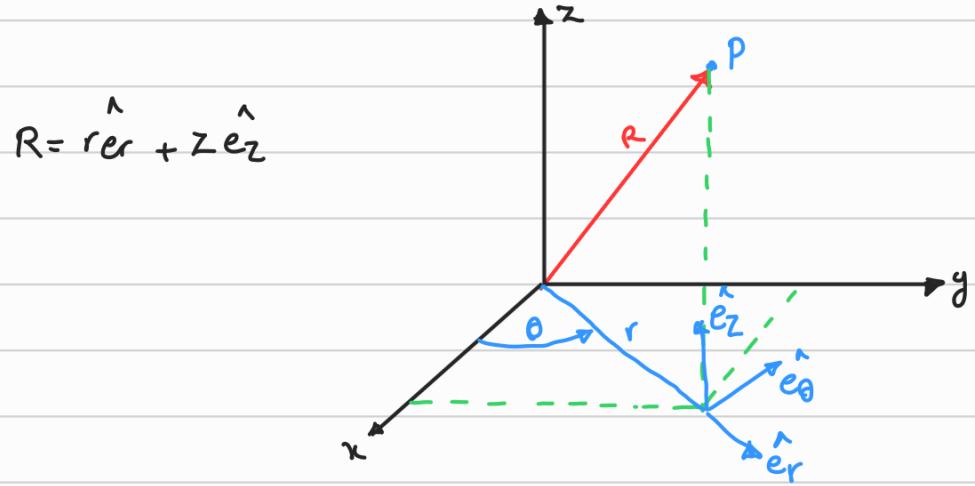


Cylindrical Coordinate:

Introduction:



$$dR = \underbrace{dr \hat{e}_r + r d\theta \hat{e}_\theta + dz \hat{e}_z}_{d\theta \hat{e}_\theta} = dr \hat{e}_r + r d\theta \hat{e}_\theta + dz \hat{e}_z \quad (*)$$

Gradient of a Scalar Field:

Let f be a scalar field, $f(r, \theta, z)$

$$\frac{df}{dr} = \nabla f \cdot \hat{e}_r \Rightarrow df = \nabla f \cdot dr = (a_r \hat{e}_r + a_\theta \hat{e}_\theta + a_z \hat{e}_z) \cdot (dr \hat{e}_r + r d\theta \hat{e}_\theta + dz \hat{e}_z)$$

$$= a_r dr + a_\theta r d\theta + a_z dz \quad (1)$$

$$f(r, \theta, z) : df = \frac{\partial f}{\partial r} dr + \frac{\partial f}{\partial \theta} d\theta + \frac{\partial f}{\partial z} dz \quad (2)$$

compare (1) $a_r = \frac{\partial f}{\partial r}$, $a_\theta = \frac{1}{r} \frac{\partial f}{\partial \theta}$, $a_z = \frac{\partial f}{\partial z}$
and (2)

$$\nabla f = \frac{\partial f}{\partial r} \hat{e}_r + \frac{1}{r} \frac{\partial f}{\partial \theta} \hat{e}_\theta + \frac{\partial f}{\partial z} \hat{e}_z$$

Gradient of a Vector Field:

$$v(r, \theta, z) = v_r(r, \theta, z) \hat{e}_r + v_\theta(r, \theta, z) \hat{e}_\theta + v_z(r, \theta, z) \hat{e}_z$$

$$\frac{dv}{dr} = \nabla v \Rightarrow dv = \nabla v dr = \underbrace{T dr}_{\text{2nd-order tensor}} \quad \nabla v = T$$

$$dv = T dr = T \left(dr \hat{e}_r + r d\theta \hat{e}_\theta + dz \hat{e}_z \right) = dr (T_r \hat{e}_r) + r d\theta (T_\theta \hat{e}_\theta) + dz (T_z \hat{e}_z)$$

$$\left\{ \begin{array}{l} T_r \hat{e}_r = T_{jr} \hat{e}_j \stackrel{j=r,\theta,z}{=} T_{rr} \hat{e}_r + T_{\theta r} \hat{e}_\theta + T_{zr} \hat{e}_z \\ T_\theta \hat{e}_\theta = T_{j\theta} \hat{e}_j \stackrel{j=r,\theta,z}{=} T_{r\theta} \hat{e}_r + T_{\theta\theta} \hat{e}_\theta + T_{z\theta} \hat{e}_z \\ T_z \hat{e}_z = T_{jz} \hat{e}_j \stackrel{j=r,\theta,z}{=} T_{rz} \hat{e}_r + T_{\theta z} \hat{e}_\theta + T_{zz} \hat{e}_z \end{array} \right.$$

$$dv = dr T_{rr} \hat{e}_r + r d\theta T_{\theta r} \hat{e}_\theta + dz T_{zr} \hat{e}_z$$

$$+ r d\theta T_{r\theta} \hat{e}_r + r d\theta T_{\theta\theta} \hat{e}_\theta + r d\theta T_{z\theta} \hat{e}_z$$

$$+ dz T_{rz} \hat{e}_r + dz T_{\theta z} \hat{e}_\theta + dz T_{zz} \hat{e}_z$$

$$= (dr T_{rr} + r d\theta T_{\theta r} + dz T_{zr}) \hat{e}_r + (dr T_{\theta r} + r d\theta T_{\theta\theta} + dz T_{\theta z}) \hat{e}_\theta$$

$$+ (dr T_{zr} + dz T_{\theta z} + dz T_{zz}) \hat{e}_z \quad (3)$$

$$\text{Next, } v(r, \theta, z) = v_r(r, \theta, z) \hat{e}_r + v_\theta(r, \theta, z) \hat{e}_\theta + v_z(r, \theta, z) \hat{e}_z$$

$$dv = dv_r \hat{e}_r + v_r dr \hat{e}_r + dv_\theta \hat{e}_\theta + v_\theta d\theta \hat{e}_\theta + dv_z \hat{e}_z + v_z dz \hat{e}_z$$

$$= dv_r \hat{e}_r + (v_r dr) \hat{e}_r + dv_\theta \hat{e}_\theta - (v_\theta d\theta) \hat{e}_\theta + dv_z \hat{e}_z$$

$$\left\{ \begin{array}{l} dv_r = \frac{\partial v_r}{\partial r} dr + \frac{\partial v_r}{\partial \theta} d\theta + \frac{\partial v_r}{\partial z} dz \end{array} \right.$$

$$\left. \begin{array}{l} dv_\theta = \frac{\partial v_\theta}{\partial r} dr + \frac{\partial v_\theta}{\partial \theta} d\theta + \frac{\partial v_\theta}{\partial z} dz \end{array} \right.$$

$$\left. \begin{array}{l} dv_z = \frac{\partial v_z}{\partial r} dr + \frac{\partial v_z}{\partial \theta} d\theta + \frac{\partial v_z}{\partial z} dz \end{array} \right.$$

Substitute above equations in \mathbf{dv} gives

$$\begin{aligned}
 \mathbf{dv} &= \left(\frac{\partial v_r}{\partial r} dr + \frac{\partial v_r}{\partial \theta} d\theta + \frac{\partial v_r}{\partial z} dz \right) \hat{\mathbf{e}}_r + (v_r d\theta) \hat{\mathbf{e}}_\theta \\
 &\quad + \left(\frac{\partial v_\theta}{\partial r} dr + \frac{\partial v_\theta}{\partial \theta} d\theta + \frac{\partial v_\theta}{\partial z} dz \right) \hat{\mathbf{e}}_\theta - (v_\theta d\theta) \hat{\mathbf{e}}_r \\
 &\quad + \left(\frac{\partial v_z}{\partial r} dr + \frac{\partial v_z}{\partial \theta} d\theta + \frac{\partial v_z}{\partial z} dz \right) \hat{\mathbf{e}}_z \\
 &= \left(\frac{\partial v_r}{\partial r} dr + \left(\frac{\partial v_r}{\partial \theta} - v_\theta \right) d\theta + \frac{\partial v_r}{\partial z} dz \right) \hat{\mathbf{e}}_r \\
 &\quad + \left(\frac{\partial v_\theta}{\partial r} dr + \left(\frac{\partial v_\theta}{\partial \theta} + v_r \right) d\theta + \frac{\partial v_\theta}{\partial z} dz \right) \hat{\mathbf{e}}_\theta \\
 &\quad + \left(\frac{\partial v_z}{\partial r} dr + \frac{\partial v_z}{\partial \theta} d\theta + \frac{\partial v_z}{\partial z} dz \right) \hat{\mathbf{e}}_z \tag{4}
 \end{aligned}$$

Compare (3)

and (4)

$$\begin{bmatrix} T_{rr} & T_{r\theta} & T_{rz} \\ T_{\theta r} & T_{\theta\theta} & T_{\theta z} \\ T_{zr} & T_{z\theta} & T_{zz} \end{bmatrix}$$

$$= \begin{bmatrix} \frac{\partial v_r}{\partial r} & \frac{1}{r} \left(\frac{\partial v_r}{\partial \theta} - v_\theta \right) & \frac{\partial v_r}{\partial z} \\ \frac{\partial v_\theta}{\partial r} & \frac{1}{r} \left(\frac{\partial v_\theta}{\partial \theta} + v_r \right) & \frac{\partial v_\theta}{\partial z} \\ \frac{\partial v_z}{\partial r} & \frac{1}{r} \frac{\partial v_z}{\partial \theta} & \frac{\partial v_z}{\partial z} \end{bmatrix}$$

Divergence of a Vector Field:

$$\operatorname{div} \vec{v} = \operatorname{tr}(\nabla \vec{v}) = \frac{\partial v_r}{\partial r} + \frac{1}{r} \left(\frac{\partial v_\theta}{\partial \theta} + v_r \right) + \frac{\partial v_z}{\partial z}$$

Curl of a Vector Field:

$$\operatorname{curl} \vec{v} = \nabla \times \vec{v} = 2t^A$$

$$[\nabla v]^A = \frac{[\nabla v] - [\nabla v]^T}{2}$$

$$\begin{aligned}
 & \frac{1}{2} \left[\begin{bmatrix} \frac{\partial v_r}{\partial r} & \frac{1}{r} \left(\frac{\partial v_r}{\partial \theta} - v_\theta \right) & \frac{\partial v_r}{\partial z} \\ \frac{\partial v_\theta}{\partial r} & \frac{1}{r} \left(\frac{\partial v_\theta}{\partial \theta} + v_r \right) & \frac{\partial v_\theta}{\partial z} \\ \frac{\partial v_z}{\partial r} & \frac{1}{r} \left(\frac{\partial v_z}{\partial \theta} \right) & \frac{\partial v_z}{\partial z} \end{bmatrix} - \begin{bmatrix} \frac{\partial v_r}{\partial r} & \frac{\partial v_\theta}{\partial r} & \frac{\partial v_z}{\partial r} \\ \frac{1}{r} \left(\frac{\partial v_r}{\partial \theta} - v_\theta \right) & \frac{1}{r} \left(\frac{\partial v_\theta}{\partial \theta} + v_r \right) & \frac{1}{r} \frac{\partial v_z}{\partial \theta} \\ \frac{\partial v_r}{\partial z} & \frac{\partial v_\theta}{\partial z} & \frac{\partial v_z}{\partial z} \end{bmatrix} \right] \\
 & = \frac{1}{2} \begin{bmatrix} 0 & \frac{1}{r} \left(\frac{\partial v_r}{\partial \theta} - v_\theta \right) - \frac{\partial v_\theta}{\partial r} & \frac{\partial v_r}{\partial z} - \frac{\partial v_z}{\partial r} \\ \frac{\partial v_\theta}{\partial r} - \frac{1}{r} \left(\frac{\partial v_r}{\partial \theta} - v_\theta \right) & 0 & \frac{\partial v_\theta}{\partial z} - \frac{1}{r} \frac{\partial v_z}{\partial \theta} \\ \frac{\partial v_z}{\partial r} - \frac{\partial v_r}{\partial z} & \frac{1}{r} \frac{\partial v_\theta}{\partial z} - \frac{\partial v_\theta}{\partial z} & 0 \end{bmatrix}
 \end{aligned}$$

$$2t^A = -2(T_{23}\hat{e}_1 + T_{31}\hat{e}_2 + T_{12}\hat{e}_3) = -2(T_{\theta z}\hat{e}_r + T_{2r}\hat{e}_\theta + T_{r\theta}\hat{e}_z)$$

$$\begin{aligned}
 & = - \left[\left(\frac{\partial v_\theta}{\partial z} - \frac{1}{r} \frac{\partial v_z}{\partial \theta} \right) \hat{e}_r + \left(\frac{\partial v_z}{\partial r} - \frac{\partial v_r}{\partial z} \right) \hat{e}_\theta + \right. \\
 & \quad \left. \left(\frac{1}{r} \left(\frac{\partial v_r}{\partial \theta} - v_\theta \right) - \frac{\partial v_\theta}{\partial r} \right) \hat{e}_z \right] \\
 & = \left(\frac{1}{r} \frac{\partial v_z}{\partial \theta} - \frac{\partial v_\theta}{\partial z} \right) \hat{e}_r + \left(\frac{\partial v_r}{\partial z} - \frac{\partial v_z}{\partial r} \right) \hat{e}_\theta + \left(\frac{\partial v_\theta}{\partial r} - \frac{1}{r} \left(\frac{\partial v_r}{\partial \theta} - v_\theta \right) \right) \hat{e}_z
 \end{aligned}$$

Divergence of a Tensor Field:

$$(\operatorname{div} T) \cdot a = \operatorname{div}(T^T a) - \operatorname{tr}((\nabla a) T^T) \quad \forall a$$

$$a = \hat{e}_r : (\operatorname{div})^T r = \operatorname{div}(T^T \hat{e}_r) - \operatorname{tr}((\nabla \hat{e}_r) T^T)$$

$$\hat{T}_{er} = T_{jr} \hat{e}_j \stackrel{j=r, \theta, z}{=} T_{rr} \hat{e}_r + T_{r\theta} \hat{e}_\theta + T_{rz} \hat{e}_z$$

$$\hat{T}_{er} = \underbrace{T_{rr}}_{\tilde{v}_r} \hat{e}_r + \underbrace{T_{r\theta}}_{\tilde{v}_\theta} \hat{e}_\theta + \underbrace{T_{rz}}_{\tilde{v}_z} \hat{e}_z$$

$$\text{Eq (2.34.6)} : \operatorname{div}(T^T \hat{e}_r) = \frac{\partial T_{rr}}{\partial r} + \frac{1}{r} \left(\frac{\partial T_{r\theta}}{\partial \theta} + T_{rr} \right) + \frac{\partial T_{rz}}{\partial z}$$

$$\hat{e}_r = (\underbrace{1}_{\tilde{v}_r}) \hat{e}_r + (\underbrace{0}_{\tilde{v}_\theta}) \hat{e}_\theta + (\underbrace{0}_{\tilde{v}_z}) \hat{e}_z$$

$$\text{Eq (2.34.5)} : \nabla \hat{e}_r T^T = \begin{bmatrix} 0 & 0 & 0 \\ 0 & \frac{1}{r} \hat{e}_r & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} T_{rr} & T_{r\theta} & T_{rz} \\ T_{r\theta} & T_{\theta\theta} & T_{\theta z} \\ T_{rz} & T_{\theta z} & T_{zz} \end{bmatrix}$$

$$= \begin{bmatrix} 0 & 0 & 0 \\ \frac{1}{r} T_{r\theta} \hat{e}_r & \frac{1}{r} T_{\theta\theta} \hat{e}_r & \frac{1}{r} T_{\theta z} \hat{e}_r \\ 0 & 0 & 0 \end{bmatrix}$$

$$\Rightarrow \text{tr}((\nabla \hat{e}_r) T^T) = \frac{1}{r} T_{\theta\theta} \hat{e}_r$$

$$(\text{div } T)_r = \frac{\partial T_{rr}}{\partial r} + \frac{1}{r} \left(\frac{\partial T_{r\theta}}{\partial \theta} + T_{rr} \right) + \frac{\partial T_{rz}}{\partial z} - \frac{1}{r} T_{\theta\theta}$$

$$a = \hat{e}_\theta : (\text{div } T)_\theta = \text{div}(T^T \hat{e}_\theta) - \text{tr}((\nabla \hat{e}_\theta) T^T)$$

$$T^T \hat{e}_\theta = T_{j\theta} \hat{e}_j = T_{r\theta} \hat{e}_r + T_{\theta\theta} \hat{e}_\theta + T_{z\theta} \hat{e}_z$$

$$T^T \hat{e}_\theta = T_{j\theta} \hat{e}_j = \underbrace{T_{rr}}_{\tilde{v}_r} \hat{e}_r + \underbrace{T_{\theta\theta}}_{\tilde{v}_\theta} \hat{e}_\theta + \underbrace{T_{z\theta}}_{\tilde{v}_z} \hat{e}_z$$

$$\text{Eq (2.34.6)} : \text{div}(T^T \hat{e}_\theta) = \frac{\partial T_{\theta r}}{\partial r} + \frac{1}{r} \left(\frac{\partial T_{\theta\theta}}{\partial \theta} + T_{\theta r} \right) + \frac{\partial T_{\theta z}}{\partial z}$$

$$\hat{e}_\theta = (\underbrace{0}_{\tilde{v}_r}) \hat{e}_r + (\underbrace{1}_{\tilde{v}_\theta}) \hat{e}_\theta + (\underbrace{0}_{\tilde{v}_z}) \hat{e}_z$$

$$\text{Eq (2.34.5)} : (\nabla \hat{e}_\theta T^T) = \begin{bmatrix} 0 & \frac{1}{r} (-\hat{e}_\theta) & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} T_{rr} & T_{r\theta} & T_{rz} \\ T_{r\theta} & T_{\theta\theta} & T_{\theta z} \\ T_{rz} & T_{\theta z} & T_{zz} \end{bmatrix}$$

$$= \begin{bmatrix} -\frac{1}{r} T_{r\theta} \hat{e}_\theta & -\frac{1}{r} T_{\theta\theta} \hat{e}_\theta & -\frac{1}{r} T_{\theta z} \hat{e}_\theta \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

$$\text{tr}((\nabla e_r) T^T) = -\frac{1}{r} T_{r\theta} \hat{e}_\theta$$

$$(\text{div } T)_\theta = \frac{\partial T_{\theta r}}{\partial r} + \frac{1}{r} \left(\frac{\partial T_{\theta\theta}}{\partial \theta} + T_{\theta r} \right) + \frac{\partial T_{\theta z}}{\partial z} + \frac{1}{r} T_{\theta r}$$

$$a = \hat{e}_z : (\text{div } T)_z = \text{div}(T^T e_z) - \text{tr}((\nabla e_z) T^T)$$

$$T e_z = T_{jz} \hat{e}_j = T_{rz} \hat{e}_r + T_{\theta z} \hat{e}_\theta + T_{zz} \hat{e}_z$$

$$T e_z = T_{zj} \hat{e}_j = \underbrace{T_{rz}}_{vr} \hat{e}_r + \underbrace{T_{\theta z}}_{v\theta} \hat{e}_\theta + \underbrace{T_{zz}}_{vz} \hat{e}_z$$

$$\text{Eq (2.34.6)} : \text{div}(T^T e_r) = \frac{\partial T_{zr}}{\partial r} + \frac{1}{r} \left(\frac{\partial T_{\theta z}}{\partial \theta} + T_{zr} \right) + \frac{\partial T_{zz}}{\partial z}$$

$$\hat{e}_z = (0) \hat{e}_r + (0) \hat{e}_\theta + (1) \hat{e}_z$$

$$\text{Eq (2.34.5)} \quad (\nabla \hat{e}_z T^T) = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} [T^T] = [0]$$

$$(\text{div } T)_z = \frac{\partial T_{zr}}{\partial r} + \frac{1}{r} \left(\frac{\partial T_{\theta z}}{\partial \theta} + T_{zr} \right) + \frac{\partial T_{zz}}{\partial z}$$

Laplacian of a Scalar Field:

$$\nabla f = \underbrace{\frac{\partial f}{\partial r}}_{vr} \hat{e}_r + \underbrace{\frac{1}{r} \frac{\partial f}{\partial \theta}}_{v\theta} \hat{e}_\theta + \underbrace{\frac{\partial f}{\partial z}}_{vz} \hat{e}_z$$

$$\begin{aligned} \nabla^2 f &= \nabla \cdot (\nabla f) = \text{div}(\nabla f) = \underbrace{\frac{\partial}{\partial r} \left(\frac{\partial f}{\partial r} \right)}_{\text{vector}} + \frac{1}{r} \left(\frac{\partial}{\partial \theta} \left(\frac{1}{r} \frac{\partial f}{\partial \theta} \right) + \frac{\partial f}{\partial r} \right) \\ &\quad + \frac{\partial}{\partial z} \left(\frac{\partial f}{\partial z} \right) \end{aligned}$$

$$= \frac{\partial^2 f}{\partial r^2} + \frac{1}{r^2} \frac{\partial^2 f}{\partial \theta^2} + \frac{1}{r} \frac{\partial^2 f}{\partial z^2} + \frac{\partial^2 f}{\partial z^2}$$

Laplacian of a vector Field:

$$\nabla^2 \vec{v} = \nabla(\operatorname{div} \vec{v}) - \nabla \times (\nabla \times \vec{v})$$

$$\operatorname{div} \vec{v} = \frac{\partial v_r}{\partial r} + \frac{1}{r} \left(\frac{\partial v_\theta}{\partial \theta} + v_r \right) + \frac{\partial v_z}{\partial z}$$

$$\nabla(\operatorname{div} \vec{v}) = \frac{\partial}{\partial r} \left(\frac{\partial v_r}{\partial r} + \frac{1}{r} \left(\frac{\partial v_\theta}{\partial \theta} + v_r \right) + \frac{\partial v_z}{\partial z} \right) \hat{e}_r$$

$$+ \frac{1}{r} \frac{\partial}{\partial \theta} \left(\frac{\partial v_r}{\partial r} + \frac{1}{r} \left(\frac{\partial v_\theta}{\partial \theta} + v_r \right) + \frac{\partial v_z}{\partial z} \right) \hat{e}_\theta$$

$$+ \frac{\partial}{\partial z} \left(\frac{\partial v_r}{\partial r} + \frac{1}{r} \left(\frac{\partial v_\theta}{\partial \theta} + v_r \right) + \frac{\partial v_z}{\partial z} \right) \hat{e}_z$$

$$= \left(\frac{\partial^2 v_r}{\partial r^2} - \frac{1}{r^2} \left(\frac{\partial v_\theta}{\partial \theta} + v_r \right) + \frac{1}{r} \left(\frac{\partial^2 v_\theta}{\partial r \partial \theta} + \frac{\partial v_r}{\partial r} \right) + \frac{\partial^2 v_z}{\partial r \partial z} \right) \hat{e}_r$$

$$+ \left(\frac{1}{r} \frac{\partial^2 v_r}{\partial \theta \partial r} + \frac{1}{r^2} \left(\frac{\partial^2 v_\theta}{\partial \theta^2} + \frac{\partial v_r}{\partial \theta} \right) + \frac{1}{r} \frac{\partial^2 v_z}{\partial \theta \partial z} \right) \hat{e}_\theta$$

$$+ \left(\frac{\partial^2 v_r}{\partial z \partial r} + \frac{1}{r} \left(\frac{\partial^2 v_\theta}{\partial z \partial \theta} + \frac{\partial v_r}{\partial z} \right) + \frac{\partial^2 v_z}{\partial z^2} \right) \hat{e}_z \quad (5)$$

$$\nabla \times \vec{v} = \left(\frac{1}{r} \frac{\partial v_z}{\partial \theta} - \frac{\partial v_\theta}{\partial z} \right) \hat{e}_r + \left(\frac{\partial v_r}{\partial z} - \frac{\partial v_z}{\partial r} \right) \hat{e}_\theta + \left(\frac{\partial v_\theta}{\partial r} + \frac{v_\theta}{r} - \frac{1}{r} \frac{\partial v_r}{\partial \theta} \right) \hat{e}_z$$

$$\begin{aligned} \nabla \times (\nabla \times \vec{v}) &= \left(\frac{1}{r} \frac{\partial}{\partial \theta} \left\{ \frac{\partial v_\theta}{\partial r} + \frac{v_\theta}{r} - \frac{1}{r} \frac{\partial v_r}{\partial \theta} \right\} - \frac{\partial}{\partial z} \left\{ \frac{\partial v_r}{\partial z} - \frac{\partial v_z}{\partial r} \right\} \right) \hat{e}_r \\ &+ \left(\frac{\partial}{\partial z} \left\{ \frac{1}{r} \frac{\partial v_z}{\partial \theta} - \frac{\partial v_\theta}{\partial z} \right\} - \frac{\partial}{\partial r} \left\{ \frac{\partial v_\theta}{\partial r} + \frac{v_\theta}{r} - \frac{1}{r} \frac{\partial v_r}{\partial \theta} \right\} \right) \hat{e}_\theta \\ &+ \left(\frac{\partial}{\partial r} \left\{ \frac{\partial v_z}{\partial z} - \frac{\partial v_z}{\partial r} \right\} + \frac{1}{r} \left(\frac{\partial v_r}{\partial z} - \frac{\partial v_z}{\partial r} \right) - \frac{1}{r} \frac{\partial}{\partial \theta} \left(\frac{1}{r} \frac{\partial v_z}{\partial \theta} - \frac{\partial v_\theta}{\partial z} \right) \right) \hat{e}_z \end{aligned}$$

$$= \left\{ \frac{1}{r} \frac{\partial^2 v_\theta}{\partial \theta \partial r} + \frac{1}{r^2} \frac{\partial v_\theta}{\partial \theta} - \frac{1}{r^2} \frac{\partial^2 v_r}{\partial \theta^2} - \frac{\partial^2 v_r}{\partial z^2} + \frac{\partial^2 v_z}{\partial z \partial r} \right\} \hat{e}_r$$

$$+ \left\{ \frac{1}{r} \frac{\partial^2 v_r}{\partial z \partial \theta} - \frac{\partial^2 v_\theta}{\partial z^2} - \frac{\partial^2 v_\theta}{\partial r^2} + \frac{1}{r^2} v_\theta - \frac{1}{r} \frac{\partial v_\theta}{\partial r} - \frac{1}{r^2} \frac{\partial v_r}{\partial \theta} \right.$$

$$\left. + \frac{1}{r} \frac{\partial^2 v_r}{\partial \theta^2} \right\} \hat{e}_\theta$$

$$+ \left\{ \frac{\partial^2 v_r}{\partial r \partial z} - \frac{\partial^2 v_r}{\partial r^2} + \frac{1}{r} \frac{\partial v_r}{\partial z} - \frac{1}{r} \frac{\partial v_r}{\partial r} - \frac{1}{r^2} \frac{\partial^2 v_r}{\partial \theta^2} + \frac{1}{r} \frac{\partial^2 v_\theta}{\partial \theta \partial z} \right\} \hat{e}_z$$

(6)

(5) - (6) gives

$$(\nabla^2 v)_r = \frac{\partial^2 v_r}{\partial r^2} - \frac{1}{r^2} \frac{\partial v_\theta}{\partial \theta} - \frac{1}{r^2} v_r + \frac{1}{r} \cancel{\frac{\partial^2 v_\theta}{\partial r \partial \theta}} + \frac{1}{r} \frac{\partial v_r}{\partial r} + \cancel{\frac{\partial^2 v_r}{\partial r \partial z}}$$

$$- \cancel{\frac{1}{r} \frac{\partial^2 v_\theta}{\partial \theta \partial r}} - \frac{1}{r^2} \frac{\partial v_\theta}{\partial \theta} + \frac{1}{r^2} \frac{\partial^2 v_r}{\partial \theta^2} + \cancel{\frac{\partial^2 v_r}{\partial z^2}} - \cancel{\frac{\partial^2 v_r}{\partial z \partial r}}$$

$$= \frac{\partial^2 v_r}{\partial r^2} - \frac{2}{r^2} \frac{\partial v_\theta}{\partial \theta} - \frac{1}{r^2} v_r + \frac{1}{r} \frac{\partial v_r}{\partial r} + \frac{1}{r} \frac{\partial^2 v_r}{\partial \theta^2} + \frac{\partial^2 v_r}{\partial z^2}$$

$$(\nabla^2 v)_\theta = \frac{1}{r} \frac{\partial^2 v_r}{\partial \theta \partial r} + \frac{1}{r^2} \frac{\partial^2 v_\theta}{\partial \theta^2} + \frac{1}{r^2} \frac{\partial v_r}{\partial \theta} + \frac{1}{r} \frac{\partial^2 v_r}{\partial \theta \partial z}$$

$$- \frac{1}{r} \frac{\partial^2 v_r}{\partial z \partial \theta} + \frac{\partial^2 v_\theta}{\partial z^2} + \frac{\partial^2 v_\theta}{\partial r^2} - \frac{1}{r^2} v_\theta + \frac{1}{r} \frac{\partial v_\theta}{\partial r} + \frac{1}{r^2} \frac{\partial v_r}{\partial \theta} - \frac{1}{r} \frac{\partial^2 v_r}{\partial \theta \partial \theta}$$

$$= \frac{1}{r^2} \frac{\partial^2 v_\theta}{\partial \theta^2} + \frac{2}{r^2} \frac{v_r}{\partial \theta} + \frac{\partial v_\theta}{\partial z^2} + \frac{\partial^2 v_\theta}{\partial r^2} - \frac{1}{r^2} v_\theta + \frac{1}{r} \frac{\partial v_\theta}{\partial r}$$

$$(\nabla^2 v)_z = \frac{\partial^2 v_r}{\partial z \partial r} + \frac{1}{r} \frac{\partial^2 v_\theta}{\partial z \partial \theta} + \frac{1}{r} \frac{\partial v_r}{\partial z} + \frac{\partial^2 v_r}{\partial z^2}$$

$$- \frac{\partial^2 v_r}{\partial v \partial z} + \frac{\partial^2 v_r}{\partial r^2} - \frac{1}{r} \frac{\partial v_r}{\partial z} + \frac{1}{r} \frac{\partial v_r}{\partial r} + \frac{1}{r^2} \frac{\partial^2 v_r}{\partial \theta^2} - \frac{1}{r} \frac{\partial v_\theta}{\partial \theta \partial z}$$

$$= \frac{\partial^2 v_r}{\partial z^2} + \frac{\partial^2 v_r}{\partial r^2} + \frac{1}{r} \frac{\partial v_r}{\partial r} + \frac{1}{r^2} \frac{\partial^2 v_r}{\partial \theta^2}$$