

DATA STRUCTURES APPLICATIONS 15CS33

MODULE 4

TREES

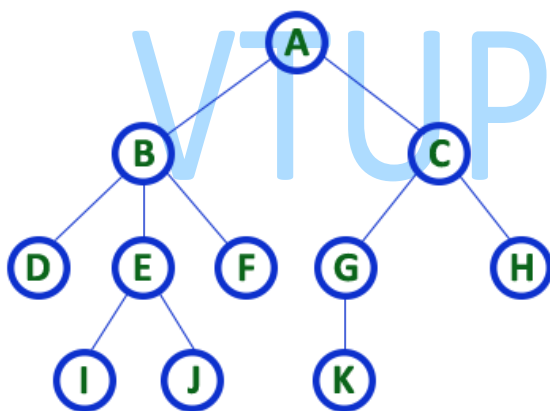
In linear data structure, data is organized in sequential order and in non-linear data structure, data is organized in random order. Tree is a very popular data structure used in wide range of applications. A tree data structure can be defined as follows...

Tree is a non-linear data structure which organizes data in hierarchical fashion and the tree structure follows a recursive pattern of organizing and storing data.

Every individual element is called as Node. Node in a tree data structure, stores the actual data of that particular element and link to next element in hierarchical structure.

if there are N number of nodes in a tree structure, then there can be a maximum of $N-1$ number of links.

Example



TREE with 11 nodes and 10 edges

- In any tree with ' N ' nodes there will be maximum of ' $N-1$ ' edges

- In a tree every individual element is called as '**NODE**'

1. Root

In a tree data structure, the first node is called as Root Node. Every tree must have root node. We can say that root node is the origin of tree data structure. In any tree, there must be only one root node. We never have multiple root nodes in a tree. **Ex: 'A' in the above tree**

2. Edge

In a tree data structure, the connecting link between any two nodes is called as EDGE. In a tree with ' N ' number of nodes there will be a maximum of ' $N-1$ ' number of edges. Ex: Line between two nodes.

3. Parent

In a tree data structure, the node which is predecessor of any node is called as PARENT NODE. In simple words, the node which has branch from it to any other node is called as parent node. Parent node can also be defined as "The node which has child / children".

Ex: A,B,C,E & G are parent nodes

4. Child

In a tree data structure, the node which is descendant of any node is called as CHILD Node. In simple words, the node which has a link from its parent node is called as child node. In a tree, any parent node can have any number of child nodes. In a tree, all the nodes except root are child nodes. Ex: B & C are children of A, G & H are children of C and K child of G

5. Siblings

In a tree data structure, nodes which belong to same Parent are called as SIBLINGS. In simple words, the nodes with same parent are called as Sibling nodes. Ex: B & C are siblings, D, E and F are siblings, G & H are siblings, I & J are siblings

6. Leaf

In a tree data structure, the node which does not have a child is called as LEAF Node. In simple words, a leaf is a node with no child. In a tree data structure, the leaf nodes are also called as External Nodes. External node is also a node with no child. In a tree, leaf node is also called as 'Terminal' node. Ex: D, I, J, F, K AND H are leaf nodes

7. Internal Nodes

In a tree data structure, the node which has atleast one child is called as INTERNAL Node. In simple words, an internal node is a node with atleast one child.

In a tree data structure, nodes other than leaf nodes are called as Internal Nodes. The root node is also said to be Internal Node if the tree has more than one node. Internal nodes are also called as 'Non-Terminal' nodes.

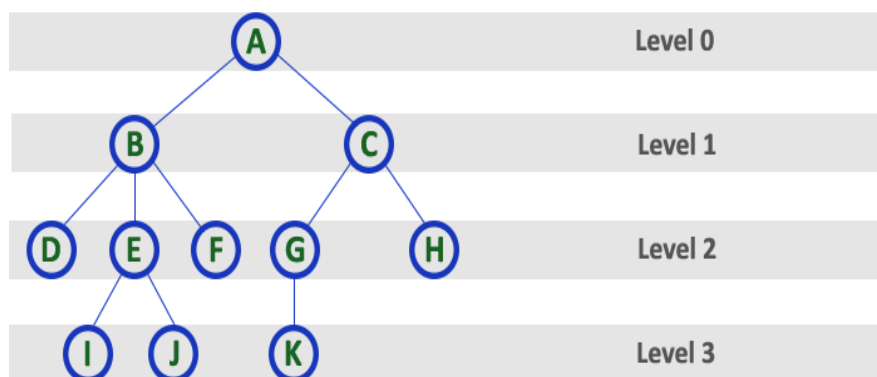
Ex: A, B, C, E & G

8. Degree of a node

In a tree data structure, the total number of children of a node is called as DEGREE of that Node. In simple words, the Degree of a node is total number of children it has. The highest degree of a node among all the nodes in a tree is called as '**Degree of Tree**'. Ex: Degree of B is 3, A is 2 and of F is 0

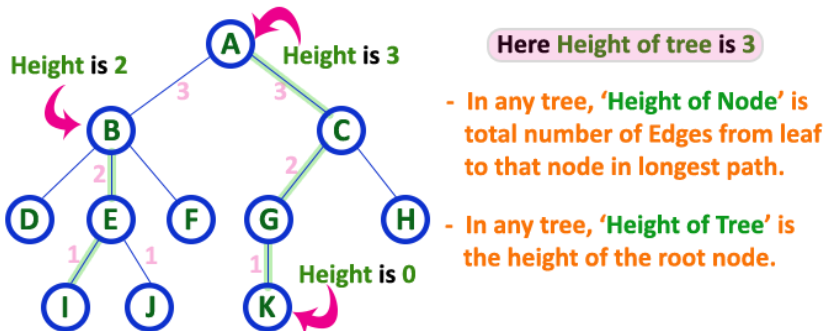
9. Level of a node

In a tree data structure, the root node is said to be at Level 0 and the children of root node are at Level 1 and the children of the nodes which are at Level 1 will be at Level 2 and so on... In simple words, in a tree each step from top to bottom is called as a Level and the Level count starts with '0' and incremented by one at each level (Step).



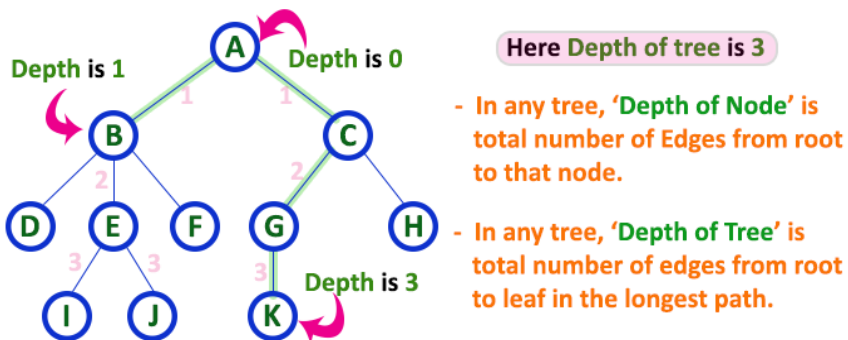
10. Height

In a tree data structure, the total number of edges from leaf node to a particular node in the longest path is called as HEIGHT of that Node. In a tree, height of the root node is said to be height of the tree. In a tree, height of all leaf nodes is '0'.



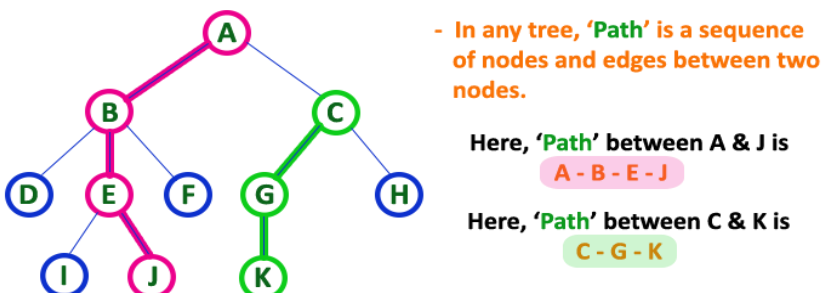
11. Depth

In a tree data structure, the total number of edges from root node to a particular node is called as DEPTH of that Node. In a tree, the total number of edges from root node to a leaf node in the longest path is said to be Depth of the tree. In simple words, the highest depth of any leaf node in a tree is said to be depth of that tree. In a tree, depth of the root node is '0'.



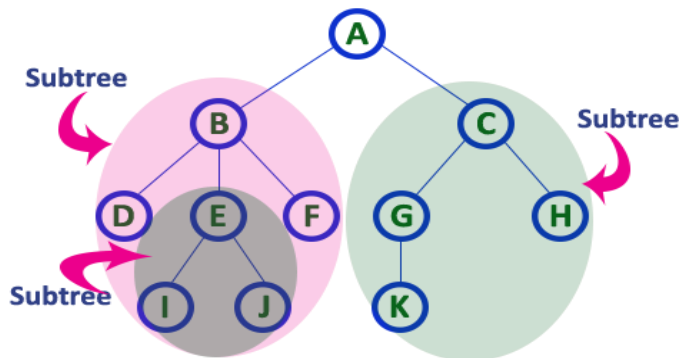
12. Path

In a tree data structure, the sequence of Nodes and Edges from one node to another node is called as PATH between the two Nodes. Length of a Path is total number of nodes in that path. In below example the path A - B - E - J has length 4.



13. Sub Tree

In a tree data structure, each child from a node forms a subtree recursively. Every child node will form a subtree on its parent node.



The **ancestors** of a node are all the nodes along the path from the root to that node.

Ex: ancestor of j is B & A

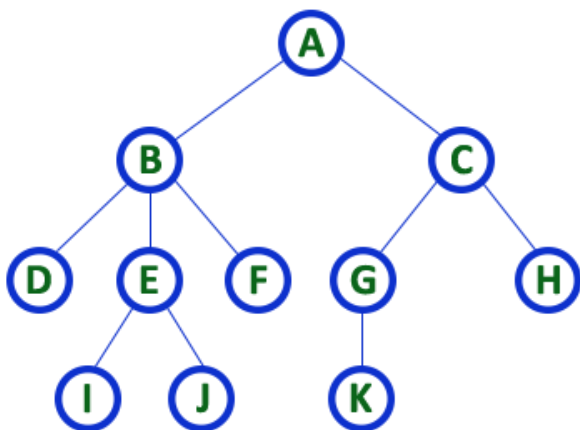
A **forest** is a set of $n \geq 0$ disjoint trees. The notion of a forest is very close to that of a tree because if we remove the root of a tree we get a forest. For example, in figure 1 if we remove A we get a forest with three trees.

General Tree Representations

A general Tree Structure can be represented with the following three methods. Those methods are as follows...

1. List Representation
2. Left Child - Right Sibling Representation
3. Degree two Representation (Binary Tree Representation)

Consider the following tree...



TREE with 11 nodes and 10 edges

- In any tree with '**N**' nodes there will be maximum of '**N-1**' edges
- In a tree every individual element is called as '**NODE**'

1. List Representation

There are several ways to draw a tree. One useful way is as a list. The tree in the above figure could be written as the list (A(B(D,E(I,J),F),C(G(K),H)) – **list representation (with rounded brackets)**. The information in the root node comes first followed by a list of the subtrees of that node. Now, how do we

represent a tree in memory? If we wish to use linked lists, then a node must have a varying number of fields depending upon the number of branches.

Possible node structure for a tree of degree k called k-ary tree

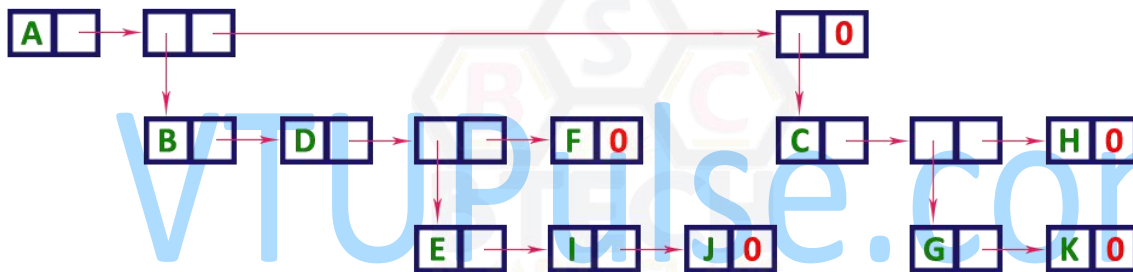
Data	link1	link2	link k
------	-------	-------	-------	--------

Each link field is used to point to a subtree. This node structure is cumbersome for the following reasons (1) Multiple node structure for different tree nodes (2) Waste of space (3) Excessive use of links.

The other alternate method is to have linked list of child nodes which allocates memory only for the nodes which have children.

In this representation, we use two types of nodes, one for representing the node with data and another for representing only references. We start with a node with data from root node in the tree. Then it is linked to an internal node through a reference node and is linked to any other node directly. This process repeats for all the nodes in the tree.

The above tree example can be represented using List representation as follows...

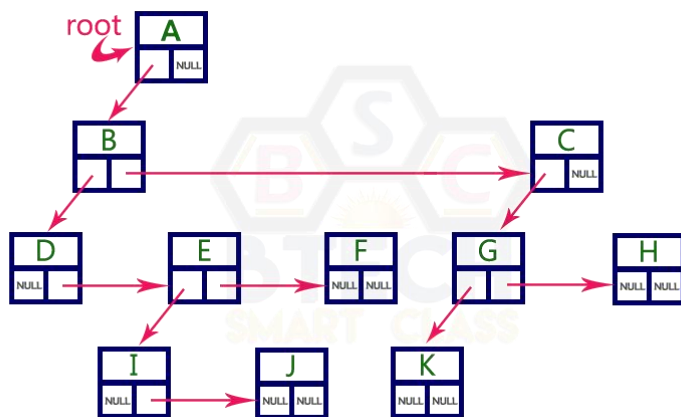


2. Left Child - Right Sibling Representation

In this representation, we use list with one type of node which consists of three fields namely Data field, Left child reference field and Right sibling reference field. Data field stores the actual value of a node, left reference field stores the address of the left child and right reference field stores the address of the right sibling node. Graphical representation of that node is as follows...

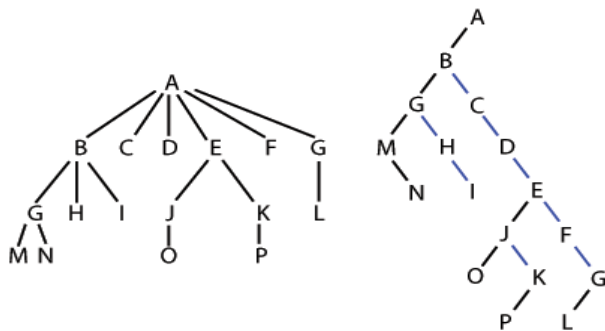
Data	
Left Child	Right Sibling

In this representation, every node's data field stores the actual value of that node. If that node has left child, then left reference field stores the address of that left child node otherwise that field stores NULL. If that node has right sibling then right reference field stores the address of right sibling node otherwise that field stores NULL. The above tree example can be represented using Left Child - Right Sibling representation as follows...



3. Degree two tree (Binary Tree)

The left child-right sibling representation can be converted to a degree two tree by simply rotating the right sibling pointers clockwise by 45 degrees. In this representation, the two children of a node are called the left child and the right child. It is equivalent to converting a normal tree to binary tree. Degree two trees or left child-right child trees are nothing but binary trees.

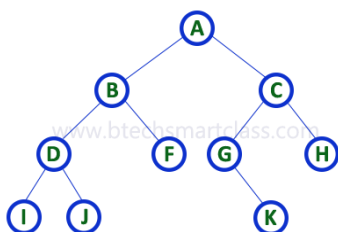


- Root of the general tree is the root of the binary tree.
- The first child node of any node in the general tree remains as the left subtree's root in the binary tree. Its right sibling in general tree becomes the right child node.

Note: refer notes for examples.

Binary Tree

In a general tree, every node can have arbitrary number of children. Binary tree is a special type of tree data structure in which every node can have a maximum of 2 children. One is known as left child and the other is known as right child. **A tree in which every node can have a maximum of two children is called as Binary Tree.** In a binary tree, every node can have either 0 children or 1 child or 2 children but not more than 2 children. Example

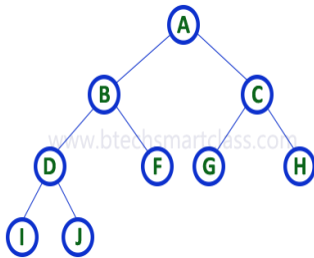


Types of Binary Trees

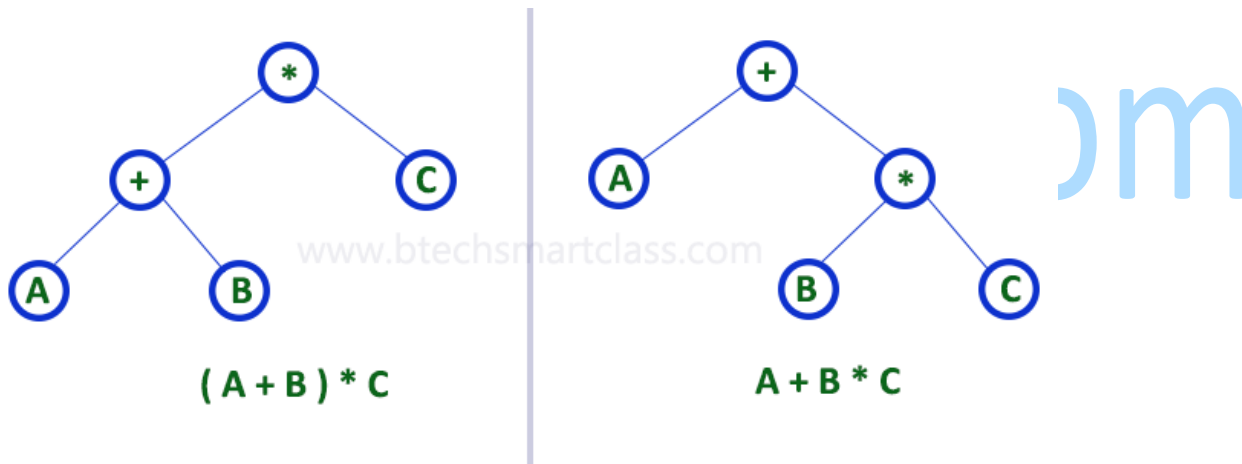
1. Strictly Binary Tree

In a binary tree, every node can have a maximum of two children. But in strictly binary tree, every node should have exactly two children or none. That means every internal node must have exactly two children. A strictly Binary Tree can be defined as follows...

A binary tree in which every node has either two or zero number of children is called Strictly Binary Tree. Strictly binary tree is also called as Full Binary Tree or Proper Binary Tree or 2-Tree.

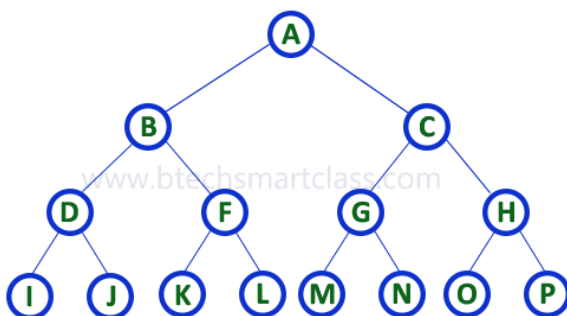


Strictly binary tree data structure is used to represent mathematical expressions.



2. Complete Binary Tree

In a binary tree, every node can have a maximum of two children. But in strictly binary tree, every node should have exactly two children or none and in complete binary tree all the nodes must have exactly two children and at every level of complete binary tree there must be 2^{level} number of nodes. For example at level 2 there must be $2^2 = 4$ nodes and at level 3 there must be $2^3 = 8$ nodes.



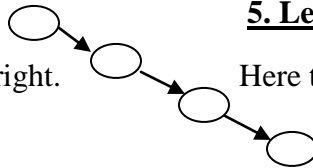
A binary tree in which every internal node has exactly two children and all leaf nodes are at same level is called Complete Binary Tree. Complete binary tree is also called as Perfect Binary Tree.

3. Almost complete Binary Tree

It is complete binary tree but completeness property is not followed in last level. In the above tree absence of leaf nodes L, M, N, O and P indicates its almost complete binary tree.

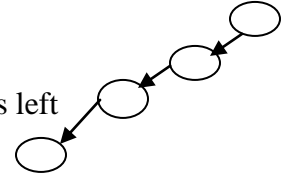
4. Right Skewed BT

Here the tree grows only towards right.



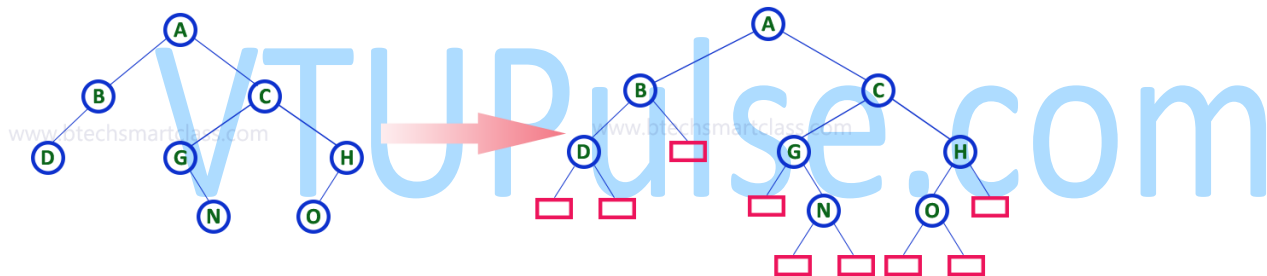
5. Left Skewed BT

Here the tree grows only towards left



6. Extended Binary Tree

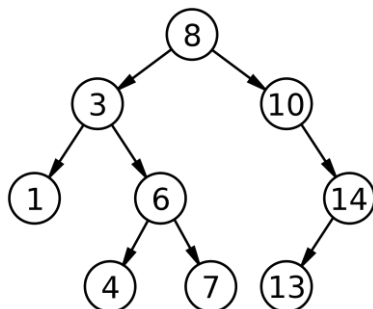
A binary tree can be converted into Full Binary tree by adding dummy nodes to existing nodes wherever required. The full binary tree obtained by adding dummy nodes to a binary tree is called as Extended Binary Tree.



In above figure, a normal binary tree is converted into full binary tree by adding dummy nodes (In pink colour).

7. Binary Search Tree(BST)

BST is a binary tree with a difference that for any node x, data of left subtree $<$ data(x) and data of right subtree \geq data(x). The above condition should be satisfied by all the nodes.

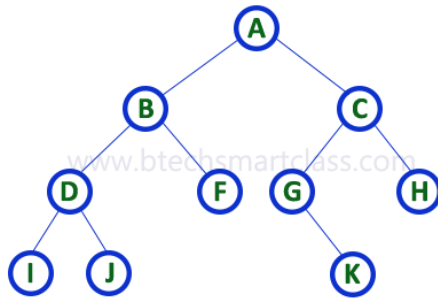


Binary Tree Representations

A binary tree data structure is represented using two methods. Those methods are as follows...

1. Array Representation
2. Linked List Representation

Consider the following binary tree...



1. Array Representation

In array representation of binary tree, we use a one dimensional array (1-D Array) to represent a binary tree. Consider the above example of binary tree and it is represented as follows...



To represent a binary tree of depth 'n' using array representation, we need one dimensional array with a maximum size of $2^{n+1} - 1$.

For any node with the position i, $2i + 1$ gives the position of the left child & $2i + 2$ gives the position of the right child. For any node with a position i, its parent node position is identified by using formula $(i-1) / 2$.

If i is the position of the left child $i+1$ gives the position of right child.

Advantages of array representation

- Faster access
- Easy for implementation
- Good for complete binary trees

Disadvantages

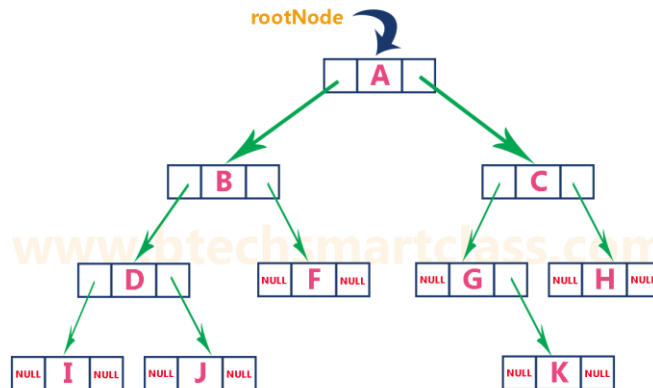
- Wastes memory for skewed trees
- Implementation of operations requires rearranging(shifting)of array elements

2. Linked List Representation

The linked notation uses a doubly linked list to represent a binary tree. In a double linked list, every node consists of three fields. First field for storing left child address, second for storing actual data and third for storing right child address. In this linked list representation, a node has the following structure...

Left Child Address	Data	Right Child Address
------------------------------	-------------	-------------------------------

The above example of binary tree represented using Linked list representation is shown as follows...



Binary Tree Traversals

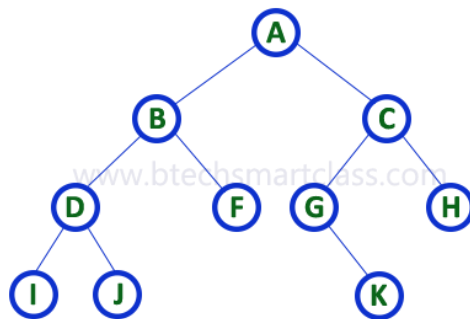
Tree traversal is a method of visiting the nodes of a tree in a particular order. The tree nodes are visited exactly once and displayed as they are visited.

Displaying (or) visiting order of nodes in a binary tree is called as Binary Tree Traversal.

There are three types of binary tree traversals.

1. In - Order Traversal
2. Pre - Order Traversal
3. Post - Order Traversal

Consider the following binary tree...



1. In - Order Traversal (leftChild - root - rightChild)

In In-Order traversal, the root node is visited between left child and right child. In this traversal, the left child node is visited first, then the root node is visited and later we go for visiting right child node. This in-order

traversal is applicable for every root node of all subtrees in the tree. This is performed recursively for all nodes in the tree.

In the above example of binary tree, first we try to visit left child of root node 'A', but A's left child is a root node for left subtree. so we try to visit its (B's) left child 'D' and again D is a root for subtree with nodes D, I and J. So we try to visit its left child 'I' and it is the left most child. So first we visit 'I' then go for its root node 'D' and later we visit D's right child 'J'. With this we have completed the left part of node B. Then visit 'B' and next B's right child 'F' is visited. With this we have completed left part of node A. Then visit root node 'A'. With this we have completed left and root parts of node A. Then we go for right part of the node A. In right of A again there is a subtree with root C. So go for left child of C and again it is a subtree with root G. But G does not have left part so we visit 'G' and then visit G's right child K. With this we have completed the left part of node C. Then visit root node 'C' and next visit C's right child 'H' which is the right most child in the tree so we stop the process.

That means here we have visited in the order of I - D - J - B - F - A - G - K - C - H using In-Order Traversal.

In-Order Traversal for above example of binary tree is

I - D - J - B - F - A - G - K - C - H

2. Pre - Order Traversal (root - leftChild - rightChild)

In Pre-Order traversal, the root node is visited before left child and right child nodes. In this traversal, the root node is visited first, then its left child and later its right child. This pre-order traversal is applicable for every root node of all subtrees in the tree.

In the above example of binary tree, first we visit root node 'A' then visit its left child 'B' which is a root for D and F. So we visit B's left child 'D' and again D is a root for I and J. So we visit D's left child 'I' which is the left most child. So next we go for visiting D's right child 'J'. With this we have completed root, left and right parts of node D and root, left parts of node B. Next visit B's right child 'F'. With this we have completed root and left parts of node A. So we go for A's right child 'C' which is a root node for G and H. After visiting C, we go for its left child 'G' which is a root for node K. So next we visit left of G, but it does not have left child so we go for G's right child 'K'. With this we have completed node C's root and left parts. Next visit C's right child 'H' which is the right most child in the tree. So we stop the process.

That means here we have visited in the order of A-B-D-I-J-F-C-G-K-H using Pre-Order Traversal.

Pre-Order Traversal for above example binary tree is

A - B - D - I - J - F - C - G - K - H

3. Post - Order Traversal (leftChild - rightChild - root)

In Post-Order traversal, the root node is visited after left child and right child. In this traversal, left child node is visited first, then its right child and then its root node. This is recursively performed until the right most node is visited.

Here we have visited in the order of I - J - D - F - B - K - G - H - C - A using Post-Order Traversal.

Post-Order Traversal for above example binary tree is

I - J - D - F - B - K - G - H - C - A

Note : refer notes for programs.

Iterative Inorder Traversal

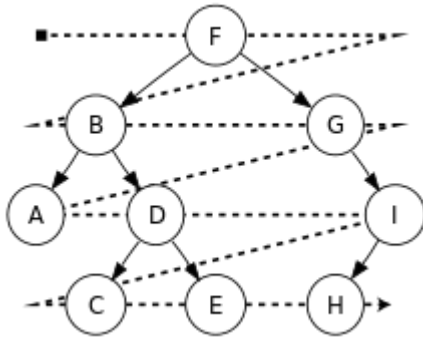
Traversal techniques using recursion consumes system stack space .The stack space used may not be acceptable for unbalanced trees of trees of larger heights.IN such cases, iterative traversal can be implemented by simulating stack space with the help of an array.Another solution would be to use threaded binary trees during traversal.

```
#define size 10
int top = -1;
struct Tree
{
    int data;
    struct Tree *lptr, *rptr;
};
typedef struct Tree node;
node *root,*stack[size];
void push(node *temp) //function to push
{
    if(top == size - 1)
    {
        Printf("stack full");
        Return;
    }
    stack[++top] = temp;
}
node *pop() //function to pop
{
    if(top == - 1)
    {
        printf("stack empty");
        Return;
    }
    return(stack[top--]);
}

void iterative inorder(node *root)
{
    node *cur = root;
    while(1)
    {
        while(cur!=NULL)
        {
            push(cur);
            cur=cur->lptr;
        }
        if(top == -1) break;
        cur = pop();
        printf("%d  ", cur->data);
        cur=cur->rptr;
    }
}
```

2. Level Order Traversal

- Level order traversal is a method of traversing the nodes of a tree level by level as in breadth first traversal.
- Level order traversal uses queue thus avoiding stack space usage.
- Here the nodes are numbered starting with the root on level zero continuing with nodes on level 1,2,3.....
- The nodes at any level is numbered from left to right
- Visiting the nodes using the ordering of levels is called level order traversal
- Queue uses FIFO principle



(ref :Wikipedia)

The level order traversal of the above tree is F B G A D I C E H

Implementation of level order traversal

```
void Level_Order(node *root)
{
    int f = 0, r = -1; //global declaration
    node *q[size], *cur;
    q[++r] = root;

    while( r >= f)
    {
        cur = q[f++];
        printf("%d ", cur->data);
        if(cur->lptr != NULL)
            q[++r] = cur->lptr;
        if(cur->rptr != NULL)
            q[++r] = cur->rptr;
    }
}
```

Building Binary Tree from Traversal Pairs:

Sometimes it is required to construct a binary tree if its traversals are known. From a single traversal it is not possible to construct unique binary tree. However any of the two traversals are given then the corresponding tree can be drawn uniquely:

- Inorder and preorder
- Inorder and postorder
- Inorder and level order

The basic principle for formulation is as follows:

If the preorder traversal is given, then the first node is the root node. If the postorder traversal is given then the last node is the root node. Once the root node is identified, all the nodes in the left sub-trees and right sub-trees of the root node can be identified using inorder.

Same technique can be applied repeatedly to form sub-trees.

It can be noted that, for the purpose mentioned, two traversal are essential out of which one should be inorder traversal and another preorder or postorder; alternatively, given preorder and postorder traversals, binary tree cannot be obtained uniquely.

Example 1:

Construct a binary tree from a given preorder and inorder sequence:

Preorder: A B D G C E H I F Inorder: D G B A H E I C F

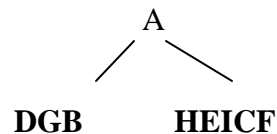
Solution:

From Preorder sequence A B D G C E H I F, the root is: A

From Inorder sequence D G B A H E I C F, we get the left and right sub trees:

Left sub tree is: D G B

Right sub tree is: H E I C F

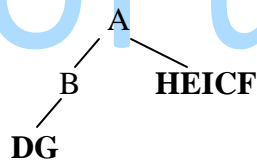


To find the root, left and right sub trees for D G B:

From the preorder sequence B D G, the root of tree is: B

From the inorder sequence D G B, we can find that D and G are to the left of B.

The Binary tree upto this point looks like:

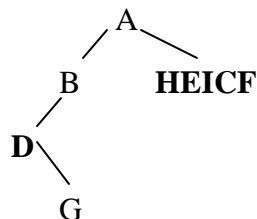


To find the root, left and right sub trees for D G:

From the preorder sequence D G, the root of the tree is: D

From the inorder sequence D G, we can find that there is no left node to D and G is at the right of D.

The Binary tree upto this point looks like

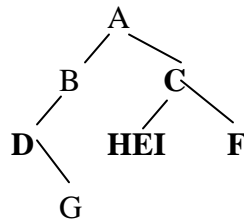


To find the root, left and right sub trees for H E I C F:

From the preorder sequence C E H I F, the root of the left sub tree is: C

From the inorder sequence H E I C F, we can find that H E I are at the left of C and F is at the right of C.

The Binary tree upto this point looks like:

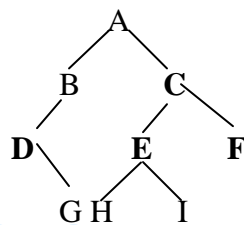


To find the root, left and right sub trees for H E I:

From the preorder sequence E H I, the root of the tree is: E

From the inorder sequence H E I, we can find that H is at the left of E and I is at the right of E.

The Binary tree upto this point looks like:



Refer class notes for other examples

Properties of Binary Tree

1. Prove that max no of nodes in a BT of depth K is $2^k - 1$

$$\text{Total no of nodes} = 2^0 + 2^1 + 2^2 + \dots + 2^i$$

The above sequence is in geometric progression

$$= (2^{i+1} - 1) / (2 - 1)$$

$$= 2^{i+1} - 1$$

$$= 2^n - 1 \quad (\text{where } i+1 = n = \text{height of tree or depth of tree})$$

$$\Rightarrow \text{max no of nodes in a BT of depth K} = 2^k - 1$$

2. Max no of nodes on level i of a BT is 2^{i-1} , $i \geq 1$ or 2^i , $i \geq 0$

Proof by induction on i;

Induction base: Root is the only node on level $i = 1$.

→ Hence max no of nodes on level $i = 1$

$$\Leftrightarrow 2^{i-1} = 2^0 = 1$$

Induction Hypothesis:

→ Let I be an arbitrary positive integer > 1

→ Assume that max no of nodes on level $i-1$ is 2

Induction Step:

- We know that max no of nodes on level $i-1-2^{i-2}$ by induction hypothesis
- We know that each node in a BT max degree is 2
- Max no of nodes on level i = twice the max no of nodes on level $i-2$ i.e 2^{i-1}

Hence the proof

3. Prove that no of leaf nodes = no of nodes of degree-2 nodes or for any nonempty Binary Tree T, if N_0 is the no of leaf nodes and N_2 no of nodes of degree 2 then $N_0 = N_2 + 1$

Proof: Let N_1 be the no of nodes of degree 1

Let N be the total no of nodes

Since all nodes in T are atmost of degree 2 we have

$$N = N_0 + N_1 + N_2 \text{-----(1)}$$

If we count no of branches in a BT we see that every node except the root has a branch leading into it.

If $B \rightarrow$ no of branches then

$$N = B + 1 \text{ (because all branches step from a node of degree 1 or 2)}$$

$$\text{Therefore } B = N_1 + 2N_2$$

$$\Rightarrow N = B + 1$$

$$\Rightarrow N = N_1 + 2N_2 + 1 \text{-----(2)}$$

\Rightarrow From (1) & (2) we get

$$N_0 + N_1 + N_2 = N_1 + 2N_2 + 1$$

$$N_0 = N_2 + 1$$

Hence the proof

Binary Search Tree

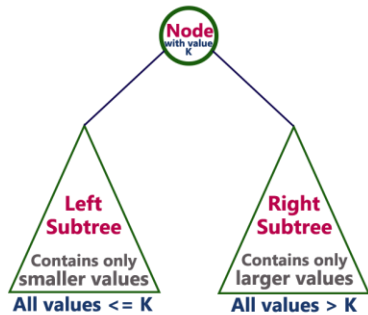
In a binary tree, every node can have maximum of two children but there is no order of nodes based on their values. In binary tree, the elements are arranged as they arrive to the tree, from top to bottom and left to right.

A binary tree has the following time complexities...

- Search Operation - $O(n)$
- Insertion Operation - $O(1)$
- Deletion Operation - $O(n)$

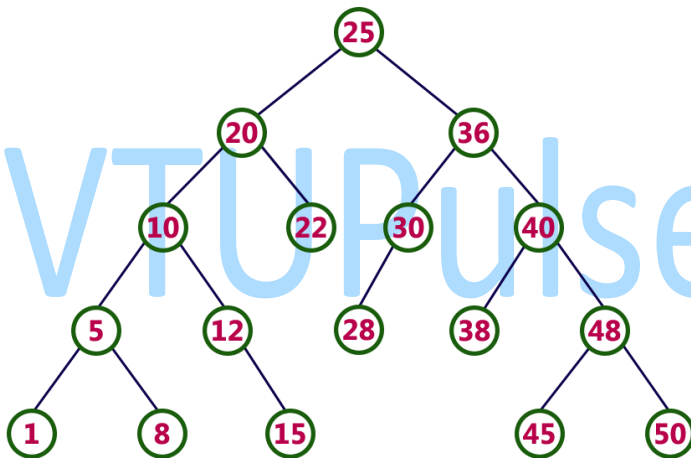
To enhance the performance of binary tree, we use special type of binary tree known as Binary Search Tree. Binary search tree mainly focus on the search operation in binary tree. Binary search tree can be defined as follows...

Binary Search Tree is a binary tree in which every node contains only smaller values in its left subtree and only larger values in its right subtree.



Example

The following tree is a Binary Search Tree. In this tree, left subtree of every node contains nodes with smaller values and right subtree of every node contains larger values.



Every Binary Search Tree is a binary tree but all the Binary Trees need not to be binary search trees.

Operations on a Binary Search Tree

The following operations are performed on a binary search tree...

- Search
- Insertion
- Deletion
- Traversal

Search Operation in BST

In a binary search tree, the search operation is performed with $O(\log n)$ time complexity. The search operation is performed as follows...

Step 1: Read the search element from the user

Step 2: Compare, the search element with the value of root node in the tree.

Step 3: If both are matching, then display "Given node found!!!" and terminate the function
 Step 4: If both are not matching, then check whether search element is smaller or larger than that node value.
 Step 5: If search element is smaller, then continue the search process in left subtree.
 Step 6: If search element is larger, then continue the search process in right subtree.
 Step 7: Repeat the same until we find exact element or we completed with a leaf node
 Step 8: If we reach the node with search value, then display "Element is found" and terminate the function.
 Step 9: If we reach a leaf node and it is also not matching, then display "Element not found" and terminate the function.

Insertion Operation in BST

In a binary search tree, the insertion operation is performed with $O(\log n)$ time complexity. In binary search tree, new node is always inserted as a leaf node. The insertion operation is performed as follows...

Step 1: Create a newNode with given value and set its left and right to NULL.
 Step 2: Check whether tree is Empty.
 Step 3: If the tree is Empty, then set root to newNode.
 Step 4: If the tree is Not Empty, then check whether value of newNode is smaller or larger than the node (here it is root node).
 Step 5: If newNode is smaller than or equal to the node, then move to its left child. If newNode is larger than the node, then move to its right child.
 Step 6: Repeat the above step until we reach to a leaf node (e.i., reach to NULL).
 Step 7: After reaching a leaf node, then insert the newNode as left child if newNode is smaller or equal to that leaf else insert it as right child.

Deletion Operation in BST

In a binary search tree, the deletion operation is performed with $O(\log n)$ time complexity. Deleting a node from Binary search tree has following three cases...

Case 1: Deleting a Leaf node (A node with no children)
 Case 2: Deleting a node with one child
 Case 3: Deleting a node with two children

Case 1: Deleting a leaf node

We use the following steps to delete a leaf node from BST...

Step 1: Find the node to be deleted using search operation
 Step 2: Delete the node using free function (If it is a leaf) and terminate the function.

Case 2: Deleting a node with one child

We use the following steps to delete a node with one child from BST...

Step 1: Find the node to be deleted using search operation
 Step 2: If it has only one child, then create a link between its parent and child nodes.
 Step 3: Delete the node using free function and terminate the function.

Case 3: Deleting a node with two children

We use the following steps to delete a node with two children from BST...

Step 1: Find the node to be deleted using search operation

Step 2: If it has two children, then find the largest node in its left subtree (OR) the smallest node in its right subtree.

Step 3: Swap both deleting node and node which found in above step.

Step 4: Then, check whether deleting node came to case 1 or case 2 else goto steps 2

Step 5: If it comes to case 1, then delete using case 1 logic.

Step 6: If it comes to case 2, then delete using case 2 logic.

Step 7: Repeat the same process until node is deleted from the tree.

Example

Construct a Binary Search Tree by inserting the following sequence of numbers...

10,12,5,4,20,8,7,15 and 13

Refer notes for examples and implementation.

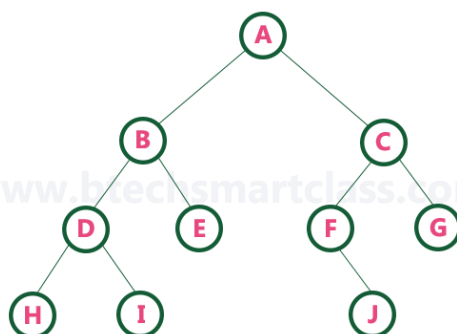
Threaded Binary Tree

A binary tree is represented using array representation or linked list representation. When a binary tree is represented using linked list representation, if any node is not having a child we use NULL pointer in that position. In any binary tree linked list representation, there are more number of NULL pointer than actual pointers. Generally, in any binary tree linked list representation, if there are $2N$ number of reference fields, then $N+1$ number of reference fields are filled with NULL ($N+1$ are NULL out of $2N$). This NULL pointer does not play any role except indicating there is no link (no child).

A. J. Perlis and C. Thornton have proposed new binary tree called "Threaded Binary Tree", which make use of NULL pointer to improve its traversal processes. In threaded binary tree, NULL pointers are replaced by references to other nodes in the tree, called threads.

Threaded Binary Tree is also a binary tree in which all left child pointers that are NULL (in Linked list representation) points to its in-order predecessor, and all right child pointers that are NULL (in Linked list representation) points to its in-order successor. If there is no in-order predecessor or in-order successor, then it points to root node.

Consider the following binary tree...

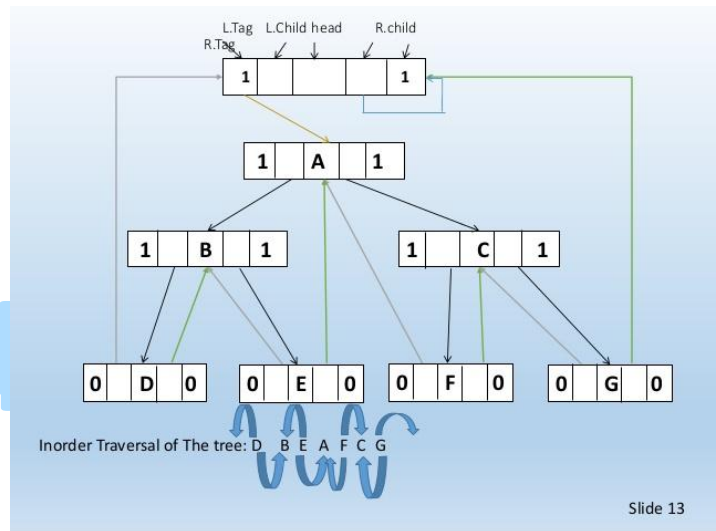
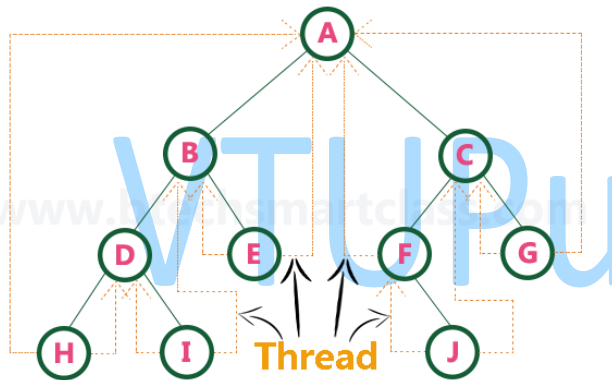


To convert above binary tree into threaded binary tree, first find the in-order traversal of that tree...

In-order traversal of above binary tree...

H - D - I - B - E - A - F - J - C - G

When we represent above binary tree using linked list representation, nodes H, I, E, F, J and G left child pointers are NULL. This NULL is replaced by address of its in-order predecessor, respectively (I to D, E to B, F to A, J to F and G to C), but here the node H does not have its in-order predecessor, so it points to the root node A. And nodes H, I, E, J and G right child pointers are NULL. This NULL pointers are replaced by address of its in-order successor, respectively (H to D, I to B, E to A, and J to C), but here the node G does not have its in-order successor, so it points to the root node A. The above example binary tree in threaded notation is as follows:



In above figure threads are indicated with dotted links.

Note :Refer notes for implementation of TBT

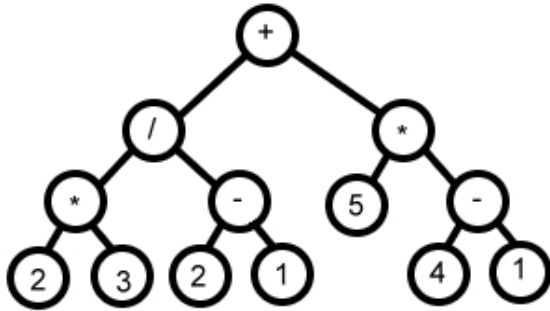
Expression Trees:

A Binary Expression Tree is ...

A special kind of binary tree in which:

1. Each leaf node contains a single operand
2. Each nonleaf node contains a single binary operator
3. The left and right subtrees of an operator node represent subexpressions that must be evaluated before applying the operator at the root of the subtree.

Example :



Expression tree for $2*3/(2-1)+5*(4-1)$

- Levels Indicate Precedence
- The levels of the nodes in the tree indicate their relative precedence of evaluation (we do not need parentheses to indicate precedence).
- Operations at higher levels of the tree are evaluated later than those below them.
- The operation at the root is always the last operation performed.

Refer class notes for examples.

References:

http://btechsmartclass.com/DS/U3_T3.html

<http://www.iare.ac.in/sites/default/files/DS.pdf>

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