

Sharif University of Technology Department of Computer Engineering

Embedded System Design

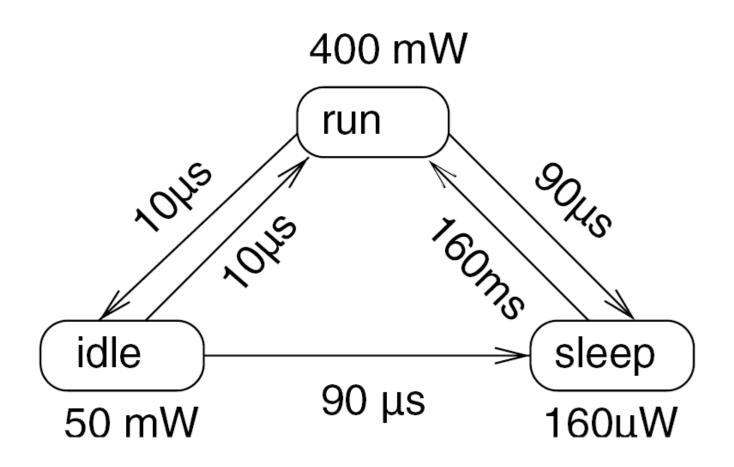
Energy Management (17)

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Dynamic Power Management

- Main Idea: the shutdown of idle system components.
- An advantage of DPM is its generality, which allows its usage not only for digital circuitry, but also for other system components such as displays, and hard drives.

Example: StrongArm SA 1100



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 The processor is fully operational in the run state.

- In the idle state, it is just monitoring the interrupt inputs.
 - reactive nature of ES

 In the sleep state, all on-chip activity is shutdown.

DVS-Enabled Processors

 DVS-enabled processors have the ability to dynamically change their supply voltage and operational frequency settings during run-time of the application.

$$P_{SW} = \alpha C_L V_{DD}^2 f$$
 $Delay \propto \frac{C_L \cdot V_{dd}}{(V_{dd} - V_{th})^{\alpha}}$

Example 1: Crusoe Processor

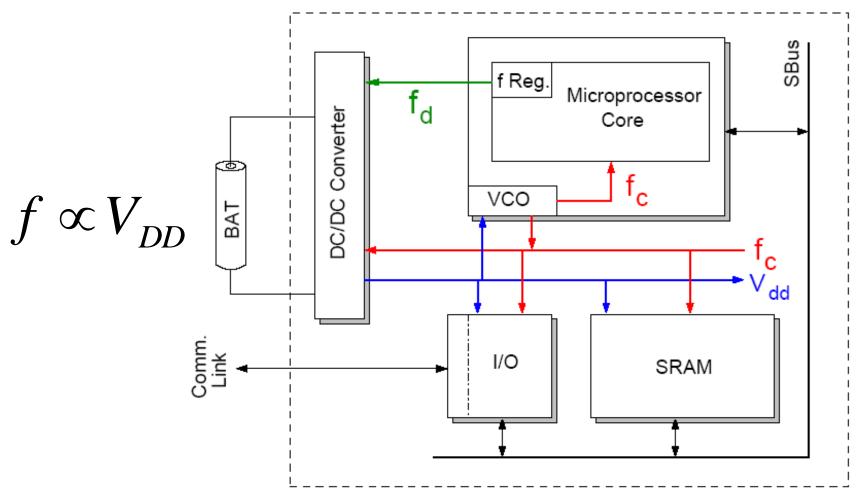
- By Transmeta
- 32 voltage levels between 1.1 and 1.6 volts
- Clock can be varied between 200 MHz and 700 MHz in increments of 33 MHz
- Transitions from one voltage/frequency pair to the next takes about 20 ms.

Example 2: Mobile Pentium III

 Two different speed/voltage pairs are provided

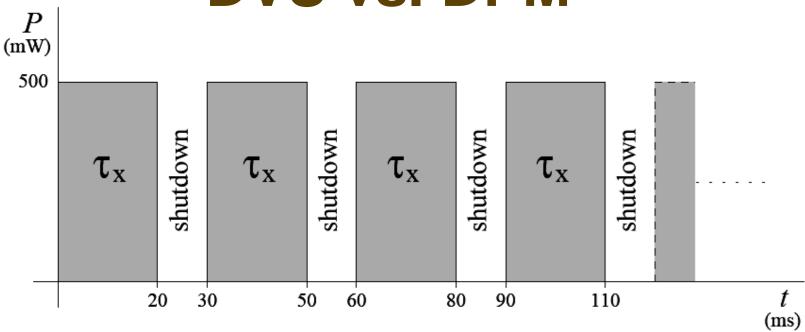
Intel SpeedStep Technology

DVS-Enabled Processors



- VCO: voltage controlled oscillator
- Note that the frequency register is under software control.

DVS vs. DPM

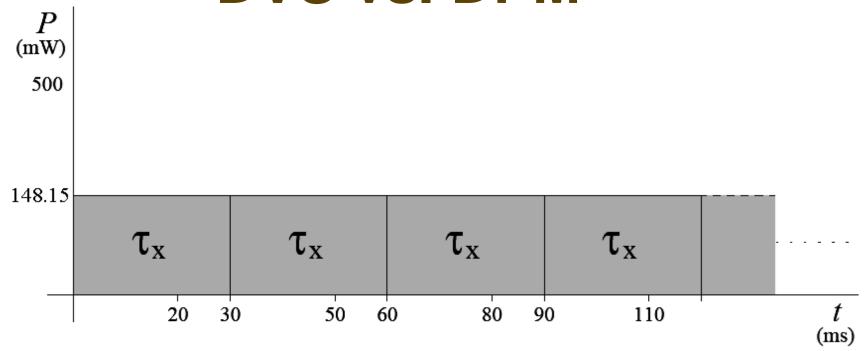


Example:

– DPM

- Execution time= 20 ms
- *F*= 33MHz, *Vdd*= 3.3V
- Power dissipation = 500 mW
- $P_{AV}=(2/3)*500 \text{ mW}= 333.333 \text{ mW}$
- Period= 30 ms

DVS vs. DPM



Example:

- DVS
 - Execution time= 20 ms -> 30 ms
 - F= 33MHz -> 22MHz, Vdd= 3.3V -> 2.2V
 - Power dissipation = 500 mW -> $(2/3)^{3*}500$ mW = 148.15mW = P_{AV}
 - Period= 30 ms

Single Event Upsets (SEU)

 Bit-flips due to the impact of particles on flip-flops.

$$\lambda_{SEU} \propto \exp(-Q_{CRIT})$$

$$Q_{CRIT} = V_{DD}.C_{L}$$

DVS has a negative impact on SEU rate