

Operating System Assignment - 4

Q6. Distributed deadlock Detection Simulation:

fragments:

$$S_1 = P_1 \rightarrow P_2, P_3 \rightarrow P_4$$

$$S_2 = P_2 \rightarrow P_5, P_5 \rightarrow P_6$$

$$S_3 = P_6 \rightarrow P_1$$

a. Global wait-for graph (combined)

$P_1 \rightarrow P_2 \rightarrow P_5 \rightarrow P_6 \rightarrow P_1$ (cycle). Also $P_3 \rightarrow P_4$ (separate)

b. Deadlock?

→ Yes. Processes involved in deadlock cycle: P_1, P_2, P_5, P_6 .

c. Suggested distributed algorithm:

→ Use the Chandy-Misra-Har edge-chasing (Probe) algorithm for distributed deadlock detection - each node sends probes along wait-for edges to detect cycles without centralized graph assembly.

Q7. Distributed file system performance:

Given: local = 5ms, remote = 25ms, prob(remote) = 0.3

a. Expected access time:

$$E = 0.7 \times 5 \text{ ms} + 0.3 \times 25 \text{ ms} = 3.5 + 7.5 = 11 \text{ ms}$$

b. Caching strategy:

Client-side read cache with LRU + TTL-based validation

→ Justification: Frequently-read remote files will be served locally reducing remote access (0.3 fraction), LRU evicts less used items. TTL keeps staleness bounded. Improves average latency while keeping consistency manageable.

Q₁
Ans

Race Condition (real-world example) and mutual exclusion. Two people (A and B) share a single car key in an office. Both check the key box at the same time, see the key present, and both take it - resulting in no key for either when they try to leave. This is a race condition: the outcome depends on timing of accesses.

Mutual Exclusion Solution: make the key box accessible to one person at a time (e.g. a lock). Only one person can take the key after acquiring exclusive access; others wait. This prevents conflicting.

Q₂

Peterston's solution vs semaphores (implementation complexity & hardware dependency).

Ans

Peterston's solution: simple algorithm for two processes using shared flags and a turn variable.

Semaphores: higher-level OS primitive with blocking, wakeup and queue management. More complex to implement but less hardware-dependent.

Q₃

Producer-consumer: advantage of monitors on multi-core systems.

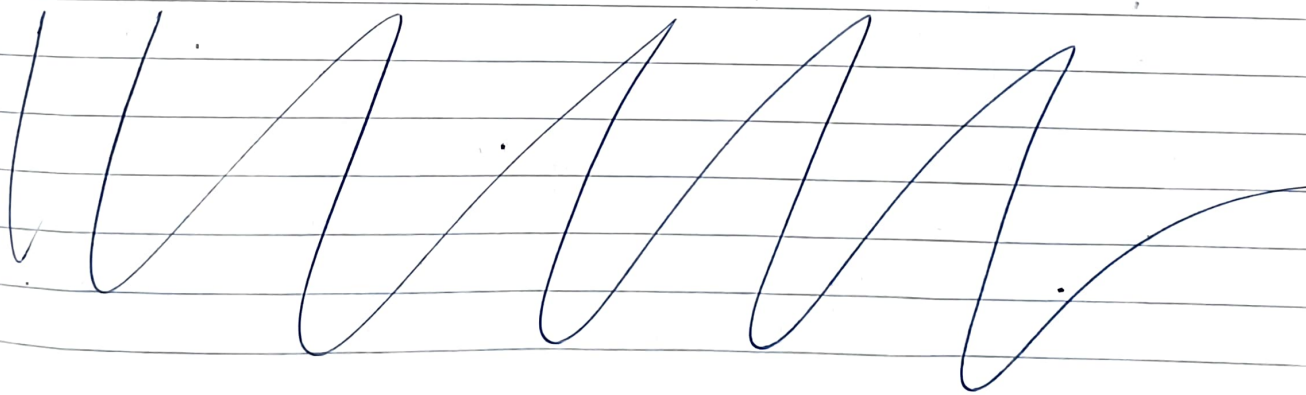
Ans

Monitors provide automatic mutual exclusion and condition variables with blocking (no busy-waiting). In multi-core systems this reduces CPU waste (no spinning) and improves scalability by letting the OS scheduler park threads, reducing contention and cache coherence traffic compared with spin-based semaphore solutions.

Q4. Reader - Writer starvation and one prevention method
Starvation scenario: If writers are rare but continuous streams of new readers keep arriving, writer can be perpetually delayed (reader preference implementations starve writers).

Prevention: Use writer preference or a fair queue (eg. queue incoming requests and access in FIFO order) or use a ticket/sequence number system so writers wait only a bounded time. This ensures fairness and prevents indefinite postponement of writers.

Q5. Eliminating "Hold and Wait" - practical drawback.
 If OS forces processes to acquire all needed resources at start (to eliminate hold-and-wait), processes must request all resources up-front or release held resources before requesting more. Practical drawback: very low resource utilization and poor concurrency - processes hold many unused resources while waiting for others, increasing blocking and reducing throughput. User programs often cannot predict all future resource needs in advance.



8. Checkpointing Mix to meet $RPO = 1s$

→ Given, full = 200 ms, incremental = 50 ms, $RPO = 1s$

a. Proposed Mix (over 10s):

- Take one full checkpoint every 10s (at $t=0$ in the period)
 - Take incremental checkpoint every 1s (at $t=1, 2 \dots 9$)
- Total overhead (per 10s): $1 \times 200 \text{ ms} + 9 \times 50 \text{ ms} = 200 + 450 = 650$

b. Reasoning:

- With incremental every 1s, the maximum work lost on failure $\leq 1s \rightarrow$ meets RPO.
- Full once per 10s bound recovery time (so restoring an older full + a small number of incrementals is feasible)
- This mix minimises full checkpoint cost while keeping incremental is feasible.
- This mix minimises full-checkpoint cost while keeping incremental frequency high enough to meet the RPO.

a. Case Study - Global E-commerce Platform:

a. Distributed Scheduling challenges for flash sales:

- Sudden spike in request
- Geographic distribution & latency - data locality matters for latency and inventory correctness.
- Heterogeneous nodes
- Strateful server.

→ Suggest algorithm for load balancing \Rightarrow Hybrid Approach

b. Fault-Tolerance Strategy (RTO & RPO):

- Active-active multi-region deployment: service run concurrently in multiple regions so failures is seamless ($RTO \approx$ near-zero at service level)

• Data Strategy:

- Critical transactional data: use synchronous replication within the region to guarantee consistency and low RPO; cross region replication can be asynchronous but with frequent replication to keep RPO small.