1.

- a) Make a graph of the boundary of the absolute stability region for the Runge-Kutta RK4 method on page 24.
- b) Apply the RK4 method to u' = 30u(1-u) with u(0) = 0.1 on the interval $0 \le t \le 2$. Use 14, 17 and 25 steps. For each run graph the numerical solution and the exact solution on the same plot.
- c) Explain the previous sequence of graphs in terms of the ODE and the plot from part a. Your answer should contain a quantitative explanation for why the transiton occurs at the value of *h* you observe.
- **2.** The θ -method for finite difference solutions of ODEs is

$$u_{n+1} = u_n + h [\theta f_{n+1} + (1 - \theta) f_n]$$

where $\theta \in [0,1]$.

- a) Compute the order of convergence of this method. Hint: it depends on θ .
- b) Numerically graph the boundary of the absolute stability region for $\theta = 1/4$.
- c) Show that the method is *A*-stable if and only if $\theta \ge 1/2$.
- d) Bonus: Analytically compute the boundary of the absolute stability region for $\theta = 1/4$
- 3. Newton's method can be used to solve

$$f(x) = 0$$

where $x \in \mathbb{R}^n$ and $f(x) \in \mathbb{R}^n$. Starting from an initial guess x_k ,

$$x_{k+1} = x_k - Df(x_k)^{-1}f(x_k).$$

Here, Df(x) is the Jacobian matrix

$$Df_{ij} = \frac{\partial f_i}{\partial x_j}$$

Implement Newton's method for systems. Your function should take as arguments f, Df and x_0 (an initial guess). It should terminate whenever either

- $|f(x)|_{\infty}$ is less than a specified tolerance
- $|f(x)|_{\infty}$ is less than a sepcified fraction of $|f(x_0)|_{\infty}$.

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These tolerances should be specified with optional arguments as used in your language of choice, with values of 10^{-8} as the default.

Your function should return the estimated root and, as a diagnostic, the number of iterations needed to find the root.

Test your code against solving the simultaneous equations $x^2 + y^2 = 1$ and x = y starting from x = 0, y = 3. Report the root found and the number of iterations needed to find it.

4. The energy for the heat equation $u_t = u_{xx}$ for $0 \le x \le 1$ is

$$E(t) = \frac{1}{2} \int_0^1 (u_x(x,t))^2 dx.$$

a) Assuming that at x = 0 and at x = 1 u satisfies either a homogeneous Dirichlet condition or a homogeneous Neumann condition, show that

$$\frac{d}{dt}E(t)\leq 0.$$

Hint: Take a time derivative, use the PDE, and integrate by parts.

- b) Conclude that the only solution of $u_t = u_{xx}$ with u = 0 at t = 0, and at x = 0 and x = 1 is the zero solution.
- 5. The backwards heat equation reads

$$u_t = -u_{xx}$$

so all that differs is a sign on the right-hand side. But this sign makes all the difference.

We will work with this equation for $0 \le x \le 1$ and $0 \le t \le 1$, and with homogeneous Dirichlet boundary conditions, so u = 0 at x = 0 and x = 1.

a) Show that

$$v(t) = \sin(k\pi x)e^{k^2\pi^2t}$$

is a solution of the PDE and the boundary conditions.

- b) For each $\epsilon > 0$, find a solution of the PDE and boundary conditions that satisfies $|u(0,x)| < \epsilon$ at each x, but $|u(1,x)| \ge 1$ at some x.
- c) Suppose you wish to find the solution u of the backwards heat equation with initial condition u_0 . But you don't know u_0 exactly, you know \hat{u}_0 , and that $|u_0(x) \hat{u}_0(x)| < 10^{-47}$ at every x. So you solve the backwards heat equation for \hat{u} instead. Find an L such that $|u(x,1) \hat{u}(x,1)| < L$ for all x, or explain why no such L exists.
- **6.** Implement the explict method for solving the heat equation with right-hand side function

$$u_t = u_{xx} + f$$

on $0 \le x \le 1$ and $0 \le t \le T$. You function should have the following signature: forcedheat(f,u0,N,M)

where

- f(x, t) is a function and provedes the desired forcing term
- u0(x) is a function and provides the desired initial condition.
- N + 1 is the number of interior spatial steps
- *M* is the number of time steps

It should return (x, t, u) where x is an array of grid coordinates that includes 0 and 1, t is a vector of t coordinates that includes 0 and T, and where u is an $(N + 2) \times (M + 1)$ matrix where column j encodes the solution at time t_j .

Test your code as follows

- Compute what *f* is if the solution is $u(t, x) = \sin(t)x(1 x)$.
- Now, working on $0 \le x \le 1$ and $0 \le t \le 2\pi$ compute solutions with this forcing term and compare your solution with the exact solution. By working with various grid sizes, confirm that your code has the expected order of convergence.