

The call `power(5, 3)` would be executed as follows:

```

power(5, 3) finds that 3 is not equal to 0, so it calls
  power(5, 2), which finds that 2 is not equal to 0, so it calls
    power(5, 1), which finds that 1 is not equal to 0, so it calls
      power(5, 0), which finds that 0 is equal to 0, so it returns 1, causing
        power(5, 1) to return  $5 \times 1 = 5$ , causing
          power(5, 2) to return  $5 \times 5 = 25$ , causing
            power(5, 3) to return  $5 \times 25 = 125$ .

```

Incidentally, we can condense the `power` function a bit by putting a conditional expression in the `return` statement:

```

int power(int x, int n)
{
    return n == 0 ? 1 : x * power(x, n - 1);
}

```

Both `fact` and `power` are careful to test a “termination condition” as soon as they’re called. When `fact` is called, it immediately checks whether its parameter is less than or equal to 1. When `power` is called, it first checks whether its second parameter is equal to 0. All recursive functions need some kind of termination condition in order to prevent infinite recursion.

## The Quicksort Algorithm

At this point, you may wonder why we’re bothering with recursion; after all, neither `fact` nor `power` really needs it. Well, you’ve got a point. Neither function makes much of a case for recursion, because each calls itself just once. Recursion is much more helpful for sophisticated algorithms that require a function to call itself two or more times.

In practice, recursion often arises naturally as a result of an algorithm design technique known as *divide-and-conquer*, in which a large problem is divided into smaller pieces that are then tackled by the same algorithm. A classic example of the divide-and-conquer strategy can be found in the popular sorting algorithm known as *Quicksort*. The Quicksort algorithm goes as follows (for simplicity, we’ll assume that the array being sorted is indexed from 1 to  $n$ ):

1. Choose an array element  $e$  (the “partitioning element”), then rearrange the array so that elements  $1, \dots, i-1$  are less than or equal to  $e$ , element  $i$  contains  $e$ , and elements  $i+1, \dots, n$  are greater than or equal to  $e$ .
2. Sort elements  $1, \dots, i-1$  by using Quicksort recursively.
3. Sort elements  $i+1, \dots, n$  by using Quicksort recursively.

After step 1, the element  $e$  is in its proper location. Since the elements to the left of  $e$  are all less than or equal to it, they’ll be in their proper places once they’ve been sorted in step 2; similar reasoning applies to the elements to the right of  $e$ .

Step 1 of the Quicksort algorithm is obviously critical. There are various methods to partition an array, some much better than others. We’ll use a technique