Bandit-style Geometric decision algorithm against an Adaptive adversary

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Online Geometric Optimization in the Bandit Setting

- Paper Title: Online Geometric Optimization in the Bandit Setting Against an Adaptive Adversary
- Authors: H. Brendan McMahan & Avrim Blum
- Published in: 2004
- Conference: Learning Theory, Springer Berlin Heidelberg

Introduction to Online Optimization

Definition: Online optimization involves making a sequence of decisions based on incoming data, where each decision is made without knowledge of future data.

Two fundamental assumptions in online optimization:

- Bunded Losses: The losses determined by an adversary should not be allowed to be unbounded.
- **2** Bounded Decision Set: The decision set must be somehow bounded and/or structured, though not necessarily finite.

Prediction from Expert Advice

- Prediction from Expert Advice is a framework in online learning and decision-making.
- Involves making sequential predictions by aggregating advice from a set of experts.
- The goal is to perform nearly as well as the best expert in hindsight.

Key Components

- **1 Experts:** Sources that provide predictions or advice.
- **2** Learner (Main Character): Aggregates expert advice to make decisions.
- **Solution Feedback:** Information about the actual outcome to update future predictions.
- Objective: Minimize the difference between the learner's performance and the best expert's performance.

Family Members as Experts

- Main character decides whether to take an umbrella each day.
- Three family members act as **experts** providing daily weather predictions, the father, mother, and brother.



Figure: Family Members as Experts

Table: Daily Weather Predictions and Outcomes

Day	Father	Mother	Brother	Actual Weather
1	No Rain	No Rain	Rain	Rain

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Cost	2	4	3	-

Weighted Majority Algorithm

• Mechanism:

- Assigns a weight to each expert based on their past performance.
- Aggregates predictions by considering these weights.
- Updates weights multiplicatively based on the correctness of experts' predictions.

Applications:

- Ensemble learning in machine learning.
- Financial decision-making.

How Weighted Majority Works

Algorithm Steps:

- **1 Initialization:** Assign equal weights to all experts.
- Prediction

Prediction = sign
$$\left(\sum_{i=1}^{N} w_t(i) \cdot \text{Prediction}_t(i)\right)$$

3 Update Weights: After observing the outcome, update weights:

$$w_{t+1}(i) = \begin{cases} w_t(i) & \text{if expert } i \text{ was correct} \\ w_t(i) \cdot \varepsilon & \text{if expert } i \text{ was incorrect} \end{cases}$$

1 Iteration: Repeat the prediction and update steps for each round.

Parameters:

- N: Number of experts.
- $\varepsilon \in (0,1)$: Penalty factor for incorrect experts.

Regret Bound for Weighted Majority

Lemma : Denote by M_t the number of mistakes the algorithm makes until time t, and by $M_t(i)$ the number of mistakes made by expert i until time t. Then, for any expert $i \in [N]$ we have

$$M_T \le 2(1+\varepsilon)M_T(i) + \frac{2\log N}{\varepsilon}$$

Corollary: The regret of the WM algorithm is bounded by

$$M_T \le 2M_T(i^*) + O(\sqrt{M_T(i^*)logN})$$

where i^* is the best expert.

Proof: Just let
$$\varepsilon^* = \sqrt{\frac{logN}{M_T(i^*)}}$$
.

Regret Bound Proof

Proof:

- Let $\phi_t = \sum_{i=1}^N w_i(t)$. Note that $\phi_1 = N$.
- If the prediction is wrong, then $\phi_{t+1} \leq \frac{1}{2}\phi_t(1-\varepsilon) + \frac{1}{2}\phi_t$.
- Thus $\phi_t \leq \phi_1 (1 \varepsilon)^{M_t} = N(1 \varepsilon)^{M_t}$.
- By definition, $w_T(i) = (1 \varepsilon)^{M_T(i)}$. Also $w_t(i) \le \phi_t$.
- $(1-\varepsilon)^{M_T(i)} \le N(1-\varepsilon)^{M_T} \to M_T(i)log(1-\varepsilon) \le logN + M_Tlog(1-\varepsilon)$.
- Using the fact that $-x x^2 \le log(1-x) \le -x$ for $x \in (0,1)$, we get:

$$-M_T(i)(\varepsilon + \varepsilon^2) \le \log N - M_T \frac{\varepsilon}{2} \to M_T \le 2(1+\varepsilon)M_T(i) + \frac{2\log N}{\varepsilon}$$



Randomized Weighted Majority Algorithm

- Algorithm Steps:
 - **1** Initialization: Set $w_1(i) = 1$ for all experts.
 - Probability Assignment:

$$P_t(i) = \frac{w_t(i)}{\sum_{j=1}^{N} w_t(j)}$$

- **3** Expert Selection: Choose expert i with probability $P_i(t)$.
- Prediction and Update: Make prediction based on selected expert and update weights as in Weighted Majority.
- Better Regret Bound:

$$\mathbb{E}[M_T] \le (1+\varepsilon)M_T(i^*) + \frac{\log N}{\varepsilon}$$



RWM Regret Bound Proof

Proof: Let $\phi_t = \sum_{i=1}^N w_i(t)$ and \tilde{m}_t be an indicator variable for the event that the prediction is wrong at time t and $\tilde{m}_t(i) = 1$ if expert i is wrong at time t.

• Note that

$$\phi_{t+1} = \sum_{i=1}^{N} w_i(t)(1 - \varepsilon \tilde{m}_t(i)) = \phi_t(1 - \varepsilon \sum_{i=1}^{N} P_t(i)\tilde{m}_t(i))$$
$$= \phi_t(1 - \varepsilon \mathbb{E}[\tilde{m}_t]) \le \phi_t e^{-\varepsilon \mathbb{E}[\tilde{m}_t]}$$

• With the same argument as in the WM proof, we get:

$$(1 - \varepsilon)^{M_T(i)} \leq Ne^{-\varepsilon M_T}$$

$$\to M_T(i)log(1 - \varepsilon) \leq logN - \varepsilon \mathbb{E}[M_T]$$

$$\to -M_T(\varepsilon + \varepsilon^2) \leq logN - \varepsilon \mathbb{E}[M_T]$$

$$\to \mathbb{E}[M_T] \leq (1 + \varepsilon)M_T(i^*) + \frac{logN}{\varepsilon}$$

Introduction to Multi-Armed Bandit Algorithms

• **Definition:** A framework for making a sequence of decisions under uncertainty, aiming to maximize cumulative rewards.

• Key Concepts:

- Exploration: Trying different actions to gather more information.
- Exploitation: Selecting the best-known action to maximize immediate reward.

• Types of Bandit Problems:

- Stochastic Bandits: Rewards are drawn from fixed probability distributions.
- Contextual Bandits: Incorporates contextual information to make more informed decisions.

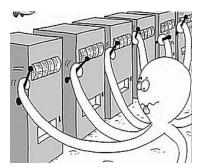
Applications:

- Recommendation Systems
- Clinical Trials
- Online Advertising



Bandit Algorithms in Online Advertising

- Use Case: Optimizing Ad Selection to Maximize CTR
- How It Works:
 - Each ad variant is considered an arm of the bandit.
 - The algorithm dynamically selects which ad to display based on past performance.
 - Balances exploration (trying new ads) with exploitation (showing top-performing ads).



Online Optimization vs. Bandit Algorithms

Both online optimization and bandit algorithms involve sequential decisions, but differ in feedback and objectives.

Online Optimization

- Full Feedback: Receives complete information about all possible actions after each decision.
- Objective: Minimize cumulative loss compared to the best fixed decision in hindsight.

Bandit Algorithms

- Partial Feedback: Only receives feedback for the action actually taken, not for all possible actions.
- Objective: Balance exploration and exploitation to maximize cumulative rewards.

Adaptive vs. Oblivious Adversaries

Oblivious Adversary

- **Definition:** Fixes the sequence of events beforehand.
- Traits:
 - Non-responsive.
 - Simpler to analyze.



Adaptive Adversary

- **Definition:** Adjusts based on algorithm's past actions.
- Traits:
 - Responsive and dynamic.
 - Harder to counter.



Introducing Follow the Perturbed Leader (FPL)

• Overview:

• FPL is a randomized online algorithm that minimizes regret in adversarial settings by adding noise to each expert's cumulative loss and selecting the leader with the lowest perturbed loss.

• Algorithm Steps:

- **1** Initialization: Set cumulative loss $L_i(0) = 0$ for all experts i.
- **2** For each round $t = 1, 2, \ldots, T$:
 - **Quantization:** Draw a random perturbation γ_i for each expert i from a specified distribution (e.g., exponential).
 - **② Leader Selection:** Choose the expert i^* with the minimum $L_i(t-1) + \gamma_i$.
 - **3 Decision:** Follow the prediction of expert i^* .
 - **① Update:** Update the cumulative loss $L_i(t) = L_i(t-1) + \ell_i(t)$ for each expert.

Why Perturbation?

Table: Daily Weather Predictions, Outcomes, and Probability of Mistake using Random Weighted Majority

Day	Father	Mother	P of Mistake	Actual Weather
1	Rain	No Rain	$\frac{1}{2}$	Rain
2	Rain	No Rain	$\frac{1}{2}$	No Rain
3	Rain	No Rain	$\frac{1}{2}$	Rain
4	Rain	No Rain	$\frac{\overline{1}}{2}$	No Rain
5	Rain	No Rain	$\frac{1}{2}$	Rain

Regret Bound for GEX

Lemma: Let $S \subseteq \mathbb{R}^n$ be a set of (not necessarily positive) decisions, and $k^t = [\mathbf{c}^1, \dots, \mathbf{c}^T]$ a set of cost vectors on those decisions, such that $|\mathbf{c}^t \cdot \mathbf{x}| \leq R$ for all $\mathbf{x} \in S$ and $\mathbf{c}^t \in k^t$. Then, there is an algorithm $\mathcal{A}(\varepsilon)$ that achieves

$$E[\operatorname{loss}(\mathcal{A}(\varepsilon), k^t)] \le \operatorname{OPT}(k^t) + \varepsilon (4n+2)R^2T + \frac{4n}{\varepsilon}$$

Use your Maximum Power

In general, oblivious adversaries are easier to handle than adaptive adversaries. However, we can convert an oblivious adversary to an adaptive by being pessimistic.



Figure: An evil adversary in machine learning using its maximum power

Regret Bound for Any Adversary

Lemma: Fix T, let H^* be the set of decision histories of length 0 to T-1, and let K^* be the set of all cost histories of length 0 to T-1. Then, fix a decision algorithm $\mathcal{A}: K^* \to \Delta(S)$, where $\Delta(S)$ is the set of probability distributions on the set S of possible decisions. Define

$$R(\mathcal{A}, \mathcal{V}) = \mathbb{E}_{\mathcal{A}, \mathcal{V}} \left[\sum_{t=1}^{T} \mathbf{c}^{t} \cdot \mathbf{x}^{t} - \min_{\mathbf{x} \in S} \sum_{t=1}^{T} \mathbf{c}^{t} \cdot \mathbf{x} \right].$$

Let $\mathcal V$ be an arbitrary adversary. Then, there exists an oblivious adversary $\mathcal V'$ such that

$$R(\mathcal{A}, \mathcal{V}') \ge R(\mathcal{A}, \mathcal{V}).$$

Exploration and Exploitation

Now that we have a way to convert an oblivious adversary to an adaptive one, we can focus on using online optimization algorithms to solve bandit problems.

- Exploration: Use the perturbation or other methods to explore different experts and their predictions.
- Exploitation: Follow the leader to exploit the best-performing expert.



Figure: Exploration vs. Exploitation in Bandit Algorithms

Usage of Basis

- **Definition:** A basis $B = \{\mathbf{b}_1, \dots, \mathbf{b}_n\}$ is a set of linearly independent vectors that span a vector space.
- Advantages:
 - Reduces the problem of exploring an infinite set to exploring a finite set.
 - Simplifies the decision-making process.
- Dimention: At most n.

Problem Formulation

Table: Summary of notation

$S \subseteq \mathbb{R}^n$	set of decisions, a compact subset of \mathbb{R}^n
$D \in \mathbb{R}$	L_1 bound on diameter of $S, \forall \mathbf{x}, \mathbf{y} \in S, \mathbf{x} - \mathbf{y} _1 \leq D$
$n \in \mathbb{N}$	dimension of decision space
$\mathcal{V}:H^* o\mathbb{R}^n$	adversary, function from decision histories to cost vectors
\mathcal{A}	an online optimization algorithm
$\mathbf{c}^t \in \mathbb{R}^n$	cost vector on time t
$\hat{\mathbf{c}}^t \in \mathbb{R}^n$	BGA's estimate of the cost vector on time t
$M \in \mathbb{R}^+$	bound on single-iteration cost, $ \mathbf{c}^t \cdot \mathbf{x}^t \leq M$
$B \subseteq S$	sampling basis $B = \{\mathbf{b}_1, \dots, \mathbf{b}_n\}$
$\ell^t \in [-M, M]^n$	vector, $\ell_i^t = \mathbf{c}^t \cdot \mathbf{b}_i$ for $\mathbf{b}_i \in B$
$\hat{\ell}^t \in \mathbb{R}^n$	BGA's estimate of ℓ^t
$T \in \mathbb{N}$	end of time, index of final iteration
$\mathbf{x}^t \in S$	BGA's decision on time t
$\tilde{\mathbf{x}}^t \in S$	decision recommended by GEX on time t
$\chi^t \in \{0, 1\}$	indicator, $\chi^t = 1$ if BGA explores on t, 0 otherwise
$\gamma \in [0,1]$	the probability BGA explores on each timestep
$\tilde{z}^t \in [-R, R]$	loss of GEX, $\tilde{z}^t = \hat{\mathbf{c}}^t \cdot \tilde{\mathbf{x}}^t$

Bandit-style Geometric decision algorithm against an Adaptive adversary

Algorithm BGA

```
1: Choose parameters \gamma and \epsilon, where \epsilon is a parameter of GEX
2: t = 1
3: Fix a basis B = \{\mathbf{b}_1, \dots, \mathbf{b}_n\} \subseteq S
4: while playing do
          Let \chi^t = 1 with probability \gamma and \chi^t = 0 otherwise
5:
6:
          if \chi^t = 0 then
7:
               Select \mathbf{x}^t from the distribution GEX(\hat{\mathbf{c}}^1, \dots, \hat{\mathbf{c}}^{t-1})
8:
               Incur cost z^t = \mathbf{c}^t \cdot \mathbf{x}^t
9:
               \hat{\mathbf{c}}^t = 0 \in \mathbb{R}^n
10:
           else
                Draw j uniformly at random from \{1, \ldots, n\}
11:
12:
                \mathbf{x}^t = \mathbf{b}_i
                Incur cost and observe z^t = \mathbf{c}^t \cdot \mathbf{x}^t
13:
                Define \hat{\ell}^t by \hat{\ell}_i^t = 0 for i \neq j and \hat{\ell}_i^t = (n/\gamma)z^t
14:
15:
                \hat{\mathbf{c}}^t = (B^\top)^{-1} \hat{\ell}^t
16:
           end if
17:
           \hat{\mathbf{c}}^{1:t} = \hat{\mathbf{c}}^{1:t-1} + \hat{\mathbf{c}}^t
18:
       t = t + 1
19: end while
```

Initialization:

- Choose parameters γ and ϵ , where ϵ is a parameter of GEX.
- Set $t \leftarrow 1$.
- Fix a basis $B = \{\mathbf{b}_1, \dots, \mathbf{b}_n\} \subseteq S$.

- Initialization:
 - Choose parameters γ and ϵ , where ϵ is a parameter of GEX.
 - Set $t \leftarrow 1$.
 - Fix a basis $B = \{\mathbf{b}_1, \dots, \mathbf{b}_n\} \subseteq S$.
- Main Loop: While playing do
 - Let $\chi^t = 1$ with probability γ and $\chi^t = 0$ otherwise.

Initialization:

- Choose parameters γ and ϵ , where ϵ is a parameter of GEX.
- Set $t \leftarrow 1$.
- Fix a basis $B = \{\mathbf{b}_1, \dots, \mathbf{b}_n\} \subseteq S$.
- Main Loop: While playing do
 - Let $\chi^t = 1$ with probability γ and $\chi^t = 0$ otherwise.
 - If $\chi^t = 0$ then
 - Select \mathbf{x}^t from the distribution GEX($\hat{\mathbf{c}}^1, \dots, \hat{\mathbf{c}}^{t-1}$).
 - Incur cost $z^t = \mathbf{c}^t \cdot \mathbf{x}^t$.
 - Set $\hat{\mathbf{c}}^t = \mathbf{0} \in \mathbb{R}^n$.

Else

- Draw j uniformly at random from $\{1, \ldots, n\}$.
- Set $\mathbf{x}^t = \mathbf{b}_i$.
- Incur cost and observe $z^t = \mathbf{c}^t \cdot \mathbf{x}^t$.
- Define $\hat{\ell}^t$ by:
 - $\hat{\ell}_i^t = 0$ for all $i \neq j$.
 - $\bullet \ \hat{\ell}_j^t = \left(\frac{n}{\gamma}\right) z^t.$
- Set $\hat{\mathbf{c}}^t = (B^\top)^{-1} \hat{\ell}^t$.

Else

- Draw j uniformly at random from $\{1, \ldots, n\}$.
- Set $\mathbf{x}^t = \mathbf{b}_i$.
- Incur cost and observe $z^t = \mathbf{c}^t \cdot \mathbf{x}^t$.
- Define $\hat{\ell}^t$ by:
 - $\hat{\ell}_i^t = 0$ for all $i \neq j$.
 - $\bullet \ \hat{\ell}_j^t = \left(\frac{n}{\gamma}\right) z^t.$
- Set $\hat{\mathbf{c}}^t = (B^\top)^{-1} \hat{\ell}^t$.
- Update cumulative costs:
 - $\bullet \ \hat{\mathbf{c}}^{1:t} = \hat{\mathbf{c}}^{1:t-1} + \hat{\mathbf{c}}^t.$
 - Increment time step: $t \leftarrow t + 1$.

Regret Bound for BGA

The regret of the BGA algorithm is bounded by

$$E[loss(BGA)] \le (1 - \gamma)E[loss(GEX)] + \gamma MT$$

Intuition: BGA explores with probability γ and exploits with probability $1 - \gamma$.

Order of Regret: It can be shown that the regret of BGA is of order $O(T^{3/4}\sqrt{\ln T})$.

Future Work

- Exploring while Exploiting: I think the exploitation phase has some information that can be used to explore better.
- **2** Hyperparameter Tuning: The parameters γ can be tuned to improve the performance of the algorithm.
- **3 Game Theory:** The algorithm can be viewed as an Stackelberg game. Thus there is a possibility of using game theory.
- **Experiments:** The algorithm hasn't tested on real-world data. It would be interesting to see how it performs in practice.
- **9 Bound Tightening:** Investigate whether the current bounds of $O(T^{3/4}\sqrt{\ln T})$ against adaptive adversaries and $O(T^{2/3})$ against oblivious adversaries can be improved to $O(\sqrt{T})$.

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