

ALEXANDER LALEJINI

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EDUCATION

Mississippi State University

August 2011 - May 2015

Degree Conferred: May 2015

B.S., Computer Science (*Summa cum Laude*)

GPA: 4.0

PUBLICATIONS

A. Lalejini, D. Duckworth, R. Sween, C. Bethel, D. Carruth; "Evaluation of Supervisory Control Interfaces for Mobile Robot Integration with Tactical Teams," *2014 IEEE Workshop on Advanced Robotics and its Social Impacts (ARSO)*, 11-13 September, 2014.

RESEARCH EXPERIENCE

Laboratory for Autonomous Systems Research (LASR)

May 2014 - July 2014

Naval Research Laboratory

- Mentor: Dr. Greg Trafton, Dr. Laura Hiatt
- I worked on using dynamic context produced by a computational cognitive model to improve a neural network based object recognition system.

Center for Advanced Vehicular Systems (CAVS)

January 2014 - Present

Mississippi State University

- Mentor: Dr. Daniel Carruth, Dr. Cindy Bethel
- I have worked on the ITAR restricted CRES-GV project, which involved writing software to integrate robotic platforms in a vehicle simulation software package.

Social, Therapeutic, & Robotic Systems (STaRS) Laboratory

August 2013 - Present

Mississippi State University

- Mentor: Dr. Cindy Bethel
- I have worked as the project co-lead on the Robot Intent and Control Project. The project involved developing a system that allows for supervisory command and control of an autonomous robot platform using a variety of interfaces. This system was used in an experiment that measured the relative success of each interface.

TECHNICAL SKILLS

Computer Languages

Python, C/C++, Java

Software Tools & Libraries

Robot Operating System (ROS), Enthought Python, Scipy, Numpy

Version Control

GIT

Robots

Kobuki TurtleBot 2, Dr. Robot Jaguar

Web

PHP, HTML/CSS, SQL

Operating Systems

Linux, Windows, Mac OS

AWARDS AND HONORS

- Graduate of Shackouls Honors College
- Stephen D. Lee Scholar
- Presenter at ARSO 2014
- Bagley College of Engineering Hall of Fame
- 2015 Inductee
- Meritorious Award in Bagley Undergraduate Research Poster Competition (Poster title: Robot Control)