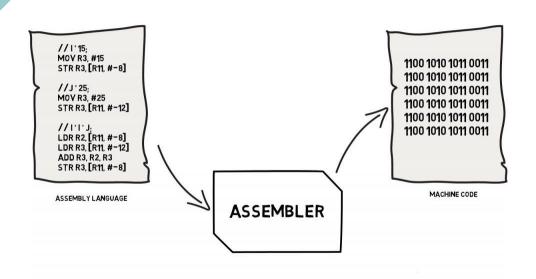
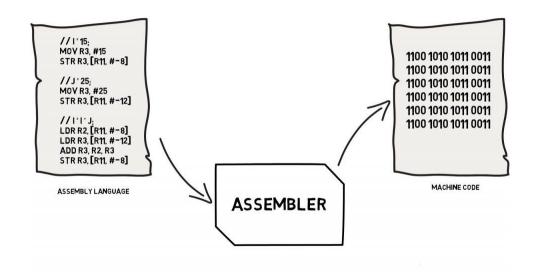
ساختار و زبان کامپیوتر

فصل جهار زبان اسمبلی MIPS-32



Computer Structure & Machine Language

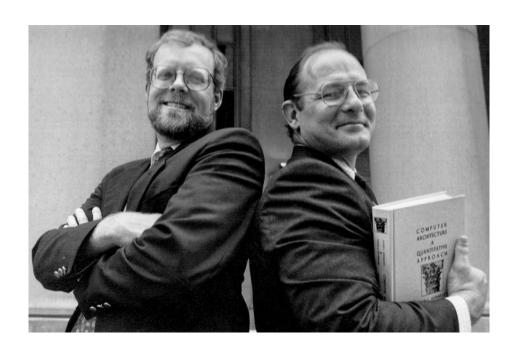
Chapter Four MIPS-32 Assemply Language



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Parts (text & figures of this lecture are adopted from:

D. Patterson, J. Hennessy, "Computer Organization & Design, The Hardware/Software Interface, MIPS Edition", 6th Ed., MK Publishing, 2020





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MIPS-32 Processor

- 32-Bit Processor
 - Registers 32 bits
 - Arithmetic & logical operations 32 bits
- Load/Store ISA
 - Only load/store instructions can access memory
 - Arithmetic/logical instructions no access to memory
- 32-Bit Instruction Length

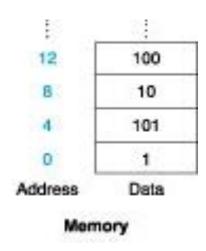


Memory Organization

- Organized as array of bytes or words
 - One Byte = 8 bits
 - Byte is smallest addressable entry in memory
- Possible Organizations
 - Byte addressable, byte accessible
- ✓ for MIPS
 - Byte addressable, word accessible
 - Word addressable, word accessible

MIPS Memory Organization

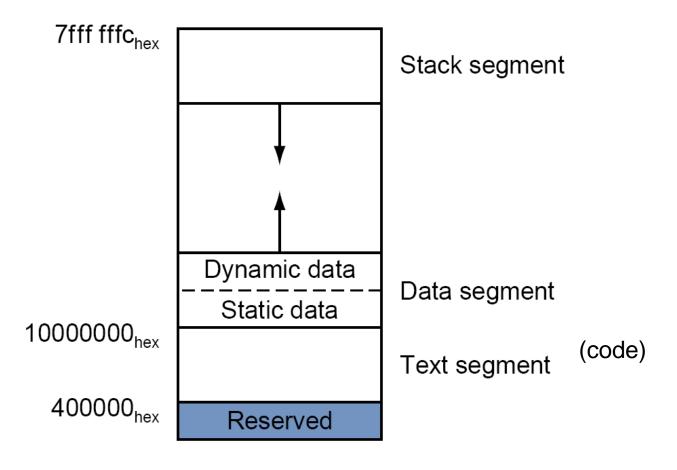
- MIPS Uses Words (4 bytes)
 - Words start at addresses that are multiples of 4
 - This is called alignment restriction
 - Addresses are byte-based addressing





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MIPS Memory Allocation





MIPS Registers

- \$s0-\$s7
 - General registers
 - Must be saved when calling subroutine
- \$t0-\$t9
 - Temporary registers
 - Local to each subroutine
- \$a0-\$a3
 - Arguments for subroutine call
- \$v0-\$v1
 - Values for results of a subroutine call



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MIPS Registers (cont.)

Register Number	Mnemonic Name	Conventional Use	Register Number	Mnemonic Name	Conventional Use
\$0	\$zero	Permanently 0	\$24, \$25	\$t8,\$t9	Temporary
\$1	\$at	Assembler Temporary (reserved)	\$26,\$27	\$k0,\$k1	Kernel (reserved for OS)
\$2,\$3	\$v0,\$v1	Value returned by a subroutine	\$28	\$gp	Global Pointer
\$4-\$7	\$a0-\$a3	Arguments to a subroutine	\$29	\$sp	Stack Pointer
\$8-\$15	\$t0-\$t7	Temporary (not preserved across a function call)	\$30	\$fp	Frame Pointer
\$16-\$23	\$s0-\$s7	Saved registers (preserved across a function call)	\$31	\$ra	Return Address



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MIPS Design Principles

- Simplicity favors regularity
- Smaller is faster
- Make the common case fast
- Good design demands good compromises

Simplicity favors regularity

- Regularity makes implementation simpler
- Simplicity enables higher performance at lower cost
- All arithmetic/logical instructions have three operands
 - two sources and one destination

```
add a, b, c # a gets b+c
```



Smaller is faster

- Arithmetic instructions use register operands
 - c.f. main memory with millions of locations
- MIPS has a 32 × 32-bit register file
 - Use for frequently accessed data
 - Numbered 0 to 31
 - 32-bit data called a "word"
- Assembler names
 - \$t0, \$t1, ..., \$t9 for temporary values
 - \$s0, \$s1, ..., \$s7 for saved variables



Make the common case fast

Constant data specified in an instruction

```
addi $s3, $s3, 4
```

- No subtract immediate instruction
- Just use a negative constant

```
addi $s2, $s1, -1
```

- Small constants are common
- Immediate operand avoids a load instruction

Good design demands good compromises

- Different formats complicate decoding, but allow 32-bit instructions uniformly
- Keep formats as similar as possible

6 bits	5 bits	5 bits	5 bits	5 bits	6 bits				
op	rs	rt	rd	shamt	funct				
op	rs	rt	16 bit address						
op	26 bit address								

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MIPS Instructions

- Arithmetic
- Data Transfer
- Logical
- Control
 - Conditional branch
 - Unconditional branch



Arithmetic Instructions

Addition/ Subtraction

- add r1,r2,r3
 - \circ eg add \$t0,\$s2,\$s4 #\$t0 = \$s2 + \$s4

$$# $t0 = $s2 + $s2$$

- sub r1,r2,r3
 - \circ eg sub \$t0,\$s2,\$s4 #\$t0 = \$s2 \$s4

$$# $t0 = $s2 - $s4$$

addi r1,r2,cnst

$$\circ$$
 e g addi \$t0,\$s2,2 #\$t0 = \$s2 + 2

$$\circ$$
 e.g. addi \$t0,\$s2,-2 #\$t0 = \$s2 - 2

$$# $t0 = $s2 - 2$$



Logical and Shift Instructions

- Operate on bits individually by
 - selective set
 - selective reset
 - selective complement
 - Unlike arithmetic, which operate on entire word
- Use to isolate fields
 - by shifting back and forth
 - selective mask



Logical Instructions

- AND/ OR/ NOR/ Complement
 - and r1,r2,r3

or r1, r2, r3

$$\circ$$
 eg or \$t0,\$s2,\$s4 # \$t0 = \$s2 | \$s4

nor r1,r2,r3

$$\circ$$
 e.g. nor $$t0,$s2,$s4 # $t0 = ~($s2|$s4)$

$$# $t0 = ~($s2 | $s4)$$

• What about complement?



Shift Instructions

- Logical Shift
 - sll r1, r2, nbits

```
\circ e.g. s11 $t0,$s2,3 # $t0 = $s2 << 3
```

• srl r1, r2, nbits

```
\circ e.g. sr1 $t0,$s2,2 # $t0 = $s2 << 2
```

- Will see more shift instructions later

Data Transfer Instructions

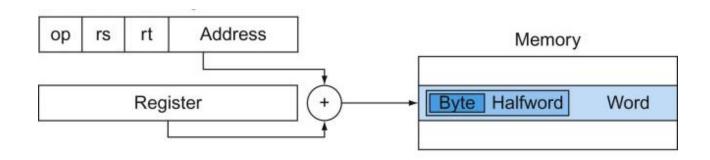
- Between registers & memory
 - Transfer data from/to memory
 - Transfer memory address to register
 - Swap
- Stack operations
 - Push
 - Pop



Transfer data from/to memory

- Load / Store
 - lw r1,address(r2)
 - \text{lw \$s1,100(\$s2)}
 - sw r1,address(r2)
 - o sw \$s1,100(\$s2)

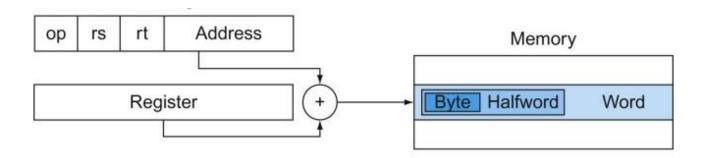
- # load word from memory
- # \$s1=Memory[\$s2+100]
- # store word to memory
- # Memory[\$s2+100]=\$s1





Base Addressing Mode

- Memory address in load & store specified by
 - a base register and an offset





MIPS Instructions: Example 1

- \circ compute f = (g+h) (i+j)
 - Assumptions
 - o g in \$t0, h in \$t1, i in \$t2, j in \$t3
 - o f in \$s0
 - Answer ?



MIPS Instructions: Example 1 (cont.)

- \circ compute f = (g+h) (i+j)
 - Assumptions
 - o g in \$t0, h in \$t1, i in \$t2, j in \$t3
 - o f in \$s0
 - Answer

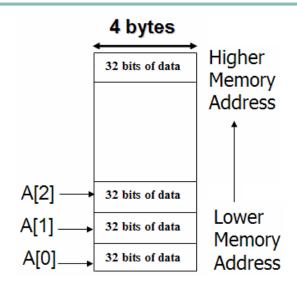
```
add $s0,$t0,$t1
add $s1,$t2,$t3
sub $s0,$s0,$s1
```



MIPS Instructions: Example 2

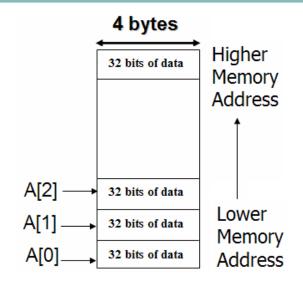
- \circ A[12] = h + A[8]
 - Assumptions
 - Address of A in \$s3
 - Variable h is in \$s2

Answer ?



MIPS Instructions: Example 2 (cont.)

- \circ A[12] = h + A[8]
 - Assumptions
 - Address of A in \$s3
 - Variable h is in \$s2



Answer

```
lw $t0,32($s3) # A[8]
add $t0,$s2,$t0 # h+A[8]
sw $t0,48($s3)
```



MIPS Instructions: Example 3

- o compute A[4] as
 - A[4] = (A[0]+A[1]) (A[2]+A[3])
- Assumptions
 - A is an array in main memory
 - Four-byte entry
 - Starting address of array A in \$s0

MIPS Instructions: Example 3 (cont.)

- \circ A[4] = (A[0]+A[1]) (A[2]+A[3])
- Answer

```
lw $t0,0($s0)
lw $t1,4($s0)
lw $t2,8($s0)
lw $t3,12($s0)
add $s1,$t0,$t1
add $s2,$t2,$t3
sub $s3,$s1,$s2
sw $s3,16($s0)
```



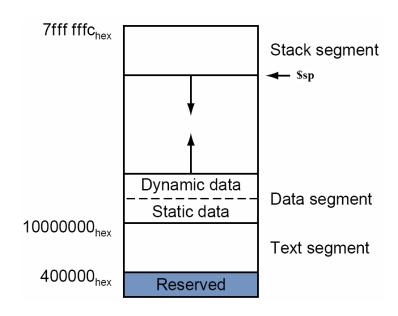
Stack Example

- Stack grows from higher to lower addresses
- \$sp contains address of word on top of stack
- o pop \$s0

7

o push \$s1

7





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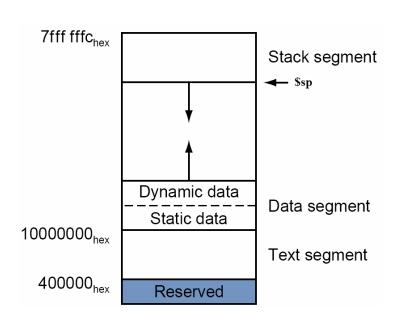
Stack Example (cont.)

- Stack grows from higher to lower addresses
- \$sp contains address of word on top of stack
- o pop \$s0:

```
lw $s0,0($sp)
addi $sp,$sp,4
```

o push \$s1:

```
addi $sp,$sp,-4
sw $s1, 0($sp)
```





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MIPS Assembly Code

- Consists of MIPS instructions and data
- Instructions given in .text segments
 - A program may have multiple .text segments
- Data defined in .data segments by directives
 - word defines 32 bit numbers
 - .space defines n number of bytes
 - .asciiz defines a string
 - •



First MIPS Assembly Program

- Compute sum of five homework assignment scores
- Scores are in memory

```
• scores: .word 95, 87, 98, 100, 100
```

- sum: .space 4
- O We need to:
 - Load address of scores to a register
 - Load first two scores
 - Add them
 - Load third score and add it to the sum and so on



Add Five Scores

```
.text
            la $50,scores # $50 has the address of the scores
2
            lw $t0,0($s0)
                            # the first score
            lw $t1,4($s0) # the 2nd score
 4
            add $t0,$t0,$t1
5
            lw $t1,8($s0) # the 3rd score
            add $t0, $t0,$tl
            lw $t1,12($s0) # the 4th score
            add $t0,$t0,$t1
9
            lw $t1,16($s0) # the 5th score
10
            add $t0,$t0,$t1
11
            la $sl,sum
12
            sw $t0,0($s1)
13
    .datal
14
15
    scores:
16
            .word 95, 87, 98, 100, 100
17
    sum:
            .space 4
18
```



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System Calls

- MIPS Assembly Notation
 - syscall
- Provided by MIPS Assembly simulators
 - Small set of OS-like services
- O How to Call?
 - Initialize \$v0 and \$a0
 - Then "syscall"



System Call (cont.)

Service	System call code	Arguments	Result
print_int	1	\$a0 = integer	
print_float	2	\$f12 = float	
print_double	3	\$f12 = double	
print_string	4	\$a0 = string	
read_int	5		integer (in \$v0)
read_float	6		float (in \$f0)
read_double	7		double (in \$f0)
read_string	8	\$a0 = buffer, \$a1 = length	
sbrk	9	\$a0 = amount	address (in \$v0)
exit	10		
print_char	11	\$a0 = char	
read_char	12		char (in \$a0)
open	13	\$a0 = filename (string), \$a1 = flags, \$a2 = mode	file descriptor (in \$a0)
read	14	\$a0 = file descriptor, \$a1 = buffer, \$a2 = length	num chars read (in \$a0)
write	15	\$a0 = file descriptor, \$a1 = buffer, \$a2 = length	num chars written (in \$a0)
close	16	\$a0 = file descriptor	
exit2	17	\$a0 = result	



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Add Two Scores

```
1 .text
 2
            la $s0,scores
                             # $s0 has the address of the scores
                             # the first score
            lw $t0,0($s0)
 3
            lw $t1,4($s0)
                             # the 2nd score
            add $t0,$t0,$t1
 5
            la $sl,sum
 6
            sw $t0.0($s1)
            li $v0,4
 8
            la $a0,msg
9
            syscall
                             # printout the message
10
11
            li $v0,1
12
            la $s0,sum
            lw $a0,0($s0)
13
14
            syscall
                             # printout the sum
15
            li $v0,4
            la $a0,nw
16
                             # printout newline
17
            syscall
18
            li $v0,10
                             # exit
19
            syscall
    .data
20
    scores:
            .word 12, 19
22
            .space 4
23
    sum:
            .asciiz "Sum of two scores is: "
    msg:
            .asciiz "\n\r"
   12W:
```



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Program Control Instructions

- To support Program Control, MIPS has one unconditional jump instruction
 - equivalent to goto in C
- MIPS has also MIPS has two conditional branch instructions
 - A distinctive feature of programs is that they can make decisions based on input data
 - o similar to an "if" statement with a goto

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Jump

- o j L1
 - Unconditional branch
 - Jump to instruction labeled with L1
 - In C, it is equivalent to
 - o goto L1



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Branch if Equal

- o beq r1, r2, L1
 - Conditional branch
 - comparing values in r1 and r2
 - go to L1 if values are equal
 - L1 is a label
 - In C, it is equivalent to
 - o if (r1 == r2) goto L1



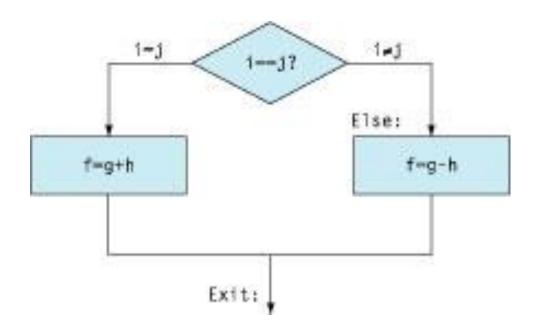
Branch if not Equal

- obne r1, r2, L1
 - Conditional branch
 - comparing values in r1 and r2
 - go to L1 if values are not equal
 - L1 is a label
 - In C, it is not equivalent to
 - \circ if (r1 \neq r2) goto L1



"if then else" Example

if (i==j) f = g + h; else f = g - h;





"if then else" Example (cont.)

if
$$(i==j)$$
 f = g + h; else f = g - h;

Variables f, g, h, i, j are in registers \$s0 through \$s4



"if then else" Example (cont.)

```
if (i==j) f = g + h; else f = g - h;
```

Variables f, g, h, i, j are in registers \$s0 through \$s4



Loop Example

while
$$(save[i]==k)$$
 i $+= 1$;

i, k & address of save are in registers \$s3, \$s5, \$s6





Loop Example

```
while (save[i]==k) i += 1;
```

i, k & address of save are in registers \$s3, \$s5, \$s6

```
Loop: sll $t1, $s3, 2
add $t1, $t1, $s6
lw $t0, 0($t1)
bne $t0, $s5, Exit
addi $s3, $s3, 1
j Loop
Exit: ...
```



Comparison Instructions

- o slt reg1, reg2, reg3 (set on less than)
 - e g slt \$t0,\$s3,\$s4
 - \circ if (\$s3 < \$s4) then \$t0 = 1
 - o otherwise \$t0 = 0
- o slti reg1,reg2,cnst (slt immediate)
 - e.g. slti \$t0,\$s3,10
 - \circ if (\$s3 < 10) then \$t0 = 1
 - o otherwise \$t0 = 0



Other Conditional Branches

- So far beq & bne
- How to implement all relative conditions?
 - less than
 - less than or equal
 - greater than
 - greater than or equal
- Use slt in combination with beq & bne



Other Conditional Branches (cont.)

Branch on "less than"





Other Conditional Branches (cont.)

Branch on "less than"

```
slt $t0,$s1,$s2 #if ($s1<$s2) $t0=1
bne $t0,$zero,L #if ($t0!=0) goto L</pre>
```

Branch on "greater than or equal"



Other Conditional Branches (cont.)

Branch on "less than"

```
slt $t0,$s1,$s2 #if ($s1<$s2) $t0=1
bne $t0,$zero,L #if ($t0!=0) goto L</pre>
```

Branch on "greater than or equal"

```
slt $t0,$s1,$s2 #if ($s1<$s2) $t0=1
beq $t0,$zero,L #if ($t0=0) goto L</pre>
```



Discussion

 Why MIPS designers didn't include all possible relative conditions in MIPS ISA?



Other Comparison Instructions

- Signed comparison: slt, slti
- Unsigned comparison: sltu, sltui
- Example

 - \$s1 = 0000 0000 0000 0000 0000 0000 0001
 - slt \$t0, \$s0, \$s1 # signed○ -1 < +1 ⇒ \$t0 = 1
 - sltu \$t0, \$s0, \$s1 # unsigned

$$\circ$$
 +4,294,967,295 > +1 \Rightarrow \$t0 = 0



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Procedures and Functions

- Ouestion?
 - Why use procedure/function/subroutine?
- o Answer:
 - Programmers use procedures to
 - o structure and organize programs
 - make them easier to understand
 - allow code to be reused

Call/ Return Instructions

- o jal label (jump and link)
 - eg jal sub1
 - Jump to sub1
 - Save return address in \$ra
- o jr reg (jump to register)
 - e.g. Jr \$ra
 - Jump to the address saved in \$ra



MIPS Calling Conventions

- \$a0 \$a3:
 - Four argument registers in which to pass parameters
- \$v0 \$v1
 - Two value registers in which to return values
- o \$ra:
 - One return address register to return to point of origin



Procedure Execution Flow

- Program must follow these Steps:
 - Place parameters in a place where procedure can access them
 - Transfer control to procedure
 - Acquire storage resources needed for procedure
- Perform desired tasks
 - Place results in a place where calling program can access them
 - Return control to point of origin



A Simple Example (in C)

```
#include <stdio.h>
int leaf_example(int g, int h, int i, int j)
  int f:
 f = (g + h) - (i + j);
 return f;
int main(int agrc, char *argv[])
  int f, g, h, i, j;
 g = 5; h = -20; i = 13; j = 3;
  f = leaf_example(g, h, i, j);
  printf("\nThe value of f is %d.\n", f);
  return 0;
```



A Simple Example: main

.text la \$t0, g lw \$a0, 0(\$t0) # \$a0=q lw \$a1, 4(\$t0) # \$a1=h lw \$a2, 8(\$t0) # \$a2=i lw \$a3, 12(\$t0) # \$a3=j jal leaf example # call procedure la \$t0, f sw \$v0, 0(\$t0) # f=\$v0 .data

#q,h,i,j

g: .word 5,-20,13,3

f: .space 4

A Simple Example: leaf

```
.globl leaf_example
leaf_example:
```

```
add $t0, $a0, $a1
add $t1, $a2, $a3
sub $s0, $t0, $t1
add $v0, $s0, $0
```

```
#register $t0 contains g + h
#register $t1 contains i + j
#f = (g + h) - (i + j)
#returns f
```



jr \$ra

#return to calling program

What else?

.globl leaf_example
leaf example:

What do we need to do in order to guarantee correctness of program?

```
add $t0, $a0, $a1
add $t1, $a2, $a3
sub $s0, $t0, $t1
add $v0, $s0, $0
```

```
#register $t0 contains g + h
#register $t1 contains i + j
#f = (g + h) - (i + j)
#returns f
```

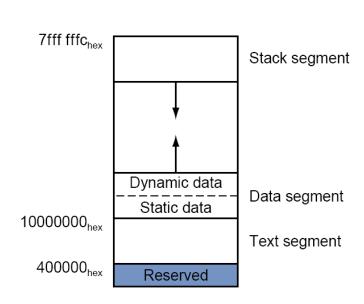


jr \$ra

#return to calling program

Register Spilling

- Callee has to save all registers it uses and restore values before it returns
 - By storing them on stack
 - At the beginning
 - Then restoring them
 - At the end

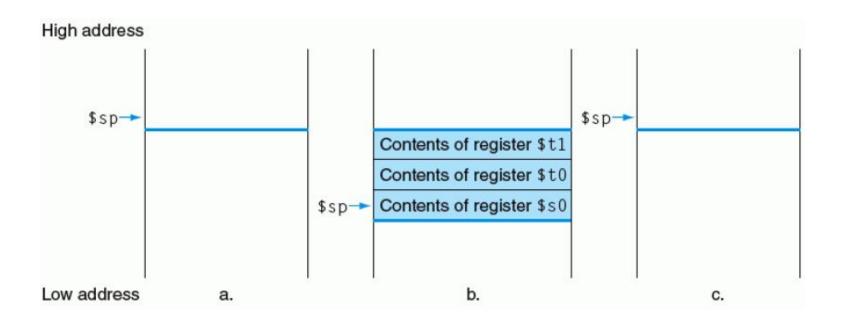




A Simple Example (complete version)

```
.globl leaf example
leaf example:
     addi $sp, $sp, -12
                          #make space on stack
        $t1, 8($sp)
                          #save $t1
     sw $t0, 4($sp)
                          #save $t2
     sw $s0, 0($sp)
                          #save $s0
     add $t0, $a0, $a1
                         #register $t0 contains g + h
     add $t1, $a2, $a3
                         #register $t1 contains i + j
     sub $s0, $t0, $t1
                          #f = (q + h) - (i + j)
     add $v0, $s0, $0
                          #returns f
           $s0, 0($sp)
                          #restore $s0
     lw
     lw $t0, 4($sp)
                          #restore $t0
     lw $t1, 8($sp)
                          #restore $t1
     addi $sp, $sp, 12
                          #adjust stack pointer
     jr $ra
                          #return to calling program
```

Stack Pointer





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Nested Procedures

- Procedures that do not call others are called leaf procedures
- Procedures may invoke other procedures
- o Caller:
 - The procedure that calls another procedure
- o Callee:
 - The procedure that is called by another procedure

MIPS General Registers

- MIPS divides 18 registers into two groups
 - \$t0 \$t9
 - 10 temporary registers not preserved by callee on a procedure call
 - Caller-saved registers
 - Caller must save those it is using
 - \$s0 \$s7
 - 8 saved registers must be preserved on a procedure call
 - Callee-saved registers
 - Callee must save those it is going to use



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Caller Must Do (before...)

- Before it calls a subroutine, it must:
 - Save caller-saved registers on stack
 - o It includes \$a0 \$a3, \$t0 \$t9, and \$ra
 - O Why \$a0 \$a3, \$ra?
 - Pass parameters
 - Up to four parameters passed by \$a0 \$a3
 - Execute a jal instruction
 - Jumps to callee's first instruction and save address of next instruction in \$ra



Caller Must Do (after...)

- After subroutine call, it needs to
 - Read returned values from \$v0 and \$v1
 - Restore caller-saved registers

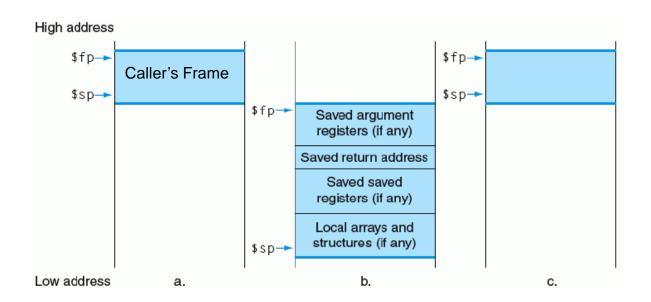
Callee Must Do (at first)

- Callee must do the following:
 - Allocate memory for its frame by subtracting its frame size from stack pointer
 - Save callee-saved registers in frame
 - It must save \$s0-\$s7, \$fp, \$ra before changing them
 - \$ra needs to be saved if callee itself makes a call
 - When needed, update frame pointer
 - In this case, \$fp must be saved



Procedure Frame (Activation Record)

Segment of stack containing a procedure's saved registers and local variables



We can avoid using \$fp by avoiding changes to \$sp within a procedure: adjust the stack only on entry and exit of the procedure

Callee Must Do (at the end)

- Obefore it returns to caller:
 - Place return values in \$v0 & \$v1 (if needed)
 - Restore all callee-saved registers
 - That were saved at procedure entrance
 - Pop stack frame
 - By adding frame size to \$sp
 - Return by jumping to address in \$ra
 - o Using jr \$ra



Earlier Example

```
.globl leaf example
leaf example:
    addi $sp, $sp, -12 #make space on stack
    sw $t1, 8($sp)
                       #save $t1
    sw $t0, 4($sp) #save $t2
    sw $s0, 0($sp) #save $s0
    add $t0, $a0, $a1
                         #register $t0 contains g + h
    add $t1, $a2, $a3
                         #register $t1 contains i + j
    sub $s0, $t0, $t1
                         #f = (q + h) - (i + j)
    add $v0, $s0, $0
                         #returns f
    lw $s0, 0($sp) #restore $s0
    lw $t0, 4($sp) #restore $t0
    lw $t1, 8($sp) #restore $t1
    addi $sp, $sp, 12
                         #adjust stack pointer
    jr $ra
                         #return to calling program
```

Revised Version

```
.globl leaf example
leaf example:
  addi $sp, $sp, -4
                              #make space on stack
  sw $s0, 0($sp)
                              #save $s0
  add $t0, $a0, $a1
                              #register $t0 contains g + h
  add $t1, $a2, $a3
                              #register $t1 contains i + j
  sub $s0, $t0, $t1
                              #f = (q + h) - (i + j)
  add $v0, $s0, $0
                              #returns f
  lw $s0, 0($sp)
                              #restore $s0
  addi $sp, $sp, 4
                              #adjust stack pointer
  jr $ra
                              #return to calling program
```



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- Introduction (Processor/ Memory Organization/ Registers)
- o Design Principles
- Basic Instructions (Arithmetic/Logic & Shift/Data Transfer)
- o Assembly Code
- o System Calls
- Program Control Instructions
- o Procedures & Functions
- Advanced Arithmetic (Multiplication/ Division/ Floating point)
- Instruction Encoding
- Supplementary Tips



MIPS Multiplication

- Two 32-bit registers for product
 - HI: most-significant 32 bits
 - LO: least-significant 32-bits
- Instructions
 - mult rs,rt / multu rs,rt
 - 64-bit product in HI/LO
 - mfhi rd / mflo rd
 - Move from HI/LO to rd
- Can test HI to see if product overflows 32 bits



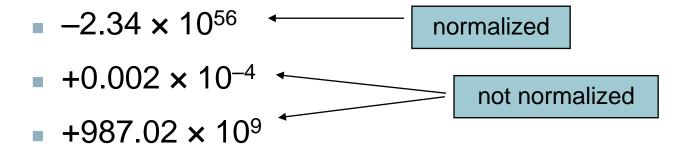
MIPS Division

- Use HI/LO registers for result
 - HI: 32-bit remainder
 - LO: 32-bit quotient
- Instructions
 - div rs,rt / divu rs,rt
 - Result in HI/LO
 - mfhi rd / mflo rd
 - Move from HI/LO to rd
- No overflow or divide-by-0 checking
- Software must perform checks if required



Floating Point

- Representation for non-integral numbers
 - Including very small and very large numbers
- Like scientific notation



- In binary
 - \bullet ±1. $xxxxxxxx_2 \times 2^{yyyy}$
- Types float and double in C



Floating Point Standard

- Defined by IEEE Std 754-1985
- Developed in response to divergence of representations
 - Portability issues for scientific code
- Now almost universally adopted
- Two representations
 - Single precision (32-bit)
 - Double precision (64-bit)

IEEE Floating-Point Format

single: 8 bits single: 23 bits double: 11 bits double: 52 bits

S Exponent Fraction

$$x = (-1)^{S} \times (1 + Fraction) \times 2^{(Exponent-Bias)}$$

- S: sign bit $(0 \Rightarrow \text{non-negative}, 1 \Rightarrow \text{negative})$
- Normalize significand: 1.0 ≤ |significand| < 2.0</p>
 - Always has a leading pre-binary-point 1 bit, so no need to represent it explicitly (hidden bit)
 - Significand is Fraction with the "1." restored
- Exponent: excess representation: actual exponent + Bias
 - Ensures exponent is unsigned
 - Single: Bias = 127; Double: Bias = 1203

Single-Precision Range

- Exponents 00000000 and 11111111 reserved
- Smallest value
 - Exponent: 00000001⇒ actual exponent = 1 - 127 = -126
 - Fraction: $000...00 \Rightarrow \text{significand} = 1.0$
 - $\pm 1.0 \times 2^{-126} \approx \pm 1.2 \times 10^{-38}$
- Largest value
 - Exponent: 11111110 ⇒ actual exponent = 254 - 127 = +127
 - Fraction: 111...11 ⇒ significand ≈ 2.0
 - $\pm 2.0 \times 2^{+127} \approx \pm 3.4 \times 10^{+38}$

Double-Precision Range

- Exponents 0000...00 and 1111...11 reserved
- Smallest value
 - Exponent: 0000000001⇒ actual exponent = 1 - 1023 = -1022
 - Fraction: $000...00 \Rightarrow \text{significand} = 1.0$
 - $\pm 1.0 \times 2^{-1022} \approx \pm 2.2 \times 10^{-308}$
- Largest value

 - Fraction: 111...11 ⇒ significand ≈ 2.0
 - $\pm 2.0 \times 2^{+1023} \approx \pm 1.8 \times 10^{+308}$

Floating-Point Precision

- Relative precision
 - all fraction bits are significant
 - Single: approx 2⁻²³
 - Equivalent to 23 x log₁₀2 ≈ 23 x 0.3 ≈ 6 decimal digits of precision
 - Double: approx 2⁻⁵²
 - Equivalent to 52 x log₁₀2 ≈ 52 x 0.3 ≈ 16 decimal digits of precision

Floating-Point Example

- Represent –0.75
 - $-0.75 = (-1)^1 \times 1.1_2 \times 2^{-1}$
 - S = 1
 - Fraction = $1000...00_2$
 - Exponent = -1 + Bias
 - Single: $-1 + 127 = 126 = 011111110_2$
 - Double: $-1 + 1023 = 1022 = 0111111111110_2$
- Single: 1011111101000...00
- Double: 10111111111101000...00

Floating-Point Example

 What number is represented by the singleprecision float

11000000101000...00

- S = 1
- Fraction = $01000...00_2$
- Fxponent = $10000001_2 = 129$
- $x = (-1)^{1} \times (1 + 01_{2}) \times 2^{(129 127)}$ $= (-1) \times 1.25 \times 2^{2}$ = -5.0

Denormal Numbers

Exponent = $000...0 \Rightarrow$ hidden bit is 0

$$x = (-1)^{S} \times (0 + Fraction) \times 2^{-Bias}$$

- Smaller than normal numbers
 - allow for gradual underflow, with diminishing precision
- Denormal with fraction = 000...0

$$x = (-1)^{S} \times (0+0) \times 2^{-Bias} = \pm 0.0$$

Two representations of 0.0!

Infinities and NaNs

- Exponent = 111...1, Fraction = 000...0
 - ±Infinity
 - Can be used in subsequent calculations, avoiding need for overflow check
- Exponent = 111...1, Fraction ≠ 000...0
 - Not-a-Number (NaN)
 - Indicates illegal or undefined result
 - e.g., 0.0 / 0.0
 - Can be used in subsequent calculations

IEEE 754 Standard: Summary

- Single precision (32bits)/Double precision (64bits)
- Normalized/ Denormalized forms
- Standard definitions for zero, infinity, NaN
- O Check: https://www.h-schmidt.net/FloatConverter/IEEE754.html

Single precision		Double p	precision	Object represented	
Exponent	Fraction	Exponent	Fraction		
0	0	0	0	0	
0	Nonzero	0	Nonzero	± denormalized number	
1-254	Anything	1-2046	Anything	± floating-point number	
255	0	2047	0	± infinity	
255	Nonzero	2047	Nonzero	NaN (Not a Number)	



MIPS Floating Point Support

- FP hardware is coprocessor 1
 - Adjunct processor that extends the ISA
- Separate FP registers
 - 32 single-precision: \$f0, \$f1, ... \$f31
 - Paired for double-precision: \$f0/\$f1, \$f2/\$f3, ...
- FP instructions operate only on FP registers
 - Programs generally don't do integer ops on FP data, or vice versa
- FP load and store instructions
 - lwc1, ldc1, swc1, sdc1e.g., ldc1 \$f8,32(\$sp)



MIPS Floating Point Instructions

F-type						
op	cop	ft	fs	fd	funct	
6 bits	5 bits	5 bits	5 bits	5 bits	6 bits	

Category	Instruction	Example	Meaning	Comments
	FP add single	add.s \$f2,\$f4,\$f6	\$f2 = \$f4 + \$f6	FP add (single precision)
	FP subtract single	sub.s \$f2,\$f4,\$f6	\$f2 = \$f4 - \$f6	FP sub (single precision)
	FP multiply single	mul.s \$f2,\$f4.\$f6	\$f2 = \$f4 × \$f6	FP multiply (single precision)
	FP divide single	div.s \$f2,\$f4,\$f6	\$f2 = \$f4 / \$f6	FP divide (single precision)
Arithmetic	FP add double	add.d \$f2,\$f4,\$f6	\$f2 = \$f4 + \$f6	FP add (double precision)
	FP subtract double	sub.d \$f2.\$f4.\$f6	\$f2 = \$f4 - \$f6	FP sub (double precision)
	FP multiply double	mul.d \$f2.\$f4.\$f6	\$f2 = \$f4 × \$f6	FP multiply (double precision)
	FP divide double	div.d \$f2,\$f4,\$f6	\$f2 = \$f4 / \$f6	FP divide (double precision)
Data transfer	load word copr. 1	lwc1 \$f1,100(\$s2)	\$f1 = Memory[\$s2 + 100]	32-bit data to FP register
	store word copr. 1	swc1 \$f1,100(\$s2)	Memory[\$s2 + 100] = \$f1	32-bit data to memory
Conditional branch	branch on FP true	bclt 25	if (cond == 1) go to PC + 4 + 100	PC-relative branch if FP cond.
	branch on FP false	bclf 25	if (cond == 0) go to PC + 4 + 100	PC-relative branch if not cond.
	FP compare single (eq.ne,lt,le,gt,ge)	c.lt.s \$f2.\$f4	if (\$f2 < \$f4) cond = 1; else cond = 0	FP compare less than single precision
	FP compare double (eq.ne,lt,le,gt,ge)	c.lt.d \$f2.\$f4	if (\$f2 < \$f4) cond = 1; else cond = 0	FP compare less than double precision



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MIPS Instruction Encoding

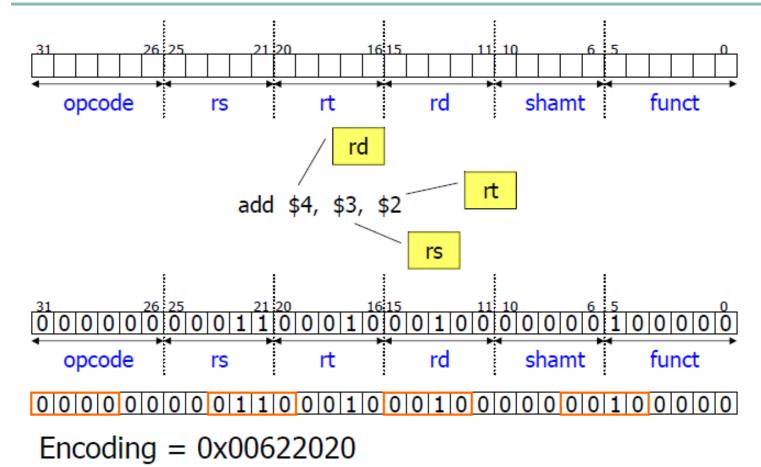
- MIPS instruction is exactly 32 bits
 - R-type (Register type)
 - I-type (Immediate type)
 - J-type (Jump type)

op	rs	rt	rd	shamt	funct
op	rs	rt	16 bit address		ess
op	26 bit address				

Instruction Encoding: Examples

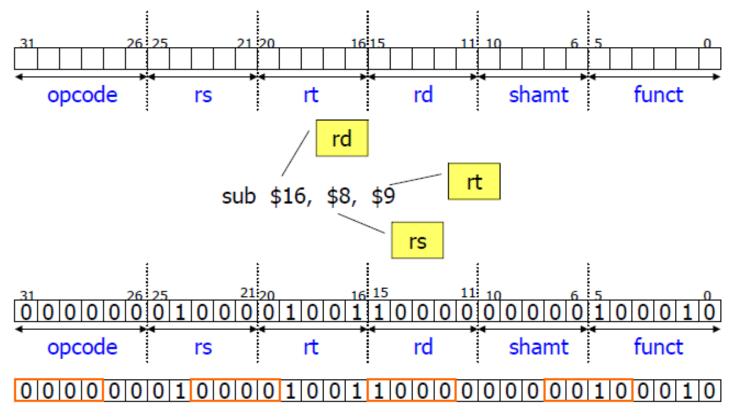
Instruction	Format	Op	rs	rt	rd	shamt	funct
add	R	0	reg	reg	reg	0	32_{ten}
sub (subtract)	R	0	reg	reg	reg	0	34_{ten}
sll (logical shift left)	R	0	0	reg	reg	shamt	0
Instruction	Format	Op	rs	rt	constant/address		
add immediate	I	8 _{ten}	reg	reg	constant		
lw (load word)	I	35 _{ten}	reg	reg	address		
sw (store word)	I	43 _{ten}	reg	reg	address		
Instruction	Format	Op	address				
j (jump)	J	2_{ten}	address				

R-Type Encoding (add)





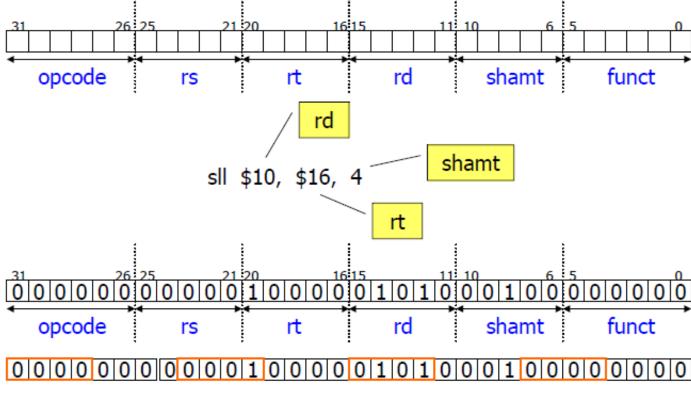
R-Type Encoding (sub)



Encoding = 0x01098022



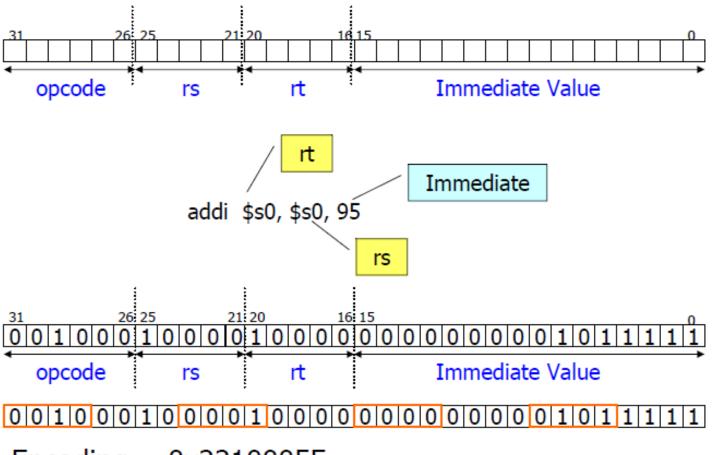
R-Type Encoding (sll)



Encoding = 0x00105100



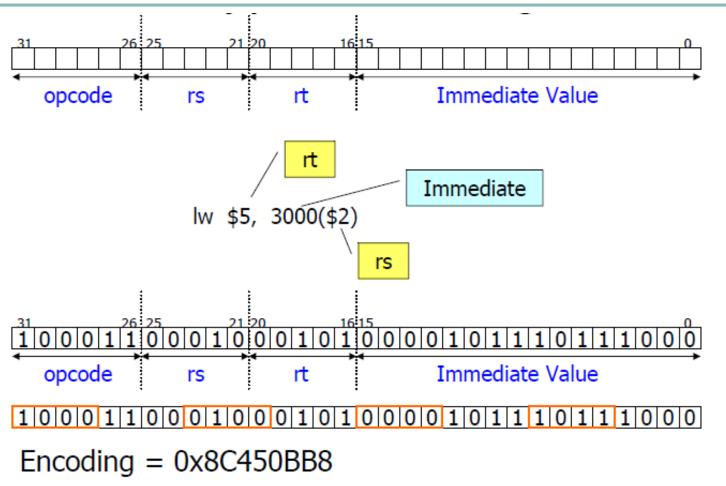
I-Type Encoding (addi)



Encoding = 0x2210005F

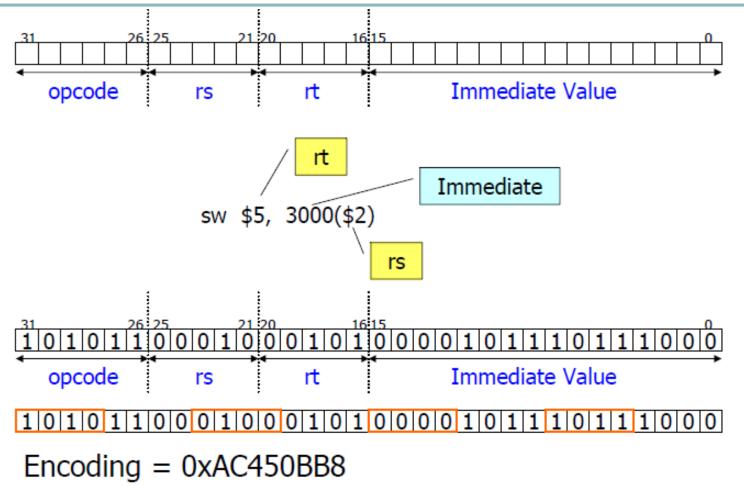


I-Type Encoding (lw)





I-Type Encoding (sw)





I-Type Encoding (sign extension)

- Immediate Field
 - Sign extended to 32-bits in
 - o addi, lw/sw, andi, ...
 - Example
 - o addi \$21,\$22,-50

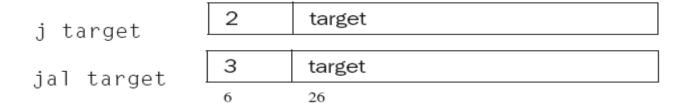
8	22	21	-50
001000	10110	10101	111111111001110

Encoding Branch Instructions

- O How to Encode Branch Instructions?
 - First figure out value for associated label
 - Will be done by assembler
 - Note MIPS has alignment restriction
 - All labels will be a multiple of 4
 - Label addresses divided by 4
 - Addresses encoded in terms of words
 - To increase address range



J-Type Instruction Encoding

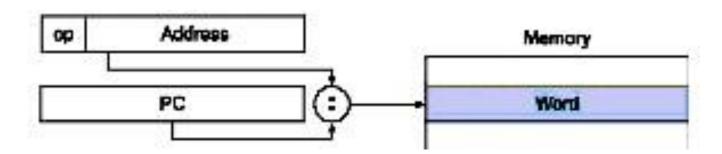


- J-Type: jump and jump-and-link instructions
- 26 Bits for Target Field
 - Represents # of instructions instead of # of bytes
 - Represents 28 bits in terms of bytes
 - But PC requires 32 bits!!!
- Where do we get other 4 bits?



Pseudo-Direct Addressing

- Jump address is formed by:
 - Upper 4 bits of current PC
 - 26 bits of target address in instruction
 - Two bits of 0's



Questions

• Maximum code when using j instruction?

O Anyway to jump to a 32-bit address?

Questions

- Maximum code when using j instruction?
 - 256 MB
- O Anyway to jump to a 32-bit address?
 - Use jr



Encoding jr instruction

- jump register (jr)
 - Unconditionally jump to address given by rs
 - After execution of jr \$s0

$$\circ$$
 PC = \$s0

R-type, J-type, or I-type?

Encoding jr instruction

- jump register (jr)
 - Unconditionally jump to address given by rs
 - After execution of jr \$s0

$$\circ$$
 PC = \$s0

R-type, J-type, or I-type?

jr rs

0	rs	0	8
6	5	15	6



Encoding Conditional Branch

- O Where to Branch?
 - Branch # of instructions specified by offset
 - o If rs equals to rt
 - Register holding address of current instruction
 - Program Counter (PC) / Instruction Register (IR)
 - What is value of PC after executing current instruction?

beq rs, rt, label

4	rs	rt	Offset
6	5	5	16



Encoding Conditional Branch (cont.)

- PC-Relative Addressing
 - Offset of conditional branch instructions relative to PC + 4
 - MIPS instructions are 4 bytes long → offset refers to number of words to next instruction instead of number of bytes

Encoding Conditional Branch (cont.)

- Branch Calculation
 - If we don't take branch:

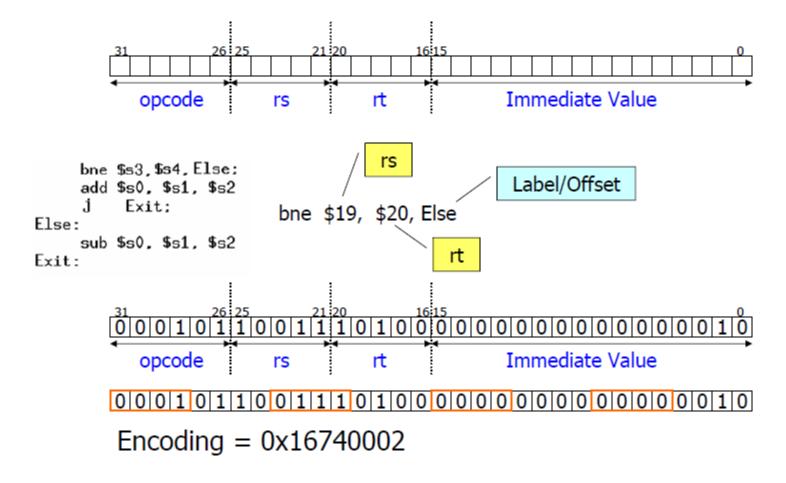
PC = PC+4 : byte # of next instruction

• If we do take branch:

$$PC = (PC+4) + (immediate*4)$$

immediate can be positive or negative

I-Type Encoding (bne)





Jump Instructions Summary

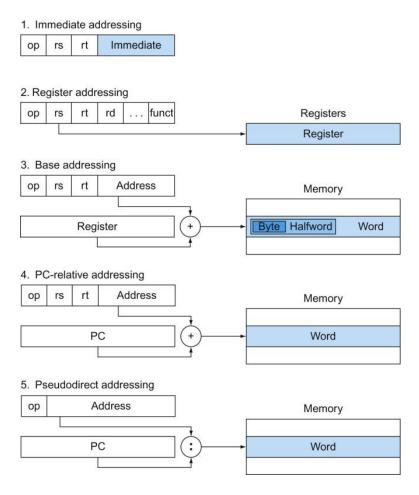
Unconditional Jump (j, jal): Pseudo-direct addressing

Conditional Jump (bne, beq): PC-relative addressing

Jump Register (jr): Register addressing



Addressing Mode Summary





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Supplementary Tips

- Big Immediate
- Byte/ Halfword Operations
- More Shift Instructions
- Endianness



Big Immediate

- In MIPS, immediate field has 16 bits
- For 32-bit immediate operands
 - MIPS includes load upper immediate (lui)
 - Which sets upper 16 bits of a constant in a register and fills lower 16 bits with 0's
 - Then one can set lower 16 bits using ori



Byte/ Halfword Operations

- Load byte/halfword (sign extend to 32 bits in rt)
 - lb rt, offset (rs)
 - lh rt,offset(rs)
- Load unsigned byte/halfword (zero extend to 32 bits in rt)
 - lbu rt,offset(rs)
 - lhu rt, offset(rs)
- Store just rightmost byte/halfword
 - sb rt,offset(rs)
 - sh rt,offset(rs)



Shift Instructions

- Logical shift left/right (by specified number of bits)
 - sll \$rd,\$rt,shamt
 - srl \$rd,\$rt,shamt
- Logical shift left/right (by variable number of bits)
 - sllv rd, rt, rs
 - srlv rd,rt,rs
- Arithmetic Shift (keep sign while shifting)
 - sra rd,rt,shamt
 - srav rd,rt,rs



Big Endian vs. Little Endian

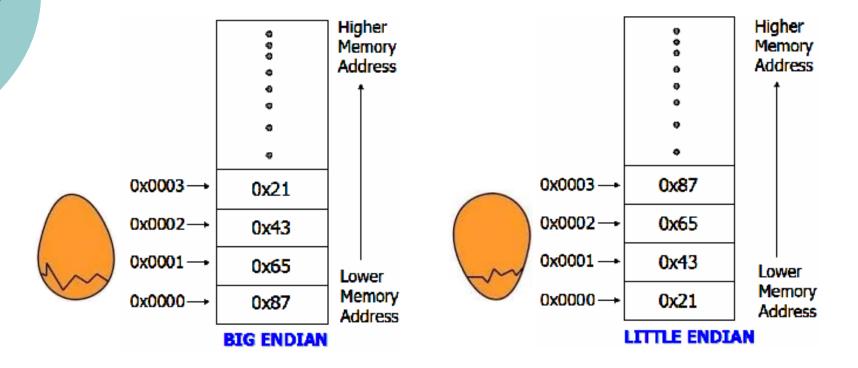
- How a multiple byte data word stored in memory
- Big Endian
 - Most significant byte of a multi-byte word is stored at lowest memory address (e.g. Sun Sparc, PowerPC)
- Little Endian
 - Least significant byte of a multi-byte word is stored at lowest memory address (e.g. Intel x86)
 - LLL (Least significant in Lowest address)





Example of Endianness

Store 0x87654321 at address 0x0000, byte-addressable





Why Worry?

- Two computers with different byte orders may be communicating
- Failure to account for varying endianness ->
 hard to detect bug
- Read a 32-bit value and store it in a 32-bit register
 - Do I need to know Endianness? (No)
- Endianness only makes sense when you are breaking up a multi-byte quantity



MIPS Registers (revisiting)

Register Number	Mnemonic Name	Conventional Use	Register Number	Mnemonic Name	Conventional Use
\$0	\$zero	Permanently 0	\$24, \$25	\$t8,\$t9	Temporary
\$1	\$at	Assembler Temporary (reserved)	\$26,\$27	\$k0,\$k1	Kernel (reserved for OS)
\$2,\$3	\$v0,\$v1	Value returned by a subroutine	\$28	\$gp	Global Pointer
\$4-\$7	\$a0-\$a3	Arguments to a subroutine	\$29	\$sp	Stack Pointer
\$8-\$15	\$t0-\$t7	Temporary (not preserved across a function call)	\$30	\$fp	Frame Pointer
\$16-\$23	\$s0-\$s7	Saved registers (preserved across a function call)	\$31	\$ra	Return Address

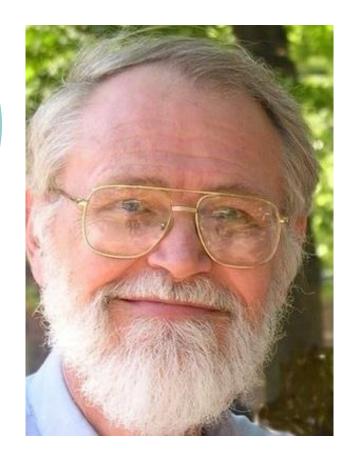


MIPS Processor Summary

- MIPS Registers
- MIPS Instructions
 - Arithmetic (add, sub, mul, div)
 - Data Transfer (load & store)
 - Logical & Shift
 - Program Control (conditional/ unconditional)
- Subroutine Call/ Return
- MIPS Instruction Encoding
- MIPS Addressing Modes
- Other issues:
 - Endianness, Big Immediate, Byte/Halfword Ops, System Calls







Debugging is twice as hard as writing the code in the first place. Therefore, if you write the code as cleverly as possible, you are, by definition not smart enough to debug it. Brian Karnighan



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