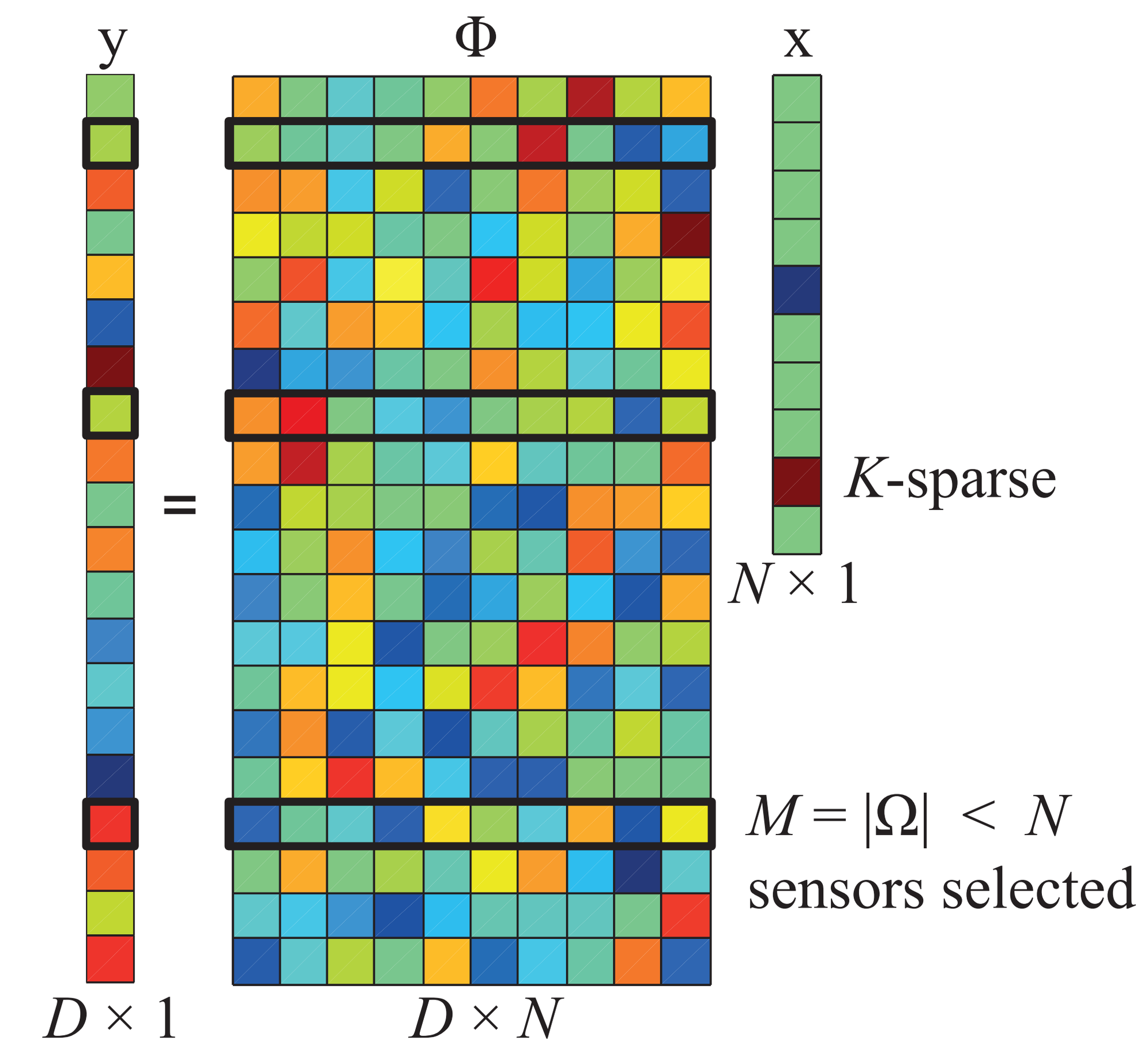
y
Φ
x
=
K-sparse
N × 1
M = |Ω| < N
sensors selected
D × 1
D × N