

Javad Amirian

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Research Interests

- Computer Vision
- Deep Learning and Generative Models
- Crowd Simulation and Motion Planning

Education

PhD Candidate in Robotics and Artificial Intelligence

Jan. 2018 - Now

Inria Rennes (Rainbow Team), France

Thesis: Short-term Pedestrian Motion Prediction for Robot Navigation in Crowd

Supervisor: Dr. Julien Pettré

MSc in Computer Engineering (Artificial Intelligence)

Sept. 2012 - Sept. 2014

Sharif University of Technology, Tehran, Iran (1st Rank University in Iran)

Thesis: Dynamic Motion Planning and Obstacle Avoidance for Simulated SDV in Webots

Supervisor: Dr. Mansour Jamzad

• **Graduate Courses:** Machine Learning, Statistical Pattern Recognition, Computational Intelligence, Image Processing, Planning in Artificial Intelligence, Speech Processing, Stochastic Processes.

GPA: 16.66/20

- Ranked 11th in nationwide M.Sc. university entrance exam for Artificial Intelligence, Iran 2012

BSc in Electrical Engineering (Electronics)

Sept. 2007 - Sept. 2012

Shahid Behesti University (National University of Iran), Tehran, Iran

GPA: 15.44/20

- Top 0.6% nationwide entrance exam of Iranian Universities among ~300,000 participants. 2007

Professional Experience

Doctoral Researcher @ CrowdBot (European H2020 Research Project)

Jan. 2018 - Jun. 2021

CrowdBot focuses on developing platforms and algorithms to ensure safe navigation of social robots. My main task is to develop tools for *Motion Prediction* of pedestrians around the robot, to improve robot navigation in crowd. I'm working on Crowd Simulation algorithms and Deep Learning models. As a result I developed a model called "Social-Ways" that uses Generative Adversarial Networks (GAN) to take agent's observed trajectories and predict multi-modal distribution of their future trajectories.

Computer Vision Engineer @ PixBall

May 2015 - Nov. 2018

PixBall is an AI startup providing smart solutions for sports video analysis. My task was developing image processing and machine vision algorithms and providing high-level API for UI layers. I contributed to PixArt, a video processing software for embedding graphical overlays and virtual advertisements into sports contents. One of the most challenging parts was to estimate the camera calibration parameters in near real-time. In this process only rotation and intrinsic parameters need to be updated, since the camera location is usually fixed, during a game. We used Matlab symbolic toolbox to derive the tracking equations and convert it to C++ instructions. Then we used a Levenberg–Marquardt solver with a set of tracked keypoints to find the parameters.

Computer Vision Engineer @ Spad System Co.

April 2016 - present

Spadsystem is a startup founded in 2013, specialized in traffic management solutions. In 2016, I joined the team to start a project for automatic recognition of Iranian license plates (Didbaan). I developed a ALPR engine based on an open-source software (OpenALPR). This software has been in use to manage the entrance and exit of cars from parking in multiple sites.

Co-Founder and Team Leader @ Cyrus (Team of Small-Size Soccer Robots)

2010 - 2015

I co-founded **Cyrus** under the supervision of Dr. Eslam Nazemi, during my undergrad study. I collaborated with more than 20 undergrad and graduate students that joined the team to develop hardware and software of the robots and prepare them for Robocup competitions. My main role was in the technical management of the project. Moreover, I contributed to designing the electronic boards, programming the robot firmware, and latterly developing codes for motion planning and playing of the robots. As research results of the project, we presented a new approach to improve the robot movements and compensating inaccuracies in robot building using a Fuzzy approach. We also proposed a new motion-planning algorithm for the robots, that is able to adapt the navigation parameters by optimizing multiple objectives, simultaneously.

Teaching Experience

- *Teaching Assistant* of Numerical Optimization course Spring 2017
Dr. S. Hamid Amiri (Shahid Rajaee University)
- *Teaching Assistant* of Machine Vision course (CE-40687) Spring 2014
Dr. Mansour Jamzad (Sharif University of Technology)
- *Teaching Assistant* of Digital Design course Spring 2010, Spring 2011
Dr. Somayeh Timarchi (Shahid Beheshti University)
- *Lecturer* of Introduction to AVR Microcontrollers 2009-2011
At Scientific Association of Electrical Engineering (Shahid Behshti University)

Publications

- **Amirian, J.**, Zhang, B., Valente Castro, F., Baldelomar, J., Hayet, J. B., Pettr , J. **"OpenTraj: Assessing Prediction Complexity in Human Trajectories Datasets."** In Proceedings of the 15th Asian Conference on Computer Vision (ACCV), Dec. 2020.
- Zhang, B., **Amirian, J.** Eberle, H., Pettr , J. Holloway, C., Carlson, T. **"Towards Safe Human-Robot Interactions in Crowds: Empirical Study of Pedestrian Dynamics with a Wheelchair and a Pepper Robot."** International Journal of Social Robotics (IJSR) - [Under review]
- **Amirian, J.**, Van Toll, W., Hayet, J. B., Pettr , J. **"Data-Driven Crowd Simulation with Generative Adversarial Networks."** In Proceedings of the 32nd International Conference on Computer Animation and Social Agents (CASA'19), Jul. 2019.
- **Amirian, J.**, Hayet, J. B., Pettr , J., **"Social ways: Learning multi-modal distributions of pedestrian trajectories with GANs,"** IEEE Conference on Computer Vision and Pattern Recognition (CVPR) Precognition Workshop, Jul. 2019.
- (TDP) **Amiryan, J.**, Raeessi, S., Payandeh, P., Nadimi, B., Nouri, N., Kamali, M. R., Nazemi, E., **"CYRUS 2016 Team Description Paper,"** 2016.
- **Amiryan, J.**, Jamzad, M., **"Adaptive motion planning with artificial potential fields using a prior path,"** 3rd RSI International Conference on Robotics and Mechatronics (ICROM), 2015.
- Mazloun, J., Jalali, A., **Amiryan, J.**, **"A novel bidirectional neural network for face recognition,"** 2nd International eConference on Computer and Knowledge Engineering (ICCKE), 2012.

Skills

- **Programming Languages:** Python, C/C++, Matlab.
- **Deep Learning Frameworks:** Pytorch, Keras (TensorFlow)
- **Version Control:** Git.

- **AI and Robotics Tools:** OpenCV, ROS.
- **Software Design:** OOD; Concurrent and Multithread; Modular Programming.
- **Graphic Tools:** Adobe Photoshop, Adobe Premiere; 3ds Max.

Activities

- Former member of technical committee (TC) of Small Size League at Robocup Iran Open. [Link](#).
- Interested in football and fan of Perspolis club. Going to stadium and encouraging my favorite team is one of my most exciting entertainments.
- Interested in playing soccer, hiking, body-building.

References

- **Dr. Julien Pettre**
Research Scientist at Rainbow, INRIA-Rennes, Brittany, France
Email: julien.pettre@inria.fr
- **Dr. Jean-Bernard Hayet**
Researcher at CIMAT, Department of Computer Science., Guanajuato, Mexico
Email: jbhayet@cimat.mx
- **Dr. Mansour Jamzad**
Department of Computer Engineering, Sharif University of Technology, Tehran, Iran
Email: jamzad@sharif.edu
- **Dr. Eslam Nazemi**
Department of Electrical and Computer Engineering, Shahid Beheshti University, Tehran , Iran
Email: nazemi@sbu.ac.ir