Bayesian Networks

Read R&N Ch. 14.1-14.2

Next lecture: Read R&N 18.1-18.4

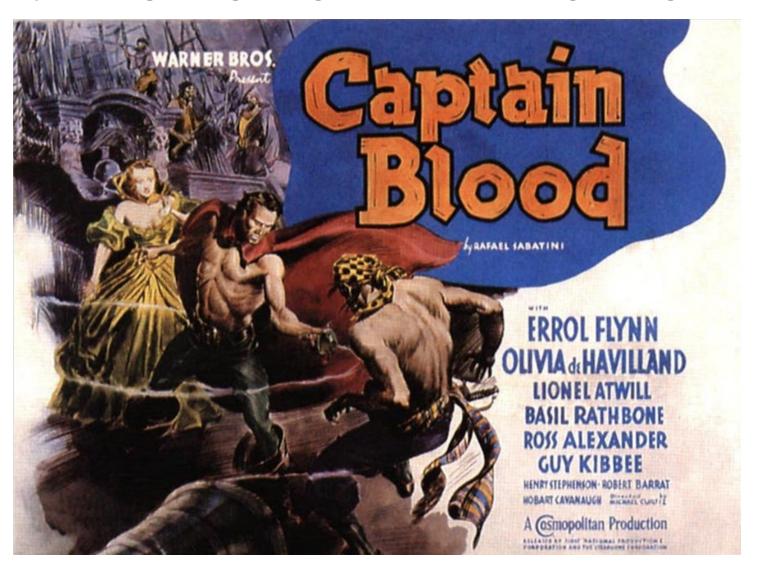
You will be expected to know

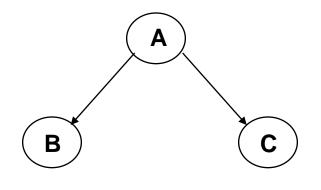
- Basic concepts and vocabulary of Bayesian networks.
 - Nodes represent random variables.
 - Directed arcs represent (informally) direct influences.
 - Conditional probability tables, P(Xi | Parents(Xi)).
- Given a Bayesian network:
 - Write down the full joint distribution it represents.
- Given a full joint distribution in factored form:
 - Draw the Bayesian network that represents it.
- Given a variable ordering and some background assertions of conditional independence among the variables:
 - Write down the factored form of the full joint distribution, as simplified by the conditional independence assertions.

"Faith, and it's an uncertain world entirely."

--- Errol Flynn, "Captain Blood" (1935)

= We need probability theory for our agents!! The world is chaos!! Could you design a logical agent that does the right thing below??





Conditionally independent effects: p(A,B,C) = p(B|A)p(C|A)p(A)

B and C are conditionally independent Given A

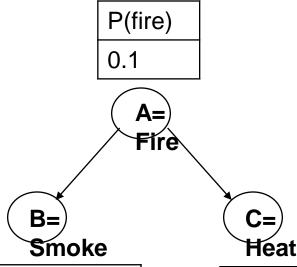
E.g., A is a disease, and we model B and C as conditionally independent symptoms given A

E.g., A is Fire, B is Heat, C is Smoke. "Where there's Smoke, there's Fire."

If we see Smoke, we can infer Fire.

If we see Smoke, observing Heat tells us very little additional information.

Suppose I build a fire in my fireplace about once every 10 days...



Conditionally independent effects: P(A,B,C) = P(B|A)P(C|A)P(A)

Smoke and Heat are conditionally independent given Fire.

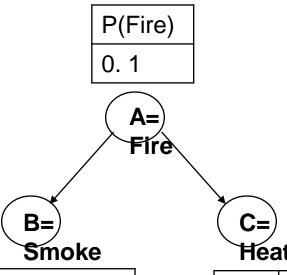
If we see B=Smoke, observing C=Heat tells us very little additional information.

Fire	P(Smoke)
t	.90
f	.001

Fire	P(Heat)
t	.99
Ť	.0001

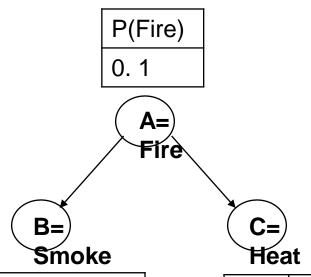


=P(Fire=t & Smoke=t) / P(Smoke=t)



P(Smoke)
.90
.001

Fire	P(Heat)
t	.99
f	.0001



What is P(Fire=t & Smoke=t)?

P(Fire=t & Smoke=t)

 $=\Sigma_{\text{heat P(Fire=t\&Smoke=t\&heat)}}$

 $=\Sigma$ _heat P(Smoke=t&heat|Fire=t)P(Fire=t)

 $=\Sigma_{\text{heat P(Smoke=t|Fire=t) P(heat|Fire=t)P(Fire=t)}}$

=P(Smoke=t|Fire=t) P(heat=t|Fire=t)P(Fire=t)

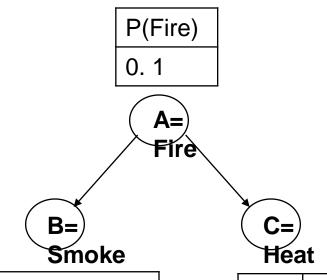
+P(Smoke=t|Fire=t)P(heat=f|Fire=t)P(Fire=t)

= (.90x.99x.1) + (.90x.01x.1)

= 0.09

Fire	P(Smoke)
t	.90
f	.001

Fire	P(Heat)
t	.99
f	.0001



What is P(Smoke=t)?

P(Smoke=t)

 $=\Sigma_{\text{fire }}\Sigma_{\text{heat P(Smoke=t\&fire\&heat)}}$

 $=\Sigma_{\text{fire }}\Sigma_{\text{heat }}P(Smoke=t\&heat|fire)P(fire)$

 $=\Sigma_{\text{fire}} \Sigma_{\text{heat}} P(\text{Smoke=t|fire}) P(\text{heat|fire}) P(\text{fire})$

=P(Smoke=t|fire=t) P(heat=t|fire=t)P(fire=t)

+P(Smoke=t|fire=t)P(heat=f|fire=t)P(fire=t)

+P(Smoke=t|fire=f) P(heat=t|fire=f)P(fire=f)

+P(Smoke=t|fire=f)P(heat=f|fire=f)P(fire=f)

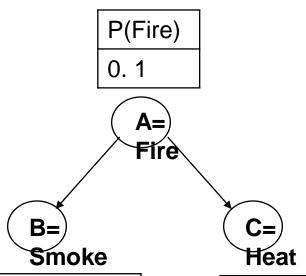
= (.90x.99x.1) + (.90x.01x.1)

+(.001x.0001x.9)+(.001x.9999x.9)

 ≈ 0.0909

Fire	P(Smoke)
t	.90
f	.001

Fire	P(Heat)
t f	.99 .0001



What is P(Fire=t | Smoke=t)?

P(Fire=t | Smoke=t) =P(Fire=t & Smoke=t) / P(Smoke=t) ≈ 0.09 / 0.0909 ≈ **0.99**

So we've just proven that

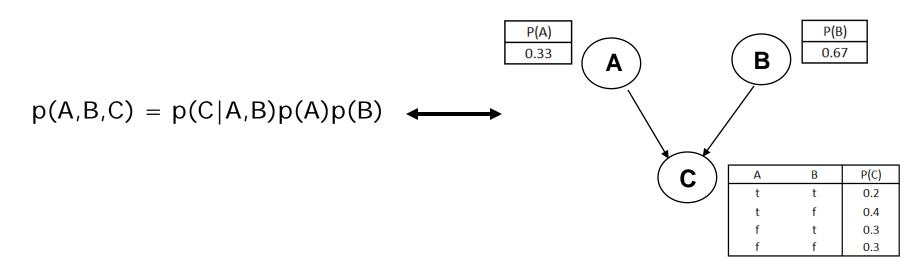
"Where there's smoke, there's (probably) fire."

Fire	P(Smoke)
t	.90
f	.001

Fire	P(Heat)
t	.99
f	.0001

Bayesian Network

A Bayesian network specifies a joint distribution in a structured form:



- Dependence/independence represented via a directed graph:
 - Node = random variable
 - Directed EdgeAbsence of Edge = conditional dependence
 - = conditional independence
- •Allows concise view of joint distribution relationships:
 - Graph nodes and edges show conditional relationships between variables.
 - Tables provide probability data.

Bayesian Networks

Structure of the graph ⇔ Conditional independence relations

- Requires that graph is acyclic (no directed cycles)
- 2 components to a Bayesian network
 - The graph structure (conditional independence assumptions)
 - The numerical probabilities (for each variable given its parents)
- Also known as belief networks, graphical models, causal networks

Examples of 3-way Bayesian Networks

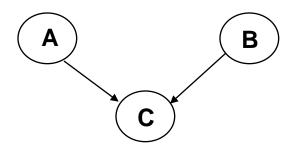






Marginal Independence: p(A,B,C) = p(A) p(B) p(C)

Examples of 3-way Bayesian Networks

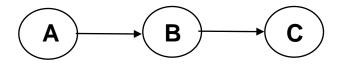


Independent Causes: p(A,B,C) = p(C|A,B)p(A)p(B)

"Explaining away" effect: Given C, observing A makes B less likely e.g., earthquake/burglary/alarm example

A and B are (marginally) independent but become dependent once C is known

Examples of 3-way Bayesian Networks

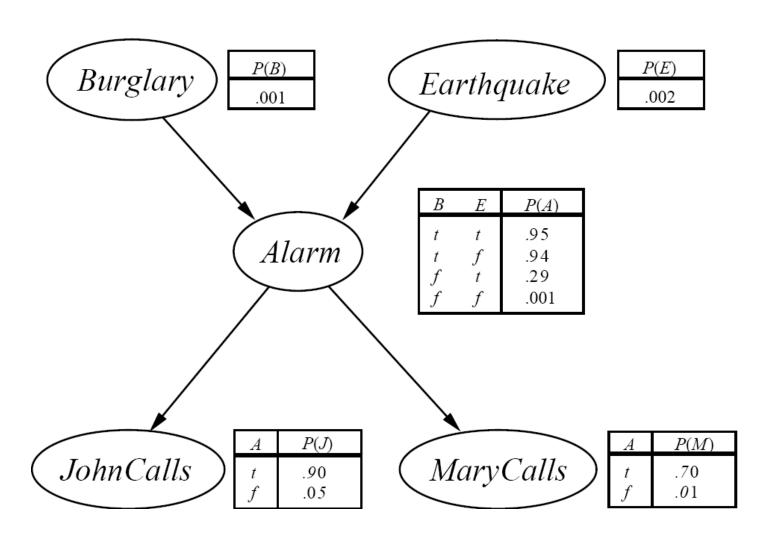


Markov dependence: p(A,B,C) = p(C|B) p(B|A)p(A)

Burglar Alarm Example

- Consider the following 5 binary variables:
 - B = a burglary occurs at your house
 - E = an earthquake occurs at your house
 - -A =the alarm goes off
 - J = John calls to report the alarm
 - M = Mary calls to report the alarm
 - What is P(B | M, J) ? (for example)
 - We can use the full joint distribution to answer this question
 - Requires 2⁵ = 32 probabilities
 - Can we use prior domain knowledge to come up with a Bayesian network that requires fewer probabilities?

The Desired Bayesian Network



Only requires 10 probabilities!

Constructing a Bayesian Network: Step 1

Order the variables in terms of influence (may be a partial order)

e.g.,
$$\{E, B\} \rightarrow \{A\} \rightarrow \{J, M\}$$

• P(J, M, A, E, B) = P(J, M | A, E, B) P(A | E, B) P(E, B)

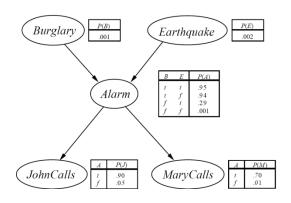
$$\approx P(J, M | A)$$
 $P(A | E, B) P(E) P(B)$

$$\approx P(J \mid A) P(M \mid A) P(A \mid E, B) P(E) P(B)$$

These conditional independence assumptions are reflected in the graph structure of the Bayesian network

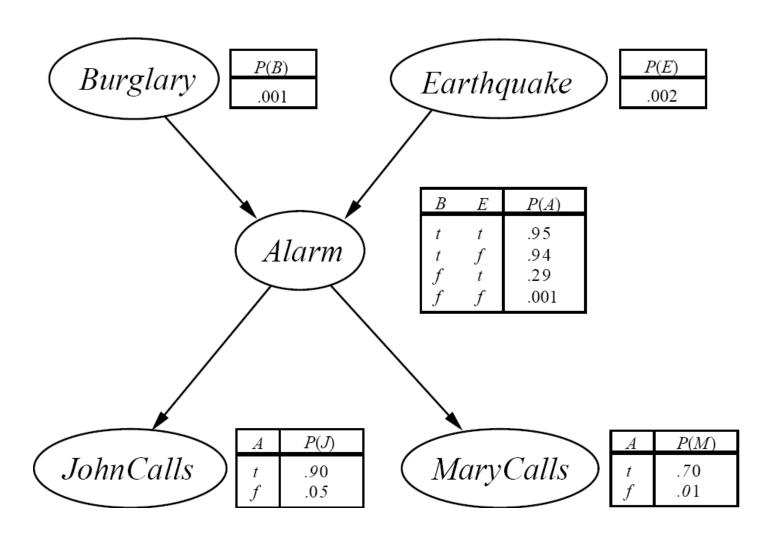
Constructing this Bayesian Network: Step 2

P(J, M, A, E, B) =
 P(J | A) P(M | A) P(A | E, B) P(E) P(B)



- There are 3 conditional probability tables (CPDs) to be determined:
 P(J | A), P(M | A), P(A | E, B)
 - Requiring 2 + 2 + 4 = 8 probabilities
- And 2 marginal probabilities P(E), P(B) -> 2 more probabilities
- Where do these probabilities come from?
 - Expert knowledge
 - From data (relative frequency estimates)
 - Or a combination of both see discussion in Section 20.1 and 20.2 (optional)

The Resulting Bayesian Network



Example of Answering a Probability Query

• So, what is $P(B \mid M, J)$? E.g., say, $P(b \mid m, \neg j)$, i.e., $P(B=true \mid M=true \land J=false)$

$$P(b \mid m, \neg j) = P(b, m, \neg j) / P(m, \neg j)$$
; by definition

$$P(b, m, \neg j) = \Sigma A \in \{a, \neg a\} \Sigma E \in \{e, \neg e\} P(\neg j, m, A, E, b) ; marginal$$

 $P(J, M, A, E, B) \approx P(J \mid A) P(M \mid A) P(A \mid E, B) P(E) P(B)$; conditional indep. $P(\neg j, m, A, E, b) \approx P(\neg j \mid A) P(m \mid A) P(A \mid E, b) P(E) P(b)$

Say, work the case A=a ∧ E=¬e

$$P(\neg j, m, a, \neg e, b) \approx P(\neg j \mid a) P(m \mid a) P(a \mid \neg e, b) P(\neg e) P(b)$$

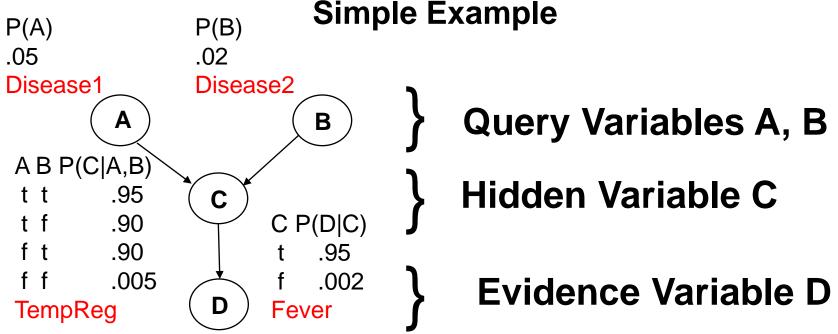
 $\approx 0.10 \times 0.70 \times 0.94 \times 0.998 \times 0.001$

Similar for the cases of a \land e, \neg a \land e, \neg a \land e.

Similar for P(m, \neg j). Then just divide to get P(b | m, \neg j).

- $X = \{ X1, X2, ..., Xk \} =$ query variables of interest
- E = { E1, ..., El } = evidence variables that are observed
 (e, an event)
- **Y** = { *Y1, ..., Ym* } = **hidden variables** (nonevidence, nonquery)

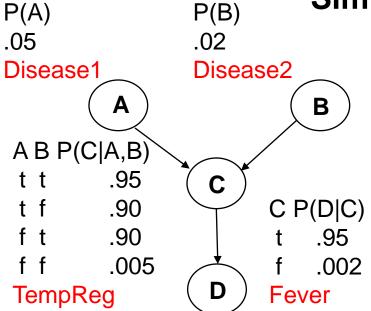
- What is the posterior distribution of X, given E?
- $P(X | e) = \alpha \Sigma_v P(X, y, e)$
- What is the most likely assignment of values to X, given E?
- $\operatorname{argmax}_{x} P(x \mid e) = \operatorname{argmax}_{x} \Sigma_{y} P(x, y, e)$



Note: Not an anatomically correct model of how diseases cause fever!

Suppose that two different diseases influence some imaginary internal body temperature regulator, which in turn influences whether fever is present.

Simple Example



What is the posterior conditional distribution of our query variables, given that fever was observed?

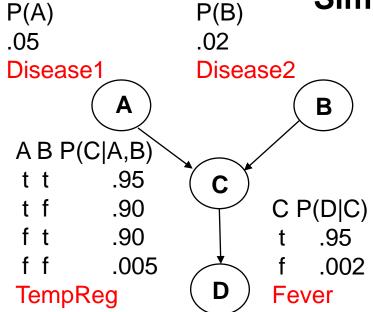
$$P(A,B|d) = \alpha \Sigma_c P(A,B,c,d)$$

$$= \alpha \Sigma_c P(A)P(B)P(c|A,B)P(d|c)$$

$$= \alpha P(A)P(B) \Sigma_c P(c|A,B)P(d|c)$$

```
\begin{split} P(a,b|d) &= \alpha \ P(a)P(b) \ \Sigma_c \ P(c|a,b)P(d|c) = \alpha \ P(a)P(b) \{ \ P(c|a,b)P(d|c) + P(\neg c|a,b)P(d|\neg c) \ \} \\ &= \alpha \ .05x.02x \{ .95x.95 + .05x.002 \} \approx \alpha \ .000903 \approx .014 \\ P(\neg a,b|d) &= \alpha \ P(\neg a)P(b) \ \Sigma_c \ P(c|\neg a,b)P(d|c) = \alpha \ P(\neg a)P(b) \{ \ P(c|\neg a,b)P(d|c) + P(\neg c|\neg a,b)P(d|\neg c) \ \} \\ &= \alpha \ .95x.02x \{ .90x.95 + .10x.002 \} \approx \alpha \ .0162 \approx .248 \\ P(a,\neg b|d) &= \alpha \ P(a)P(\neg b) \ \Sigma_c \ P(c|a,\neg b)P(d|c) = \alpha \ P(a)P(\neg b) \{ \ P(c|a,\neg b)P(d|c) + P(\neg c|a,\neg b)P(d|\neg c) \ \} \\ &= \alpha \ .05x.98x \{ .90x.95 + .10x.002 \} \approx \alpha \ .0419 \approx .642 \\ P(\neg a,\neg b|d) &= \alpha \ P(\neg a)P(\neg b) \ \Sigma_c \ P(c|\neg a,\neg b)P(d|c) = \alpha \ P(\neg a)P(\neg b) \{ \ P(c|\neg a,\neg b)P(d|c) + P(\neg c|\neg a,\neg b)P(d|\neg c) \ \} \\ &= \alpha \ .95x.98x \{ .005x.95 + .995x.002 \} \approx \alpha \ .00627 \approx .096 \\ \alpha \approx 1 \ / \ (.000903 + .0162 + .0419 + .00627) \approx 1 \ / \ .06527 \approx 15.32 \end{split}
```

Simple Example

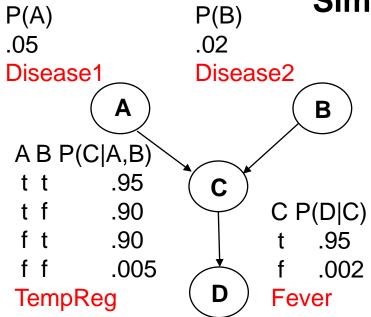


What is the most likely posterior conditional assignment of values to our query variables, given that fever was observed?

```
argmax_{\{a,b\}} P(a, b | d)
= argmax_{\{a,b\}} \Sigma_c P(a,b,c,d)
= \{a, \neg b\}
```

```
\begin{split} P(a,b|d) &= \alpha \; P(a)P(b) \; \Sigma_{\, c} \; \; P(c|a,b)P(d|c) = \alpha \; P(a)P(b) \{ \; P(c|a,b)P(d|c) + P(\neg c|a,b)P(d|\neg c) \; \} \\ &= \alpha \; .05x.02x \{.95x.95 + .05x.002\} \approx \alpha \; .000903 \approx \; .014 \\ P(\neg a,b|d) &= \alpha \; P(\neg a)P(b) \; \Sigma_{\, c} \; \; P(c|\neg a,b)P(d|c) = \alpha \; P(\neg a)P(b) \{ \; P(c|\neg a,b)P(d|c) + P(\neg c|\neg a,b)P(d|\neg c) \; \} \\ &= \alpha \; .95x.02x \{.90x.95 + .10x.002\} \approx \alpha \; .0162 \approx \; .248 \\ P(a,\neg b|d) &= \alpha \; P(a)P(\neg b) \; \Sigma_{\, c} \; \; P(c|a,\neg b)P(d|c) = \alpha \; P(a)P(\neg b) \{ \; P(c|a,\neg b)P(d|c) + P(\neg c|a,\neg b)P(d|\neg c) \; \} \\ &= \alpha \; .05x.98x \{.90x.95 + .10x.002\} \approx \alpha \; .0419 \approx .642 \\ P(\neg a,\neg b|d) &= \alpha \; P(\neg a)P(\neg b) \; \Sigma_{\, c} \; \; P(c|\neg a,\neg b)P(d|c) = \alpha \; P(\neg a)P(\neg b) \{ \; P(c|\neg a,\neg b)P(d|c) + P(\neg c|\neg a,\neg b)P(d|\neg c) \; \} \\ &= \alpha \; .95x.98x \{.005x.95 + .995x.002\} \approx \alpha \; .00627 \approx .096 \\ \alpha \approx 1 \; / \; (.000903 + .0162 + .0419 + .00627) \approx 1 \; / \; .06527 \approx 15.32 \\ \end{split}
```

Simple Example



What is the posterior conditional distribution of A, given that fever was observed? (I.e., temporarily make B into a hidden variable.)

We can use P(A,B|d) from above.

$$P(A|d) = \alpha \Sigma_b P(A,b|d)$$

$$P(a|d) = \sum_{b} P(a,b|d) = P(a,b|d) + P(a,\neg b|d)$$

= (.014+.642) \approx .656

$$P(\neg a|d) = \sum_{b} P(\neg a,b|d) = P(\neg a,b|d) + P(\neg a,\neg b|d)$$

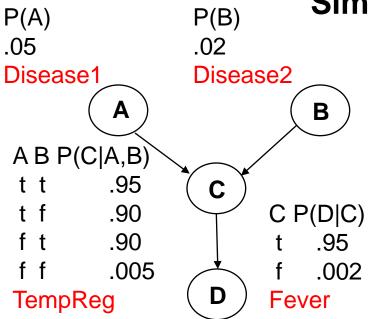
= (.248+.096) \approx .344

This is a marginalization, so we expect from theory that $\alpha = 1$; but check for round-off error.

A B P(A,B|d) from above
t t
$$\approx .014$$

f t $\approx .248$
t f $\approx .642$
f f $\approx .096$

Simple Example



What is the posterior conditional distribution of A, given that fever was observed, and that further lab tests definitely rule out Disease2? (I.e., temporarily make B into an evidence variable with B = false.)

$$P(A|\neg b,d) = \alpha P(A,\neg b|d)$$

A B P(A,B|d) from above t t
$$\approx .014$$
 f t $\approx .248$ t f $\approx .642$ f f $\approx .096$

General Strategy for inference

Want to compute P(q | e)

Step 1:

$$P(q \mid e) = P(q,e)/P(e) = \alpha P(q,e)$$
, since $P(e)$ is constant wrt Q

Step 2:

$$P(q,e) = \sum_{a \in Z} P(q, e, a, b, ..., z)$$
, by the law of total probability

Step 3:

$$\Sigma_{\text{a..z}}$$
 P(q, e, a, b, z) = $\Sigma_{\text{a..z}}$ Π_{i} P(variable i | parents i) (using Bayesian network factoring)

Step 4:

Distribute summations across product terms for efficient computation

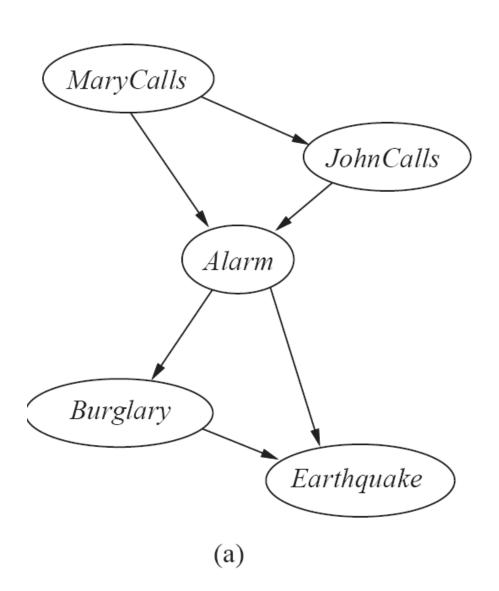
Section 14.4 discusses exact inference in Bayesian Networks. The complexity depends strongly on the network structure. The general case is intractable, but there are things you can do. Section 14.5 discusses approximation by sampling.

Number of Probabilities in Bayesian Networks

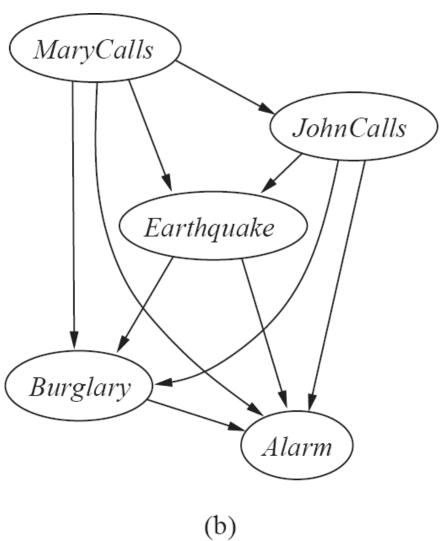
- Consider n binary variables
- Unconstrained joint distribution requires O(2ⁿ) probabilities

- If we have a Bayesian network, with a maximum of k parents for any node, then we need O(n 2^k) probabilities
- Example
 - Full unconstrained joint distribution
 - n = 30, k = 4: need 10^9 probabilities for full joint distribution
 - Bayesian network
 - n = 30, k = 4: need 480 probabilities

The Bayesian Network from a different Variable Ordering



The Bayesian Network from a different Variable Ordering



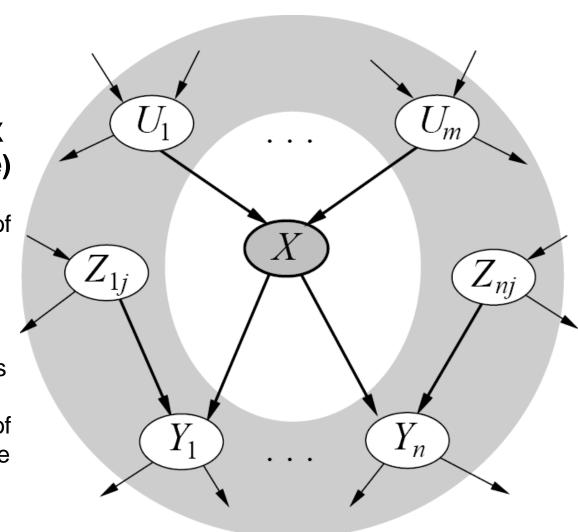
Given a graph, can we "read off" conditional independencies?

The "Markov Blanket" of X (the gray area in the figure)

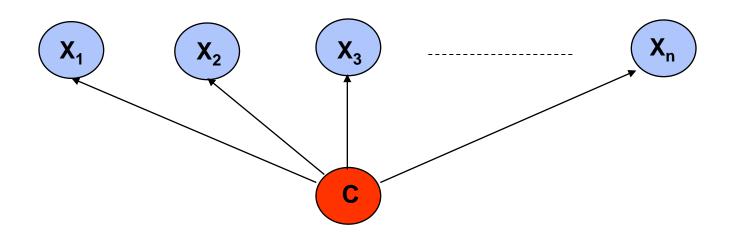
X is conditionally independent of everything else, GIVEN the values of:

- * X's parents
- * X's children
- * X's children's parents

X is conditionally independent of its non-descendants, GIVEN the values of its parents.



Naïve Bayes Model



$$P(C \mid X_1,...,X_n) = \alpha \Pi P(X_i \mid C) P(C)$$

Features X are conditionally independent given the class variable C

Widely used in machine learning

e.g., spam email classification: X's = counts of words in emails

Probabilities P(C) and P(Xi | C) can easily be estimated from labeled data

Naïve Bayes Model (2)

$$P(C \mid X_1,...X_n) = \alpha \Pi P(X_i \mid C) P(C)$$

Probabilities P(C) and P(Xi | C) can easily be estimated from labeled data

 $P(C = cj) \approx \#(Examples with class label cj) / \#(Examples)$

Usually easiest to work with logs

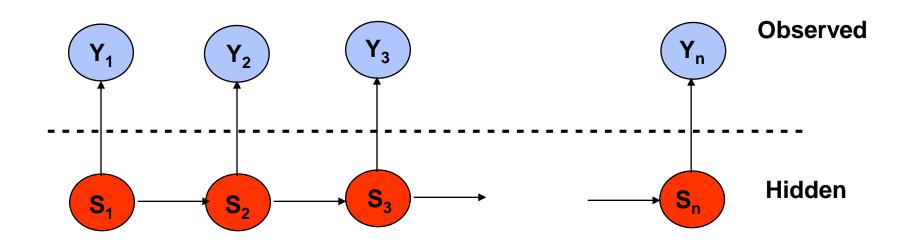
$$\log [P(C \mid X_1,...X_n)]$$

$$= \log \alpha + \sum [\log P(X_i \mid C) + \log P(C)]$$

DANGER: Suppose ZERO examples with Xi value xik and class label cj? An unseen example with Xi value xik will NEVER predict class label cj!

<u>Practical solutions:</u> Pseudocounts, e.g., add 1 to every #(), etc. <u>Theoretical solutions:</u> Bayesian inference, beta distribution, etc.

Hidden Markov Model (HMM)



Two key assumptions:

- 1. hidden state sequence is Markov
- 2. observation Y_t is CI of all other variables given S_t

Widely used in speech recognition, protein sequence models

Since this is a Bayesian network polytree, inference is linear in n

Summary

- Bayesian networks represent a joint distribution using a graph
- The graph encodes a set of conditional independence assumptions
- Answering queries (or inference or reasoning) in a Bayesian network amounts to efficient computation of appropriate conditional probabilities
- Probabilistic inference is intractable in the general case
 - But can be carried out in linear time for certain classes of Bayesian networks