Introduction to mirror descent

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Problem statement

$$\min_{x \in G} f(x)$$

- ▶ *f* is smooth and convex
- G is convex and closed
- ▶ Condition number $\kappa = \frac{L}{\mu}$, where L is Lipschitz constant of gradient and μ is strong convexity constant

Projected gradient descent

$$x_{k+1} = \pi_G(x_k - \alpha_k f'(x_k)) = \underset{x \in G}{\arg\min} \frac{1}{2} \|(x - x_k) + \alpha_k f'(x_k)\|_2^2$$

$$= \underset{x \in G}{\arg\min} \left\{ \underbrace{\frac{f(x_k) + \langle f'(x_k), x - x_k \rangle}{\|f(x)\|_2} + \underbrace{\frac{1}{2\alpha_k} \|x - x_k\|_2^2}_{\text{proximity term}} \right\}$$

$$f(x)$$

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$$f(x) + \langle \nabla f(x^t), x - x^t \rangle$$

Use euclidean distance to measure discrepancy between f and FO approximation

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- ▶ Main issue: local geometry might sometimes be highly inhomogeneous or even non-euclidean
- Can you give some examples?

Mirror descent: main idea

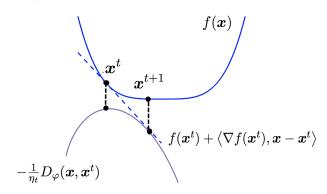
Nemirovsky & Yudin, 1983 Adjust gradient updates to fit problem geometry

Mirror descent: formalism

Replace euclidean distance with distance-like function D_{arphi}

$$x_{k+1} = \operatorname*{arg\,min}_{x \in G} \bigg\{ f(x_k) + \langle f'(x_k), x - x_k \rangle + \underbrace{\frac{1}{\alpha_k} D_\varphi(x, x_k)}_{\text{Bregman divergence}} \bigg\},$$

where $D_{\varphi}(x,z)=\varphi(x)-\varphi(z)-\langle \varphi'(z),x-z\rangle$ for convex and differentiable φ



Bregman divergence

Definition

Let φ be strictly convex and differentiable on G then for any $x,z\in G$

$$D_{\varphi}(x,z) = \varphi(x) - \varphi(z) - \langle \varphi'(z), x - z \rangle$$

- Similar to squared euclidean distance
- Locally quadratic measure:

$$D_{\varphi}(x,z) = (x-z)^{\top} \varphi''(\xi)(x-z)$$

for some ξ

How to choose Bregman divergence?

- ightharpoonup Fit local curvature of f
- ▶ Use geometry of feasible set G
- ▶ Inexpensive computation of Bregman projection

Examples

▶ Squared Mahalanobis distance, $A \in \mathbb{S}_{++}^n$

$$\varphi(x) = \frac{1}{2} x^{\top} A x, \quad D_{\varphi}(x, z) = \frac{1}{2} (x - z)^{\top} A (x - z)$$

$$MD: x_{k+1} = x_k - \alpha_k A^{-1} f'(x_k)$$

▶ KL divergence for $G = \Delta$

$$\varphi(x) = \sum_{i} x_i \log x_i, \quad D_{\varphi}(x, z) = \sum_{i} x_i \log \frac{x_i}{z_i}$$

$$\text{MD: } x_{k+1}^i = \frac{x_k^i \exp(-\alpha_k [f'(x_k)]_i)}{\sum_{j=1}^n x_k^j \exp(-\alpha_k [f'(x_k)]_j)}$$

Also known as exponential gradient method

Some more cases

Table is from this paper

Function Name	$\varphi(x)$	$\mathrm{dom}\varphi$	$D_{\varphi}(x;y)$
Squared norm	$\frac{1}{2}x^2$	$(-\infty, +\infty)$	$\frac{1}{2}(x-y)^2$
Shannon entropy	$x \log x - x$	$[0,+\infty)$	$x \log \frac{x}{y} - x + y$
Bit entropy	$x \log x + (1-x) \log(1-x)$	[0, 1]	$x \log \frac{x}{y} + (1-x) \log \frac{1-x}{1-y}$
Burg entropy	$-\log x$	$(0,+\infty)$	$\frac{x}{y} - \log \frac{x}{y} - 1$
Hellinger	$-\sqrt{1-x^2}$	[-1, 1]	$(1-xy)(1-y^2)^{-1/2}-(1-x^2)^{1/2}$
ℓ_p quasi-norm	$-x^p \qquad (0$	$[0,+\infty)$	$-x^{p}+pxy^{p-1}-(p-1)y^{p}$
ℓ_p norm	$ x ^p \qquad (1$	$(-\infty, +\infty)$	$ x ^{p} - p x \operatorname{sgn} y y ^{p-1} + (p-1) y ^{p}$
Exponential	$\exp x$	$(-\infty, +\infty)$	$\exp x - (x - y + 1) \exp y$
Inverse	1/x	$(0,+\infty)$	$1/x + x/y^2 - 2/y$

$$x_{k+1} = y_{k+1} = (\varphi')^{-1}(\varphi'(x_k) - \alpha_k f'(x_k))$$

Assume $G = \mathbb{R}^n$, then

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 - 2. Perform gradient step in dual space
 - 3. Project new point in primal space w.r.t. Bregman divergence proximity

Conjugacy and inversion

Lemma

$$(\varphi')^{-1} = (\varphi^*)'$$

Proof

- Assume $y = \varphi'(x)$
- By definition $\langle x,y\rangle=\varphi(x)+\varphi^*(y)$
- From convexity of φ : $\langle x,y\rangle=\varphi^{**}(x)+\varphi^{*}(y)$
- From definition follows $x = (\varphi^*)'(y)$
- Finally $x = (\varphi^*)'(y) = (\varphi^*)'(\varphi'(x))$

Then unconstrained MD can be written as

$$x_{k+1} = (\varphi^*)'(\varphi'(x_k) - \alpha_k f'(x_k))$$

Optimization over probability simplex with ℓ_2

Assume $G = \Delta$ and $x_0 = n^{-1}\mathbf{1}$

(1) Use euclidean proximity term: $\varphi(x)=\frac{1}{2}\|x\|_2^2$ – 1-strongly convex in $\|\cdot\|_2$. Then

$$\sup_{x \in G} D_{\varphi}(x, x_0) = \sup_{x \in \Delta} \frac{1}{2} \|x - n^{-1}\mathbf{1}\|_2^2 = \sup_{x \in \Delta} \frac{1}{2} \left(\|x\|_2^2 - \frac{1}{n} \right) \le \frac{1}{2}$$

and

$$f_K^{best} - f^* \le \mathcal{O}\left(L_{f,2} \frac{\log k}{\sqrt{k}}\right),$$

i.e. for all subgradients $g: ||g||_2 \le L_{f,2}$

Optimization over probability simplex with ℓ_1

Assume $G = \Delta$ and $x_0 = n^{-1}\mathbf{1}$

(2) Use ℓ_1 proximity term: $\psi(x) = -\sum_{i=1}^n x_i \log x_i - 1$ -strongly convex in $\|\cdot\|_1$. Then

$$\sup_{x \in G} D_{\psi}(x, x_0) = \sup_{x \in \Delta} D_{KL}(x||x_0) = \sup_{x \in \Delta} \sum_{i=1}^n x_i \log x_i - \sum_{i=1}^n x_i \log \frac{1}{n}$$
$$= \log n + \sum_{i=1}^n x_i \log x_i \le \log n$$

and

$$f_K^{best} - f^* \le \mathcal{O}\left(L_{f,\infty}\sqrt{\log n} \frac{\log k}{\sqrt{k}}\right)$$

i.e. for all subgradients $g: ||g||_{\infty} \leq L_{f,\infty}$

Optimization over probability simplex: comparison

Ignore log-terms and compare

- Euclidean: $\mathcal{O}\left(\frac{L_{f,2}}{\sqrt{k}}\right)$
- $D_{KL}: \mathcal{O}\left(\frac{L_{f,\infty}}{\sqrt{k}}\right)$
- ▶ Equivalence norm

$$||g||_{\infty} \le ||g||_2 \le \sqrt{n} ||g||_{\infty}$$

▶ Why D_{KL} is better:

$$\frac{1}{\sqrt{n}} \le \frac{L_{f,\infty}}{L_{f,2}} \le 1$$

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- Mirror descent separates steps in primal and dual spaces