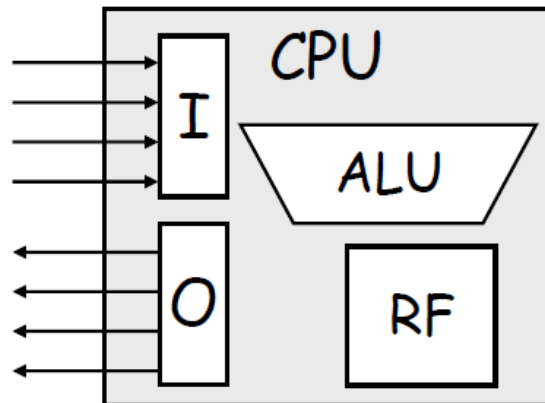


ساختار و زبان کامپیوتر

فصل نه

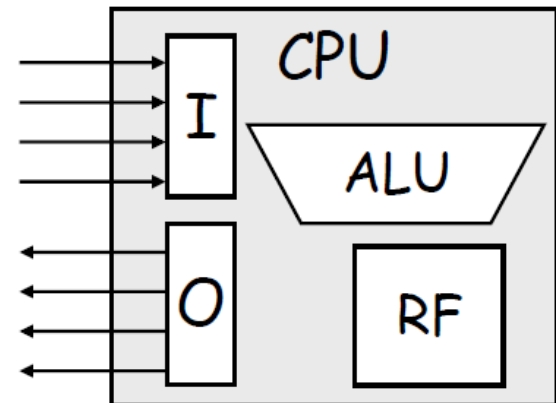
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Computer Structure & Machine Language

Chapter Nine

8086 Assembly Language



Copyright Notice

Parts (text & figures of this lecture are adopted from:

- ④ “The 80x86 IBM PC and Compatible Computers, Vol.I & II”, 4th Ed., M. Mazidi & J. Mazidi, Pearson, 2003
- ④ M. Rafiquzzaman, “Microprocessors and Microcomputer-Based System Design”, 2nd Ed., CRC Press, 1995
- ④ A. Tanenbaum, “Structured Computer Organization”, 6th Ed., Pearson, 2013



Contents

- Introduction
- Fundamentals
- Memory Structure
- More on Instructions
- Addressing Modes
- Instruction Formats
- Conclusion
- Sample Codes
- Extra Topics

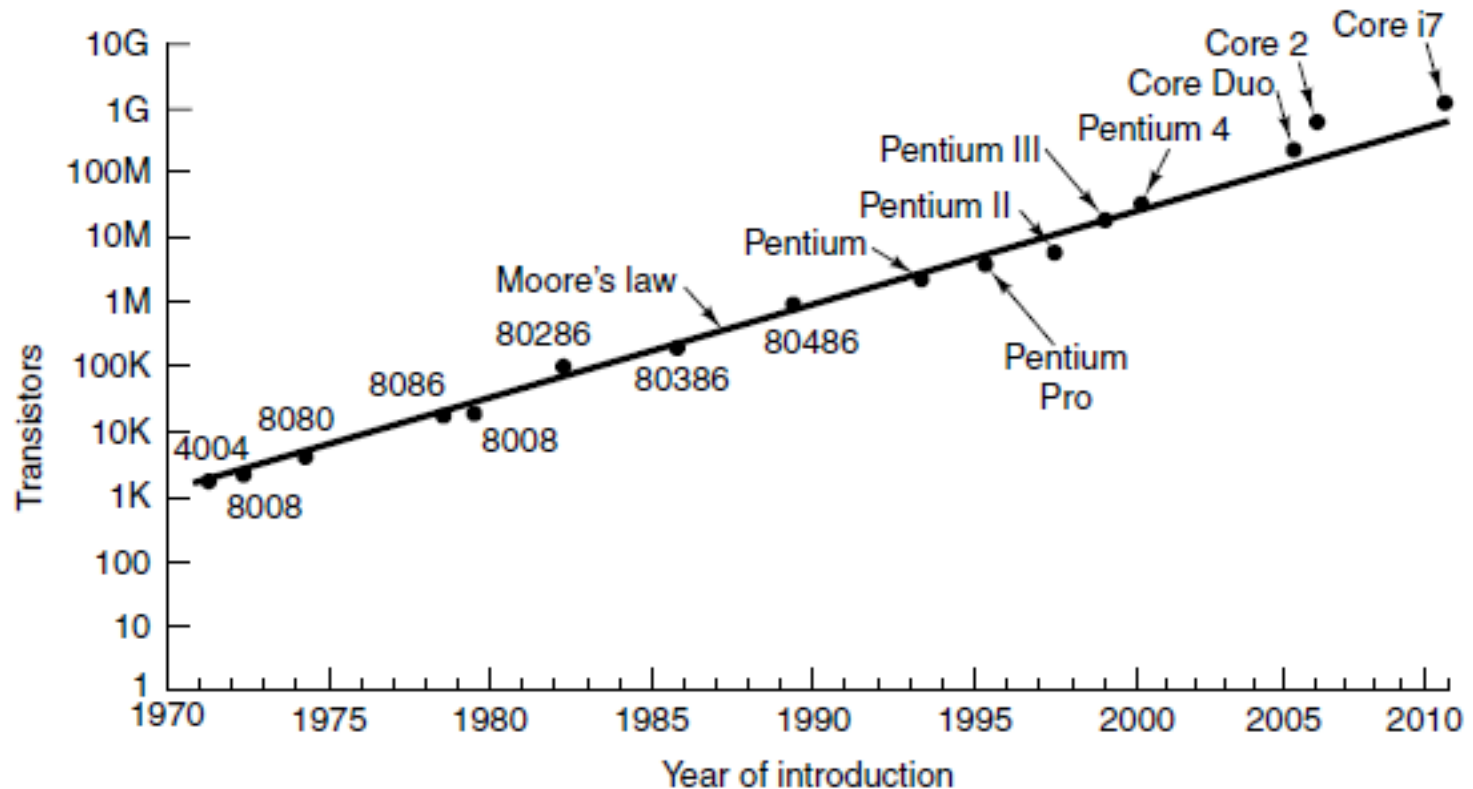


The Intel Family History

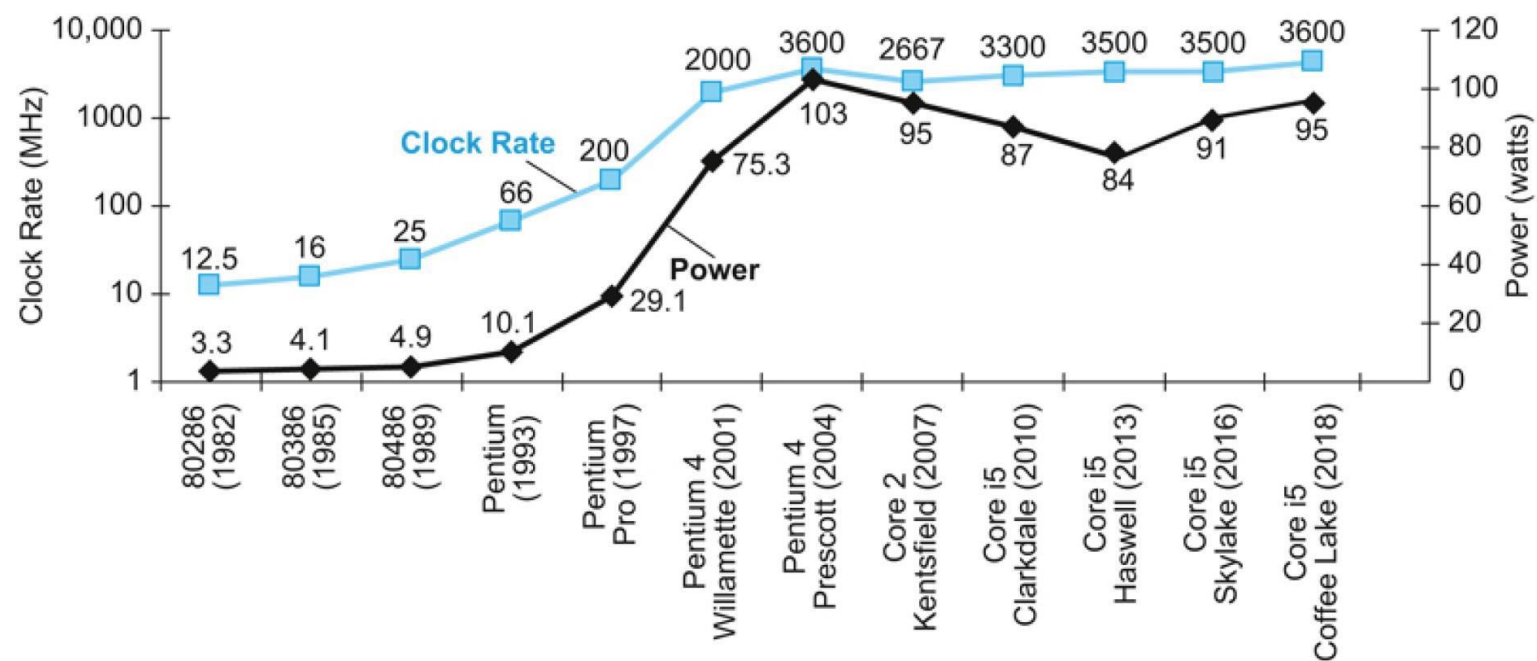
Chip	Date	MHz	Trans.	Memory	Notes
4004	4/1971	0.108	2300	640	First microprocessor on a chip
8008	4/1972	0.108	3500	16 KB	First 8-bit microprocessor
8080	4/1974	2	6000	64 KB	First general-purpose CPU on a chip
8086	6/1978	5–10	29,000	1 MB	First 16-bit CPU on a chip
8088	6/1979	5–8	29,000	1 MB	Used in IBM PC
80286	2/1982	8–12	134,000	16 MB	Memory protection present
80386	10/1985	16–33	275,000	4 GB	First 32-bit CPU
80486	4/1989	25–100	1.2M	4 GB	Built-in 8-KB cache memory
Pentium	3/1993	60–233	3.1M	4 GB	Two pipelines; later models had MMX
Pentium Pro	3/1995	150–200	5.5M	4 GB	Two levels of cache built in
Pentium II	5/1997	233–450	7.5M	4 GB	Pentium Pro plus MMX instructions
Pentium III	2/1999	650–1400	9.5M	4 GB	SSE Instructions for 3D graphics
Pentium 4	11/2000	1300–3800	42M	4 GB	Hyperthreading; more SSE instructions
Core Duo	1/2006	1600–3200	152M	2 GB	Dual cores on a single die
Core	7/2006	1200–3200	410M	64 GB	64-bit quad core architecture
Core i7	1/2011	1100–3300	1160M	24 GB	Integrated graphics processor



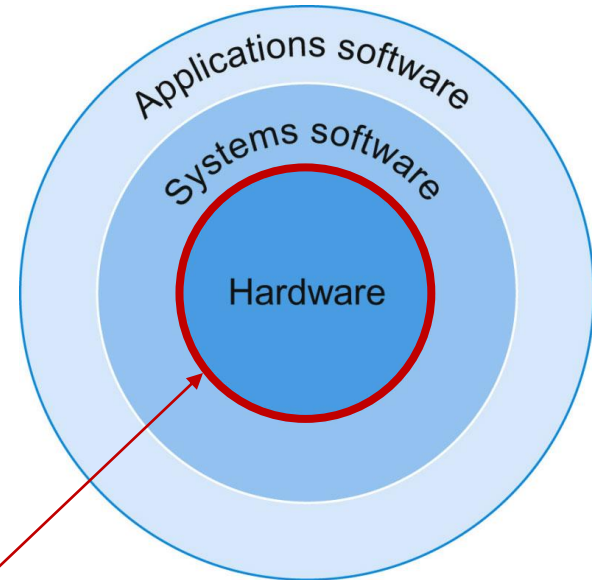
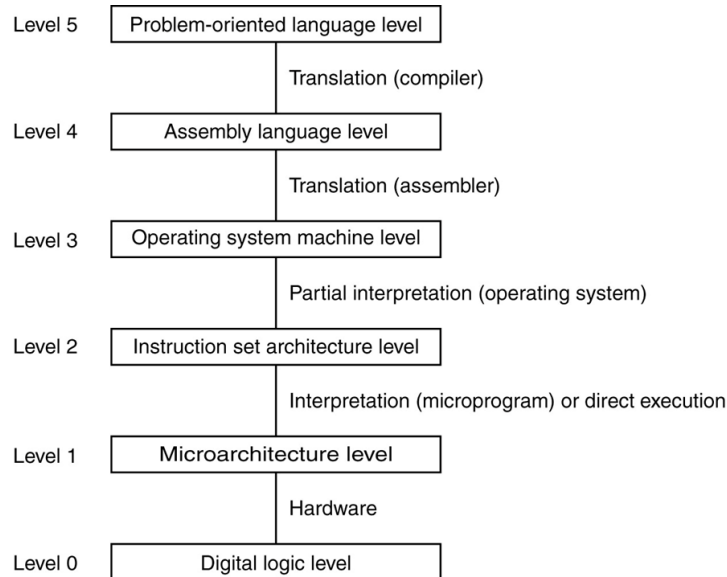
Moore's Law for Intel CPU Chips



Clock Rate & Power for Intel CPU Chips



Hierarchical Levels (Reminder)



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Tanenbaum, Structured Computer Organization, 5th Edition

Instruction Set Architecture (ISA)



Instruction Set Architecture (ISA)

- How the machine appears to a machine language programmer
- What a compiler outputs
 - ignoring operating-system calls & symbolic assembly language
- Specifies:
 - Memory Model
 - Registers
 - Available data types
 - Available **instructions**



Fundamentals

- Registers
- Basic Instructions
- An Assembly Program
- Directives
- Examples
- Instruction Formats
- Interrupt 21H



8086/88 Registers

General registers

AX	AH	AL
BX	BH	BL
CX	CH	CL
DX	DH	DL
	15 8 7	0

Segment registers

CS	Code segment
DS	Data segment
SS	Stack segment
ES	Extra segment
	15 0

Pointer and index

SP	Stack pointer
BP	Base pointer
SI	Source index
DI	Destination index
	15 0

Condition codes

SF	15	OD	I	T	S	Z	A	P	C	0	CC
		Status flags									

Instruction pointer

IP	15	Program counter	0	PC
----	----	-----------------	---	----



IA-32 Registers

Name	31	0	Use
EAX			GPR 0
ECX			GPR 1
EDX			GPR 2
EBX			GPR 3
ESP			GPR 4
EBP			GPR 5
ESI			GPR 6
EDI			GPR 7
	CS		Code segment pointer
	SS		Stack segment pointer (top of stack)
	DS		Data segment pointer 0
	ES		Data segment pointer 1
	FS		Data segment pointer 2
	GS		Data segment pointer 3
EIP			Instruction pointer (PC)
EFLAGS			Condition codes



The MOV Instruction

○ MOV dest, source

- reg, reg
- mem, reg
- reg, mem
- mem, imm
- reg, imm

GENERAL REGISTERS	AH	AL
	BH	BL
	CH	CL
	DH	DL
	SP	
	BP	
	SI	
	DI	

○ Sizes of both operands must be the same



Basic Arithmetic Instructions

- `ADD dest, source`
- `SUB dest, source`
- `INC dest`
- `DEC dest`
- `NEG dest`



An Assembly Program Shell

```
1  ; Program description
2
3  StSeg    Segment
4          DB 100H DUP (?)
5  StSeg    ENDS
6
7  DtSeg    Segment
8          ; place data here
9  DtSeg    ENDS
10
11 CDSeg    Segment
12          ASSUME CS:CDSeg, DS:DtSeg, SS:StSeg
13 start:
14          MOV AX, DtSeg      ; set DS to point to the data segment
15          MOV DS, AX
16
17          ; type your code here
18
19          MOV AH, 4CH        ; DOS: terminate program
20          MOV AL, 0          ; return code will be 0
21          INT 21H           ; terminate the program
22 CDSeg    ENDS
23 END start
```



Defining A Segment

```
label    SEGMENT    [options]
           ;place the statements belonging to this segment here
label    ENDS
```

Example

```
STSEG    SEGMENT    ;the "SEGMENT" directive begins the segment
           DB 64 DUP (?) ;this segment contains only one line
STSEG    ENDS        ;the "ENDS" segment ends the segment

DTSEG    SEGMENT
DATA1    DB 52H
DATA2    DB 29H
SUM      DB ?
DTSEG    ENDS
```



A Sample Line

label opcode operand(s) comment

↓ ↓ ↓ ↓

`L1: MOV AX,10 ; move 10 to AX`

label directive value comment

↓ ↓ ↓ ↓

`Data1 DB 52H ; define a byte`



8086 Directives

- ASSUME
- ORG
- DB (Define Byte)
- DUP (Duplicate)
- DW (Define Word)
- DD (Define Double Words)
- DQ (Define Four Words)
- DT (Define Ten Bytes)
- EQU
- EVEN

	ORG	100
aByte	DB	12
aStr	DB	"Salam"
aVec	DB	1, 2, 3
	EVEN	
aSpace	DB	6 DUP (?)
aWord	DW	1A2FH
Cnst	EQU	01011110B
aDD	DD	100000
aDQ	DQ	?
BCDno	DT	14567
DECno	DT	14567D



Add two Numbers

```

StSeg    Segment STACK 'STACK'
         DB 100H DUP (?)
StSeg    ENDS

DtSeg    Segment
num1     DB 100
num2     DB 27
sum      DB ?
DtSeg    ENDS

CDSeg    Segment
ASSUME CS:CDSeg, DS:DtSeg, SS:StSeg

Start:
    MOV AX, DtSeg      ; set DS to point to the data segment
    MOV DS, AX

    MOV AL, num1
    ADD AL, num2
    MOV sum, AL

    MOV AH, 4CH        ; DOS: terminate program
    MOV AL, 0          ; return code will be 0
    INT 21H           ; terminate the program
CDSeg    ENDS
END Start

```



Add Five Consecutive Numbers

```
.MODEL SMALL
.STACK 100H

.DATA
dataIN DB 1,2,3,1,1
        EVEN
sum     DB ?

.CODE
start:
    MOV AX,@DATA    ; set DS to point to the data segment
    MOV DS,AX

    MOV CX,5         ; setup loop counter
    MOV BX, OFFSET dataIN ; setup data pointer
    MOV AL,0         ; initilaize AL
AGAIN:  ADD AL,[BX]
        INC BX       ; make BX point to next data item
        DEC CX       ; decrement loop counter
        JNZ AGAIN
        MOV sum,AL   ; load result into sum

    MOV AH,4CH      ;DOS: terminate program
    MOV AL,0        ;return code will be 0
    INT 21H         ;terminate the program

END start
```



Add Four Consecutive Numbers

```

.MODEL SMALL

.STACK 100H

.DATA
dataIN DW 15, 185, 125, 25
sum     DW ?

.CODE
start:
    MOV AX, @DATA    ; set DS to point to the data segment
    MOV DS, AX

    MOV CX, 4         ; setup loop counter
    MOV BX, OFFSET dataIN ; setup data pointer
    MOV AX, 0         ; initilaize AL
L1:    ADD AX, [BX]
    INC BX           ; make BX point to next data item
    INC BX
    DEC CX           ; decrement loop counter
    JNZ L1
    MOV sum, AX      ; load result into sum

    MOV AH, 4CH      ;DOS: terminate program
    MOV AL, 0        ;return code will be 0
    INT 21H          ;terminate the program

END start

```



Copy An Array to A New Location

```
.MODEL SMALL
.STACK 100H

.DATA
    ORG 200H
dataIn DB 'Q','W','E','R','T','Y'
copy   DB 6 DUP (?)
       DB '$'

.CODE
start:
    MOV AX,@DATA    ;set DS to point to the data segment
    MOV DS,AX

    MOV SI,OFFSET dataIn
    MOV DI,OFFSET copy
    MOV CX,6
movL:  MOV AL,[SI]
       MOV [DI],AL
       INC SI
       INC DI
       LOOP movL

    MOV AH,4CH      ;DOS: terminate program
    MOV AL,0        ;return code will be 0
    INT 21H         ;terminate the program
END start
```



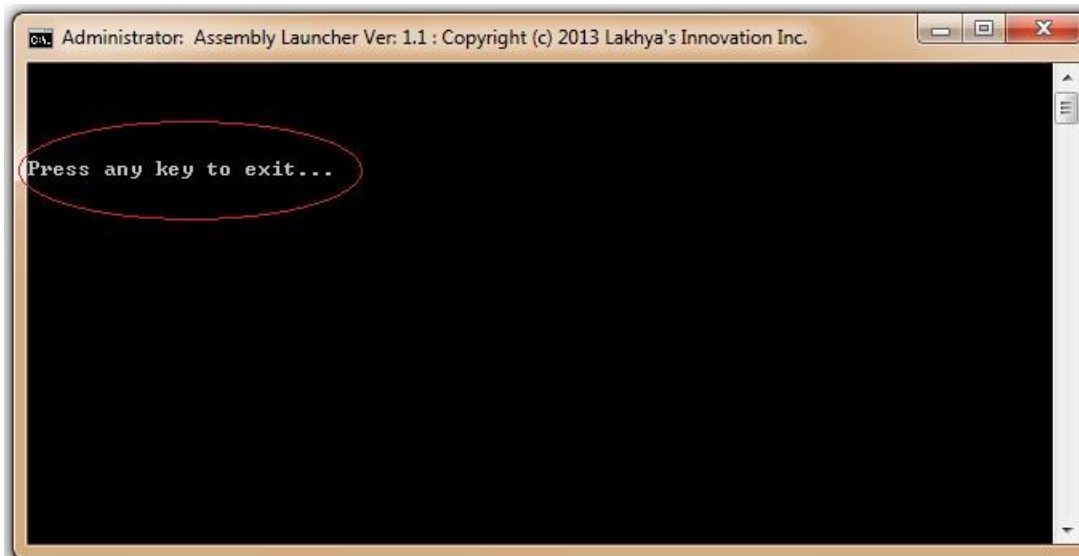
DOS Interrupt 21H

AH	Operation	Input Register(s)	Output
4C	Program Terminate	AL=return code	None
01	Character Input (with echo)	None	AL=char
07	Character Input (no echo)	None	AL=char
0A	Buffered Keyboard Input	DX=string offset	None
02	Character Output	DL=char	None
09	Display String	DX=string offset	None



Program Termination

```
MOV AH, 4CH    ; DOS: terminate program
MOV AL, 0      ; return code will be 0
INT 21H        ; terminate the program
```



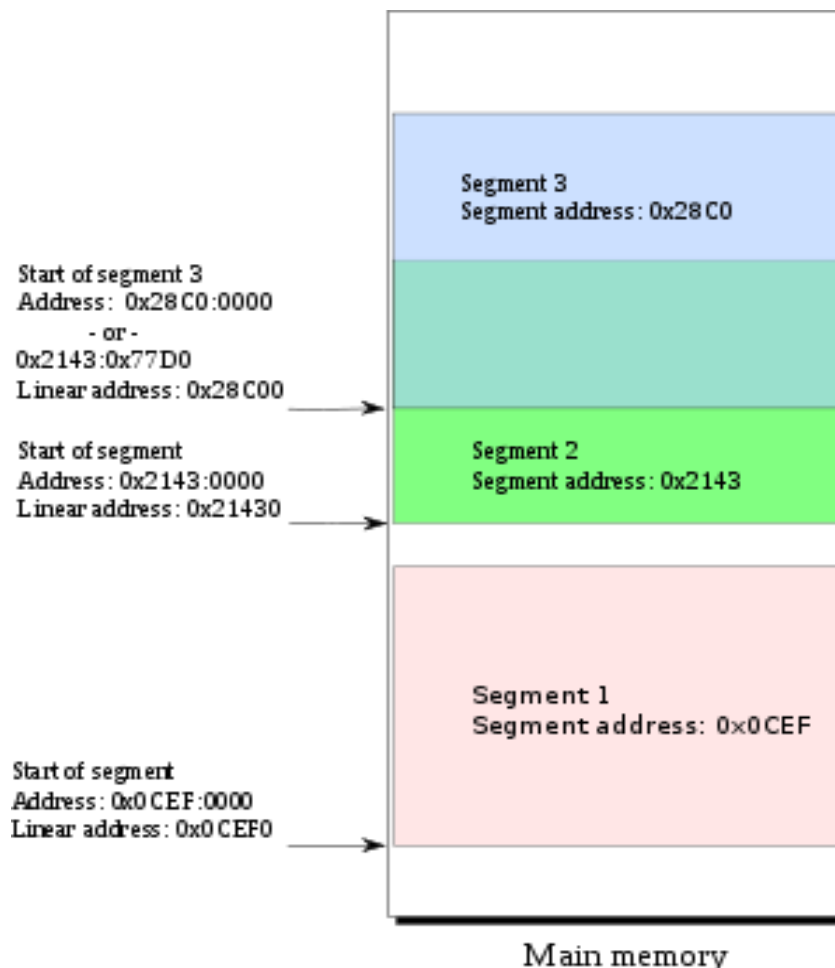

```

1  .MODEL  SMALL
2  .STACK  100H
3  .DATA
4  TimePrompt      DB  'Is it after 12 noon (Y/N)?$'
5  MorningMsg      DB  13,10, 'Good morning, world!' ,13,10, '$'
6  AfternoonMsg    DB  13,10, 'Good afternoon, world!' ,13,10, '$'
7  DefaultMsg      DB  13,10, 'Good day, world!' ,10,13, '$'
8  .CODE
9  start:          MOV  AX,@data      ;set DS to point to the data segment
10                 MOV  DS,AX
11                 LEA  DX,TimePrompt ;point to the time prompt
12                 MOV  AH,9          ;DOS: print string
13                 INT  21H           ;display the time prompt
14                 MOV  AH,1          ;DOS: get character
15                 INT  21H           ;get a single-character response
16                 OR   AL, 20H        ;force character to lower case
17                 CMP  AL,'y'        ;typed Y for afternoon?
18                 JE   IsAfternoon
19                 CMP  AL,'n'        ;typed N for morning?
20                 JE   IsMorning
21                 LEA  DX,DefaultMsg ;default greeting
22                 JMP  DisplayG
23  IsAfternoon:    LEA  DX,AfternoonMsg ;afternoon greeting
24                 JMP  DisplayG
25  IsMorning:      LEA  DX,MorningMsg ;before noon greeting
26  DisplayG:      MOV  AH,9          ;DOS: print string
27                 INT  21H           ;display the appropriate greeting
28                 MOV  AH,4cH        ;DOS: terminate program
29                 MOV  AL,0          ;return code will be 0
30                 INT  21H           ;terminate the program
31  END  start
32

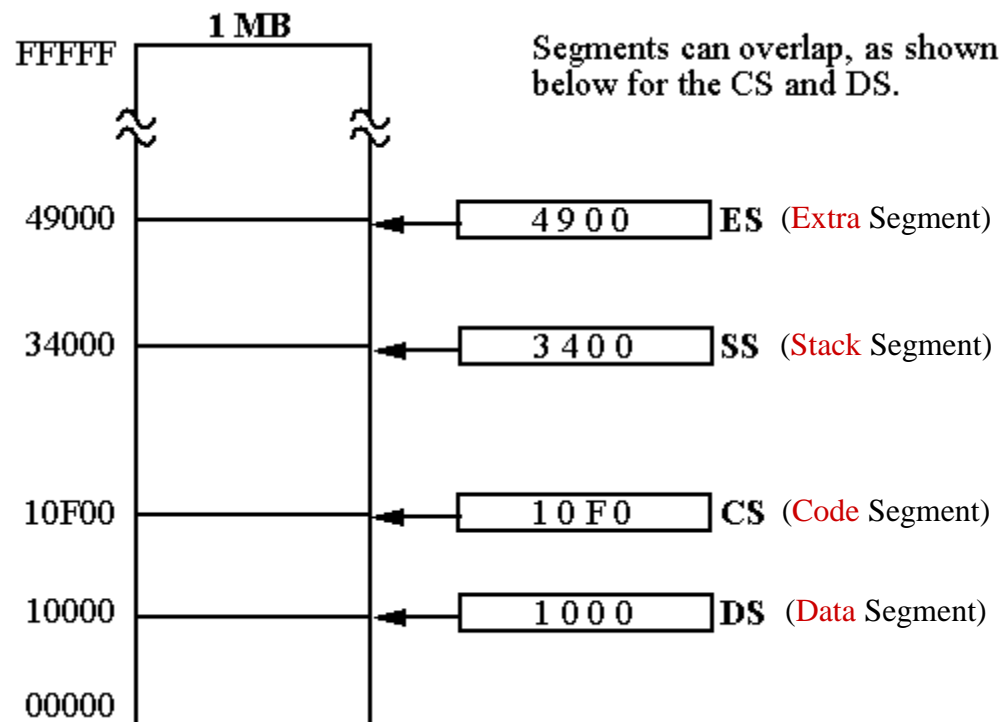
```



Memory Structure

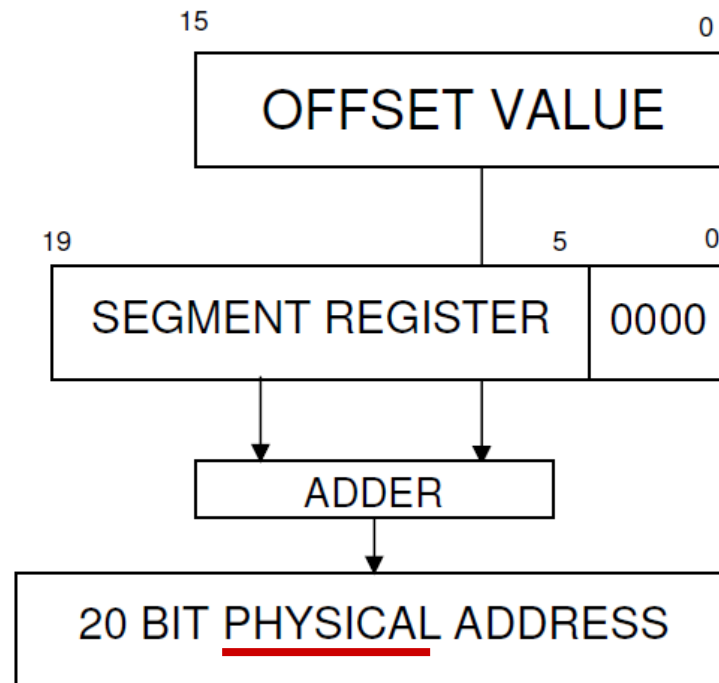


Segment Registers

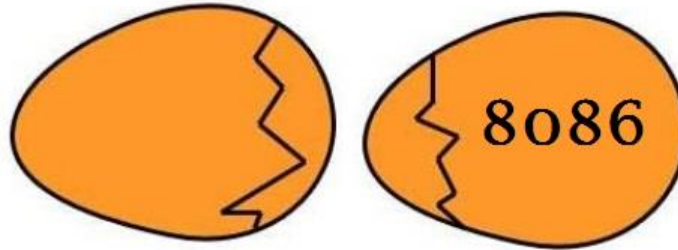


Logical vs. Physical Address

“Segment:Offset” is the **Logical** Address



Endianness (x86 vs. MIPS)



BIG ENDIAN - The way people always broke their eggs in the Lilliput land

LITTLE ENDIAN - The way the king then ordered the people to break their eggs



Endianness in 8086

```
MOV    AX,35F3H    ;load 35F3H into AX
MOV    [1500],AX    ;copy the contents of AX to offset 1500H
```

DS:1500 = F3

DS:1501 = 35



8086 Instructions

- Data movement instructions
 - move
 - push and pop
 - input/output operations
- Arithmetic, logic and shift instructions
- Decisions Making Instructions
 - conditional branches, unconditional jumps
 - calls & returns



Register/Memory Data Movement

Instruction	Operation	Comments
<code>MOV dst,src</code>	$dst \leftarrow src$	
<code>XCHG src,dst</code>	$dst \leftrightarrow src$	
<code>LAHF</code>	$AH \leftarrow flags1$	
<code>SAHF</code>	$flags1 \leftarrow AH$	
<code>IN AL/AH/AX,port#</code> <code>IN AL/AH/AX,DX</code>	$AL/AH/AX \leftarrow port\#$ $AL/AH/AX \leftarrow DX\ port$	for port# < 256 for port# > 255
<code>OUT port#,AL/AH/AX</code> <code>OUT DX,AL/AH/AX</code>	$port\# \leftarrow AL/AH/AX$ $DX\ port \leftarrow AL/AH/AX$	for port# < 256 for port# > 255
<code>LEA dst,src</code>	$dst \leftarrow EA(src)$	Load Effective Address
<code>LDS reg,ptr</code>	$reg(L) \leftarrow [ptr]$ $reg(H) \leftarrow [ptr+1]$ $DS(L) \leftarrow [ptr+2]$ $DS(H) \leftarrow [ptr+3]$	Load pointer using DS
<code>LES reg,ptr</code>	$reg(L) \leftarrow [ptr]$ $reg(H) \leftarrow [ptr+1]$ $ES(L) \leftarrow [ptr+2]$ $ES(H) \leftarrow [ptr+3]$	Load pointer using ES
<code>XLAT</code>	$AL \leftarrow \text{memory byte } DS:[BX + \text{unsigned } AL]$	



Stack Manipulation

Instruction	Operation	Comments
PUSH <i>src</i>	$SP \leftarrow SP-2$ $[SP] \leftarrow \text{src}(0-7)$ $[SP+1] \leftarrow \text{src}(8-15)$	Push <i>src</i> into stack
POP <i>dst</i>	$\text{dst}(0-7) \leftarrow [SP]$ $\text{dst}(8-15) \leftarrow [SP+1]$ $SP \leftarrow SP+2$	Pop <i>dst</i> out of stack
PUSHF	$SP \leftarrow SP-2$ $[SP, SP+1] \leftarrow \text{flags}$	Push Flag Register into stack
POPF	$\text{flags} \leftarrow [SP, SP+1]$ $SP \leftarrow SP+2$	Pop Flag Register out of stack



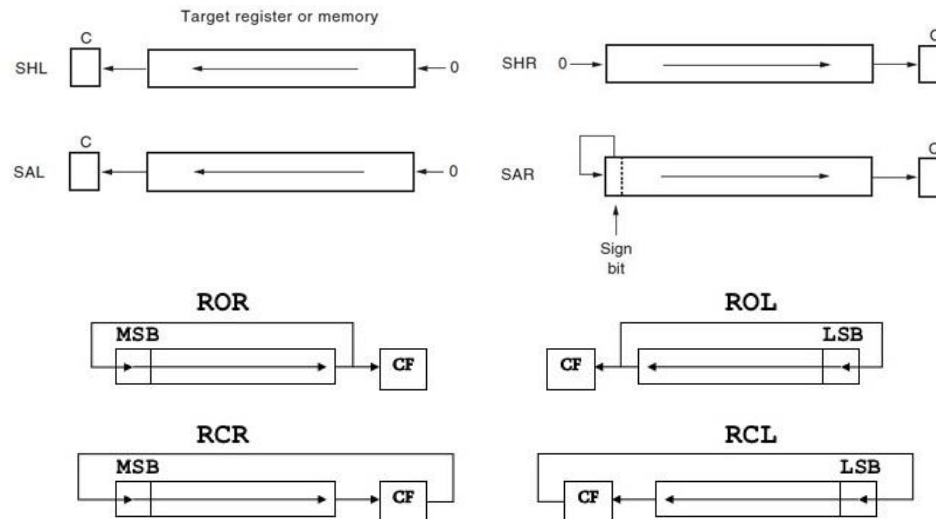
Logical Instructions

Instruction	Operation
NOT <code>dst</code>	$\text{dst} \leftarrow \neg \text{dst}$
AND <code>dst, src</code>	$\text{dst} \leftarrow \text{dst} \wedge \text{src}$
OR <code>dst, src</code>	$\text{dst} \leftarrow \text{dst} \vee \text{src}$
XOR <code>dst, src</code>	$\text{dst} \leftarrow \text{dst} \oplus \text{src}$
TEST <code>dst, src</code>	$\text{dst} \wedge \text{src}$, update flags



Shift Instructions

Instruction	Operation	Comments
SAL dst, cnt	Shift dst to left cnt times	Arithmetic/Logic Shift Left
SHL dst, cnt		
SAR dst, cnt	Shift dst to right cnt times	Arithmetic Shift Right
SHR dst, cnt		Logic Shift Right
RCL dst, cnt	Rotate dst to left cnt times	Rotate with carry
RCR dst, cnt	Rotate dst to right cnt times	
ROL dst, cnt	Rotate dst to left cnt times	Rotate dst without carry
ROR dst, cnt	Rotate dst to right cnt times	



Arithmetic Instructions

Instruction	Operation	Comments
ADD dst,src	$dst \leftarrow dst + src$	Add
ADC dst,src	$dst \leftarrow dst + src + CF$	Add with carry
SUB dst,src	$dst \leftarrow dst - src$	Subtract
SBB dst,src	$dst \leftarrow dst - src - CF$	Subtract with carry
INC dst	$dst \leftarrow dst + 1$	Increment
DEC dst	$dst \leftarrow dst - 1$	Decrement
NEG dst	$dst \leftarrow 0 - dst$	Negate
CMP dst,src	$dst - src$, update flags	Compare
MUL src	$AX \leftarrow AL * src$ $DX:AX \leftarrow AX * src$	8 bit src 16 bit src
IMUL src	$AX \leftarrow AL * src$ $DX:AX \leftarrow AX * src$	8 bit signed src 16 bit signed src
DIV src	$AL \leftarrow AX / src$, $AH \leftarrow AX \% src$ $AX \leftarrow DX:AX / src$, $DX \leftarrow DX:AX \% src$	8 bit src 16 bit src
IDIV src	$AX \leftarrow AX / src$, $AH \leftarrow AX \% src$ $AX \leftarrow DX:AX / src$, $DX \leftarrow DX:AX \% src$	8 bit signed src 16 bit signed src



Arithmetic Adjust Instructions

Instruction	Comments
DAA	Decimal Adjust for Add
DAS	Decimal Adjust for Subtract
AAA	ASCII Adjust for Add
AAS	ASCII Adjust for Subtract
AAM	ASCII Adjust for Multiply
AAD	ASCII Adjust for Division
CBW	Convert Byte to Word
CWD	Convert Word to Double Word



Unsigned Multiplication/Division

MUL src	AX \leftarrow AL*src DX:AX \leftarrow AX*src	8 bit src 16 bit src
DIV src	AL \leftarrow AX/src, AH \leftarrow AX%src AX \leftarrow DX:AX/src, DX \leftarrow DX:AX%src	8 bit src 16 bit src

Multiplication	Operand 1	Operand 2	Result
Byte \times Byte	AL	Register or Memory	AX
Word \times Word	AX	Register or Memory	DX,AX
Word \times Byte	AL=Byte, AH=0	Register or Memory	DX,AX

Division	Numerator	Denominator	Quotient	Rem
Byte / Byte	AL=byte, AH=0	Register or Memory	AL	AH
Word / Word	AX=word, DX=0	Register or Memory	AX	DX
Word / Byte	AX=word	Register or Memory	AL	AH
DWord / Word	DX,AX=DWord	Register or Memory	AX	DX



Print a 3-digit Number

```
06 .Data
07 num      DB 123          ; =7BH
08 numSTR    DB "000$"
09
10 .CODE
11 Start:
12     MOV AX,@DATA          ; set DS to point to the data segment
13     MOV DS,AX
14
15     MOV AH,0
16     MOV AL,num
17     LEA SI,numSTR
18     ADD SI,2
19     MOV CL,10
20     MOV CH,3
21 L2:   DIV CL
22     ADD [SI],AH
23     DEC SI
24     MOV AH,0
25     DEC CH
26     JNZ L2
27
28     LEA DX,numSTR
29     MOV AH,9
30     INT 21H
31
32     MOV AH,4CH             ; DOS: terminate program
33     MOV AL,0               ; return code will be 0
34     INT 21H               ; terminate the program
35 END Start
```



Signed Multiplication/Division

IMUL for signed multiplication

IDIV for signed division

CBW (Convert Byte to Word)

CWD (Convert Word to Double word)

Multiplication	Operand 1	Operand 2	Result
Byte \times Byte	AL	Register or Memory	AX
Word \times Word	AX	Register or Memory	DX,AX
Word \times Byte	AL=Byte, CBW	Register or Memory	DX,AX

Division	Numerator	Denominator	Quotient	Rem
Byte / Byte	AL=byte, CBW	Register or Memory	AL	AH
Word / Word	AX=word, CWD	Register or Memory	AX	DX
Word / Byte	AX=word	Register or Memory	AL	AH
DWord / Word	DX,AX=DWord	Register or Memory	AX	DX



Finding the Average

```

.MODEL SMALL
.STACK 100H
.DATA
dataIN DB -1,1,2,-2,0
        EVEN
sum      DW ?
avg      DW ?
.CODE
start:
        MOV AX,@DATA      ; set DS to point to the data segment
        MOV DS,AX
        MOV CX,5           ; setup loop counter
        MOV SI, OFFSET dataIN ; setup data pointer
        SUB BX,BX          ; initilaize BX
AGAIN:  ★ MOV AL,[SI]       ; move byte to AL
        ★ CBW             ; extend sign
        ADD BX,AX
        INC SI             ; make SI point to next data item
        DEC CX             ; decrement loop counter
        JNZ AGAIN
        MOV sum,BX         ; load result into sum
        ★ MOV AX,sum      ; load sum in AX
        ★ CWD             ; extend sign
        MOV CX,5
        IDIV CX            ; divide DX:AX to CX
        MOV avg,AX         ; move quotient to avg
        MOV AH,4CH         ;DOS: terminate program
        MOV AL,0           ;return code will be 0
        INT 21H           ;terminate the program
END start

```



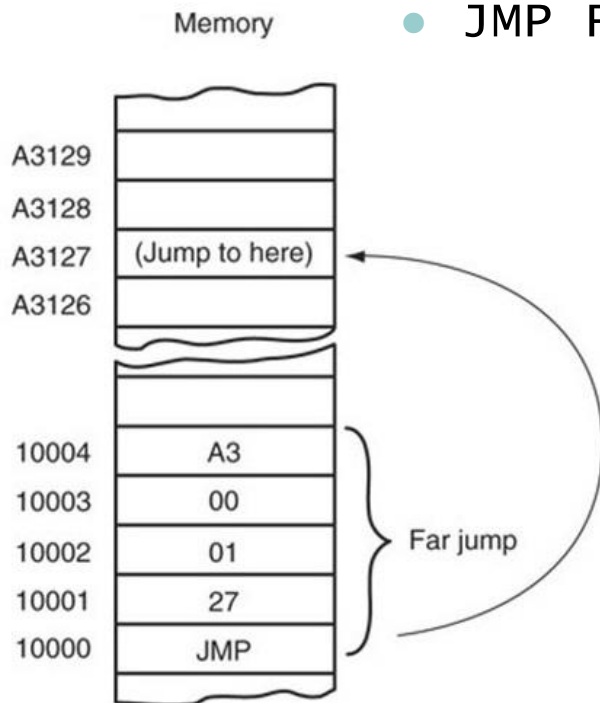
Decisions Making Instructions

- Unconditional Jump
- Conditional Jump
- Loop Control
- Subroutine Call/Return
- Software Interrupts



Unconditional Jump (JMP)

- Jump **inside** the segment (**near jump**)
 - `JMP label ; label in the same segment`
- Jump **outside** the segment (**far jump**)
 - `JMP FAR PTR label ; label=A300:0127`



Conditional Jumps

★
★

Mnemonic	Condition Tested	“Jump IF ...”
JA/JNBE	$(CF = 0) \text{ and } (ZF = 0)$	above/not below nor zero
JAЕ/JNB	$CF = 0$	above or equal/not below
JB/JNAE	$CF = 1$	below/not above nor equal
JBE/JNA	$(CF \text{ or } ZF) = 1$	below or equal/not above
JC	$CF = 1$	carry
JE/JZ	$ZF = 1$	equal/zero
JG/JNLE	$((SF \text{ xor } OF) \text{ or } ZF) = 0$	greater/not less nor equal
JGE/JNL	$(SF \text{ xor } OF) = 0$	greater or equal/not less
JL/JNGE	$(SF \text{ xor } OF) = 1$	less/not greater nor equal
JLE/JNG	$((SF \text{ xor } OF) \text{ or } ZF) = 1$	less or equal/not greater
JNC	$CF = 0$	not carry
JNE/JNZ	$ZF = 0$	not equal/not zero
JNO	$OF = 0$	not overflow
JNP/JPO	$PF = 0$	not parity/parity odd
JNS	$SF = 0$	not sign
JO	$OF = 1$	overflow
JP/JPE	$PF = 1$	parity/parity equal
JS	$SF = 1$	sign

unsigned
signed



Short Jump

- All conditional jumps are **short**
- Conditional jump is a 2-bytes instruction:
 - jump operation code
 - relative address of jump target
- Target should be within **[-128..127]** bytes distance from IP



Loop Control Instructions

LOOP **label** ; loop as long as CX!=0

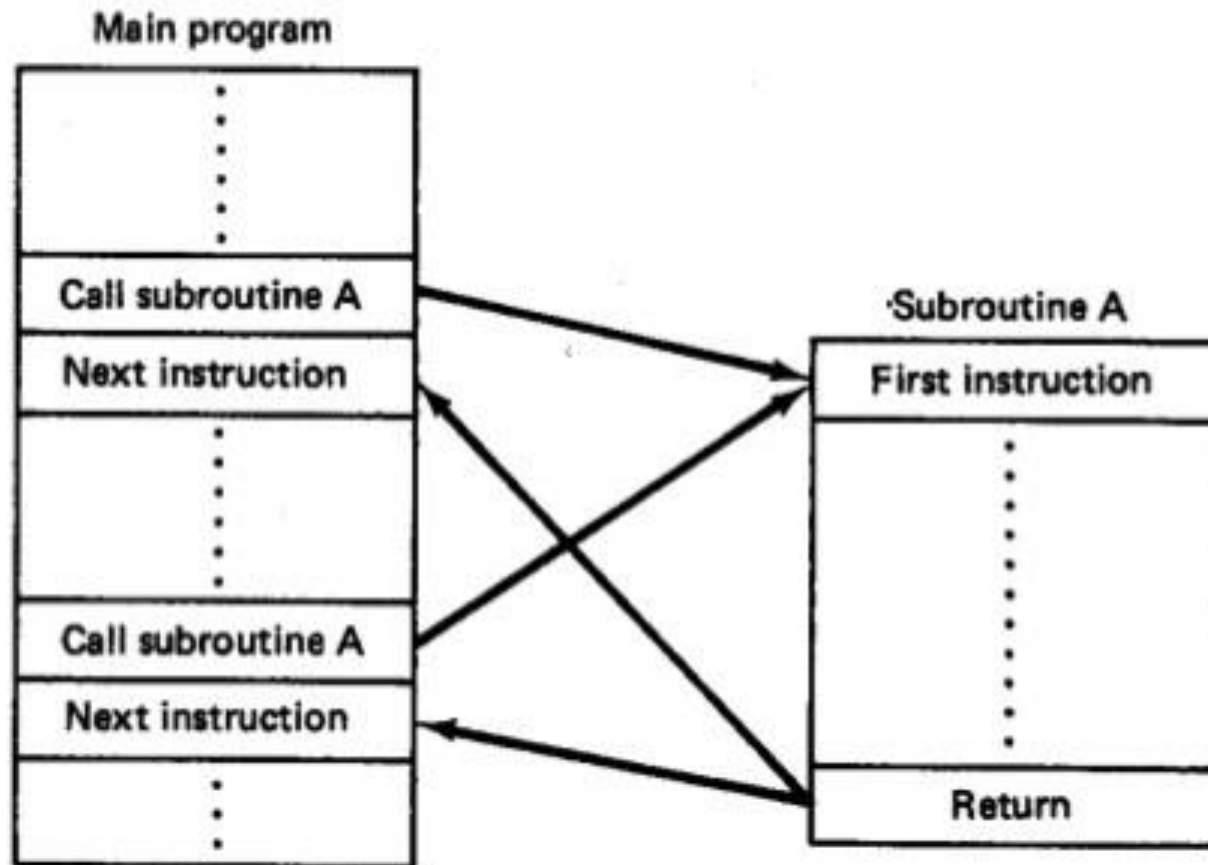
LOOPE/LOOPZ **label** ; loop as long as ZF=1 and CX!=0

LOOPNE/LOOPNZ **label** ; loop as long as ZF=0 and CX!=0

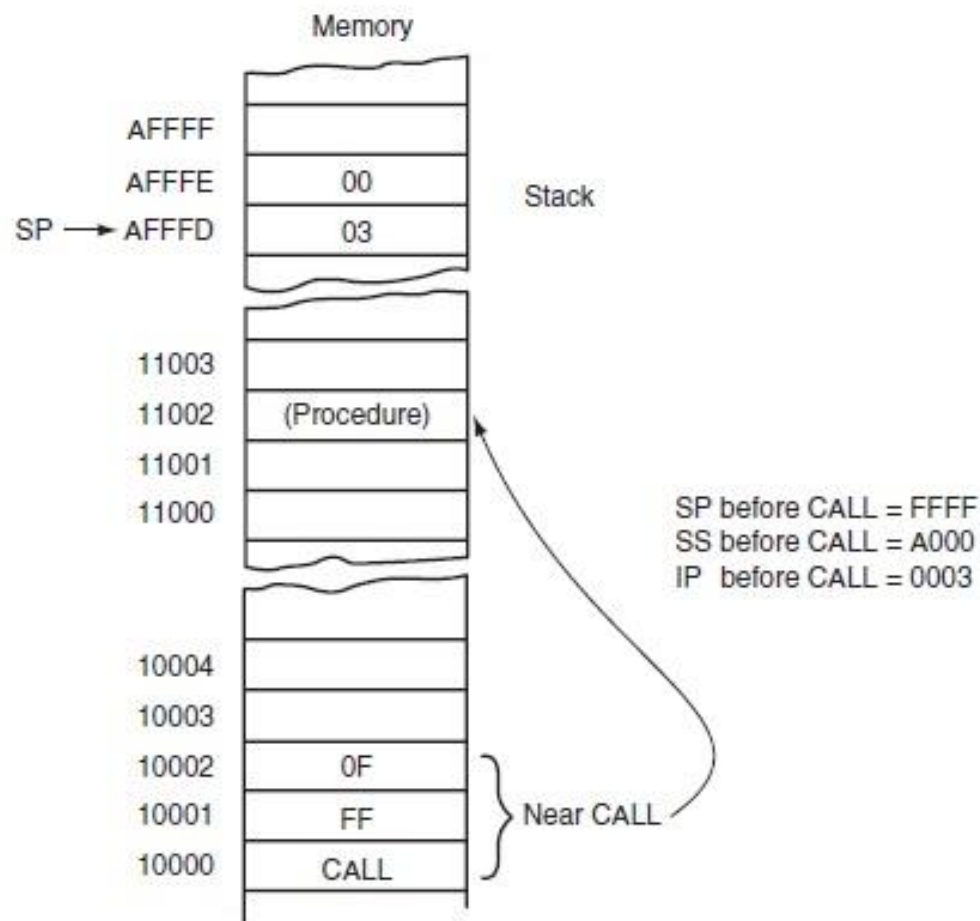
Register CX is **decremented** each time before
jump to label is executed



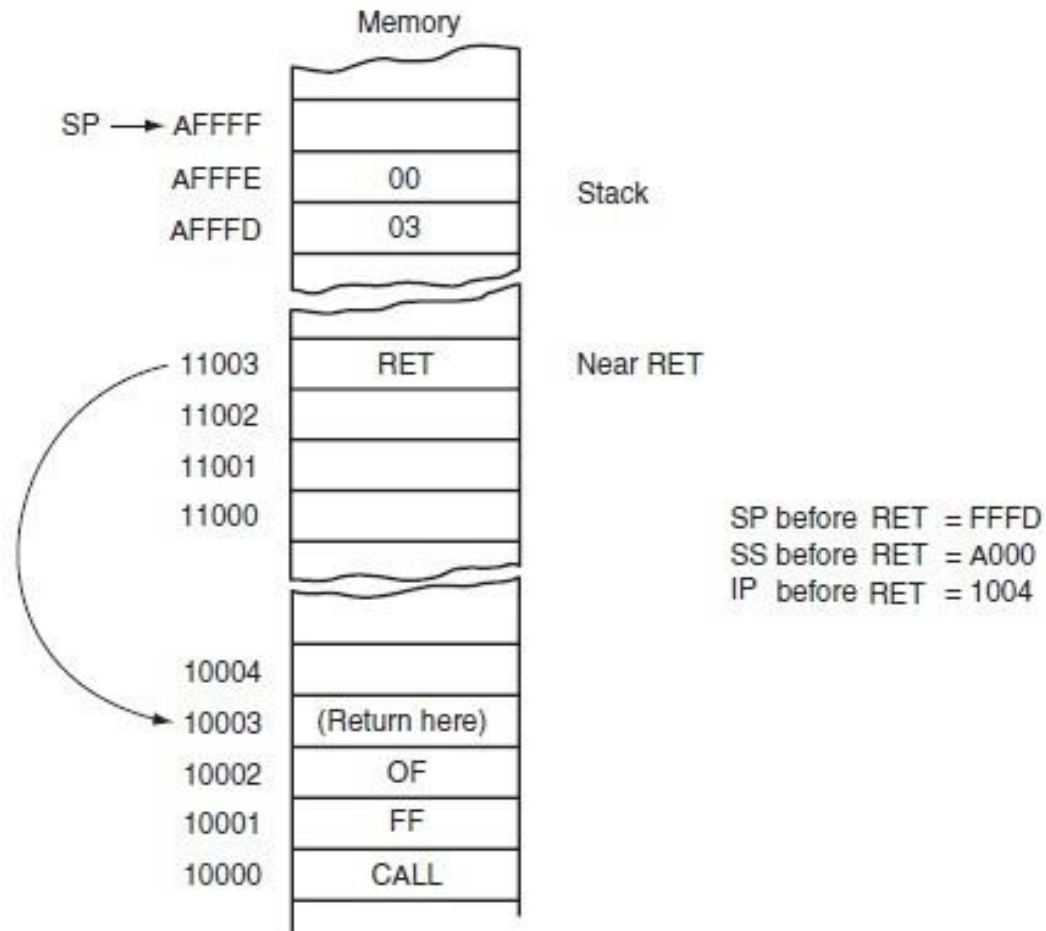
Call & Return from Subroutine



Call Inside the Segment (Near Call)



Return Inside the Segment (Near)



Near Procedure (Example)

```
.MODEL SMALL
.STACK 100H

.DATA
    ; place your data here

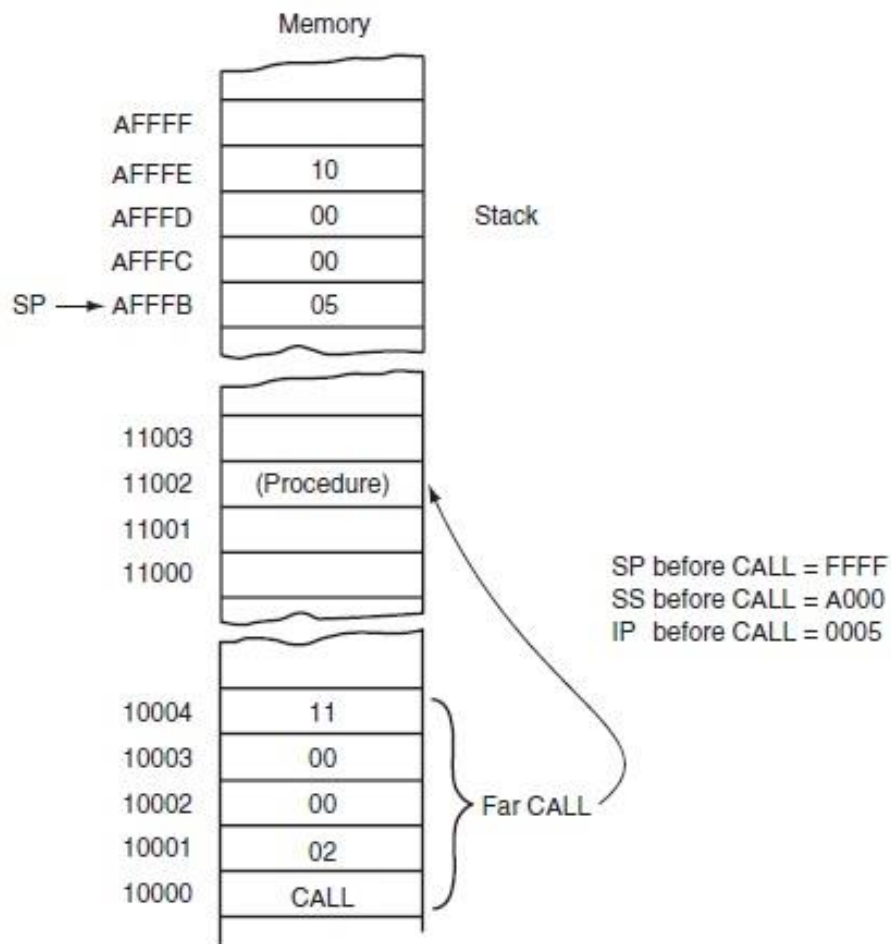
.CODE
Start:
    ; ...
    CALL SBN    ; call SBN
    ; ...

    ;-----
    ; subroutine SBN
SBN    PROC NEAR
    ; ...
    RET        ; return from subroutine
SBN    ENDP

END    Start
```



Call Outside the Segment (Far Call)



Far Procedure (Example)

```

.MODEL SMALL
.STACK 100H

.DATA
    ; place your data here

CDSeg1 Segment          ; 1st Code Segment Start
ASSUME CS:CDSeg1
Start:
    ; ...
    CALL FAR PTR SBF    ; call SBF
    ; ...

CDSeg1 ENDS              ; 1st Code Segment End

CDSeg2 Segment          ; 2nd Code Segment Start
ASSUME CS:CDSeg2

    ; subroutine SBF
SBF PROC FAR
    ; ...
    RET                  ; return from subroutine
SBF ENDP

CDSeg2 ENDS              ; 2nd Code Segment End

END Start

```



Parameter Passing

- via Registers
 - Put parameter values in registers
- via Memory
 - Use the same variable names in the subroutine
- via Stack
 - Put parameter values in stack



via Register (Example)

```

1  ; Add A & B and put the result in C
2  ; Pass parameters in registers
3  STSEG    SEGMENT STACK 'stack'
4      DB   100H dup (?)
5  STSEG    ENDS
6  DTSEG    SEGMENT
7      A      DW 2      ; 1st operand
8      B      DW 4      ; 2nd operand
9      C      DW ?      ; C=A+B
10 DTSEG    ENDS
11 CDSEG    SEGMENT
12 Start:
13          ASSUME DS:DTSEG, CS:CDSEG, SS:STSEG
14          MOV AX, DTSEG      ; set DS to point to the data segment
15          MOV DS, AX
16          MOV AX, A
17          MOV BX, B
18          MOV CX, 0
19          CALL SB1          ; call subroutine SB1
20          MOV C, CX
21
22 SB1      PROC NEAR
23          PUSHF
24          MOV CX, AX      ; CX <- A
25          ADD CX, BX      ; CX <- A+B
26          POPF
27          RET
28 SB1      ENDP
29 CDSEG    ENDS
30 END      start

```



via Memory (Example)

```

1  ; Add A & B and put the result in C
2  ; Pass parameters in Memory
3  STSEG    SEGMENT STACK 'stack'
4          DB  100H dup (?)
5  STSEG    ENDS
6  DTSEG    SEGMENT
7          A      DW  2      ; 1st operand
8          B      DW  4      ; 2nd operand
9          C      DW  0      ; C=A+B
10 DTSEG    ENDS
11 CDSEG    SEGMENT
12 Start:
13          ASSUME DS:DTSEG,CS:CDSEG,SS:STSEG
14          MOV AX,DTSEG      ; set DS to point to the data segment
15          MOV DS,AX
16          CALL SB2          ; call subroutine SB2
17
18 SB2      PROC NEAR
19          PUSHF
20          PUSH AX
21          MOV AX,A          ; AX <- A
22          ADD AX,B          ; AX <- A+B
23          MOV C,AX          ; C <- AX
24          POP AX
25          POPF
26          RET
27 SB2      ENDP
28 CDSEG    ENDS
29 END      Start

```



via Stack-1

```
1  ; Add A & B and put the result in C
2  ; Pass parameters via Stack
3  STSEG    SEGMENT STACK 'stack'
4      DB   100H dup (?)
5  STSEG    ENDS
6  DTSEG    SEGMENT
7      A      DW 2    ; 1st operand
8      B      DW 4    ; 2nd operand
9      C      DW 0    ; C=A+B
10 DTSEG    ENDS
11 CDSEG    SEGMENT
12 Start:
13         ASSUME DS:DTSEG, CS:CDSEG, SS:STSEG
14         MOV AX, DTSEG
15         MOV DS, AX
16         PUSH C
17         PUSH B
18         PUSH A
19         CALL SB3    ; call subroutine SB1
20         POP BX      ; BX <- A
21         POP BX      ; BX <- B
22         POP BX      ; BX <- C    (C is updated by sub3)
23         MOV C, BX
```



via Stack-2

```
25 SB3      PROC NEAR
26          PUSHF
27          PUSH AX
28          PUSH BX
29          PUSH BP
30          MOV BP, SP
31          MOV AX, SS:[BP+10]    ; AX <- A the value of A is in the stack
32          MOV BX, SS:[BP+12]    ; BX <- B the value of B is in the stack
33          ADD AX, BX
34          MOV SS:[BP+14], AX    ; C <- AX+BX update the value of C in the stack
35          POP BP
36          POP BX
37          POP AX
38          POPF
39          RET
40 SB3      ENDP
41 CDSEG  ENDS
42 END      Start
```



CPU Control Instructions

Instruction	Operation	Comments
STC	$CF \leftarrow 1$	Set Carry Flag
CLC	$CF \leftarrow 0$	Clear Carry Flag
CMC	$CF \leftarrow !CF$	Complement Carry Flag
STD	$DF \leftarrow 1$	Set Direction Flag
CLD	$DF \leftarrow 0$	Clear Direction Flag
STI	$IF \leftarrow 1$	Set Interrupt Flag
CLI	$IF \leftarrow 0$	Clear Interrupt Flag
HLT		Halt
WAIT		Wait
LOCK		Lock
NOP		No Operation
ESC		Escape



Addressing Modes (in general)

- Implicit
- Immediate
- Register (direct)
- Register indirect
- Base or displacement addressing
- Indexed
- Auto-increment / Auto-decrement
- PC-relative
- Memory direct
- Memory indirect



MIPS Addressing Modes

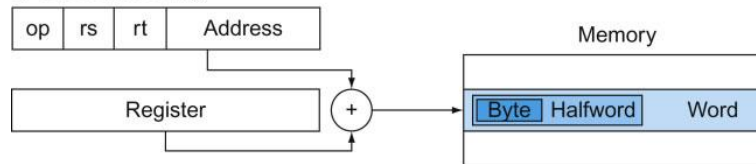
1. Immediate addressing



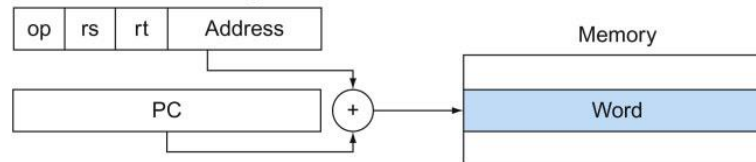
2. Register addressing



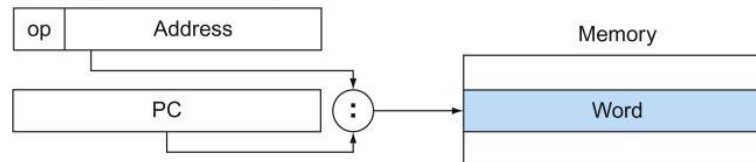
3. Base addressing



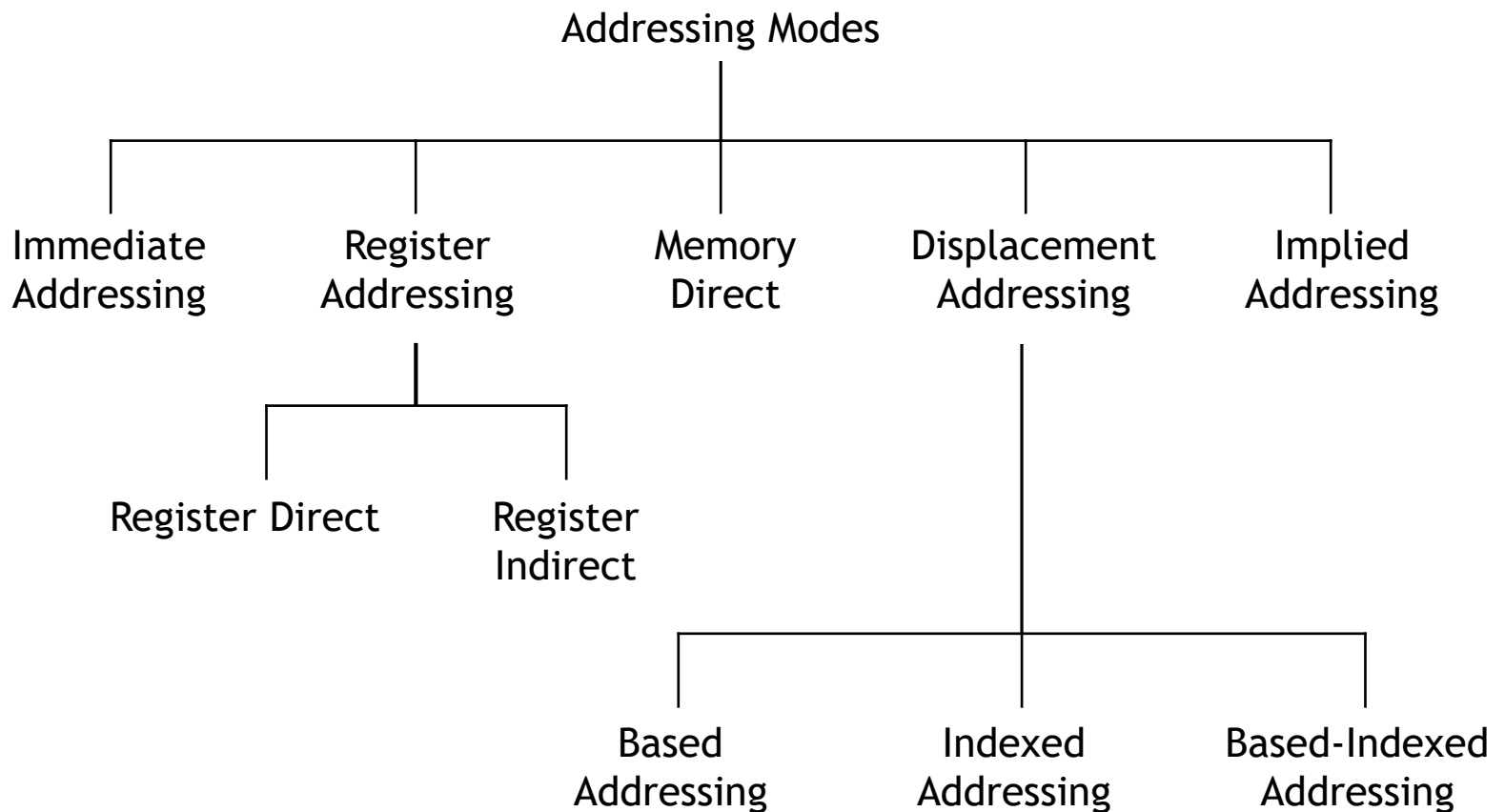
4. PC-relative addressing



5. Pseudodirect addressing



8086 Addressing Modes



Immediate Addressing

MOV AX, 2550H	; move 2550H into AX
MOV CX, 625	; load the decimal value 625 into CX
MOV BL, 40H	; load 40H into BL



Register Reference

MOV	BX,DX	;copy the contents of DX into BX
MOV	ES,AX	;copy the contents of AX into ES
ADD	AL,BH	;add the contents of BH to contents of AL

Direct

Indirect

MOV	AL,[BX]	;moves into AL the contents of the memory location pointed to by DS:BX.
MOV	CL,[SI]	;move contents of DS:SI into CL
MOV	[DI],AH	;move contents of AH into DS:DI



Memory Direct

MOV DL, [2400H] ; move contents of DS:2400H to DL

Example:

Assuming DS=1512H, find physical memory address and its contents after executing the following code:

```
MOV AL, 99H
```

```
MOV [3518], AL
```



Based Relative

MOV CX,[BX]+10 ;move DS:BX+10 and DS:BX+10+1 into CX
;PA = DS (shifted left) + BX + 10

↙ ↘
"MOV CX,10[BX]" ∪ "MOV CX,[BX+10]"

MOV AL,[BP]+5 ;PA = SS (shifted left) + BP + 5

↙ ↘
"MOV AL,5[BP]" ∪ "MOV AL,[BP+5]"



Indexed Relative

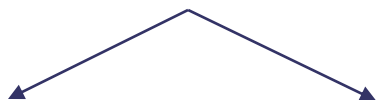
MOV DX, [SI]+5 ; PA=DS (shifted left) + SI + 5

MOV CL, [DI]+20 ; PA=DS (shifted left) + DI + 20



Based Indexed Relative

MOV	CL,[BX][DI]+8	;PA = DS (shifted left) + BX + DI + 8
MOV	CH,[BX][SI]+20	;PA = DS (shifted left) + BX + SI + 20
MOV	AH,[BP][DI]+12	;PA = SS (shifted left) + BP + DI + 12
MOV	AH,[BP][SI]+29	;PA = SS (shifted left) + BP + SI + 29



MOV	AH,[BP+SI+29]	MOV	AH,[SI+BP+29]
-----	---------------	-----	---------------



Summary

Addressing Mode	Operand	Default Segment
Register	reg	none
Immediate	data	none
Direct	[offset]	DS
Register indirect	[BX]	DS
	[SI]	DS
	[DI]	DS
Based relative	[BX]+disp	DS
	[BP]+disp	SS
Indexed relative	[DI]+disp	DS
	[SI]+disp	DS
Based indexed relative	[BX][SI]+disp	DS
	[BX][DI]+disp	DS
	[BP][SI]+ disp	SS
	[BP][DI]+ disp	SS



x86 Memory Addressing Modes

src/dst operand	2nd src operand
Register	Register
Register	Immediate
Register	Memory
Memory	Register
Memory	Immediate

Memory addressing modes

- Address in register
- Address = $R_{\text{base}} + \text{displacement}$
- Address = $R_{\text{base}} + 2^{\text{scale}} \times R_{\text{index}}$ (scale = 0, 1, 2, or 3)
- Address = $R_{\text{base}} + 2^{\text{scale}} \times R_{\text{index}} + \text{displacement}$



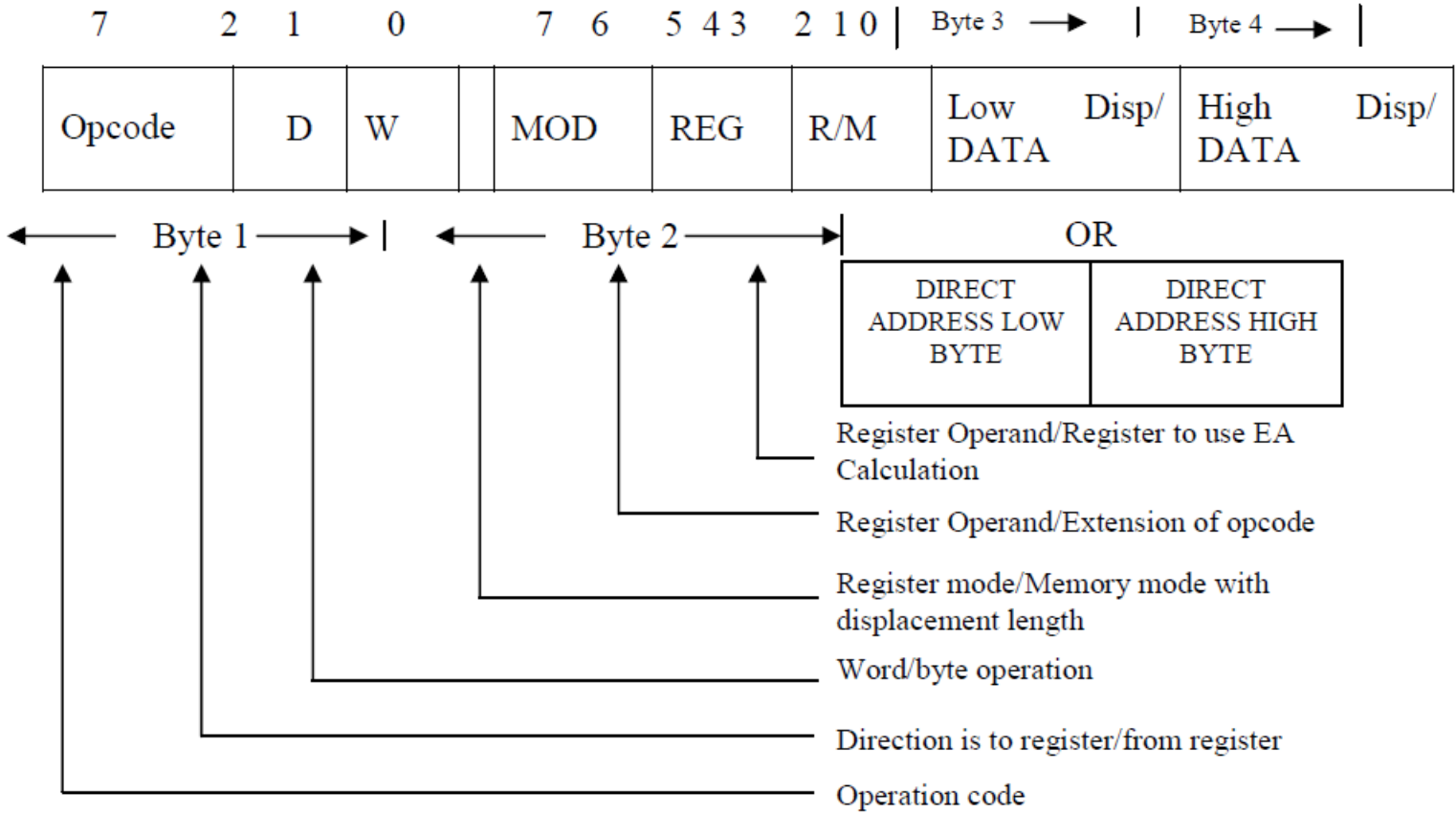
x86 vs. MIPS

Mode	Description	Register restrictions	MIPS equivalent
Register indirect	Address is in a register.	Not ESP or EBP	lw \$s0,0(\$s1)
Based mode with 8- or 32-bit displacement	Address is contents of base register plus displacement.	Not ESP	lw \$s0,100(\$s1) # <= 16-bit # displacement
Base plus scaled index	The address is Base + (2 ^{Scale} x Index) where Scale has the value 0, 1, 2, or 3.	Base: any GPR Index: not ESP	mul \$t0,\$s2,4 add \$t0,\$t0,\$s1 lw \$s0,0(\$t0)
Base plus scaled index with 8- or 32-bit displacement	The address is Base + (2 ^{Scale} x Index) + displacement where Scale has the value 0, 1, 2, or 3.	Base: any GPR Index: not ESP	mul \$t0,\$s2,4 add \$t0,\$t0,\$s1 lw \$s0,100(\$t0) # <= 16-bit # displacement

FIGURE 2.38 x86 32-bit addressing modes with register restrictions and the equivalent MIPS code. The Base plus Scaled Index addressing mode, not found in ARM or MIPS, is included to avoid the multiplies by 4 (scale factor of 2) to turn an index in a register into a byte address (see Figures 2.25 and 2.27). A scale factor of 1 is used for 16-bit data, and a scale factor of 3 for 64-bit data. A scale factor of 0 means the address is not scaled. If the displacement is longer than 16 bits in the second or fourth modes, then the MIPS equivalent mode would need two more instructions: a lui to load the upper 16 bits of the displacement and an add to sum the upper address with the base register \$s1. (Intel gives two different names to what is called Based addressing mode—Based and Indexed—but they are essentially identical and we combine them here.)



8086 Instruction Encoding



8086 Instruction Encoding (cont.)

MOD (2 bits)	Interpretation
00	Memory mode with no displacement follows except for 16 bit displacement when R/M=110
01	Memory mode with 8 bit displacement
10	Memory mode with 16 bit displacement
11	Register mode (no displacement)

REG	W=0	W=1
000	AL	AX
001	CL	CX
010	DL	DX
011	BL	BX
100	AH	SP
101	CH	BP
110	DH	SI
111	BH	DI

R/M	W=0	W=1
000	AL	AX
001	CL	CX
010	DL	DX
011	BL	BX
100	AH	SP
101	CH	BP
110	DH	SI
111	BH	DI

Opcode	D	W		MOD	REG	R/M	Low DATA	Disp/	High DATA	Disp/
--------	---	---	--	-----	-----	-----	----------	-------	-----------	-------



8086 Instruction Encoding (cont.)

MOD (2 bits)	Interpretation
00	Memory mode with no displacement follows except for 16 bit displacement when R/M=110
01	Memory mode with 8 bit displacement
10	Memory mode with 16 bit displacement
11	Register mode (no displacement)

R/M	MOD=00	MOD 01	MOD 10
000	(BX) + (SI)	(BX)+(SI)+D8	(BX)+(SI)+D16
001	(BX)+(DI)	(BX)+(DI)+D8	(BX)+(DI)+D16
010	(BP)+(SI)	(BP)+(SI)+D8	(BP)+(SI)+D16
011	(BP)+(DI)	(BP)+(DI)+D8	(BP)+(DI)+D10
100	(SI)	(SI) + D8	(SI) + D16
101	(DI)	(DI) + D8	(DI) + D16
110	Direct address	(BP) + D8	(BP) + D16
111	(BX)	(BX) + D8	(BX) + D16



8086 Instruction Encoding (example1)

Example 1 : Code for MOV CH, BL

This instruction transfers 8 bit content of BL into CH
 The 6 bit Opcode for this instruction is 100010₂ D bit indicates whether the register specified by the REG field of byte 2 is a source or destination operand.

D=0 indicates BL is a source operand.
 W=0 byte operation
 In byte 2, since the second operand is a register MOD field is 11₂.
 The R/M field = 101 (CH)
 Register (REG) field = 011 (BL)
 Hence the machine code for MOV CH, BL is
 10001000 11 011 101
 Byte 1 Byte2
 = 88DDH

7	2	1	0	7	6	5	4	3	2	1	0	Byte 3 →	Byte 4 →
Opcode				D	W	MOD		REG		R/M		Low DATA	Disp/ High DATA



8086 Instruction Encoding (example2)

Example 2: Code for SUB BX, (DI)

This instruction subtracts the 16 bit content of memory location addressed by DI and DS from Bx. The 6 bit Opcode for SUB is 001010₂.

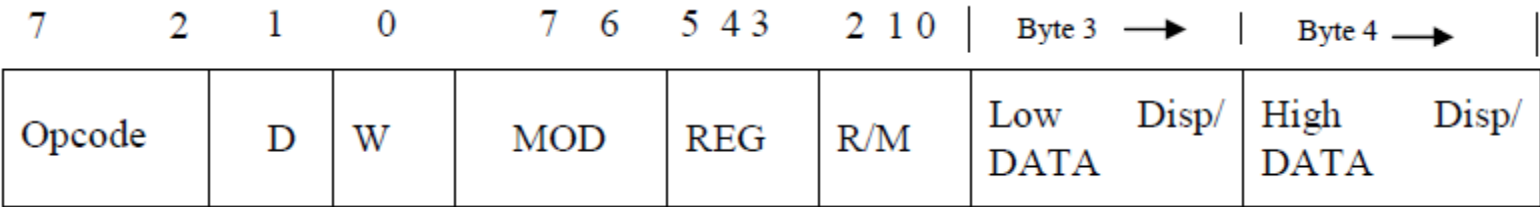
D=1 so that REG field of byte 2 is the destination operand. W=1 indicates 16 bit operation.

MOD = 00

REG = 011

R/M = 101

The machine code is 0010 1011 0001 1101
 2 B 1 D



8086 Instruction Encoding (example2)

Example 2: Code for SUB BX, (DI)

This instruction subtracts the 16 bit content of memory location addressed by DI and DS from Bx. The 6 bit Opcode for SUB is 001010₂.

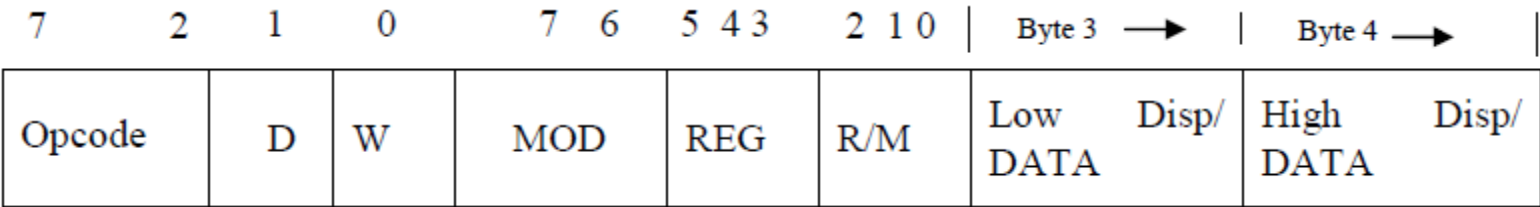
D=1 so that REG field of byte 2 is the destination operand. W=1 indicates 16 bit operation.

MOD = 00

REG = 011

R/M = 101

The machine code is 0010 1011 0001 1101
 2 B 1 D



8086 Instruction Encoding (example4)

Example 4 : Code for MOV DS : 2345 [BP]. DX

Here we have to specify DX using REG field. The D bit must be 0, indicating that Dx is the source register. The REG field must be 010 to indicate DX register. The w bit must be 1 to indicate it is a word operation. 2345 [BP] is specified with MOD=10 and R/M = 110 and displacement = 2345 H.

Whenever BP is used to generate the Effective Address (EA), the default segment would be SS. In this example, we want the segment register to be DS, we have to provide the **segment override prefix** byte (SOP byte) to start with. The SOP byte is 001 xx 110, where SR value is provided as per table shown below.

xx	Segment register
00	ES
01	CS
10	SS
11	DS

To specify DS register, the SOP byte would be 001 11 110 = 3E H. Thus the 5 byte code for this instruction would be 3E 89 96 45 23 H.

SOP	Opcode	D	W	MOD	REG	R/M	LB disp.	HD disp.
3EH	1000 10	0	1	10	010	110	45	23



Intel 80x86 Architecture

- Intel 80x86 CISC Architecture
 - Supports many addressing modes
 - Supports complicated instructions
 - Reference manuals more than thousand pages
 - But its performance is **no worse than RISC** architectures (if not better)
 - e.g., Apple recently switched from PowerPC to Intel chips
 - Why? **Microarchitecture**
 - Translates CISC instructions into RISC ones in hardware



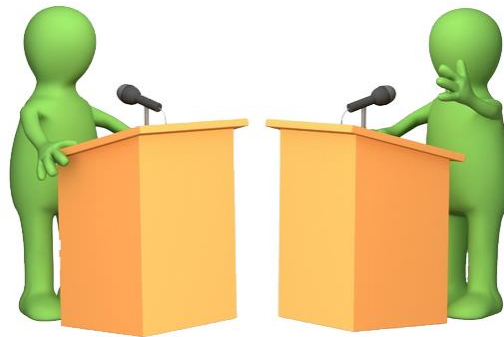
Implementing IA-32

- Complex Instr. Set Makes Implementation Difficult
 - HW translates instructions to simpler micro-operations
 - Simple instructions: 1-1
 - Complex instructions: 1-many
 - Micro-engine similar to RISC
- Comparable performance to RISC
 - Compilers avoid complex instructions



RISC & CISC

- Hybrid Solution
 - RISC core & CISC interface
 - Taking advantage of both architectures



RISC / CISC Debate



“XCHG” Example

```
01 ; Exchange two variables in Memory
02
03 .MODEL    SMALL
04 .STACK    100H
05
06 .Data
07 var1  DB  'A'
08 var2  DB  'B'
09
10 .CODE
11 Start:
12     MOV  AX,@DATA      ; set DS to point to the data segment
13     MOV  DS,AX
14
15     MOV  AL,var1       ; move contents of var1 to AL
16     XCHG AL,var2       ; exchange contents of AL and var2
17     MOV  var1,AL       ; move new contents of AL to var2
18
19     MOV  AH,4CH        ; DOS: terminate program
20     MOV  AL,0          ; return code will be 0
21     INT  21H          ; terminate the program
22
23 END Start
```



Lookup Table Example

```
01 ; Lookup Table Example
02
03 .MODEL    SMALL
04 .STACK    100H
05
06 .Data
07 ATAB      DB '0','1','2','3','4','5','6','7'
08           DB '8','9','A','B','C','D','E','F'
09 HexV      DB 11
10 ASCV      DB ?
11
12 .CODE
13 Start:
14           MOV AX,@DATA      ; set DS to point to the data segment
15           MOV DS,AX
16
17           LEA BX,ATAB
18           MOV AL,HexV
19           XLAT
20           MOV ASCV,AL
21
22           MOV DL,ASCV
23           MOV AH,2
24           INT 21H
25
26           MOV AH,4CH        ; DOS: terminate program
27           MOV AL,0          ; return code will be 0
28           INT 21H          ; terminate the program
29
30 END Start
```



Stack Example

```

; This program evaluates  $Q=A+(B-C)$ 
; in the form of  $Q=ABC-+$  using stack

STSEG    SEGMENT STACK 'stack'
         DB 100H DUP (?)
STSeg    ENDS

DTSeg    Segment
A        DW 3
B        DW 8
C        DW 6
DTSeg    ENDS

CDSeg    Segment
         ASSUME CS:CDSeg, DS:DtSeg, SS:StSeg
start:
         MOV AX,DTSeg      ; set DS to point to the data segment
         MOV DS,AX
         MOV AX,STSeg      ; set DS to point to the stack segment
         MOV SS,AX

         PUSH A
         PUSH B
         PUSH C
         POP CX            ; pop C into CX
         POP BX            ; pop B into BX
         SUB BX,CX         ; CX=B-C
         PUSH BX
         POP CX            ; pop B-C into CX
         POP BX            ; pop A into BX
         ADD BX,CX         ; BX=A+(B-C)
         PUSH BX

         MOV AH,4CH        ; DOS: terminate program
         MOV AL,0          ; return code will be 0
         INT 21H          ; terminate the program
CDSeg    ENDS
END Start

```



Convert to Capital Letters

```
.DATA
data1 DB "mY naME Is joEz"
data2 DB 15 DUP (?)
DB '$'
```

Letter	ASCII Code	Letter	ASCII Code
A	01000001	a	01100001
B	01000010	b	01100010
C	01000011	c	01100011
...
Y	01011001	y	01111001
Z	01011010	z	01111010

```
.CODE
start:
    MOV AX,@DATA      ;set DS to point to the data segment
    MOV DS,AX

    MOV SI,OFFSET data1
    MOV DI,OFFSET data2
    MOV CX,15
L1:    MOV AL,[SI]
    CMP AL,'a'
    JB OVER           ; no need to convert
    CMP AL,'z'
    JA OVER           ; no need to convert
    AND AL,11011111B  ; mask D5 to convert to uppercase
OVER:  MOV [DI],AL     ; copy the letter back
    INC SI
    INC DI
    LOOP L1

    MOV AH,4CH        ;DOS: terminate program
    MOV AL,0          ;return code will be 0
    INT 21H           ;terminate the program
END start
```



Check Parity Flag

				OF	DF	IF	TF	SF	ZF	0	AF	1	PF	1	CF
--	--	--	--	----	----	----	----	----	----	---	----	---	----	---	----

```

; Check Parity Flag
.MODEL SMALL
.STACK 100H

.DATA
ParityF      DB 'P'
NoParity     DB 'N'

.CODE
Start:
    MOV AX, @DATA      ; set DS to point to the data segment
    MOV DS, AX

    SUB AL, AL          ; force parity flag to 1
    INC AL              ; force parity flag to 0
    LAHF                ; load flag reg into AH
    MOV DL, NoParity    ; suppose there is no parity
    SHR AH, 3           ; shift parity flag into CF
    JNC NEXT
    MOV DL, ParityF
NEXT:  MOV AH, 2         ;DOS: print char
       INT 21H          ;display result
       MOV AH, 4CH      ; DOS: terminate program
       MOV AL, 0        ; return code will be 0
       INT 21H          ; terminate the program
END Start

```



Find Maximum Number in a List

```

1 DtSeg      Segment
2 dataIn     DB 12,23,1,45,26
3 max        DB ?
4 DtSeg      ENDS
5
6 CDSeg      Segment
7            ASSUME CS:CDSeg,DS:DtSeg,SS:StSeg
8 start:
9            MOV AX,DtSeg      ; set DS to point to the data segment
10           MOV DS,AX
11
12           MOV CX,5
13           MOV BX,OFFSET dataIn
14           MOV AL,0
15 L1:        CMP AL,[BX]
16           JA  NEXT          ; continue to search if AL is already greater
17           MOV AL,[BX]       ; update AL
18 Next:      INC BX
19           LOOP L1
20           MOV max,AL
21
22           MOV AH,4CH        ; DOS: terminate program
23           MOV AL,0          ; return code will be 0
24           INT 21H           ; terminate the program
25 CDSeg      ENDS
26 END start

```



Character Input

```
.DATA
```

```
inChar DB ?
```

```
MOV AH, 01      ; move option (01) to AH  
INT 21H         ; input character (with echo)  
MOV inChar, AL  ; move the input char to inChar
```

```
MOV AH, 07      ; move option (01) to AH  
INT 21H         ; input character (no echo)  
MOV inChar, AL  ; move the input char to inChar
```



String Input

```
.DATA
inBuf    Label BYTE      ; input buffer
Bsize    DB 10           ; buffer size
Rsize    DB ?            ; real size
inStr1    DB 10 DUP ' '  ; input string
```

```
LEA DX,inBuf      ; move buffer offset to DX
MOV AH,0AH        ; move option (0AH) to AH
INT 21H           ; input string
```

```
LEA BX,inStr1     ; move string offset to BX
MOV CL,Rsize      ; move real buffer size to CL
SUB CH,CH         ; clear CH
MOV SI,CX         ; move index of CR to SI
MOV BYTE PTR[BX+SI], '$' ; replace CR with $
```

```
LEA DX,inStr1     ; move string offset to DX
MOV AH,09         ; move option (09) to AH
INT 21H           ; display string
```



Character/ String Output

```
.DATA
CR      EQU 13
LF      EQU 10
outStr  DB "Have a nice day $"

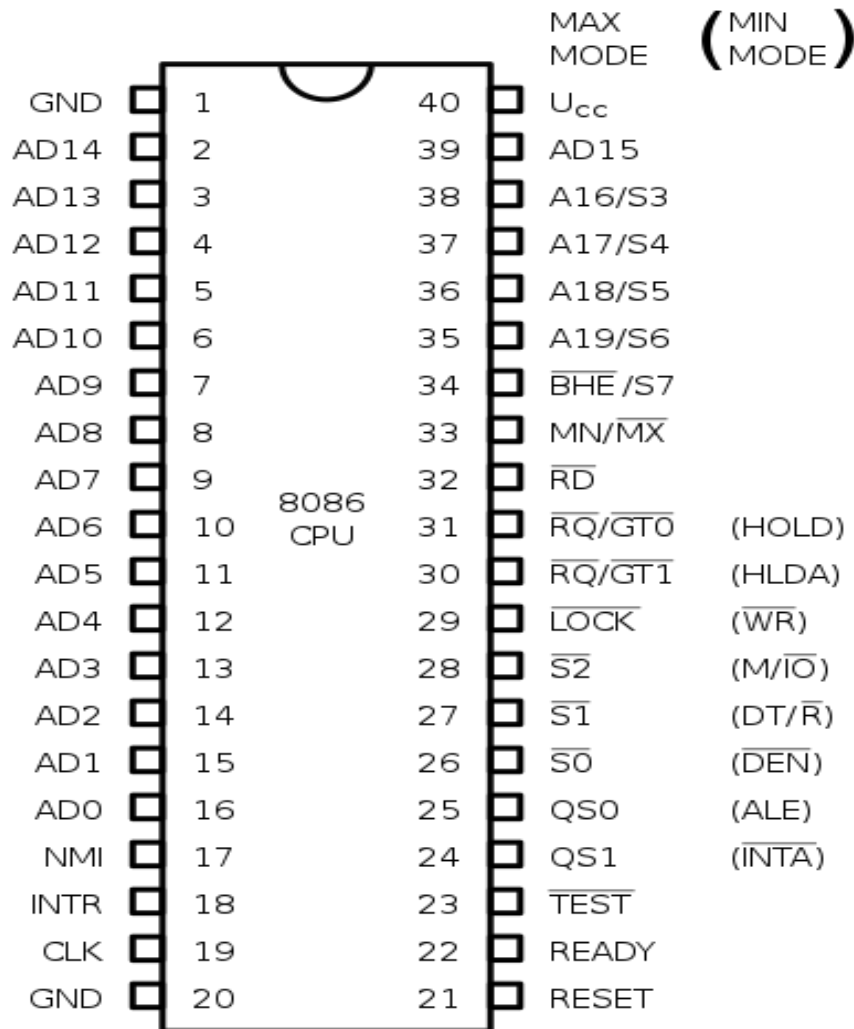
MOV DL, CR      ; move the character to be displayed
MOV AH, 02      ; move option (02) to AH
INT 21H         ; display character

MOV DL, LF      ; move the character to be displayed
MOV AH, 02      ; move option (02) to AH
INT 21H         ; display character

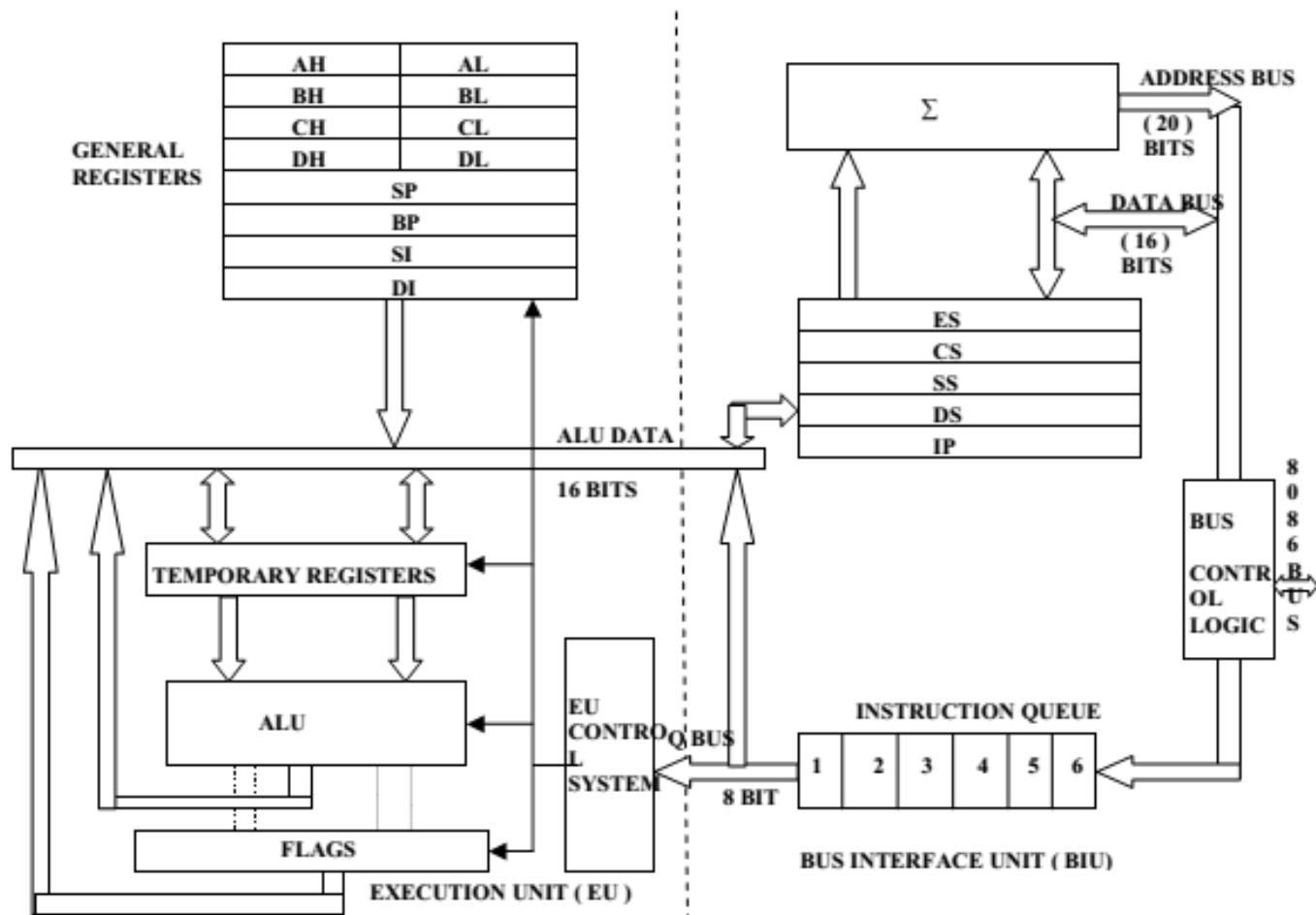
LEA DX, outStr  ; move string offset to DX
MOV AH, 09      ; move option (09) to AH
INT 21H         ; display string
```



8086 Chip



8086 Internal Architecture



Bus Interface Unit (BIU)

- Takes care of all data and addresses transfers on the buses:
 - sending addresses
 - fetching instructions from the memory
 - reading data from the ports and the memory
 - writing data to the ports and the memory
- EU has no direction connection with System Buses
- EU and BIU are connected with the Internal Bus



BIU Functional Parts

- Instruction queue:
 - Up to 6 bytes of next instructions is stored in the instruction queue
 - When EU executes instructions and is ready for its next instruction, then it reads the instruction from this instruction queue resulting in increased execution speed
 - Fetching the next instruction while the current instruction executes is called pipelining
- Segment registers (CS, DS, SS, ES)
- Instruction pointer:
 - A 16-bit register that holds the address of the next instruction to be executed



Execution Unit (EU)

- Telling the BIU from where to **fetch the data**
- **Decode** the instructions
 - using the instruction decoder
- **Execute** the instructions
 - using the ALU
- EU has no direct connection with system buses



EU Functional Parts

- ALU: Arithmetic and Logical Unit
- Flag Register
- General Purpose Registers:
 - AX: Accumulator Register
 - BX: Base Register
 - CX: Counter
 - DX: Data Register
- Stack Pointer Register



8086/88 ISA

- History
- ISA Concerns:
 - Memory model/ Registers/ Addressing modes
- Instruction Set
 - Move, Arithmetic, Logic, Shift, Control Transfer, ...
- Instruction Encoding
- 8086 Internal Architecture

