CS563-NLP

ASSIGNMENT-I: Part-of-Speech (PoS) tagging using HMM (Read all the instructions carefully and adhere to them)

Date: Jan 25, 2022 **Deadline**: Feb 04, 2022

Scores: 20

Instructions:

- 1. Markings will be based on the correctness and soundness of the outputs.
- 2. Marks will be deducted in case of plagiarism.
- 3. Proper indentation and appropriate comments (if necessary) are mandatory.
- 4. You should zip all the required files and name the zip file as:
- <roll_no>_assignment_<#>.zip , eg. 1701cs11_assignment_01.zip.
- 5. Upload your assignment (the zip file) in the following link:

<TO BE ADDED>

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Problem Statement: Part-of-Speech (PoS) tagging assigns grammatical categories to every token in a sentence. In this assignment, you have to develop a PoS tagger using 2nd order Hidden Markov Model (HMM).

Dataset name: English Penn Treebank (PTB) corpus

Number of PoS tags: 36 (Alphabetical list of part-of-speech tags used in the Penn

Treebank Project)

Link to download the dataset:

https://drive.google.com/file/d/1ncGHhCeQ7oTOhuvuCaaavF0lpsJmYxUe/view?usp=sh aring

Hidden Markov Model (HMM)

You have to implement HMM on your own. Do not use any existing libraries. Consider a bigram HMM model. Calculate the Emission and Transition Probability matrices. Use Viterbi decoding to obtain the best PoS sequence.

Evaluation:

- 1. Split the dataset in 80:20 ratio for train and test sets.
- 2. Compute and report the overall accuracy of HMM models on the test set.
- 3. Compute and report the class-wise accuracies.
- 4. Collapse all the 36 tags into 4 tags as follows: all the noun PoS tags to "N"; all the verb PoS tags to "V"; all the adjectives and adverbs to "A", and the rest to "O".
- 5. Repeat points 2 and 3 for (4).
- 6. Comment on the following: overall performance of 36-tag vs 4-tag model; if the overall performance of 4-tag is better than the 36-tag model, explain with intuition with respect to transition and emission probabilistic assumption why is such the case?

Note: For the unseen word, consider the default PoS tag, which should be the most frequent tag in the entire dataset.