object_detection_tutorial

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1 Object Detection Demo

Welcome to the object detection inference walkthrough! This notebook will walk you step by step through the process of using a pre-trained model to detect objects in an image. Make sure to follow the installation instructions before you start.

2 Imports

```
In [21]: import numpy as np
         import os
         import six.moves.urllib as urllib
         import sys
         import tarfile
         import tensorflow as tf
         import zipfile
         from distutils.version import StrictVersion
         from collections import defaultdict
         from io import StringIO
         from matplotlib import pyplot as plt
         from PIL import Image
         # This is needed since the notebook is stored in the object_detection folder.
         sys.path.append("..")
         from object_detection.utils import ops as utils_ops
         if StrictVersion(tf.__version__) < StrictVersion('1.12.0'):</pre>
           raise ImportError('Please upgrade your TensorFlow installation to v1.12.*.')
```

2.1 Env setup

2.2 Object detection imports

Here are the imports from the object detection module.

3 Model preparation

3.1 Variables

Any model exported using the export_inference_graph.py tool can be loaded here simply by changing PATH_TO_FROZEN_GRAPH to point to a new .pb file.

By default we use an "SSD with Mobilenet" model here. See the detection model zoo for a list of other models that can be run out-of-the-box with varying speeds and accuracies.

3.2 Download Model

In []:

3.3 Load a (frozen) Tensorflow model into memory.

```
In [25]: detection_graph = tf.Graph()
    with detection_graph.as_default():
        od_graph_def = tf.GraphDef()
        with tf.gfile.GFile(PATH_TO_FROZEN_GRAPH, 'rb') as fid:
        serialized_graph = fid.read()
        od_graph_def.ParseFromString(serialized_graph)
        tf.import_graph_def(od_graph_def, name='')
```

3.4 Loading label map

Label maps map indices to category names, so that when our convolution network predicts 5, we know that this corresponds to airplane. Here we use internal utility functions, but anything that returns a dictionary mapping integers to appropriate string labels would be fine

```
In [26]: category_index = label_map_util.create_category_index_from_labelmap(PATH_TO_LABELS, use
```

3.5 Helper code

```
return np.array(image.getdata()).reshape(
     (im_height, im_width, 3)).astype(np.uint8)
```

4 Detection

```
In [28]: # For the sake of simplicity we will use only 2 images:
         # image1.jpg
         # image2.jpg
         # If you want to test the code with your images, just add path to the images to the TES
         PATH_TO_TEST_IMAGES_DIR = 'test_images'
         TEST_IMAGE_PATHS = [ os.path.join(PATH_TO_TEST_IMAGES_DIR, '{}.png'.format(i)) for i in
         # Size, in inches, of the output images.
         IMAGE\_SIZE = (12, 8)
In [29]: def run_inference_for_single_image(image, graph):
           with graph.as_default():
             with tf.Session() as sess:
               # Get handles to input and output tensors
               ops = tf.get_default_graph().get_operations()
               all_tensor_names = {output.name for op in ops for output in op.outputs}
               tensor_dict = {}
               for key in [
                   'num_detections', 'detection_boxes', 'detection_scores',
                   'detection_classes', 'detection_masks'
               ]:
                 tensor_name = key + ':0'
                 if tensor_name in all_tensor_names:
                   tensor_dict[key] = tf.get_default_graph().get_tensor_by_name(
                       tensor_name)
               if 'detection_masks' in tensor_dict:
                 # The following processing is only for single image
                 detection_boxes = tf.squeeze(tensor_dict['detection_boxes'], [0])
                 detection_masks = tf.squeeze(tensor_dict['detection_masks'], [0])
                 # Reframe is required to translate mask from box coordinates to image coordinat
                 real_num_detection = tf.cast(tensor_dict['num_detections'][0], tf.int32)
                 detection_boxes = tf.slice(detection_boxes, [0, 0], [real_num_detection, -1])
                 detection_masks = tf.slice(detection_masks, [0, 0, 0], [real_num_detection, -1,
                 detection_masks_reframed = utils_ops.reframe_box_masks_to_image_masks(
                     detection_masks, detection_boxes, image.shape[0], image.shape[1])
                 detection_masks_reframed = tf.cast(
                     tf.greater(detection_masks_reframed, 0.5), tf.uint8)
                 # Follow the convention by adding back the batch dimension
                 tensor_dict['detection_masks'] = tf.expand_dims(
                     detection_masks_reframed, 0)
               image_tensor = tf.get_default_graph().get_tensor_by_name('image_tensor:0')
```

```
# Run inference
               output_dict = sess.run(tensor_dict,
                                      feed_dict={image_tensor: np.expand_dims(image, 0)})
               # all outputs are float32 numpy arrays, so convert types as appropriate
               output_dict['num_detections'] = int(output_dict['num_detections'][0])
               output_dict['detection_classes'] = output_dict[
                   'detection_classes'][0].astype(np.uint8)
               output_dict['detection_boxes'] = output_dict['detection_boxes'][0]
               output_dict['detection_scores'] = output_dict['detection_scores'][0]
               if 'detection_masks' in output_dict:
                 output_dict['detection_masks'] = output_dict['detection_masks'][0]
           return output_dict
In [30]: for image_path in TEST_IMAGE_PATHS:
           image = Image.open(image_path)
           # the array based representation of the image will be used later in order to prepare
           # result image with boxes and labels on it.
           image_np = load_image_into_numpy_array(image)
           # Expand dimensions since the model expects images to have shape: [1, None, None, 3]
           image_np_expanded = np.expand_dims(image_np, axis=0)
           # Actual detection.
           output_dict = run_inference_for_single_image(image_np, detection_graph)
           # Visualization of the results of a detection.
           vis_util.visualize_boxes_and_labels_on_image_array(
               image_np,
               output_dict['detection_boxes'],
               output_dict['detection_classes'],
               output_dict['detection_scores'],
               category_index,
               instance_masks=output_dict.get('detection_masks'),
               use_normalized_coordinates=True,
               line_thickness=8)
           plt.figure(figsize=IMAGE_SIZE)
           plt.imshow(image_np)
```





















