# Amirtha Varshini A S

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## **EDUCATION**

• Georgia Institute of Technology, Atlanta, GA

Master of Science in Computer Science (ML Concentration)

Graduate Teaching Assistant - CS 6603: AI, Ethics and Society

• National Institute of Technology Tiruchirappalli, India

Bachelor of Technology in Electronics and Communication Engineering

Aug. 2021 - May 2023 **GPA:** 4.0/4.0

Jul. 2014 - May 2018

GPA: 8.90/10

# TECHNICAL SKILLS

- Languages: Python, C, C++, C#, SQL, HTML, CSS, JS, PHP, Bash, TCL
- Frameworks: PyTorch, TensorFlow, Scikit-Learn, SciPy, Pandas, Numpy, OpenCV, Linux, QNX, ARM V8, CUDA, Unity3D
- Graduate Coursework: Machine Learning with Limited Supervision, Computer Vision (CV), Deep Reinforcement Learning for Intelligent Control, Graduate Algorithms, ML, Qualitative HCI methods, Deep Learning Specialization (Coursera)

#### EXPERIENCE

• Amazon Robotics, Westborough, MA - Software Engineer Intern

May 2022 - Aug. 2022

- Performed object tracking on packages in a warehouse by integrating with segmented shipping labels returned by AR-ID, an ML, and CV-based solution. Successfully enabled AR-ID to process multiple packages using this tracking.
- Developed an app using Augmented Reality (AR) in Microsoft Hololens 2 to identify the current package picked or stowed, based on the collision of the tracked package's hologram with a spatially anchored hologram mesh.
- Qualcomm, Bengaluru, India Software Engineer

Jul. 2018 - Aug. 2021

- ADAS platform team Designed Minidump feature on QNX Real-time operating system to capture a snapshot of system post-crash. Also built a GDB-based Python and C parser to extract debug information from the RAM dump.
- Brought down the dump download time by 70% and the size from 12 GB to 300 MB, enabling faster analysis.
- Developed FastRPC to offload high-compute tasks from CPU to Digital Signal Processors, improving performance.

#### ACADEMIC PROJECTS

• Leveraging object movement predictions for Interactive Robot Assistance

Aug. 2022 - current

- Advised by Prof. Sonia Chernova Developing an explainable deep generative graph neural network model (GNN) that performs spatio-temporal object tracking and models the future movement of daily-use objects in a home environment.
- Deep Reinforcement Learning (RL) based autonomous driving

Jan. 2022 - May 2022

- Trained a model-free RL algorithm TQC (Truncated Quantile Critics) and increased rewards by 17% with experience replay for navigation in self-driving simulator Donkeycar, outperforming benchmark algorithms DDPG, SAC, and PPO.
- o Trained a Variational Autoencoder to compress input into a latent space representation and improved rewards by 42%.
- Generated a semantic segmentation mask using a pretrained autoencoder to visualize model's interpretability. (Link)
- Semantic Similarity and Toxicity Detection of Questions in Quora

Sep. 2021 - Dec. 2021

- Using PyTorch, compared the results of BERT, Bi-LSTM, Bi-RNN, and Bi-GRU models with NLP word-embedding techniques TF-IDF Vectorization and Word2Vec to predict intent similarity and toxicity of questions on Quora. (Link)
- Achieved F1-score of 0.7 by fine-tuning BERT to predict question sincerity and accuracy 0.89 for questions' similarities.
- Computer Vision Tools for Non-verbal Communication in Interviews

Aug. 2021 - Dec. 2021

- Trained K Nearest Neighbours (KNN) model to estimate head pose in videos with accuracy 83%. Obtained features as the difference in minima and maxima of first-order pitch differences, from OpenFace Keypoints output on AMI corpus.
- Runner-up at Innovation Competition 2022, an Entrepreneurial challenge of VentureLabs, Georgia Tech. (Link)
- Low-cost intelligent vision in automotive (LIVA)

Jun. 2019 - Oct. 2019

- $\circ$  Collected dataset of depth images using Kinect V2 mounted on a moving car. Achieved object detection accuracy 85% in real-time to recognize pedestrians and vehicles by fine-tuning YOLO V3 model with depth images and COCO dataset.
- o Top 6 finalists out of the 230+ applicants in Maker's Challenge of QBuzz 2019, Qualcomm's annual tech conference.
- Real-Time Hand Gesture Recognition system

Jan. 2018 - May 2018

- Fine-tuned Inception V3 Architecture on ASL dataset to detect gestures with 98% accuracy and controlled a robotic arm
- o A.S.Amirtha Varshini, "Real-time Hand Gesture Recognition for Robotic Arm and Home Automation", (ISEEIE 2021).

## AWARDS & ACHIEVEMENTS

- Recipient of K. C. Mahindra Scholarship for Post Graduate Studies Abroad, 2021.
- Recipient of AIEEE Merit Scholarship for Rank 1448 (Top 0.1% amongst 1.3 million candidates) in JEE Main'14.