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Ex9

Task 1)

@ KKT conditions:

1. Primal feasibility: $g_p(x_1, x_2) = x_1 + 2x_2 - 3 = 0$ ①

2. Dual feasibility: $\lambda \geq 0$

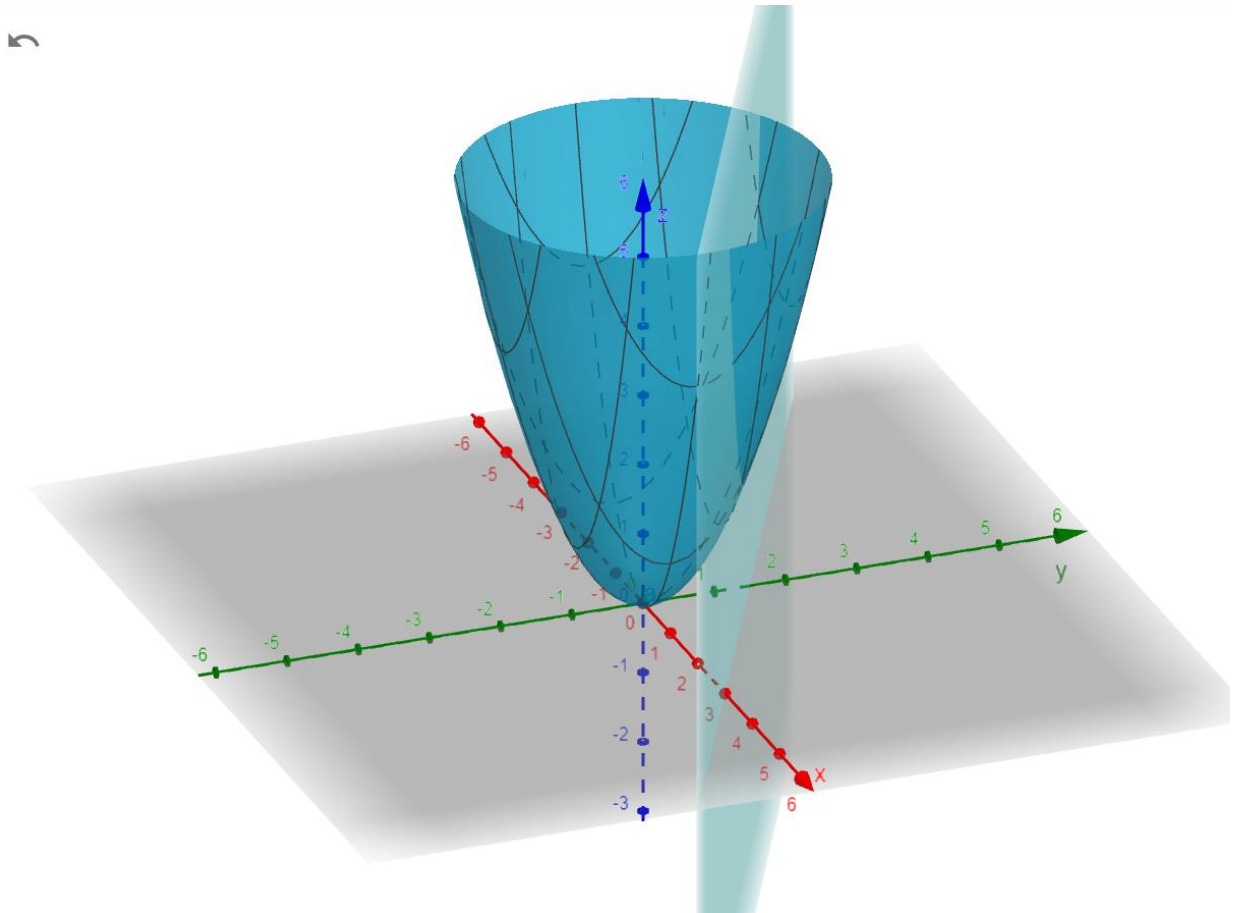
3. Complementary slackness: $\lambda \nabla h_q = 0 \quad \forall q$ $\left\{ \begin{array}{l} \rightarrow \text{Since we don't have inequality} \\ \text{constraints, these are satisfied!} \end{array} \right.$

4. Stationarity: $\nabla f(x) + \sum_p v_p \nabla g_p(x) + \sum_q \lambda_q \nabla h_q(x) = 0$

$$\Rightarrow \begin{pmatrix} 2x_1 \\ 2x_2 \end{pmatrix} + v \begin{pmatrix} 1 \\ 2 \end{pmatrix} = 0 \Rightarrow \begin{cases} 2x_1 + v = 0 & \text{②} \\ 2x_2 + 2v = 0 & \text{③} \end{cases}$$

From ①, ②, ③ we get the optimum solution $x^* = \left(\frac{3}{5}, \frac{6}{5}\right), v^* = -\frac{6}{5}$

The function is plotted as below. And we can find the solution based on the graphics.



$$\textcircled{b} \quad L(u, v, \lambda) = f(u) + \sum_{p=1}^P v_p g_p(u) + \sum_{q=1}^Q \lambda_q h_q(u)$$

$$= u_1 + u_2 + (u_1 - u_2 - 2)v - \lambda_1 u_1 - \lambda_2 u_2 = 0$$

$$\nabla_u L = \begin{pmatrix} 1 + v - \lambda_1 \\ 1 - v - \lambda_2 \end{pmatrix} = 0 \quad \text{and} \quad f(u) \text{ is unbounded}$$

and based on a theorem, if the primal is unbounded, the dual is infeasible.

Task 2)

$$L(u, \lambda, v) = f_0(u_1, u_2) + v h(u_1, u_2) + \lambda f_1(u_1, u_2)$$

$$= u_1^2 + u_2^2 + v(u_2 - 2u_1 - 0.5) + \lambda(u_1 + u_2 - 1)$$

$$\nabla_u L = \begin{pmatrix} 2u_1 - 2v + \lambda \\ 2u_2 + v + \lambda \end{pmatrix} = 0 \Rightarrow u^* = \left(\frac{2v - \lambda}{2}, \frac{-v - \lambda}{2} \right)$$

$$\Rightarrow L(u^*, \lambda, v) = \left(\frac{2v - \lambda}{2} \right)^2 + \left(\frac{-v - \lambda}{2} \right)^2 + v \left(\frac{-v - \lambda}{2} - 2 \left(\frac{2v - \lambda}{2} \right) - 0.5 \right) + \lambda \left(\frac{2v - \lambda}{2} + \frac{-v - \lambda}{2} - 1 \right)$$

$$= \frac{5v^2 - 2v\lambda + 2\lambda^2}{4} + \frac{-5v^2 + \lambda v - v + \lambda v - 2\lambda^2 - 2\lambda}{2}$$

$$= \frac{-5v^2 + 2v\lambda - 2\lambda^2 - 2v - 4\lambda}{4} =$$

Hence the dual problem is: $\max_{v, \lambda} g(v, \lambda) = \left(\frac{-16}{9}, \frac{-44}{9} \right)$

$$g(v, \lambda) = -\frac{5v^2}{4} + \frac{v\lambda}{2} - \frac{\lambda^2}{2} - \frac{v}{2} - \frac{\lambda}{2}$$

$$\lambda \geq 0$$