view frames Result Recorded at time: 1635004380.4548383 (map) Broadcaster: /amcl Average rate: 10.207 Buffer length: 4.899 Most recent transform: 1635004380.191 Oldest transform: 1635004375.293 odom Broadcaster: /rf2o laser odometry Average rate: $6.1\overline{2}4$ Buffer length: 4.899 Most recent transform: 1635004380.091 Oldest transform: 1635004375.193 base_link Broadcaster: /robot state publisher Broadcaster: /base to laser broadcaster Broadcaster: /robot state publisher \ Average rate: $1000\overline{0}.0$ Average rate: 10000.0 Average rate: $1000\overline{0}.0$ Average rate: 10000.0 Average rate: $1000\overline{0}.0$ Average rate: $1000\overline{0}.0$ Average rate: $1000\overline{0}.0$ Average rate: $1000\overline{0}.0$ Average rate: 10.189 Buffer length: 0.0 Buffer length: 4.907 Most recent transform: 0.0 Most recent transform: 1635004380.459 Oldest transform: 0.0 Oldest transform: 1635004375.552 front_caster_base lt_wheel_shaft rt_wheel_shaft back_caster_base pcb_boards (laser rt_antenna lt antenna camera mount base Broadcaster: /robot state publisher Broadcaster: /robot state publisher | Broadcaster: /robot state publisher Average rate: 10000.0 Average rate: 10000.0 Average rate: 10000.0 Average rate: $1000\overline{0}.0$ Average rate: $1000\overline{0}.0$ Average rate: $10.2\overline{03}$ Average rate: $1000\overline{0}.0$ Average rate: $10.2\overline{03}$ Average rate: $1000\overline{0}.0$ Average rate: $1000\overline{0}.0$ Average rate: $1000\overline{0}.0$ Buffer length: 0.0 Buffer length: 4.9 Buffer length: 0.0 Buffer length: 0.0 Buffer length: 4.9 Buffer length: 0.0 Most recent transform: 1635004380.375 Most recent transform: 0.0 Most recent transform: 1635004380.375 Most recent transform: 0.0 Most recent transform: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 Oldest transform: 0.0 Oldest transform: 1635004375.474 Oldest transform: 0.0 Oldest transform: 0.0 Oldest transform: 1635004375.474 Oldest transform: 0.0 lt_wheelc rt_wheelc front_caster_rt_cyl front_caster_ball lt_antenna_top rt_antenna_top back_caster_lt_cyl back_caster_rt_cyl back_caster_ball front_caster_lt_cyl camera_mount_over Broadcaster: /robot state publisher Broadcaster: /robot state publisher Broadcaster: /robot state publisher Average rate: 10000.0 Average rate: $10.\overline{203}$ Average rate: $10.\overline{203}$ Buffer length: 0.0 Buffer length: 4.9 Buffer length: 4.9 Most recent transform: 1635004380.375 Most recent transform: 1635004380.375 Most recent transform: 0.0 Oldest transform: 1635004375.474 Oldest transform: 1635004375.474 Oldest transform: 0.0 rt_wheel (lt_wheel camera_mount_angled Broadcaster: /robot state publisher Average rate: $1000\overline{0}.0$ Buffer length: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 camera_screen_base Broadcaster: /robot state publisher Average rate: 10000.0 Buffer length: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 camera_pcb_base Broadcaster: /robot state publisher Average rate: 10000.0 Buffer length: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 camera_lens_body Broadcaster: /robot state publisher Average rate: 10000.0 Buffer length: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 camera_lens_body_out Broadcaster: /robot state publisher Average rate: 10000.0 Buffer length: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 camera_lens