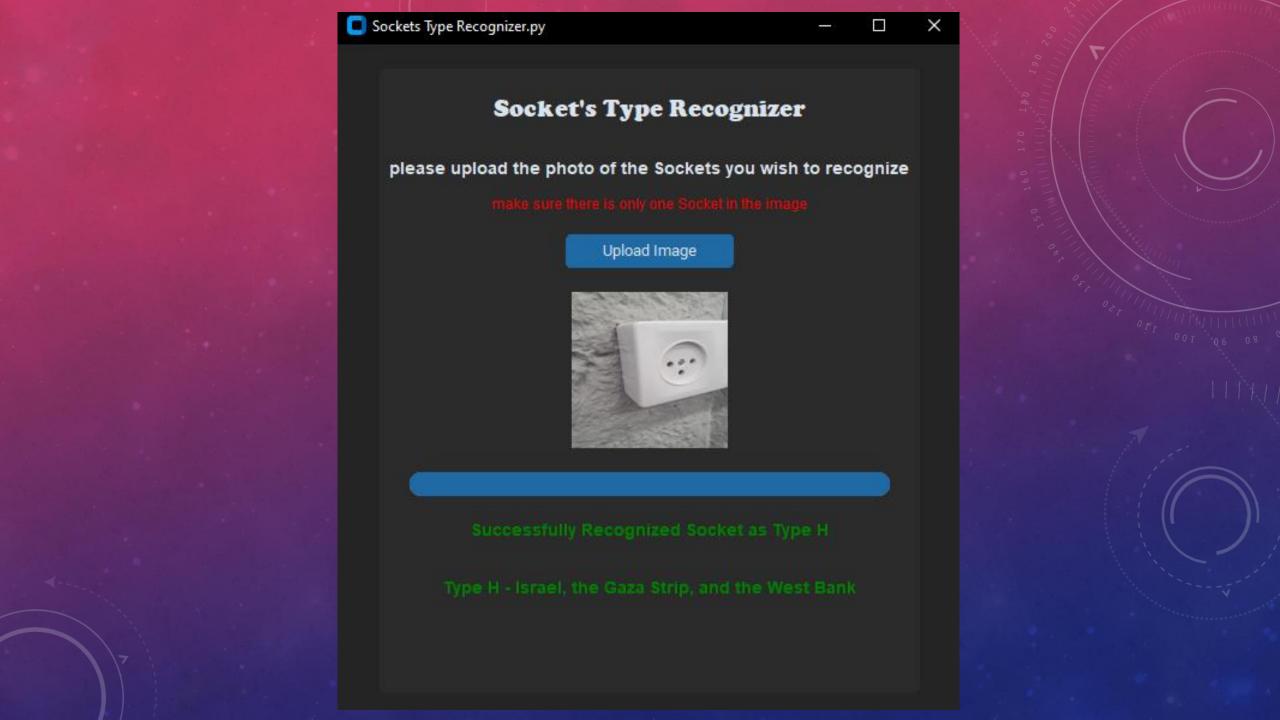


Socket's type recognizer

By Amit Shraga & Tomer Tal



MAIN STEPS

- Resize and crop the main object (Socket)
- detect the holes
- Classify if hole is circle or rectangle
- Find relation between the holes to determine the socket's type

RESIZE AND CROP THE MAIN OBJECT (SOCKET)





DETECT THE HOLES

- Guide line the holes are black,
 The rest is white
- Threshold
- find contours
- Check number of contours

CROP THE HOLES AREA, PROCESS THE IMAGE

- After finding holes, crop for proceing
- Use bigger threshold
- Classify if circle or rectangle (using cv2.approxPolyDp)





FIND RELATIONS

Type K

Type L

Type M

Type N

Type J

Type O

```
if is_Three_linear(points[0], points[1], points[2]):
        return "L"
    elif has_one_bigger_hole(radii[0], radii[1], radii[2]):
        return "D"
        if up_or_down(points[0][1], points[1][1], points[2][1]) == 'Down':
                                                                               H
            if has_big_angle(points):
               return "N"
                                                                              Type B
                return "H"
       else:
            return "0"
                                                                                                                1
elif len(rectangles) == 3:
   y_points = []
    for contour in contours:
        (x, y), radius = cv2.minEnclosingCircle(contour)
                                                                             Type G
                                                                                              Type H
                                                                                                                Type I
       y_points.append(y)
   G_or_I = up_or_down(y_points[0], y_points[1], y_points[2])
   if G_or_I == 'Up':
       return "G"
    else:
```

QUESTIONS?