Unit 1

ASSIGNMENT SOLUTION

CONTROL SYSTEM (BEC-302)

- 1. What are the basic components of a control system?
- 2. Compare open loop control system with close loop control system.
- 3. How many types of feedbacks are there? Explain the advantages and disadvantages of each.
- 4. Define feedback and its effect on control system.
- 5. Explain all rules for block diagram reduction techniques.
- 6. Find the transfer function for the given block diag. representations.

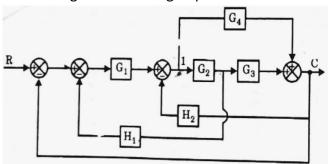
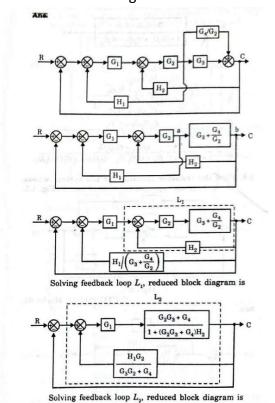
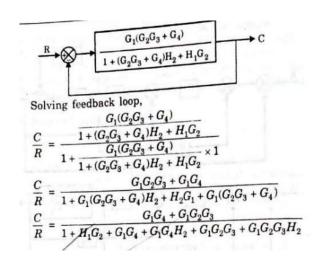
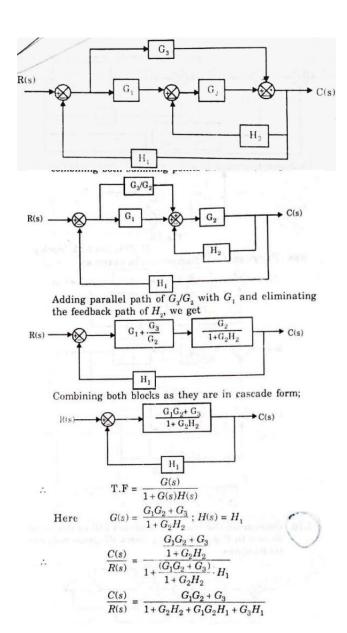


Fig 1







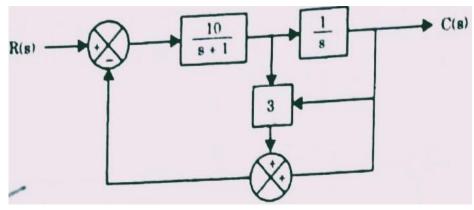
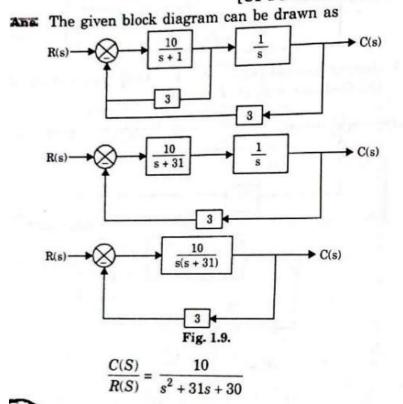


Fig 3



7. Determine the transfer function (C1/R1),(C1/R2),(C2/R1), and (C2/R2) for the given block diag. representation.

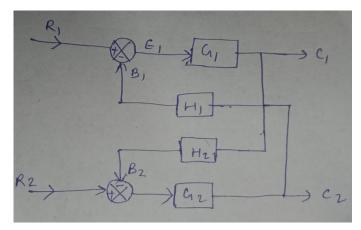


Fig 4

	FIG 4	utput Relationship // 43
	$E_2 = R_2 - B_2$	Par Acationship // 43
Solution:	$B_2 = C_1 H_2$	-(1.119a)
	$C_2 = E_2 G_2$	-(1.119b)
out the value of E	2 from 1.119a in 1.119c	-(1.119c)
	$C_2 = C_2(R_2 - B_2)$	
from (1.119b) put	the value of B ₂ in (1.119d)	(1.1194)
	$C_2 = G_2(R_2 - C_1H_2)$	-(1.1196)
	$B_1 = C_2H_1$	-(1.1196
put the value of C	2 from (1.119e.) in (1.119f)	
	$B_1 = G_2 H_1 (R_2 - C_1 H_2)$	-(1.119g)
	$E_1 = R_1 - B_1$	
	$E_1 = R_1 - G_2 H_1 (R_2 - C_1 H_2)$ $C_1 = E_1 G_1$	-(1.119h)
Also,		-(1.119i)
from (1.1190) put	the value of E_1 in (1.119i) $C_1 = G_1 [R_1 - G_2H_1 (R_2 - C_1H_2)]$	
c n.	$G_1 = G_1 \left[K_1 - G_2 K_1 \left(K_2 - G_1 K_2 \right) \right]$ $= G_1 G_2 H_1 H_2 = G_1 G_1 H_1 R_2$	-(L119))
	$R_1 = 0 \text{ from (1.119K)}$	-(T.119K)
When		
	$\frac{C_1}{R_2} = \frac{-G_1G_2H_1}{1 - G_1G_2H_1H_2}$	Ans(1.1191)
(com (1.119f) put	the value of C_1 in (1.119e)	
iloni (iliini) par	$C_2 = G_2 \left[R_2 + \frac{G_1 G_2 H_1 H_2 R_2}{1 - G_1 G_2 H_1 H_2} \right]$	
	$\frac{C_2}{R_2} = \frac{G_2}{1 - G_1 G_2 H_1 H_2}$	Ans(1.119m)
	$R_2 = 1 - G_1G_2H_1H_2$	Aug(1.117m)
When	R ₂ = 0, (1.119K) becomes	
	$C_1 = G_1 [R_1 + C_1 G_2 H_1 H_2]$	
	$C_1 = G_1 R_1 + C_1 G_1 G_2 H_1 H_2$	
	$\frac{C_1}{R_1} = \frac{G_2}{1 - G_2G_2H_1H_2}$	Ans(1.119a
110		
When	$R_2 = 0$, (1.119e) becomes	
from /1 110	$C_2 = -G_2C_1H_2$	
from (1.119n) put	Control of the Contro	
	$C_2 = \frac{-G_1G_2R_1H_2}{1 - G_1G_2H_1H_2}$	
	$\frac{C_2}{R_1} = \frac{-C_1C_2H_2}{1 - C_1C_2H_1H_2}$	Ans(1.119n
	R. 1-GGHH.	

8. Find the transfer function for the signal flow graph.

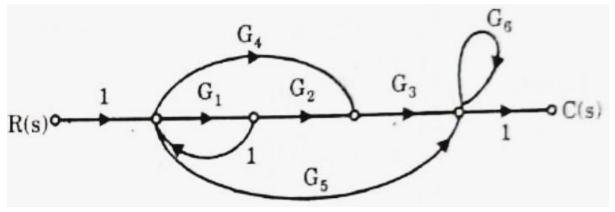


Fig 5

Number of forward paths
$$T_1 = G_1G_2G_3, \quad T_2 = G_4G_3, \quad T_3 = G_5$$
 Number of individual loops
$$L_1 = G_1, \quad L_2 = G_6$$
 Number of non touching loops, $L_1L_2 = G_1G_6$
$$\Delta_1 = 1, \, \Delta_2 = 1, \, \Delta_3 = 1$$

$$T.F. = \frac{T_1 \, \Delta_1 + T_2\Delta_2 + T_2\Delta_3}{1 - (L_1 + L_2) + (L_1 \, L_2)}$$

$$T.F. = \frac{G_1 \, G_2 \, G_3 + G_4 \, G_3 + G_5}{1 - G_1 - G_6 + G_1 \, G_6}$$

- 9. What is signal flow graph? How it is constructed?
- 10. What are the two different methods to obtain SFG? Explain with example.
- 11. Draw the SFG of the given block diag. and find its transfer function.

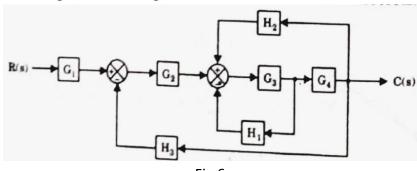


Fig 6

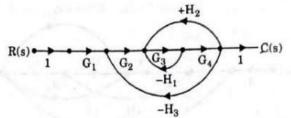


Fig. 1.15. The forward path is $P_1 = G_1 \ G_2 \ G_3 \ G_4$

$$\begin{split} L_1 &= -\,G_3\,H_1 \\ L_2 &= -\,G_2\,G_3\,G_4\,H_3 \\ L_3 &= G_3\,G_4\,H_2 \end{split}$$



Here, non-touching loops are not present

$$\Delta = 1 - [L_1 + L_2 + L_3]$$

$$= 1 - [-G_3 H_1 - G_2 G_3 G_4 H_3 + G_3 G_4 H_2]$$

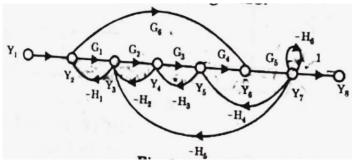
$$= 1 + G_3 H_1 + G_2 G_3 G_4 H_3 - G_3 G_4 H_2$$

$$\Delta_1 = 1$$

$$\therefore \qquad \text{T.F.} = \frac{P_1 \Delta_1}{\Delta}$$

$$\text{T.F.} = \frac{G_1 G_2 G_3 G_4}{1 + G_3 H_1 + G_2 G_3 G_4 H_3 - G_3 G_4 H_2 }$$

12. Find the transfer function Y7/Y1 of the signal flow graph.



uns Using Mason's Gain formula,

$$T(s) = \frac{C(s)}{R(s)} = \begin{bmatrix} \sum_{i=1}^{K} P_i \Delta_i \\ \frac{1}{\Delta} \end{bmatrix}$$

$$\frac{Y_7}{Y_1} = \begin{pmatrix} P_1 \Delta_1 + P_2 \Delta_2 \\ \frac{1}{\Delta} \end{pmatrix}$$
(** Two forward paths exist here)

where, $\Delta = 1 - (Sum of all loops) + (Sum of all two$ non-touching loops) - (Sum of all three non-touching loops) + ...

$$\begin{split} P_1 &= G_1 G_2 G_3 G_4 G_5 \\ P_2 &= G_6 G_5 \end{split}$$

Number of loops present are:

$$L_1 = -H_1G_1,$$

$$L_2 = -H_2G_2,$$

$$L_3 = -H_3G_3,$$

$$L_4 = -H_4G_4G_5,$$

$$L_5 = -H_6$$

$$L_6 = G_5G_6H_5H_1,$$

$$L_7 = -G_3G_2G_4G_5H_5,$$

$$L_3L_5 = H_3G_3H_6$$
of two poputous local part of the poputous local part of

Number of two non-touching loop:

$$L_1L_3 = H_1G_1H_3G_3$$

$$L_1L_4 = H_1G_1H_4G_4G_5$$

$$L_1L_5 = H_1G_1H_6$$

$$L_2L_4 = H_2G_2H_4G_4G_5$$

$$L_2L_5 = H_2G_2H_6$$
Number of three non-touching loops :

$$\frac{Y_7}{Y_1} = \frac{C_1 C_2 G_3 G_4 G_5 \Delta_1 + G_6 G_5 \Delta_2}{1 + H_1 G_1 + H_2 G_2 + H_3 G_3 + H_4 G_4 G_5 + H_6 - G_5 G_6 H_5 H_1 + G_3 G_2 G_4 G_5 H_5 - G_6 H_4 H_3 H_2 H_1 + H_1 G_1 H_3 G_3 + H_1 G_1 H_4 G_4 G_5 + H_2 G_2 H_4 G_4 G_5 + H_2 G_2 H_6 + H_3 G_3 H_6 + H_1 G_1 H_3 G_3 H_6$$
where, $\Delta_1 = 1 - [0] = 1$

where,
$$\Delta_1 = 1 - [0] = 1$$

 $\Delta_2 = 1 + G_2H_2 + G_3H_3$

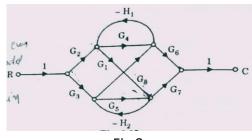


Fig 8

The Mason's gain formula of given by, $\frac{C}{R} = \frac{\sum P_k \Delta_k}{\Delta}$ where,

 $\Delta = 1 - (\text{some of all loops}) + (\text{some of non-touching loops})$

.....

$$P_k$$
 = forward paths
 $\Delta_k = 1 - (\text{loop not touching } P_k)$

Forward paths of SFG:

$$P_{1} = G_{2}G_{4}G_{6}$$

$$P_{2} = G_{3}G_{5}G_{7}$$

$$P_{3} = G_{2}G_{1}G_{7}$$

$$P_{4} = G_{3}G_{8}G_{6}$$

$$P_{5} = -G_{2}G_{1}H_{2}G_{8}G_{6}$$

$$P_{6} = -G_{5}G_{5}H_{5}G_{6}$$

Loops of SFG :

 $L_1=-G_4H_1$, $L_2=-G_5H_2$, $L_3=G_1H_2G_8H_1$ Non-touching loops of SFG: There is one pair having gain product

$$L_{1} L_{2} = G_{4} H_{1} G_{5} H_{2}.$$

$$\Delta = 1 + G_{4} H_{1} + G_{5} H_{2} - G_{1} H_{2} G_{8} H_{1} + G_{4} H_{1} G_{5} H_{2}$$

$$\Delta_{1} = 1 + G_{5} H_{2}$$

$$\Delta_{2} = 1 + G_{4} H_{1}$$

$$\Delta_{3} = \Delta_{4} = \Delta_{5} = \Delta_{6} = 1$$

$$\vdots \quad \frac{C}{R} = T = \frac{P_{1} \Delta_{1} + P_{2} \Delta_{2} + P_{3} \Delta_{3} + P_{4} \Delta_{4} + P_{5} \Delta_{5} + P_{6} \Delta_{6}}{\Delta}$$

$$= \frac{G_{2} G_{4} G_{6} (1 + G_{5} H_{2}) + G_{3} G_{5} G_{7} (1 + G_{4} H_{1}) + G_{2} G_{1} G_{7}}{1 + G_{4} H_{1} + G_{5} H_{2} - G_{1} H_{2} G_{8} H_{1} + G_{4} G_{5} H_{1} H_{2}}$$

$$+ \frac{G_{3} G_{8} G_{6} - G_{2} G_{6} G_{8} G_{1} H_{2} - G_{3} G_{7} G_{8} G_{1} H_{1}}{1 + G_{4} H_{1} + G_{5} H_{2} - G_{1} H_{2} G_{8} H_{1} + G_{4} G_{5} H_{1} H_{2}}$$

- 14. What is modelling in electrical system?
- 15. Find the transfer function of the circuit.

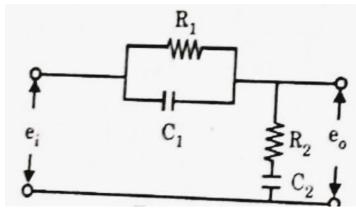
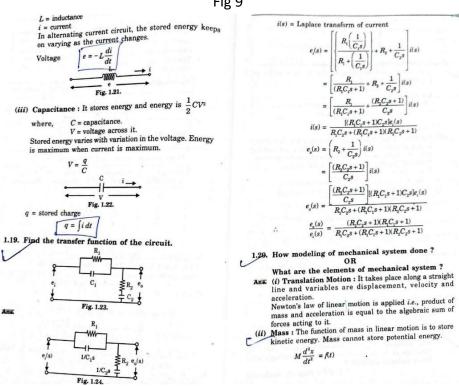


Fig 9



- 16. How modelling of mechanical system is done?
- 17. Draw the electrical analogous circuit of the system given below

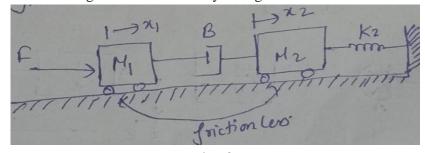
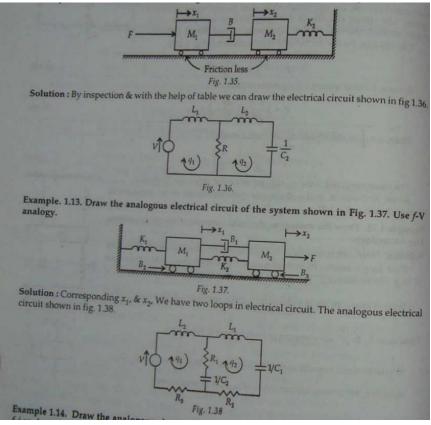


Fig 10



- **18.** What are the physical quantities (i) force (ii) mass (iii) damper (iv) displacement and (v) velocity analogous to in the force current analogy and force voltage analogy?
- 19. Explain: (i) force-voltage analogy (ii) force-current analogy