# MA 412: Complex Analysis

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## §1. Introduction

#### 1.1. Some basic definitions

Consider the equation  $X^2 + 1 = 0$ . Clearly, this equation has no roots over  $\mathbb{R}$ . Consider the set

$$\mathbb{C} = \{(a, b) : a, b \in \mathbb{R}\} = \mathbb{R}^2,$$

and define addition and subtraction over  $\mathbb C$  as

$$(a,b) + (c,d) = (a+c,b+d)$$
  
 $(a,b) \cdot (c,d) = (ac-bd,ad+bc).$ 

It is easy to show that  $(\mathbb{C}, +, \cdot)$  is a field with additive identity (0,0) and multiplicative identity (1,0). Further observe that  $\mathbb{R}$  is a subfield of  $\mathbb{C}$  – consider the field homomorphism  $\mathbb{R} \to \mathbb{C}$  defined by  $a \mapsto (a,0)$ . Now, we denote  $\iota = (0,1)$ , and write (a,b) as  $a+b\iota$ .

Observe that the equation  $X^2 + 1 = 0$  does have roots over  $\mathbb{C}$  since it can be written as  $(X + \iota)(X - \iota)$ . For the sake of completeness, we also note that the multiplicative identity of  $a + \iota b$  is

$$\frac{1}{a+\iota b} = \frac{a-\iota b}{a^2+b^2} = \frac{a}{a^2+b^2} - \frac{b}{a^2+b^2}\iota.$$

When writing  $z = a + b\iota$  where  $a, b \in \mathbb{R}$ , we write  $a = \Re z$  (the real part of z) and  $b = \Im z$  (the imaginary part of z). We also define the absolute value  $|z| = (a^2 + b^2)^{1/2}$  of z, and the conjugate  $\overline{z} = a - \iota b$  of z. We clearly have

$$z\overline{z} = |z|^2$$

$$\Re z = \frac{z + \overline{z}}{2}$$

$$\Im z = \frac{z - \overline{z}}{2}.$$

It is easy to check that

$$\overline{z+w} = \overline{z} + \overline{w}$$
 and  $\overline{z \cdot w} = \overline{z} \cdot \overline{w}$ .

We also have

$$\left| \frac{z}{w} \right| = \frac{|z|}{|w|}$$
$$|\overline{z}| = |z|.$$

Exercise 1.1. Check that the set

$$M = \begin{pmatrix} \alpha & \beta \\ -\beta & \alpha \end{pmatrix} : \alpha, \beta \in \mathbb{R}$$

with matrix addition and multiplication is a field isomorphic to  $\mathbb{C}$ .

To close out the tedious part of things, we have

$$|z + w|^2 = |z|^2 + |w|^2 + 2\Re(z\overline{w})$$
  

$$|z + w| \le |z| + |w|$$
(1.1)

Equation (1.1) is referred to as the *triangle inequality*.

#### 1.2. Polar representations and roots

Consider  $z = x + \iota y \in \mathbb{C}$ . We may then define

$$x = r\cos\theta \qquad y = r\sin\theta,$$

where |z| = r and the angle  $\theta$  is called the *argument* of z as is denoted  $\theta = \arg z$ . We typically restrict  $\theta$  to  $(-\pi, \pi]$ . We denote  $\operatorname{cis} \theta = \cos \theta + \iota \sin \theta$ . Therefore, we have

$$z = |z| \operatorname{cis}(\arg z).$$

Observe that rather conveniently,

$$cis \theta_1 \cdot cis \theta_2 = cis(\theta_1 + \theta_2).$$

Therefore, inductively,

$$z_1 z_2 \cdots z_n = \left(\prod_i |z_i|\right) \cdots r_n \operatorname{cis}\left(\sum_i \operatorname{arg} z_i\right).$$

In particular,

$$z^n = r^n \operatorname{cis}(n\theta)$$

for any n > 0. If  $z \neq 0$  (equivalently,  $r \neq 0$ ), the above holds for all  $n \in \mathbb{Z}$ . In the case where r = 1, we have

$$(\cos \theta + \iota \sin \theta)^n = \cos(n\theta) + \iota \sin(n\theta) \tag{1.2}$$

Equation (1.2) is referred to as de Moivre's formula.

Let us consider the equation  $z^n = a$ . This equation has n roots of the form

$$z = |a|^{1/n} \operatorname{cis}\left(\frac{2k\pi + \arg z}{n}\right)$$

for  $k = 0, 1, \dots, n - 1$ .

A line in the complex plane is a set of the form

$$L = \{ z = a + tb : t \in \mathbb{R} \},$$

for some fixed  $a, b \in \mathbb{C}$ , where b is a directional vector whose absolute value may be assumed to be 1. Since  $b \neq 0$ , we equivalently have

$$L = \{z : \Im\left(\frac{z-a}{b}\right) = 0\}.$$

We can also define the half-planes

$$H_a = \{z : \Im\left(\frac{z-a}{b}\right) > 0\}$$

$$K_a = \{z : \Im\left(\frac{z-a}{b}\right) < 0\}.$$

Note that  $H_a = a + H_0$ , where the addition is Minkowski addition:

$$H_a = \{a + z : z \in H_0\}.$$

#### 1.3. The extended plane

Define  $\mathbb{C}_{\infty} = \mathbb{C} \cup \{\infty\}$  and let  $S = \{(x_1, x_2, x_3) : x_1^2 + x_2^2 + x_3^2 = 1\}$  be the unit sphere in  $\mathbb{R}^3$ . We shall show a bijection from  $\mathbb{C}_{\infty}$  to S.

Let N = (0,0,1) be the 'north pole' of S, and orient  $\mathbb{C}$  (as  $\mathbb{R}^2$ ) in the horizontal plane in a manner such that  $\mathbb{C}$  cuts S along the equator. For  $z = x + \iota y \in \mathbb{C}$ , let us define the corresponding point  $Z = (x_1, x_2, x_3) \in S$ . We shall draw a line connecting z to N, and let Z be the point of intersection (other than N) of this line with S. Finally, we shall map  $\infty$  to N.

Let us define this more explicitly. The line through N and z is

$$L = \{tN + (1 - t)z : t \in \mathbb{R}\}.$$

Then, letting z = (x, y, 0), we have

$$t^2 + (1-t)^2|z|^2 = 1.$$

So,

$$|z|^2 = \frac{1-t^2}{(1-t)^2} = \frac{1+t}{1-t}$$

and

$$t = 1 - \frac{|z|^2 - 1}{|z|^2 + 1}.$$

Therefore, we map z to

$$Z = \left(\frac{2\Re z}{|z|^2 + 1}, \frac{2\Im z}{|z|^2 + 1}, \frac{|z|^2 - 1}{|z|^2 + 1}\right) \in S.$$

Based on this, we can define a distance metric between points in  $\mathbb{C}_{\infty}$ . For  $z, z' \in \mathbb{C}_{\infty}$  mapping to  $Z, Z' \in S$ , we let d(z, z') be the Euclidean distance between Z, Z' in  $\mathbb{R}^3$ . More explicitly,

$$d(z, z')^{2} = (x_{1} - x'_{1})^{2} + (x_{2} - x'_{2})^{2} + (x_{3} - x'_{3})^{2}$$

$$= 2 - 2(x_{1}x'_{1} + x_{2}x'_{2} + x_{3}x'_{3})$$

$$= \frac{2|z - z'|}{\left((|z|^{2} + 1)(|z'|^{2} + 1)\right)^{1/2}}$$

when  $z, z' \in \mathbb{C}$  and if  $z' = \infty$  (so Z' = (0, 0, 1)), we have

$$d(z, z') =$$

This correspondence between points of S and  $\mathbb{C}_{\infty}$  is called the *stereographic projection*.

**Exercise 1.2.** If P is a plane in  $\mathbb{R}^3$  and  $\Lambda = P \cap S$  is a circle on S, show that the projection of  $\Lambda$  on  $\mathbb{C}$  under the stereographic projection is a circle as well (possibly a circle of infinite radius, namely a line).

#### 1.4. Power series

In this section, we begin discussing convergence of series in  $\mathbb{C}$  and related properties.

**Definition 1.1.** If  $a_n \in \mathbb{C}$  for every  $n \geq 0$ , the series  $\sum_{n=0}^{\infty} a_n$  is said to *converge* to z iff for all  $\epsilon > 0$ , there exists  $N \in \mathbb{N}$  such that

$$\left| \sum_{n=0}^{m} a_n - z \right| < \epsilon$$

for all  $m \geq N$ .

The series  $\sum_{n=0}^{\infty} a_n$  is said to converge absolutely if  $\sum_{n=0}^{\infty} |a_n|$  converges.

**Theorem 1.1.**  $\mathbb{C}$  is complete. That is, every Cauchy sequence in  $\mathbb{C}$  is convergent.

Proof. Suppose  $\{x_n + \iota y_n\}$  is a Cauchy sequence in  $\mathbb{C}$ , where  $x_n, y_n \in \mathbb{R}$  for each n. We then have the existence of  $N \in \mathbb{N}$  such that for all m, k > N,  $|(x_m - x_k) + \iota(y_m - y_k)| < \epsilon$ . Consequently,  $|x_m - x_k| < \epsilon$  and  $|y_m - y_k| < \epsilon$ . However, since  $\mathbb{R}$  is complete, this implies that  $(x_n)$  and  $(y_n)$  are convergent, completing the proof.

**Theorem 1.2.** If  $\sum a_n$  converges absolutely,  $\sum a_n$  converges.

*Proof.* Let  $\epsilon > 0$ ,  $z_n = \sum_{i=0}^n a_i$ , and  $S_n = \sum_{i=0}^n |a_i|$ . Because  $\mathbb C$  is complete, it suffices to show that  $(z_n)$  is Cauchy. Since  $\sum |a_n|$  is convergent, there exists  $N \in \mathbb N$  such that  $|S_m - S_k| < \epsilon$  for all m, k > N. Supposing m > k, we have

$$S_m - S_k = \sum_{i=k+1}^m |a_i|.$$

So,

$$|z_m - z_k| = \left| \sum_{i=k+1}^m a_i \right|$$
$$\ge \sum_{i=k+1}^m |a_i| < \epsilon,$$

completing the proof.

**Exercise 1.3.** Show that  $\sum_{n=0}^{\infty} z_n$  converges iff |z| < 1.

**Theorem 1.3.** For a given power series  $\sum_{n=0}^{\infty} a_n (z-a)^n$ , define the number of R  $(0 \le R \le \infty)$  by

$$\frac{1}{R} = \limsup_{n \to \infty} |a_n|^{1/n}.$$

Then,

- (a) If |z a| < R, the series converges absolutely.
- (b) If |z-a| > R, the terms of the series become unbounded and the series diverges.
- (b) If 0 < r < R, the series converges uniformly on the set  $\{z : |z a| \le r\}$ .

This R is referred to as the radius of convergence of the power series.

Proof.

(a) We assume without loss of generality that a = 0. If |z| < R, there exists r with |z| < r < R. By the definition of R, for all  $\epsilon > 0$ , there exists  $N \in \mathbb{N}$  such that

$$\frac{1}{R} - \epsilon < \sup_{k \ge n} |a_k|^{1/k} < \frac{1}{R} + \epsilon$$

for all n > N. If we take  $\epsilon = 1/r - 1/R$ , it follows that  $|a_n|^{1/n} < 1/r$  for all n > N. That is, for all n > N,  $|a_n| < 1/r^n$  and so

$$|a_n z^n| < \left(\frac{|z|}{r}\right)^n.$$

Therefore,  $\sum_{n=N}^{\infty} a_n z^n$  is dominated by  $\sum_{n=N}^{\infty} (|z|/r)^n$ . Now however, we can just use the result of Exercise 1.3 to conclude absolute convergence since |z|/r < 1.

(b) Let |z| > R and choose r with |z| > r > R. For  $\epsilon > 0$ , there exists  $N \in \mathbb{N}$  such that

$$\frac{1}{R} - \epsilon < \sup_{k \ge n} |a_k|^{1/k} \text{ for all } n > N.$$

Choosing  $\epsilon = 1/R - 1/r$ ,

$$|a_n|^{1/n} > 1/r$$

for infinitely many  $n \in \mathbb{N}$ . It follows that  $|a_n z^n| > (|z|/r)^n$  for infinitely many  $n \in \mathbb{N}$ . Since |z|/r > 1, these terms become unbounded and therefore the series diverges.

(c) Now, suppose r < R and choose  $\rho$  such that  $r < \rho < R$ . Similar to the argument in (a), we get that

$$|a_n| < \frac{1}{\rho^n}$$
 for all  $n \ge N$ .

If  $|z| \le r$ ,  $|a_n z^n| \le (r/\rho)^n$  and  $r/\rho < 1$ . The Weierstrass *M*-test then gives that the power series converges uniformly on  $\{z : |z| \le r\}$ .

It should be noted that we cannot conclude anything when |z - a| = R.

**Theorem 1.4.** If  $\sum a_n(z-a)^n$  is a power series with radius of convergence R, then if it exists,

$$\lim_{n \to \infty} \left| \frac{a_n}{a_{n+1}} \right| = R.$$

*Proof.* Again, assume that a=0 and let  $\alpha=\lim |a_n/a_{n+1}|$ , which we assume exists. Suppose that  $|z|<\alpha$  and take  $r\in\mathbb{R}$  such that  $|z|< r<\alpha$ . For all  $\epsilon>0$ , there exists  $N\in\mathbb{N}$  such that for  $n\geq N$ ,

$$\alpha - \epsilon < \left| \frac{a_n}{a_{n+1}} \right| < \alpha + \epsilon.$$

Taking  $\epsilon = \alpha - r$ ,  $|a_n/a_{n+1}| > r$  for all  $n \ge N$ . Let  $B = |a_N|r^N$ . Then,

$$a_{N+1}r^{N+1} = |a_{N+1}|r \cdot r^N < |a_N|r^N = B.$$

Similarly, we get that  $|a_n|r^n < B$  for all  $n \ge N$ . Therefore,

$$|a_n z^n| < B\left(\frac{|z|}{r}\right)^n$$

for all  $n \ge N$ . Thus, the sequence converges absolutely since |z| < r. Since  $r < \alpha$  was arbitrary, this implies that  $\alpha \le R$ .

On the other hand, if  $|z| > \alpha$ , take  $r \in \mathbb{R}$  such that  $|z| > r > \alpha$ . Taking  $\epsilon = r - \alpha$ , we get  $N \in \mathbb{N}$  such that

$$\left| \frac{a_n}{a_{n+1}} \right| < r$$

for all  $n \ge N$ . Letting  $B = |a_N|r^N$  again, we once more obtain that  $|a_n|r^n > B$  for all  $n \ge N$ . This gives that

$$|a_n z^n| > B\left(\frac{|z|}{r}\right)^n$$

for all  $n \ge N$ , and since |z| > r, the sequence diverges (we may assume that  $B \ne 0$  by making N larger if required to ensure that  $a_N \ne 0$  – if this is not possible, the problem is trivial since it means that  $(a_n)$  is eventually 0). Since the choice of r was arbitrary, this implies that  $R \le \alpha$ , completing the proof.

Now, consider the series

$$\sum_{n=0}^{\infty} \frac{z^n}{n!}.$$

The radius of convergence of this series is  $\infty$ . So, it converges for any complex number z, and convergence is uniform on every compact subset of  $\mathbb{C}$ .

The above defines a function  $\exp : \mathbb{C} \to \mathbb{C}$ .

We also denote  $e^z = \exp(z)$ .

**Definition 1.2** (Differentiability). If G is an open set in  $\mathbb{C}$  and  $f: G \to \mathbb{C}$ , then f is said to be differentiable at a point  $a \in G$  if the limit

$$\lim_{h \to 0} \frac{f(a+h) - f(a)}{h}$$

exists. If it exists, the value of this limit is denoted f'(a) and is called the *derivative* of f at a.

If f is differentiable at each point of G, we say that f is differentiable on G. Note that if f is differentiable on G, then  $f': G \to \mathbb{C}$  is a function. If f' is continuous, f is said to be *continuously differentiable*.

**Theorem 1.5.** If  $f: G \to \mathbb{C}$  is differentiable at a point  $a \in G$ , f is continuous at a.

*Proof.* The proof of this is direct:

$$\lim_{z \to a} |f(z) - f(a)| = \left(\lim_{z \to a} \frac{|f(z) - f(a)|}{|z - a|}\right) \cdot \lim_{z \to a} |z - a|$$
$$= f'(a) \cdot 0 = 0.$$

**Definition 1.3.** A function  $f: G \to \mathbb{C}$  is said to be analytic if f is continuously differentiable on G.

Let f, g be analytic on G and  $\Omega$  respectively, and suppose that  $f(G) \subseteq \Omega$ . Then,  $g \circ f$  is analytic on G and

$$(g \circ f)'(z) = g'(f(z)) \cdot f'(z)$$

for all  $z \in G$ . This is called the *chain rule*.

We shall show later that if f is differentiable then its derivative is continuous, and so f is analytic.

**Theorem 1.6.** Let  $f(z) = \sum_{n=0}^{\infty} a_n (z-a)^n$  have radius of convergence R > 0. Then

(a) For each  $k \ge 1$ , the series

$$\sum_{n=k}^{\infty} n(n-1)\cdots(n-k+1)a_n(z-a)^{n-k}$$

has radius of convergence R.

- (b) The function f is infinitely differentiable on B(a, R) (the open ball of radius R centered at a), and further,  $f^{(k)}(z)$  is given by the series in (a) for all  $k \ge 1$  and |z a| < R.
- (c) For  $n \ge 0$ ,  $a_n = \frac{1}{n!} f^{(n)}(a)$ .

*Proof.* Assume that a = 0.

(a) Note that it suffices to prove the result for k = 1 (Why?). To show this, it is enough to show that

$$\limsup_{n \to \infty} |a_n|^{1/n} = \limsup_{n \to \infty} |na_n|^{1/(n-1)}$$

First, it is not difficult to show that  $\lim_{n\to\infty} n^{1/(n-1)} = 1$ . It may be shown that for any sequences  $(c_n)$ ,  $(d_n)$  in  $\mathbb{R}$  where  $c_n \geq 0$ , if  $\lim c_n = c$  and  $\lim \sup d_n = d$ , then  $\lim \sup c_n d_n = cd$ . Therefore, we are done if we show that  $\lim \sup_{n\to\infty} |a_n|^{1/n} = \lim \sup_{n\to\infty} |a_n|^{1/(n-1)}$ .

$$\sum_{n=0}^{\infty} a_n z^n = a_0 + z \sum_{n=0}^{\infty} a_{n+1} z^n.$$

Let R' be the radius of convergence of  $\sum_{n=0}^{\infty} a_{n+1} z^n$ . We want to show that R' = R. If |z| < R', then

$$\sum |a_n z^n| \le |a_0| + |z| \sum_{n=0}^{\infty} |a_{n+1} z^n| < \infty,$$

so  $R' \leq R$ . On the other hand, if |z| < R and  $z \neq 0$ ,

$$\sum |a_{n+1}z^n| < \frac{1}{|z|} \left( \sum |a_n z^n| + |a_0| \right) < \infty,$$

so  $R \leq R'$  and we are done.

(b) Once again, it suffices to prove the result for k = 0. For |z| < R and  $g(z) = \sum_{n=1}^{\infty} n a_n z^{n-1}$ ,

$$s_n(z) = \sum_{k=0}^n a_k z^k$$
 and  $R_n(z) = \sum_{k=n+1}^\infty a_k z^k$ ,

fix a point  $w \in B(0, R)$  and  $\underline{r}$  such that |w| < r < R. We wish to show that f'(w) exists and is equal to g(w). Let  $\delta > 0$  be arbitrary with  $\overline{B(w, \delta)} \subseteq B(0, r)$ . Letting  $z \in B(w, \delta)$ , we have

$$\frac{f(z) - f(w)}{z - w} - g(w) = \frac{s_n(z) - s_n(w)}{z - w} - s'_n(w) + s'_n(w) - g(w) + \frac{R_n(z) - R_n(w)}{z - w}$$

$$= \frac{s_n(z) - s_n(w)}{z - w} - s'_n(w) + s'_n(w) - g(w) + \frac{1}{z - w} \sum_{k=n+1}^{\infty} a_k (z^k - w^k)$$

$$= \frac{s_n(z) - s_n(w)}{z - w} - s'_n(w) + s'_n(w) - g(w) + \sum_{k=n+1}^{\infty} a_k \frac{z^k - w^k}{z - w}.$$

We have

$$|z^{k} - w^{k}| = |z - w||z^{k-1} + z^{k-2}w + \dots + w^{k-1}| \le |z - w|kr^{k-1}.$$

Therefore,

$$\left| \frac{R_n(z) - R_n(w)}{z - w} \right| \le \sum_{k=n+1}^{\infty} |a_k| k r^{k-1}.$$

Since r < R,  $\sum_{k=1}^{\infty} |a_k| k r^{k-1}$  converges and so for any  $\epsilon > 0$ , there exists  $N_1 \in N$  such that

$$\left| \frac{R_n(z) - R_n(w)}{z - w} \right| < \epsilon/3.$$

Since  $\lim s'_n(w) = g(w)$ , there exists  $N_2 \in \mathbb{N}$  such that

$$|s_n'(w) - g(w)| < \epsilon/3$$

for  $n \ge N_2$ . Choose  $n \ge \max(N_1, N_2)$ . Then, there exists  $\delta < 0$  such that whenever  $0 < |z - w| < \delta$ ,

$$\left| \frac{s_n(z) - s_n(w)}{z - w} - s'_n(w) \right| < \epsilon/3.$$

Putting all these together, we get the desideratum.

(c) This is straightforward using the explicit expression for  $f^{(k)}(a)$ .

If the series  $f(z) = \sum_{n=0}^{\infty} a_n (z-a)^n$  has radius of convergence R > 0, then f is analytic on B(a,R). Therefore, exp is analytic on  $\mathbb{C}$ .

#### 1.5. Cauchy-Riemann Equations

Let  $f: G \to \mathbb{C}$  be analytic and let

$$u(x,y) = \Re(f(x+\iota y)), v(x,y) = \Re(f(x+\iota y))$$

for  $x + \iota y \in G$ . Let us evaluate the limit

$$f'(z) = \lim_{h \to 0} \frac{f(z+h) - f(z)}{h}.$$

in two different ways.

First, if we let  $h \to 0$  through real values, we get

$$f'(z) = \frac{\partial u}{\partial x}(x, y) + \iota \frac{\partial v}{\partial x}(x, y).$$

Along the imaginary axis, we get

$$f'(z) = -\iota \frac{\partial u}{\partial y}(x, y) + \frac{\partial v}{\partial y}(x, y).$$

Therefore,

$$\frac{\partial u}{\partial x} = \frac{\partial v}{\partial y}$$
 and  $\frac{\partial u}{\partial y} = -\frac{\partial v}{\partial x}$ .

Supposing that u and v have continuous second derivative (we shall later show that they are infinitely differentiable), we have that

$$\frac{\partial^2 u}{\partial x^2} = \frac{\partial^2 v}{\partial x \partial y} \text{ and } \frac{\partial^2 u}{\partial y^2} = \frac{\partial^2 v}{\partial y \partial x}.$$

Therefore, since the second derivatives are continuous.

$$\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} = 0. ag{1.3}$$

A function u with continuous second partial derivatives satisfying Equation (1.3) is said to be *harmonic*. Similarly, v is also harmonic.

**Theorem 1.7.** Let u, v be real-valued functions defined on an open connected set (a region) G and suppose that they have continuous second partial derivatives. Then,  $f: G \to \mathbb{C}$  defined by  $f(z) = u(z) + \iota v(z)$  is analytic iff u and v satisfy the Cauchy-Riemann equations.

*Proof.* We have already shown the forward direction.

For the other direction, let  $z = x + \iota y \in G$  and  $B(z,r) \subseteq G$ . Let  $h = s + \iota t \in B(0,r)$ . Our goal is to show that for all  $\epsilon > 0$ , there exists  $\delta > 0$  such that

$$\left| \frac{f(z+h) - f(z) - f'(z)h}{h} \right| < \epsilon$$

for all  $h \in B(0, \delta)$  for some  $f'(z) \in \mathbb{C}$ . Note that

$$u(x+s,y+t) - u(x,y) = (u(x+s,y+t) - u(x,y+t)) + (u(x,y+t) - u(x,y)).$$

Now, for fixed  $t \in (-r, r)$ ,  $s \mapsto u(x + s, y + t)$  is a differentiable function on (-r, r). We apply the mean value theory to conclude that there exist  $s_1, t_1 \in (-r, r)$  for each  $s + \iota t \in B(0, r)$  such that  $|s_1| < |s|$ ,  $|t_1| < |t|$ , and

$$u(x+s,y+t) - u(x,y+t) = u_x(x+s_1,y+t)s$$
  
$$u(x,y+t) - u(x,y) = u_y(x,y+t_1)t.$$

Now, let

$$\varphi(s,t) = \left(u(x+s,y+t) - u(x,y)\right) - \left(u_x(x,y)s + u_y(x,y)t\right).$$

We get that

$$\varphi(s,t) = (su_x(x+s_1,y+t) - su_x(x,y)) + (tu_y(x,y+t_1) - tu_y(x,y)).$$

So,

$$\frac{\varphi(s,t)}{s+\iota t} = \frac{s}{s+\iota t} \left( u_x(x+s_1,y+t) - u_x(x,y) \right) + \frac{t}{s+\iota t} \left( u_y(x,y+t_1) - u_y(x,y) \right)$$

and on taking the limit of both sides as  $s + \iota t \to 0$ , we can use the fact that  $|s| \le |s + \iota t|$ ,  $|t| \le |s + \iota t|$ ,  $|s_1| < |s|$ ,  $|t_1| < t$ , and the continuity of  $u_x$ ,  $u_y$ , to conclude that

$$\lim_{s+\iota t\to 0} \frac{\varphi(s,t)}{s+\iota t} = 0.$$

Therefore,

$$u(x + s, y + t) - u(x, y) = u_x(x, y)s + u_y(x, y)t + \varphi(s, t).$$

We get a similar equation for v as well, with a function  $\psi$  (in place of  $\varphi$ ). Combining the two,

$$\frac{f(z+s+\iota t) - f(z)}{s+\iota t} = \frac{u(x+s,y+t) - u(x,y)}{s+\iota t} + \iota \frac{v(x+s,y+t) - v(x,y)}{s+\iota t}$$

$$= \frac{su_x(x,y) + tu_y(x,y) + \varphi(s,t) + \iota \left(sv_x(x,y) + tv_y(x,y) + \psi(s,t)\right)}{s+\iota t}$$

$$= \frac{u_x(x,y)(s+\iota t) + \iota v_x(x,y)(s+\iota t) + \varphi(s,t) + \iota \psi(s,t)}{s+\iota t},$$

where we used Cauchy-Riemann equations in the final step and thus,

$$\lim_{s+\iota t\to 0} \frac{f(z+s+\iota t)-f(z)}{s+\iota t} = u_x(x,y) + \iota v_x(x,y),$$

completing the proof. Since  $u_x$  and  $v_x$  are continuous, f' is continuous and f is analytic.

A next question is: given some u such that

$$\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2},$$

when does there exist harmonic v such that  $u + \iota v$  is analytic? Such a v is referred to as a harmonic conjugate of u. It turns out that the answer is not always. Indeed,  $u(x,y) = \log((x^2 + y^2)^{1/2})$  on  $\mathbb{C} \setminus \{0\}$ , despite being harmonic, does not have a harmonic conjugate.

**Theorem 1.8.** Let G be either the entirety of  $\mathbb{C}$  or some open disk. If  $u: G \to \mathbb{R}$  is a harmonic function, then u has a harmonic conjugate.

*Proof.* Let G = B(0, R) for some  $0 < R \le \infty$  and let  $u : G \to \mathbb{R}$  be analytic. Define

$$v(x,y) = \int_0^y u_x(x,t) dt + \varphi(x)$$

so that  $u_x = v_y$ . We shall determine  $\varphi$  such that  $v_x = -u_y$ . Differentiating with respect to x, we get

$$v_x(x,y) = \int_0^y u_{xx}(x,t) dt + \varphi'(x)$$
$$= -\int_0^y u_{yy}(x,t) dt + \varphi'(x)$$
$$= -u_y(x,y) + u_y(x,0) + \varphi'(x).$$

Therefore,  $\varphi'(x) = -u_y(x,0)$ , and the function

$$v(x,y) = \int_0^y u_x(x,t) dt - \int_0^x u_y(s,0) ds$$

is a harmonic conjugate of u.

The above proof requires that the entire segments [(0,0),(x,0)] [(x,0),(x,y)] are contained in G, which is true when we are on a disk.

#### 1.6. Transformations

Consider the two hyperbolas defined by

$$x^2 - y^2 = c$$
$$2xy = d,$$

where  $c, d \neq 0$ .

This gives

$$y = \pm \sqrt{\frac{-c \pm \sqrt{d^2 + c^2}}{2}}.$$

Consider the functions

$$u(x,y) = x^2 - y^2$$
$$v(x,y) = 2xy.$$

The two hyperbolas above are mapped by this  $f = u + \iota v$  to the straight lines u = c and v = d.

**Definition 1.4.** A path in a region  $G \subseteq \mathbb{C}$  is a continuous function  $\gamma : [a, b] \to G$  for some interval [a, b] in  $\mathbb{R}$ . If  $\gamma'(t)$  exists for each  $t \in [a, b]$  and  $\gamma' : [a, b] \to \mathbb{C}$  is continuous, then  $\gamma$  is

By the existence of  $\gamma'$ , we mean that the two-sided limit

$$\lim_{h \to 0} \frac{\gamma(t+h) - \gamma(t)}{h}$$

exists for  $t \in (a, b)$  and the right and left sided limits exist for t = a, b respectively. This is equivalent to saying that  $\Re \gamma$  and  $\Im \gamma$  have derivatives.

Suppose  $\gamma: [a, b] \to G$  is a smooth path and for some  $t_0 \in (a, b)$ ,  $\gamma'(t_0) \neq 0$ . Then,  $\gamma$  has a tangent line at the point  $z_0 = \gamma(t_0)$ . This lines goes through the point  $z_0$  in the direction of the vector  $\gamma'(t_0)$ , that is, the slope of the line is

 $\tan(\arg \gamma'(t_0)).$ 

If  $\gamma_1$  and  $\gamma_2$  are two smooth paths with  $\gamma_1(t_1) = \gamma_2(t_2) = z_0$  and  $\gamma'_1(t_1), \gamma'_2(t_2) \neq 0$ , then define the angle between the paths  $\gamma_1, \gamma_2$  at  $z_0$  to be  $\arg(\gamma'_2(t_2)) - \arg(\gamma'_1(t_1))$ .

Suppose  $\gamma$  is a smooth path in G and  $f: G \to \mathbb{C}$  is analytic. Then,  $\sigma = f \circ \gamma$  is also a smooth path and  $\sigma'(t) = f'(\gamma(t)) \cdot \gamma'(t)$ . Further, if  $t_0$  is a fixed point of f with  $\gamma(t_0) = z_0$ ,

$$\arg(\sigma'(t_0)) - \arg(\gamma'(t_0)) = \arg(f'(z_0)).$$

Letting  $\gamma_1, \gamma_2$  be smooth paths with  $\gamma_1(t_1) = \gamma_2(t_2) = z_0$  with non-zero derivatives at  $t_1, t_2$  respectively, and lt  $\sigma_1 = f \circ \gamma_1, \sigma_2 = f \circ \gamma_2$ . Further suppose that the two paths  $\gamma_1, \gamma_2$  are not tangent to each other at  $z_0$ . Then,

$$\arg(\gamma_2'(t_2)) - \arg(\gamma_1'(t_1)) = \arg(\sigma_2'(t_2)) - \arg(\sigma_1'(t_1)).$$

This says that the angle between two paths are preserved after applying an analytic function to both. A function f satisfying this is said to have the *angle-preserving property*.

**Definition 1.5.** A function  $f: G \to \mathbb{C}$  which has the angle-preserving property and also has

$$\lim_{z \to a} \left| \frac{f(z) - f(a)}{z - a} \right|$$

existing is called a *conformal map*.

It turns out that a function f is a conformal map if and only if it is analytic and  $f'(z) \neq 0$  for all z (How?).

**Definition 1.6.** A mapping of the form

$$S(z) = \frac{az+b}{cz+d}$$

is called a linear fractional transformation. If we further have that  $ad - bc \neq 0$ , then S(z) is called a Möbius transformation.

We have

$$S'(z) = \frac{ad - bc}{(cz + d)^2}.$$

If w = S(z), it is relatively simple to show that

$$z = S^{-1}(w) = \frac{dw - b}{-cw + a}.$$

Therefore, the inverse of a Möbius transformation is a Möbius transformation. The composition of two Möbius transformations is a Möbius transformation as well.

Also observe that the coefficiencts a,b,c,d for a given Möbius transformation are not unique since we can multiply them by a constant. We may also extend S to  $\mathbb{C}_{\infty}$  with  $S(\infty) = a/c$  and  $S(-d/c) = \infty$ .

S(z)=z+a is called a translation, S(z)=az with  $a\neq 0$  is called a dilation,  $S(z)=e^{i\theta}z$  is called a rotation, and S(z)=1/z is called the inversion. We shall see later that any Möbius transformation is a composition of these five types of transformations.

What are the fixed points of a Möbius transformation S? S(z) = z gives

$$cz^2 + (a-d)z + b = 0.$$

Therefore, a Möbius transformation has at most two fixed points unless S(z) = z for all  $z \in \mathbb{C}_{\infty}$ .

Let  $a, b, c \in \mathbb{C}_{\infty}$  be distinct with  $S(a) = \alpha$ ,  $S(b) = \beta$ ,  $S(c) = \gamma$ . Let T be another Möbius transformation with  $T(a) = \alpha$ ,  $T(b) = \beta$ ,  $T(c) = \gamma$ . Then  $T^{-1} \circ S$  has three (distinct) fixed points, and therefore S = T. Therefore, any Möbius transformation is uniquely determined by its value at any three distinct points.

Let  $z_2, z_3, z_4 \in \mathbb{C}_{\infty}$  be distinct. Define  $S : \mathbb{C}_{\infty} \to \mathbb{C}_{\infty}$  by

$$S(z) = \begin{cases} \frac{(z-z_3)/(z-z_4)}{(z_2-z_3)(z_2-z_4)}, & z_2, z_3, z_4 \in \mathbb{C}, \\ \frac{z_2-z_4}{z-z_4}, & z_3 = \infty, \\ \frac{z-z_3}{z_2-z_3}, & z_4 = \infty. \end{cases}$$

In any case,  $S(z_2) = 1$ ,  $S(z_3) = 0$ ,  $S(z_4) = \infty$ , and S is the only transformation having this property.

**Definition 1.7.** If  $z_1 \in \mathbb{C}_{\infty}$ , then  $(z_1, z_2, z_3, z_4)$  is referred to as the *cross-ratio* of  $z_1, z_2, z_3, z_4$  and is the image of  $z_1$  under the Möbius transformation described above, which is the unique Möbius transformation taking  $z_2$  to 1,  $z_3$  to 0, and  $z_4$  to  $\infty$ .

For example,  $(z_2, z_2, z_3, z_4) = 1$  and  $(z, 1, 0, \infty) = z$ . If M is any Möbius transformation with  $M(w_2) = 1$ ,  $M(w_3) = 0$ ,  $M(w_4) = \infty$ , then  $M(z) = (z, w_2, w_3, w_4)$  for any  $z \in \mathbb{C}_{\infty}$ .

**Theorem 1.9.** If  $z_2, z_3, z_4$  are distinct points and T is any Möbius transformation, then

$$(z_1, z_2, z_3, z_4) = (Tz_1, Tz_2, Tz_3, Tz_4).$$

*Proof.* Let  $S(z) = (z, z_2, z_3, z_4)$ . If  $M = ST^{-1}$ , then

$$M(T(z_2)) = 1$$
,  $M(T(z_3)) = 0$ ,  $M(T(z_4)) = \infty$ .

Therefore,  $M = (z, Tz_2, Tz_3, Tz_4)$ . That is,

$$ST^{-1}z = (z, Tz_2, Tz_3, Tz_4)$$

for all  $z \in \mathbb{C}_{\infty}$ . Setting  $z = Tz_1$  yields the required.

**Lemma 1.10.** If  $\{z_2, z_3, z_4\}$ ,  $\{w_2, w_3, w_4\} \subseteq \mathbb{C}_{\infty}$ , then there exists a unique Möbius transformation S with  $Sz_i = w_i$  for each i.

We omit the proof of the above.

**Lemma 1.11.** Let  $\{z_1, z_2, z_3, z_4\} \subseteq \mathbb{C}_{\infty}$ . Then,  $(z_1, z_2, z_3, z_4)$  is real iff the four points lie on a circle.

*Proof.* Define  $S: \mathbb{C}_{\infty} \to \mathbb{C}_{\infty}$  by  $Sz = (z, z_2, z_3, z_4)$ . We are done if we show that  $S^{-1}(\mathbb{R}_{\infty})$  is a circle (since a circle is uniquely determined by three distinct points on it). Let  $S^{-1}(z) = (az + b)/(cz + d)$ .

First, let us show that  $S^{-1}(\mathbb{R}_{\infty}) \subseteq \Gamma$  for a circle  $\Gamma$  in  $\mathbb{C}_{\infty}$ . Let  $w \in S^{-1}(\mathbb{R}_{\infty})$ . Then,  $Sw = \overline{Sw}$  so

$$\frac{aw+b}{cw+d} = \frac{\overline{aw} + \overline{b}}{\overline{cw} + \overline{d}}.$$

This gives that

$$(a\overline{c} - \overline{a}c)|w|^2 + (a\overline{d} - \overline{b}c)w + (b\overline{c} - d\overline{a})\overline{w} + (b\overline{d} - \overline{b}d) = 0.$$
 ((\*))

If  $a\overline{c}$  is real, we get that

$$\Im\left((a\overline{d} - \overline{b}c)w + b\overline{d}\right) = 0,$$

which is a circle through  $\infty$  (a line).

If on the other hand  $a\overline{c}$  is not real, then Equation ((\*)) becomes

$$2\iota \underbrace{\Im(a\overline{c})}_{\alpha \neq 0} |w|^2 + (a\overline{d} - b\overline{c})w + (b\overline{c} - \overline{a}d)\overline{w} + (b\overline{d} - \overline{b}d) = 0.$$

Dividing by  $2\iota\alpha$ ,

$$|w|^2 + \frac{(a\overline{d} - b\overline{c})w}{2\iota\alpha} + \frac{(b\overline{c} - \overline{a}d)\overline{w}}{2\iota\alpha} + \frac{(b\overline{d} - \overline{b}d)}{2\iota\alpha} = 0.$$

Since  $\alpha$  is real,

$$\frac{\overline{(b\overline{c}-\overline{a}d)\overline{w}}}{2\iota\alpha} = \frac{(a\overline{d}-b\overline{c})w}{2\iota\alpha}$$

and

$$\frac{(b\overline{d} - \overline{b}d)}{2\iota\alpha}$$

is real. This gives

$$|w|^2 + \overline{\gamma}w + \gamma \overline{w} - \delta = 0$$

for some  $\gamma \in \mathbb{C}, \delta \in \mathbb{R}$ . This is equivalent to  $|w+\gamma|=(|\gamma|^2+\delta)^{1/2}$ , which is the equation of a circle<sup>1</sup>.

Letting  $T = S^{-1}$  and  $\Gamma$  be the circle obtained in the previous part of the proof, we must now show that  $T(\mathbb{R}_{\infty}) = \Gamma$ . Since  $\mathbb{R}_{\infty}$  is connected and compact and T is a homeomorphism,  $T(\mathbb{R}_{\infty})$  is a closed arc, say  $\Gamma_1$ , of  $\Gamma$ . If  $\Gamma_1 \neq \Gamma$ , let  $z_1, z_2$  be the endpoints of this arc. If  $T(\infty) = z_3$  which is distinct from  $z_1, z_2$ , then  $\mathbb{R}_{\infty} \setminus \{\infty\}$  is connected but  $\Gamma_1 \setminus \{z_1\}$  is disconnected, which is a contradiction. So, suppose  $T(\infty) = z_1$ . Then,  $\mathbb{R}_{\infty} \setminus \{\infty, T^{-1}(z_2)\}$  is disconnected but  $\Gamma_1 \setminus \{z_1, z_2\}$  is connected, yielding a contradiction once more and completing the proof.

Next, we give a more general version of the above.

#### **Theorem 1.12.** A Möbius transformation takes circles to circles.

Note that Lemma 1.11 follows from this since  $\mathbb{R}_{\infty}$  is a circle (of infinite radius) in  $\mathbb{C}_{\infty}$ .

*Proof.* Let  $\Gamma$  be a circle in  $\mathbb{C}_{\infty}$  and S a Möbius transformation. Let  $z_2, z_3, z_4$  be three distinct points on  $\Gamma$ , and set  $w_j = Sz_j$  for each j. We claim that  $S(\Gamma)$  is the circle  $\Gamma'$  determined by  $w_2, w_3, w_4$ . Indeed,

$$(z, z_2, z_3, z_4) = (Sz, w_2, w_3, w_4)$$

for any z, and if  $z \in \Gamma$ , the LHS is real by Lemma 1.11, and using the same theorem on the RHS completes the proof.

**Definition 1.8.** Let  $\Gamma$  be a circle through  $z_2, z_3, z_4$ . The points  $z, z^* \in \mathbb{C}_{\infty}$  are said to be *symmetric* with respect to  $\Gamma$  if

$$(z^*, z_2, z_3, z_4) = \overline{(z, z_2, z_3, z_4)}.$$

*Remark.* The above definition only depends on  $\Gamma$ , not the choice of  $z_2, z_3, z_4$ .

<sup>&</sup>lt;sup>1</sup>it may be checked that  $|\gamma|^2 + \delta$  is a positive real by substituting their values

Observe that z is symmetric with respect to itself with respect to  $\Gamma$  if and only if  $z \in \Gamma$ . Indeed, it implies that  $(z, z_2, z_3, z_4)$  is real, which by Lemma 1.11 implies that  $z \in \Gamma$ .

What does it mean for  $z, z^*$  to be symmetric?

If  $\Gamma$  is a straight line,  $z, z^*$  are symmetric with respect to  $\Gamma$  iff their perpendicular bisector is equal to  $\Gamma$ . That is, the line joining  $z, z^*$  is perpendicular to  $\Gamma$  and they are the same distance from  $\Gamma$  (but on opposite sides). Indeed, choosing  $z_4 = \infty$ , we get that

$$\frac{z^* - z_3}{z_2 - z_3} = \frac{\overline{z} - \overline{z_3}}{\overline{z_2} - \overline{z_3}},$$

SO

$$|z - z_3| = |z^* - z_3|$$

for all  $z_3 \in \Gamma$ .

Now, suppose that  $\Gamma = \{z : |z - a| = R\}$  for some  $0 < R < \infty$ . We extensively use Theorem 1.9 and the five types of Möbius translations in the following sequence of equations. Then,

$$(z^*, z_2, z_3, z_4) = \overline{(z, z_2, z_3, z_4)}$$

$$= \overline{(z - a, z_2 - a, z_3 - a, z_4 - a)}$$

$$= \left(\overline{z} - \overline{a}, \frac{R^2}{z_2 - a}, \frac{R^2}{z_3 - a}, \frac{R^2}{z_4 - a}\right)$$

$$= \left(\frac{R^2}{\overline{z} - \overline{a}}, z_2 - a, z_3 - a, z_4 - a\right)$$

$$= \left(\frac{R^2}{\overline{z} - \overline{a}} + a, z_2, z_3, z_4\right).$$

Therefore,  $z^* = a + \frac{R^2}{\overline{z} - \overline{a}}$ , that is,

$$(z^* - a)(\overline{z} - \overline{a}) = R^2.$$

Since

$$\frac{z^* - a}{z - a} = \frac{R^2}{|z - a|^2} > 0$$

is real, it follows that  $z^*$  is on the ray  $\{a + t(z - a) : 0 < t < \infty\}$ . We also have that

$$|z^* - a||z - a| = R^2,$$

so one can easily obtain  $z^*$  from z or vice-versa.

**Lemma 1.13** (Symmetry Principle). If a Möbius transformation takes a circle  $\Gamma_1$  to the circle  $\Gamma_2$ , then any pair of points symmetric with respect to  $\Gamma_1$  is mapped to a pair of points symmetric with respect to  $\Gamma_2$ .

*Proof.* The proof of this is near-direct.

$$(Tz, Tz_2, Tz_3, Tz_4) = (z^*, z_2, z_3, z_4)$$

$$= \overline{(z, z_2, z_3, z_4)}$$

$$= \overline{(Tz, Tz_2, Tz_3, Tz_4)}.$$

**Definition 1.9.** If  $\Gamma$  is a circle, then an *orientation* for  $\Gamma$  is an ordered triple  $(z_1, z_2, z_3)$  of points in  $\Gamma$ .

An orientation is used to represent a "direction" of the circle, where we "go" from  $z_1$  to  $z_2$  to  $z_3$ .

Let  $\Gamma = \mathbb{R}$  and  $z_1, z_2, z_3 \in \mathbb{R}$ . Also put  $Tz = (z, z_1, z_2, z_3)$ . Since  $T(\mathbb{R}_{\infty}) = \mathbb{R}_{\infty}$ , a, b, c, d can be chosen to be reals. Then,

$$Tz = \frac{az+b}{cz+d}$$

$$= \frac{az+b}{|cz+d|^2}(c\overline{z}+d)$$

$$= \frac{1}{|cz+d|^2} \left(ac|z|^2 + bd + bc\overline{z} + adz\right).$$

So,

$$\Im(z, z_1, z_2, z_3) = \frac{ad - bc}{|cz + d|^2} \Im z$$

and thus,  $\{z: \Im(z, z_1, z_2, z_3)\}$  is either the upper or lower half-plane depending on whether ad - bc is positive or negative. Note that ad - bc is the determinant of  $\begin{pmatrix} a & b \\ c & d \end{pmatrix}$ .

Let  $\Gamma$  be an arbitrary circle and suppose that  $z_1, z_2, z_3 \in \Gamma$ . Then, for any Möbius transformation S,

$$\begin{split} \{z:\Im(z,z_1,z_2,z_3)>0\} &= \{z:\Im(Sz,Sz_1,Sz_2,Sz_3)>0\} \\ &= S^{-1}\{z:\Im(z,Sz_1,Sz_2,Sz_3)>0\}. \end{split}$$

So, if S is chosen to map  $\Gamma$  to  $\mathbb{R}_{\infty}$ , then the above set is equal to  $S^{-1}$  of either the upper or lower halfspace.

**Definition 1.10.** If  $z_1, z_2, z_3$  is an orientation of  $\Gamma$ , we denote the *right side* and *left side* of  $\Gamma$  (with respect to  $(z_1, z_2, z_3)$ ) to be

$$\{z: \Im(z, z_1, z_2, z_3) > 0\}$$
 and  $\{z: \Im(z, z_1, z_2, z_3) < 0\}$ 

respectively.

**Theorem 1.14** (Orientation Principle). Let  $\Gamma_1, \Gamma_2$  be circles in  $\mathbb{C}_{\infty}$  such that  $T\Gamma_1 = \Gamma_2$  for some Möbius transformation T. Let  $(z_1, z_2, z_3)$  be an orientation of  $\Gamma_1$ . Then, T takes the right side (resp. left side) of  $\Gamma_1$  with respect to the orientation  $(z_1, z_2, z_3)$  to the right side (resp. left side) of  $\Gamma_2$  with respect to the orientation  $(Tz_1, Tz_2, Tz_3)$ .

The proof of the above is left as an exercise to the reader.

Since  $(z, 1, 0, \infty) = z$  by definition, the right side of  $\mathbb{R}_{\infty}$  with respect to the orientation  $(1, 0, \infty)$  is the upper half-plane.

**Exercise 1.4.** Find an analytic function  $f: G \to \mathbb{C}$  where  $G = \{z : \Re z > 0\}$ , such that  $f(G) = \{z : |z| < 1\}$ .

Similar to the above exercise, one may show that

$$g(z) = \frac{e^z - 1}{e^z + 1}$$

maps the infinite strip  $\{z: |\Im z| < \pi/2\}$  to the open unit disk D.