambda (\alpha a)$$

for the Identity tensor (I):

$$I a = a$$

in other words:

$$I a = (1) a$$

$$I \alpha a = (1)(\alpha a)$$

How to find Eigenvalues?

$$a \cdot a = 1$$

$$T a = \lambda a \quad \text{assume } \vec{a} \text{ is a unit vector}$$

replace a on the right-hand side with $I a$

$$T a = \lambda (I a) \Rightarrow T a - \lambda (I a) \Rightarrow a (T - \lambda I) = 0$$

For nontrivial solution $|T - \lambda I| = 0$

$$\begin{vmatrix} T_{11} - \lambda & T_{12} & T_{13} \\ T_{21} & T_{22} - \lambda & T_{23} \\ T_{31} & T_{32} & T_{33} - \lambda \end{vmatrix} = 0$$

the determinate gives us an equation which is called the "Characteristic Equation".

How to find Eigenvectors?

$$\begin{array}{l} \xrightarrow[\text{a with } I\mathbf{a}]{\text{replace}} \quad T\mathbf{a} = \lambda\mathbf{a} \\ T\mathbf{a} - \lambda I\mathbf{a} = 0 \Rightarrow \mathbf{a}(T - \lambda I) = 0, (T - \lambda I)\mathbf{a} = 0 \end{array}$$

$$\text{indicial notation: } (T_{ij} - \lambda \delta_{ij}) a_j = 0$$

$$\text{let } \mathbf{a} = \alpha_i \mathbf{e}_i \quad : (T_{ij} - \lambda \delta_{ij}) \alpha_j = 0 \quad \text{Wait!}$$

Is this correct?

$$(T_{11} - \lambda) \alpha_1 + T_{21} \alpha_2 + T_{31} \alpha_3 = 0$$

But this is incorrect because we agreed to fill in the tensors by column.

$$\therefore \text{indicial notation: } (T_{ij} - \lambda \delta_{ij}) \alpha_j = 0$$

(CORRECT)

$$\left\{ \begin{array}{l} (T_{11} - \lambda) \alpha_1 + (T_{12}) \alpha_2 + (T_{13}) \alpha_3 = 0 \\ (T_{21}) \alpha_1 + (T_{22} - \lambda) \alpha_2 + (T_{23}) \alpha_3 = 0 \\ (T_{31}) \alpha_1 + (T_{32}) \alpha_2 + (T_{33} - \lambda) \alpha_3 = 0 \end{array} \right.$$

$$\text{Since } \vec{\mathbf{a}} \text{ is a unit vector } \therefore \alpha_1^2 + \alpha_2^2 + \alpha_3^2 = 1$$