# Amirhossein Kazerouni

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### Education

#### Iran University of Science and Technology (IUST)

Tehran, Iran

B.S. IN ELECTRICAL ENGINEERING

Sep. 2017 - Feb. 2022

- **GPA:** 17.95/20 (3.85/4)
- Thesis topic: Design, Simulation, and Construction of an Autonomous Vehicle with Environment Perception, Planning, and Control Capabilities. (Thesis Grade: 20/20) Supervisor: Dr. Saeed Shamaghdari

### **Publications**

Moein Heidari\*, Amirhossein Kazerouni\*, Milad Soltany\*, Reza Azad, Ehsan Khodapanah Aghdam, Julien Cohen-Adad, and Dorit Merhof (2022).

HiFormer: Hierarchical multi-scale representations using transformers for medical image segmentation. arXiv preprint arXiv:2207.08518 (Link, PDF)

Milad Soltany Kadarvish\*, Hesam Mojtahedi\*, Hossein Entezari Zarch\*, **Amirhossein Kazerouni\***, Alireza Morsali, Azra Abtahi, and Farokh Marvasti (2021). **Ensemble Neural Representation Networks**. *arXiv preprint arXiv:2110.04124* (**Link**, **PDF**)

Amirhossein Kazerouni, Amirhossein Heydarian, Milad Kadarvish, Aida Mohammadshahi, Abbas Omidi, and Saeed Ebadollahi (2022). An Intelligent Modular Real-Time Vision-Based System for Environment Perception. *Under review* 

Reza Azad, **Amirhossein Kazerouni**, Moein Heidari, Abin Jose, Ehsan Khodapanah Aghdam, Yiwei Jia, Amirali Molaei, Rijo Roy, Johannes Stegmaier, Ehsan Adeli, and Dorit Merhof (2022). **Medical Image Analysis with Transformers: A Review**. *Prepared for submission* (**Paper list**)

### Research Interests

- Computer Vision
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- Deep Learning
- Machine Learning
- Computer Graphics

- Medical Image Processing
- Autonomous Vehicles
- Transformers
- Neural Representations

### Honors & Awards

| 2022 | Ranked 3rd among 41 students who chose Control as a subfield                   | IUST, Iran                      |
|------|--|---------------------------------|
| 2022 | Ranked 4th among 127 Electrical Engineering students                           | IUST, Iran                      |
| 2021 | Ranked 1st team in the national Rahneshan competitions for autonomous vehicles | INEF, Iran                      |
| 2021 | Ranked 2nd team in FIRA World Cup Competitions in Autonomous Cars League       | FIRA, Iran                      |
| 2015 | Ranked 1st team in the A-lympiad National Mathematical Competition             | Iran                            |
| 2016 | Hold a diploma from the A-lympiad World Mathematical Competition               | Utrecht University, Netherlands |
| 2017 | Ranked within the top 1% among approximately 148,000 participants in the       | Iran                            |
|      | National University Entrance Exam  | nan                             |

### Skills

**Programming** Python, MATLAB, C/C++, Latex, Familiar with HTML, CSS, PHP

**Al Tools/ Libraries** PyTorch, TensorFlow, OpenCV, NPM (NumPy - Pandas - Matplotlib), etc.

**Tools** Linux, Git

### Research Experience \_\_\_\_\_

Research Assistant Aachen, Germany

RWTH AACHEN UNIVERSITY — SUPERVISOR: DR. DORIT MERHOF AND REZA AZAD

- Worked on Transformer models which resulted in one conferance paper and one survey paper.
- Currently, I am working on using Diffusion Models in the medical field.

2022 - Present

<sup>\*</sup> denotes equal contribution.

**Machine Learning and Computer Vision Researcher** 

Montreal, Canada

DGSCULPTOR 2021 - Present

 Worked on the "Ensemble Neural Representation Networks" paper and proposed a novel suboptimal ensemble architecture for Implicit Neural Representation (INR).

• Currently, I am working on using Transformers for Super-Resolution.

Al Researcher IUST, Irai

Al and Control Lab — Supervisor: Dr. Saeed Shamaghdari

2019 - 2021

• Worked on "Fusion-Based 3D Shape Analysis in a Noisy Environment" project.

University of Tehran — Supervisor: Dr. Mohammad Ali Akhaee, Associate Professor at the University of Tehran

2019 - 2020

INEF, University of Tehran, Tehran

· Worked on "Statistical and Semantic Analysis of Football Game" project.

### **Teaching Experience**

### Teaching Assistant of "Principles of Mechatronics"

IUST, Iran

INSTRUCTOR: DR. SAEED SHAMAGHDARI

**Computer vision Researcher** 

Spring 2021

### **Working Experience**

CEO and Co-founder

AIR (ARTIFICIAL INTELLIGENCE AND ROBOTICS) CENTER

2020 - Present

· Teaching and mentoring Deep Learning, Machine Learning, and Python courses.

### **Major Projects**

#### Autonomous Vehicle Environment Perception (Link, GitHub)

INEF, Iran

NATIONAL RAHNESHAN COMPETITIONS

2021

• Designed and coded an environmental perception system for autonomous vehicles.

### Automatic Parallel Parking (Link, GitHub)

INEF, Iran

NATIONAL RAHNESHAN COMPETITIONS

2021

· Implemented a parallel parking system that includes path planning, path tracking, and parallel parking.

#### Statistical and Semantic Analysis of Football Game (Link, GitHub, Website)

INEF, Iran

SUPERVISOR: DR. MOHAMMAD ALI AKHAEE

2019 - 2020

- Created the bird's eye view of the soccer field by predicting the homography matrix using GANs.
- Created a Telegram bot with PHP to collect voice data to create a voice spotting dataset.

#### Fusion-Based 3D Shape Analysis in a Noisy Environment Using Stereo Camera (Link)

IUST, Iran

SUPERVISOR: DR. SAEED SHAMAGHDARI

2019 - 2021

Proposed a fusion-based multi-stage approach that performs 3D shape analysis on vehicles to measure the amount of load protrusion.

## Design, Simulation, and Construction of an Autonomous Vehicle with Environment Perception, Planning, and Control Capabilities (Link)

IUST, Iran Sep. 2021

SUPERVISOR: DR. SAEED SHAMAGHDARI

Designed and built a toy self-driving car from scratch.

#### Autonomous Car Simulation Based on AVIS Engine (Link, GitHub)

IUST, Iran

FIRA WORLD CUP COMPETITIONS

Summer 2021

• Developed an autonomous car having control and environment perception capabilities.

#### Persian-OCR (Link, GitHub)

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PERSONAL PROJECT Mar. 2021 - Jun. 2021

• Developed software in Python that lets you label your desired language words with Al.

### Languages\_

English IELTS (Academic): (Listening: 8, Reading:7, Speaking:6.5, Writing:6.5, Overall:7), C1 Proficiency

Persian Native