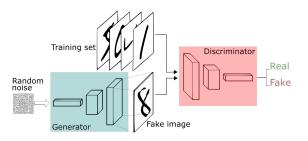
Generative Modeling by Estimating Gradients of the Data Distribution

Yang Song, Stefano Ermon

David Zimmerer Medical Image Analysis (#MIA-san-mia) DKFZ

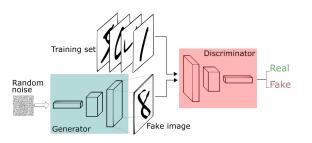


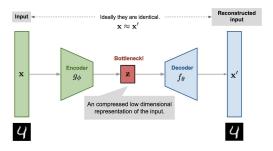




GANs

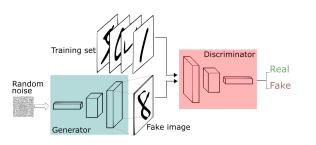


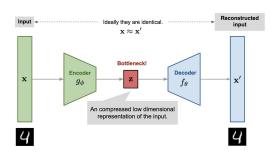


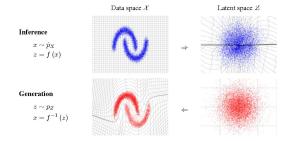


GANs VAEs

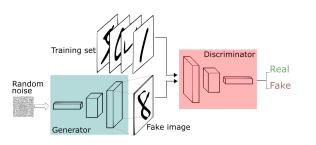


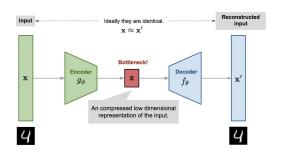


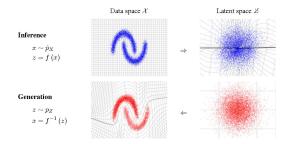




GANs VAEs Flows

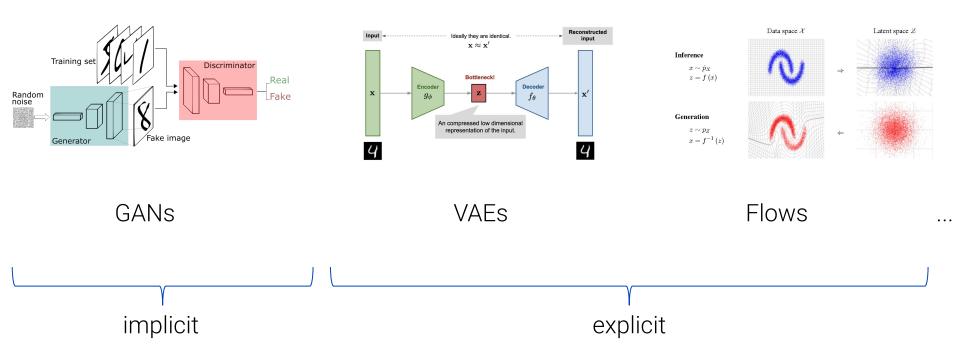


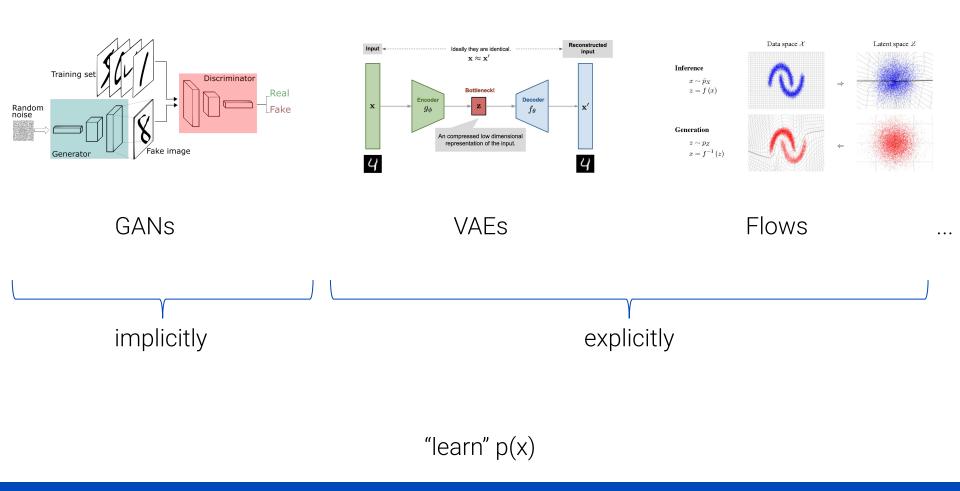




GANS VAES Flows ...





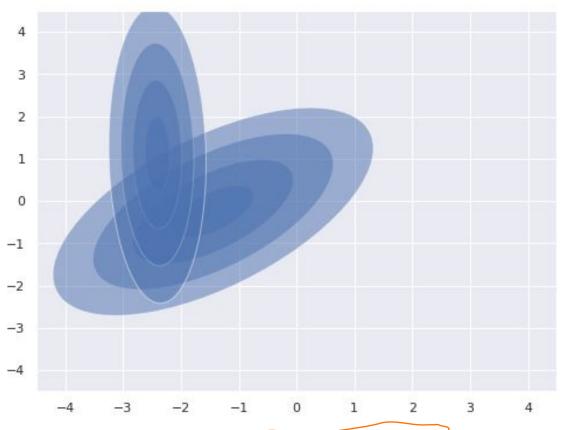


"New" Idea:

Generative Modeling by Estimating Gradients of the Data Distribution

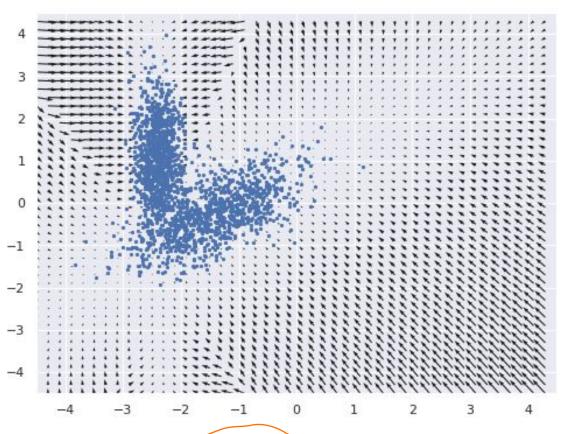


"New" Idea: Generative Modeling by Estimating Gradients of the Data Distribution



Instead of learning the data distribution directly....

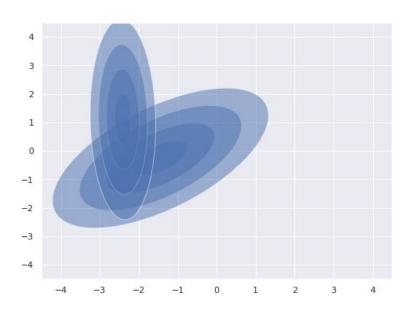
"New" Idea: Generative Modeling by Estimating Gradients of the Data Distribution

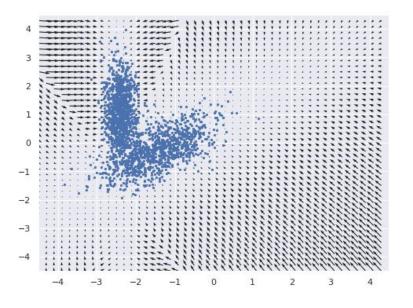


...we learn the gradients of the data distribution



"New" Idea: Generative Modeling by Estimating Gradients of the Data Distribution







 $ightarrow
abla_{\mathbf{x}} \log p(\mathbf{x})$ i.e. the Gradient of the Data Distribution a.k.a score



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Score matching^[1]:

$$\frac{1}{2}\mathbb{E}_{p_{\text{data}}}[\|\mathbf{s}_{\boldsymbol{\theta}}(\mathbf{x}) - \nabla_{\mathbf{x}} \log p_{\text{data}}(\mathbf{x})\|_{2}^{2}]$$



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equivalent up to a constant to:

$$\mathbb{E}_{p_{\text{data}}(\mathbf{x})} \left[\operatorname{tr}(\nabla_{\mathbf{x}} \mathbf{s}_{\boldsymbol{\theta}}(\mathbf{x})) + \frac{1}{2} \left\| \mathbf{s}_{\boldsymbol{\theta}}(\mathbf{x}) \right\|_{2}^{2} \right]$$



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→ So what's new?

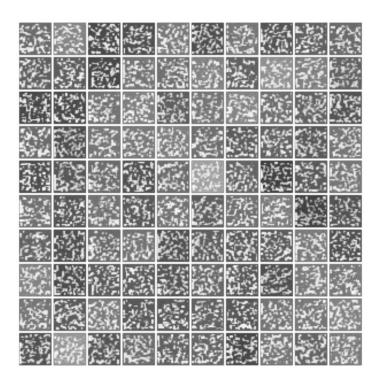




Trivial Implementation (on MNIST)

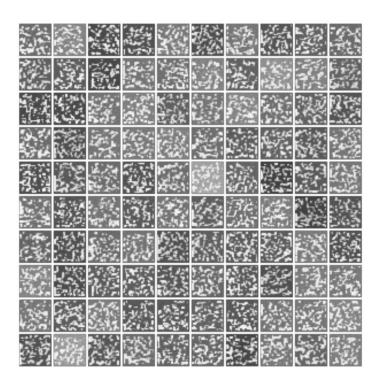


Trivial Implementation (on MNIST)





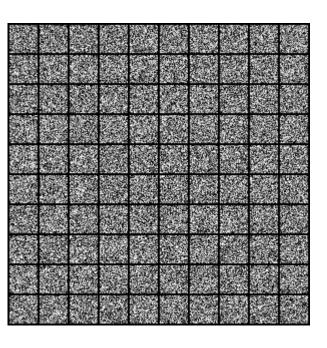
Trivial Implementation (on MNIST)





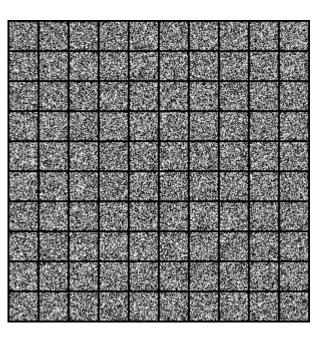


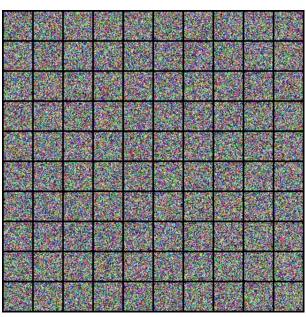






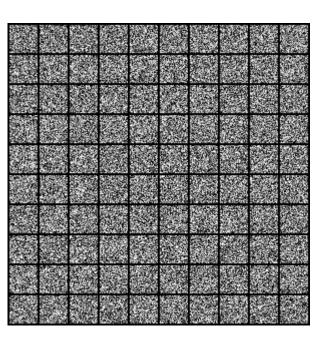


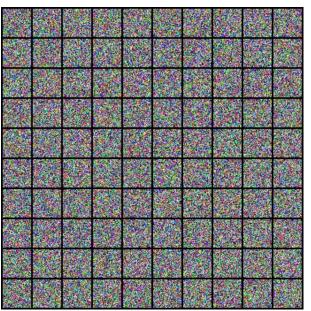


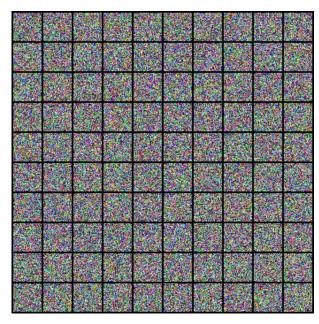


















1. No Support (everywhere)



No Support (everywhere)
 i.e. p(x) not defined and thus gradient not defined



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 - → Solution: Add Gaussian Noise

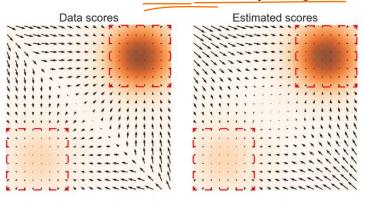


- No Support (everywhere)
 i.e. p(x) not defined and thus gradient not defined
 - → Solution: Add Gaussian Noise
- 2. Inaccurate score estimation in low density regions



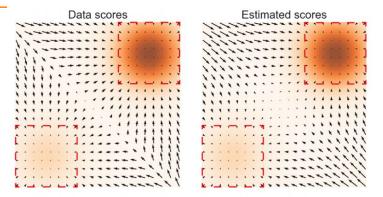
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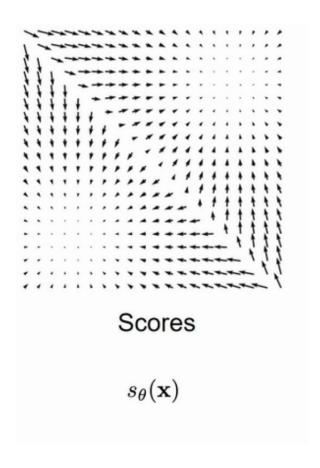


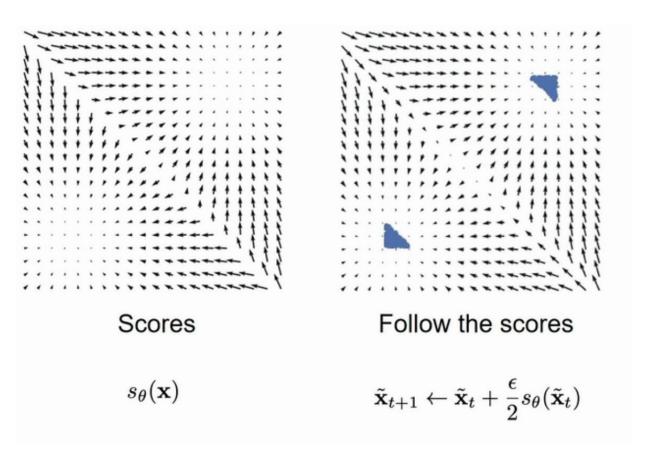
→ Solution add noise at different magnitudes

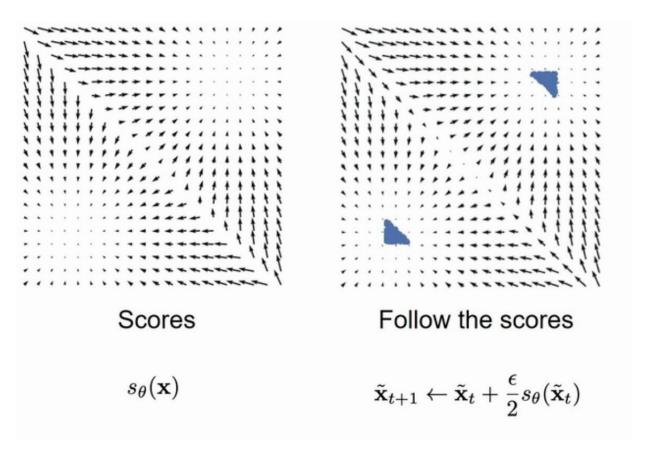
(large noise: filling low density regions, small noise: fine-adjustments in high density regions)





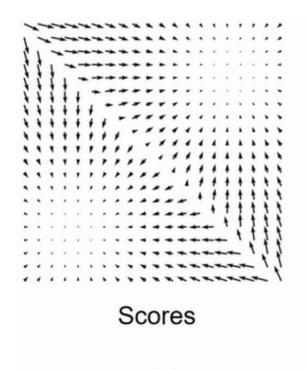




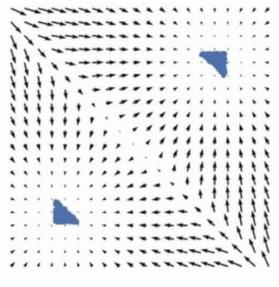


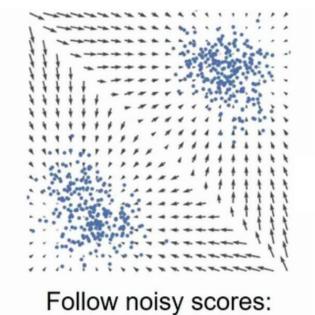






 $s_{\theta}(\mathbf{x})$



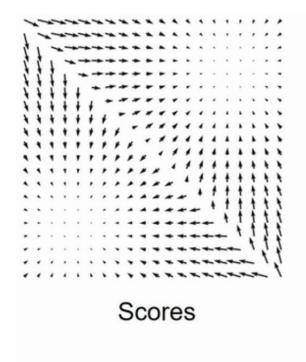


Follow the scores

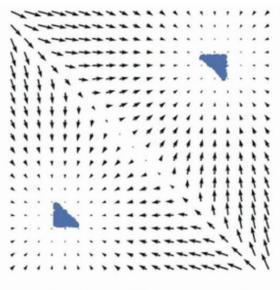
$$\tilde{\mathbf{x}}_{t+1} \leftarrow \tilde{\mathbf{x}}_t + \frac{\epsilon}{2} s_{\theta}(\tilde{\mathbf{x}}_t)$$

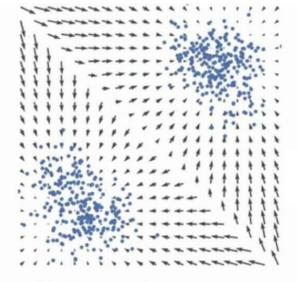
Langevin dynamics $\mathbf{z}_t \sim \mathcal{N}(0, I)$ $\tilde{\mathbf{x}}_{t+1} \leftarrow \tilde{\mathbf{x}}_t + \frac{\epsilon}{2} s_{\theta}(\tilde{\mathbf{x}}_t) + \sqrt{\epsilon} \mathbf{z}_t$

How to sample:



 $s_{\theta}(\mathbf{x})$





Follow the scores

$$\tilde{\mathbf{x}}_{t+1} \leftarrow \tilde{\mathbf{x}}_t + \frac{\epsilon}{2} s_{\theta}(\tilde{\mathbf{x}}_t)$$

Follow noisy scores: Langevin dynamics

$$\tilde{\mathbf{z}}_{t} \sim \mathcal{N}(0, I)$$

$$\tilde{\mathbf{x}}_{t+1} \leftarrow \tilde{\mathbf{x}}_{t} + \frac{\epsilon}{2} s_{\theta}(\tilde{\mathbf{x}}_{t}) + \sqrt{\epsilon} \mathbf{z}_{t}$$

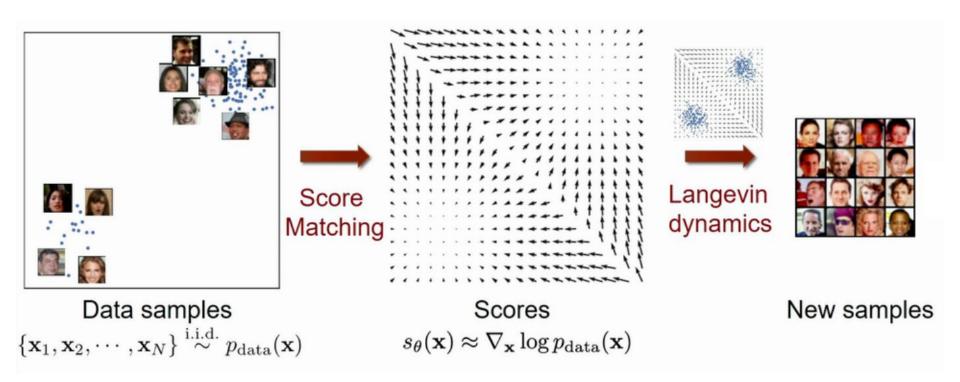




Approach



Approach



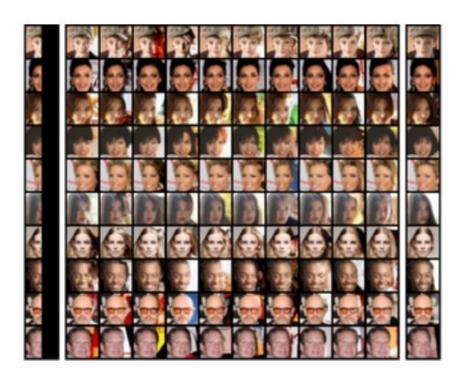
Results



Results: Qualitative



Results: Qualitative







Results: Quantitative

Model	Inception	FID
CIFAR-10 Uncondition	nal	
PixelCNN [59]	4.60	65.93
PixelIQN [42]	5.29	49.46
EBM [12]	6.02	40.58
WGAN-GP [18]	$7.86 \pm .07$	36.4
MoLM [45]	$7.90 \pm .10$	18.9
SNGAN [36]	$8.22 \pm .05$	21.7
ProgressiveGAN [25]	$8.80 \pm .05$	-
NCSN (Ours)	$8.87 \pm .12$	25.32
CIFAR-10 Conditiona	ıl	
EBM [12]	8.30	37.9
SNGAN [36]	$8.60 \pm .08$	25.5
BigGAN [6]	9.22	14.73

→ NeurIPS 2019 - Reproducibility Challenge^[2]



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Reproducible?



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Reproducible?



Hyper-parameter insensitive?



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Hyper-parameter insensitive?





The End

