

Operating System Assignment - 5

Q. 1: Necessity of operating system and essential abstraction.

Ans: Modern computer system still heavily on OS despite advantages in hardware because OS follows two crucial, non-redundant rules:

- Resources Management - It manages and allocates system resources (CPU memory, I/O device) efficiently.
- Abstraction layers: It provides a simple clean and consistent interfaces to the underlying complex, raw hardware, making it easier for programmers to write applications.

Q. 2: Comparison of OS Structure:

Ans:

<u>Feature</u>	<u>Monolithic</u>	<u>Layered</u>	<u>Microkernel</u>
<u>Structure</u>	All OS services are combined into binary running in kernel space.	Services are organized in layers, with each layer relying only on the functions of the layers	The kernel is minimal only handling core service. Other service run as user level server.
<u>Speed.</u>	Faster execution due to minimal overhead	Slower than monolithic due to the overhead of inter layer communication	Slowest because most service calls require context and inter-process.
<u>Reliability</u>	Low	Moderate	Highest

3. Analysis of thread Vs Process Efficiency:

Feature

Process

Slow. Requires allocating new virtual address space a new process central Block, and copying data structure

Context Switching

Slow. The OS must save the entire state of the old process and load the new one

Resource Usage

High. Each process requires its own private, isolated copy of resources.

Threads

Efficiency

Fast. Only requires creating a new thread control Block

Threads are more efficient.

Fast. The OS only needs to save registers and the stack pointer.

Threads are more efficient.

Low. Threads share code, data, files and heap memory of the parent process.

Threads are more efficient in terms of system memory footprint.

4. Memory allocation simulation (First-fit, Best-fit, Worst-fit):

Ans

Process

Requirement

P₁

12 MB

P₂

18 MB

P₃

6 MB

Algorithm
First-fit

Allocation Steps

P₁ (12MB): Allocates the first block that fits (20MB), remaining 8 MB

P₂ (18MB): No Block

large enough. Wait (P₃ 6MB):

fits (10MB). Remaining: 4MB

Total unused space

$$8\text{MB} + 4\text{MB} + 5\text{MB}$$

$$= 17\text{MB}$$

P₂ is waiting

Best-fit

$P_1(12\text{MB})$: Allocates the smallest block that fits

Total unused space:
 $8 + 4 + 5 = 17\text{ mb}$

$P_2(18\text{MB})$: No block large enough

$P_3(6\text{MB})$: Allocates the smallest block that fits

P_2 is waiting

Worst-fit

$P_1(12\text{MB})$: Allocates the largest block

Total unused space:

$P_2(18\text{MB})$: No blocks large enough

$8 + 4 + 5 = 17\text{ MB}$

$P_3(6\text{MB})$: Allocates the largest remaining block

P_2 is waiting

Q ① first come first served (FCFS)

→ Processes are executed in the order of their arrival time.

- P_1 arrives at 0, executes for 5ms (0-5)
- P_2 arrives at 1, but waits until P_1 finishes, execute for 3ms (5-8)
- P_3 arrives at 2, wait until P_2 finishes, execute for 8ms (8-16)
- P_4 arrives at 3, waits until P_3 finished, execute for 3ms (16-19)

P_1	P_2	P_3	P_4
0	5	8	16 19

② Shortest Job First (SJF):

Processes are selected based on the shortest burst time among those that have arrived.

- $t = 0$, only P_1 has arrived. P_1 starts ($BT=5$)
- $t = 5$, P_1 finishes P_2 ($AT=1, BT=3$), P_3 ($AT=2, BT=8$) and P_4 ($AT=3, BT=3$) have all arrived.
- Selection: P_2 and P_4 both have $BT=3$. choose P_2 (arrived first). P_2 executes.
- $t = 8$, P_2 finishes; P_3 ($BT=8$) remains, P_3 executes (11-19)

P ₁	P ₂	P ₄	P ₃
0	5	8	11 19

g. Round-Robin - Quantum = 4 ms

Processes are given a maximum of 4 ms CPU time, if not finished they are preempted and moved to the back of the ready queue.

Time(ms)	Executing Process	Remaining BT	Ready Queue
0-4	P ₁ (BT = 5)	1	P ₂ (at 1), P ₃ (at 2), P ₄
4-7	P ₂ (BT = 3)	0 (Finished)	P ₃ , P ₄ , P ₁ (remaining BT)
7-11	P ₃ (BT = 8)	4	P ₄ , P ₁ , P ₃ (remaining BT = 4)
11-14	P ₄ (BT = 3)	0 (finished)	P ₁ , P ₃
14-15	P ₁ (BT = 1)	0 (finished)	P ₃
15-19	P ₃ (BT = 4)	0 (finished)	∅

P ₁	P ₂	P ₃	P ₄	P ₁	P ₃
0	4	17	11	14	15 19

b. Calculating of Avg. Time

i. FCFS

Processes	BT	AT	Completion Time	TAT	WT
P ₁	5	0	5	5	0
P ₂	3	1	8	7	4
P ₃	8	2	16	14	6
P ₄	3	3	19	18	13
Sum				42	23

$$\text{Avg TAT} = 42/4 = 10.5 \text{ ms}$$

$$\text{Avg WT} = 23/4 = 5.75 \text{ ms}$$

2. SJF

Process	BT	AT	Completion Time	TAT	WT
P ₁	5	0	5	5	0
P ₂	3	1	8	7	4
P ₃	8	2	19	17	6
P ₄	3	3	11	19	13
Sum				31	23

* Avg TAT = $42/4 = 10.5 \text{ ms}$

* Avg WT = $23/4 = 5.75 \text{ ms}$

3. Round-Robin

Process	BT	AT	Completion Time	TAT	WT
P ₁	5	0	15	15	10
P ₂	3	1	17	6	3
P ₃	8	2	19	17	9
P ₄	3	3	14	11	8
Sum				49	30

* Avg TAT = 12.25 ms

Avg WT = 7.5 ms

d) Distributed file management

Ans a. Issues in distributed OS design for file sharing and resource management.

4. Global clock inconsistency: Distributed systems lack a single, synchronized clock. This makes it challenging to establish a consistent order of events, which is critical for file consistency and clock ordering.

1. Network latency and Partitioning: The network introduced delay after every file access, severely degrading performance. A network partition can split the system, leading to conflicting update.
2. Authentication and authorization: Securing resource is complex across control logic must be consistency and organized across multiple, independent server.
3. Resource contention and deadlock: Distributed processes can contain non-shared network resource.
4. Synchronous checkpointing and recovery
Initialization: A checkpoint initiator (process P_i) begins the process by recording its local state and sending a checkpoint request message to all other processes.
5. Coordination: Upon receiving the request, all other processes (P_j) immediately block their normal execution and stop sending application messages.
6. Local State Recording: Each blocked process records its current local state and the state of its communication channels.
7. Commit: Once all processes confirm they have recorded their state they realize their blocks and resume execution. The collection of all local states from the single consistent global checkpoint.

Q. IoT Smart Home System

Ans a. Process Scheduling Strategy

- Algorithm Selection: Preemptive Priority Scheduling with interrupt-driven activation.
- Justification and Strategy:

1. Priority Assignment: Assign the highest priority to the security device interrupts. All other task have lower priority.

2. Preemption: Use preemption if a high-priority security interrupt occurs while a low-priority task is running, due to scheduler will immediately suspend the lower-priority task and dispatch the critical security interrupt handler.

3. Justification: This ensures minimal latency for life-safety and security-critical tasks, fulfilling the primary requirement of prioritizing interrupts. The low-priority-task can tolerate a slight delay, but security alerts cannot.

Q 12 Python System Call Implementation:

Ans → Selected OS and System call

Operating System = Linux

Basic System Call demonstration: file management

Code :

```
import os
```

```
import stat
```

```
import time
```

```
FILE_NAME = "Syscall-demo-file.txt"
```

```
FILE_CONTENT = "This is a text of the \"write\" system call in python."
```

```
def demonstrate_system_calls():
```

```
try:
```

```
    print(f"\n→ calling 'open' system call to create and open: {file_name}")
```

```
    file_descriptor = os.open(
```

```
        path = file_name,
```

```
        flags = os.O_CREAT | os.O_WRONLY | os.O_TRUNC,
```

```
        mode = 0.644.
```

```
)
```

```
    print(f"\nSuccess, file descriptor (FD): {file_descriptor}\n")
```

```
    print(f"\n→ calling 'close' system call on FD: {file_descriptor}\n")
```

```
    print("Success. File closed")
```

```
    print(f"\nVerification: The file {file_name} has been  
    checked and except OS error as e: .
```

```
    print(f"\nWith OS error occurred: {e}\n")
```

```
finally:
```

```
    print(f"\n→ calling 'unlink' system call to delete: {file_name}\n")
```

```
    print("Success. File deleted")
```

```
if __name__ == "__main__":
```

```
demonstrate_system_calls()
```