

## Operating System Assignment 1

Q. 1.  
Ans

Even with advanced hardware, OS is essential for resource management (CPU, memory, I/O). It provides abstraction, multitasking, security and ensure programs can run safely and efficiently.

Q. 2.  
Ans

A real-time embedded operating system is best because the device needs quick and predictable response, low power usage, and small footprint.

Q. 3.  
Ans

Avoid microkernel, as frequent inter-process communication adds overhead. Monolithic or layered gives better raw performance.

Q. 4.  
Ans

Yes, Structure impacts performance maintainability and fault isolation. for example, micro-kernel is secure but slower, monolithic is faster but less reliable.

Q. 5.  
Ans

PCB stores registers PC and state → errors show uninitialized values.

(ii) Context switch = saving current process state, updating PCB, loading new state.

(iii) Mid-execution I/O allocation usually needs non-blocking call so process continues running.

Date / /

Part - B

Q. 6.

Ans (a) Total context switching time,

Save State = 2ms

Load State = 3ms

Scheduler overhead = 1ms

$$\text{Total time} = 2 + 3 + 1 = 6 \text{ ms}$$

- b) Context switching is pure overhead (no useful work is done during this time).
- Higher switching time reduces CPU efficiency, as more time is spent switching than executing process.

Q. 7.

Ans Execution time estimate :

In ideal conditions (perfect parallelism, no overhead)

$$T_{\text{multi}} = \frac{T_{\text{single}}}{n} = \frac{40}{n} \text{ seconds}$$

$$\text{Single-thread} = 40 \text{ sec}$$

$$\text{With 2 threads under Ideal condn} = \frac{40}{2} = 20 \text{ sec.}$$

Q. 8.

Ans

Process : P<sub>1</sub>    P<sub>2</sub>    P<sub>3</sub>    P<sub>4</sub>

Burst Time :    5    3    8    6

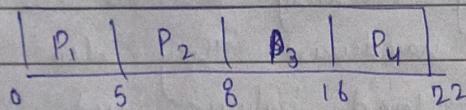
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## (a) FCFS

Process	Arrival Time (At)	Burst Time (BT)	Completion Time (CT)	Waiting Time (WT)	TAT
P <sub>1</sub>	0	5	5	5-5=0	5
P <sub>2</sub>	0	3	8	8-3=5	8
P <sub>3</sub>	0	8	16	16-8=8	16
P <sub>4</sub>	0	6	22	22-6=16	22

$$WT = Turnaround - Burst \quad (TAT - BT)$$

$$TAT = Completion - Arrival \quad (CT - AT)$$

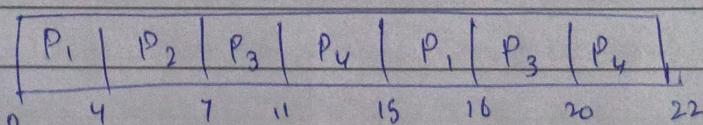
Gantt chart

$$\text{Avg. waiting time} = (0+5+8+16)/4 = 7.25 \text{ ms}$$

$$\text{Avg. turnaround time} = (5+8+16+22)/4 = 12.75 \text{ ms}$$

## (b) Round-Robin (quantum = 4 ms)

Process	AT	BT	CT	WT	TAT
P <sub>1</sub>	0	5	16	16-5=11	16-0=16
P <sub>2</sub>	0	3	7	7-3=4	7-0=7
P <sub>3</sub>	0	8	20	20-8=12	20-0=20
P <sub>4</sub>	0	6	22	22-6=16	22-0=22

Gantt chart,

$$\text{Avg waiting time} = (11+4+12+16)/4 = 10.75 \text{ ms}$$

$$\text{Avg turnaround} = (16+7+20+22)/4 = 16.25 \text{ ms}$$

SIF gives lowest waiting and turnaround times, while RR improves fairness for interactive tasks.

Q. 2  
Ans:

### Cloud migration:

for a virtualized cloud, a microkernel is suitable since it separates core services and provides better security and scalability. Virtual machines (VMs) add isolation by running multiple OS instances on the same hardware. They also support resource sharing, load balance and live migration.

(ii)

### Smart home system:

Here, many IoT devices run together. The OS uses priority scheduling and IPC. So urgent tasks like intrusion detection get CPU immediately, while low-priority scheduling and IPC. So urgent tasks like intrusion detection get CPU immediately, which low-priority tasks like lighting wait. Algorithms such as EDF (Earliest Deadline first) or RMS (Rate Monotonic Scheduling) can ensure critical tasks meet their deadlines without starving background processes.