

# HW

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## 1 Homework: numerical methods

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```
[ ]: # import needed packages
import numpy as np
from scipy.constants import g
from scipy.optimize import root
import pandas as pd

# graph settings
import matplotlib.pyplot as plt
from matplotlib_inline import backend_inline
plt.rcParams['figure.figsize'] = [10, 5]
plt.style.use('seaborn')
backend_inline.set_matplotlib_formats('png', 'pdf')
```

## 2 Range of a Projectile Under Air Drag

For a projectile with resistance, we start with these initial conditions

$$x(t=0) = y(t=0) = 0$$

$$\dot{x}(t=0) = v_0 \cos \theta \equiv U$$

$$\dot{y}(t=0) = v_0 \sin \theta \equiv V$$

Then using  $\vec{F} = m\vec{a}$  for each dimension we get

$$m\ddot{x} = -km\dot{x}$$

$$m\ddot{y} = -km\dot{y}$$

Putting  $y = 0$  we get the following equation, after defining  $T \equiv kt$

$$T = (K + 2)(1 - e^{-T})$$

Then the range will be  $R \equiv x(T)$ , with  $K \equiv kV/g$ , and  $R_0 = 2UV/g$

$$\frac{R}{R_0} = \frac{T}{2K(K+1)}$$

We need to find the value of  $T$ , and then substitute it back in the range equation

## 2.1 Check that $k \rightarrow 0$ leads to $R \rightarrow R_0$

Rewrite

## 2.2 Plot $R/R_0$ vs. $K$

```
[ ]: # define initial constants
angle = np.radians(60)
v0 = 600.0 # speed
U = v0 * np.cos(angle) # x-axis speed
V = v0 * np.sin(angle) # y-axis speed
R0 = 2* U * V / g # range

eps = 1e-9 # cannot be zero
k = np.arange(eps, 0.08, 0.08/100)

def T(k, t):
    return k * t

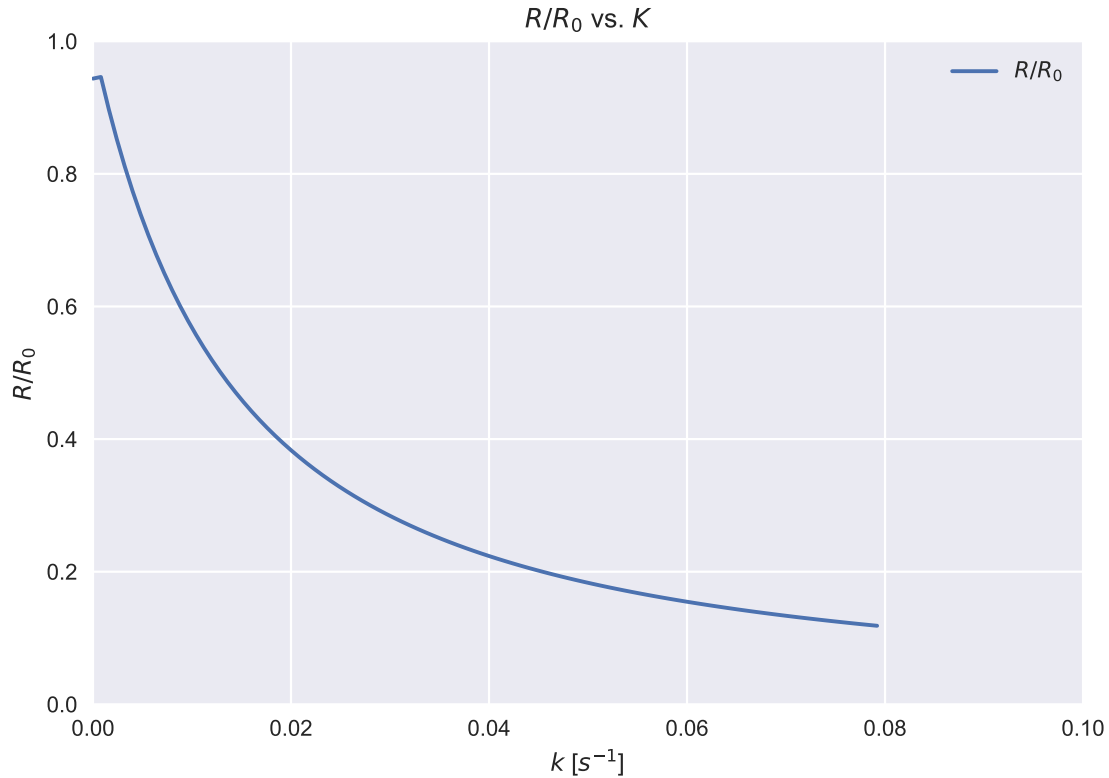
def K(k):
    return k * V / g

# time equation = 0
def time(t, k):
    return (K(k)+1) * (1 - np.exp(-T(k, t))) - T(k, t)

# range equation
def range_(k, t):
    return T(k, t) / (2 * K(k) * (K(k)+1))

# approximate T value for each k value
time_res = [root(time, args=(k_), x0=100)['x'][0] for k_ in k]
# find range R values
range_res = [range_(k_, t_) for k_, t_ in zip(k, time_res)]

plt.plot(k, range_res, label='$R/R_0$')
plt.xlim(0, 0.1)
plt.ylim(0, 1)
plt.legend()
plt.xlabel('$k$ [$s^{-1}$]')
plt.ylabel('$R/R_0$')
plt.title('$R/R_0$ vs. $K$')
plt.grid(True)
plt.show()
```



### 2.3 Check that when the limit $k \rightarrow 0$ , $R/R_0 \rightarrow 1$

We use here the same calculation as before but with very small values of  $k$ .

```
[ ]: k = np.arange(1e-10, 0.01, 1/1000)
t = np.arange(0, 150)

def f(t, k):
    return (K(k)+1) * (1 - np.exp(-T(k, t)))

# approximate T value for each k value
time_res = []
for k_ in k:
    res = root(time, args=(k_), x0=105.8)
    if res['success']:
        time_res.append(res['x'][0])
    else: print(res)
# find range R values
range_res = [range_(k_, t_) for k_, t_ in zip(k, time_res)]

pd.DataFrame({'k': k, 'Range': range_res})
```

[ ]:	k	Range
0	1.000000e-10	0.998377
1	1.000000e-03	0.933477
2	2.000000e-03	0.874337
3	3.000000e-03	0.821468
4	4.000000e-03	0.773966
5	5.000000e-03	0.731089
6	6.000000e-03	0.692224
7	7.000000e-03	0.656857
8	8.000000e-03	0.624557
9	9.000000e-03	0.594962

From the previous table we can deduce that as the drag constant  $k \rightarrow 0$ , then  $R/R_0 \rightarrow 1$  or  $R \rightarrow R_0$ , which as expected.

### 3 Quadratic Drag Force

For a particle of mass  $m$  vertically thrown upward with initial speed  $v_0$ . The air resistance experienced by the particle is propotional to  $v^2$ ;  $f_R = -\alpha v^2$ . We have the DE

$$m\dot{v} = -mg - \alpha v^2$$

The initial conditions are  $t_0 = 0$ ,  $y(t_0) = 0$ , and  $v(t_0) \equiv v_0$ . ## Velocity

Factor  $-mg$  from the RHS of the eq, we get

$$m\dot{v} = -mg(1 + \frac{\alpha}{mg}v^2)$$

We define the *terminal velocity* as  $v_t \equiv \sqrt{mg/\alpha}$  then we get

$$\frac{dv}{dt} = -g(1 + \frac{v^2}{v_t^2})$$

rearranging and setting integrals,

$$\int_{v_0}^v \frac{dv}{1 + \frac{v^2}{v_t^2}} = -g \int_{t_0}^t dt$$

$$v_t(\tan^{-1} \frac{v}{v_t} - \tan^{-1} \frac{v_0}{v_t}) = -gt$$

Taking the *tangent* of both sides

$$v = v_t \tan(\tan^{-1} \frac{v_0}{v_t} - gt/v_t)$$

We define the *characteristic time*  $\tau \equiv v_t/g$

$$v = v_t \tan\left(\tan^{-1} \frac{v_0}{v_t} - \frac{t}{\tau}\right)$$

### 3.1 Peak Time

To find the time needed to reach the trajectory peak  $t_p$ , we set  $v = 0$ , and take the arctangent of both sides

$$t_p = \tau \tan^{-1} \frac{v_0}{v_t}$$

### 3.2 Height

Now we find the  $H(t) = y$

$$y = \int_{y_0}^y dy = v_t \int_{t_0}^t \tan \left( \tan^{-1} \frac{v_0}{v_t} - \frac{t}{\tau} \right) dt$$

$$y = -v_t \tau \ln(\cos(\tan^{-1} \frac{v_0}{v_t}))$$

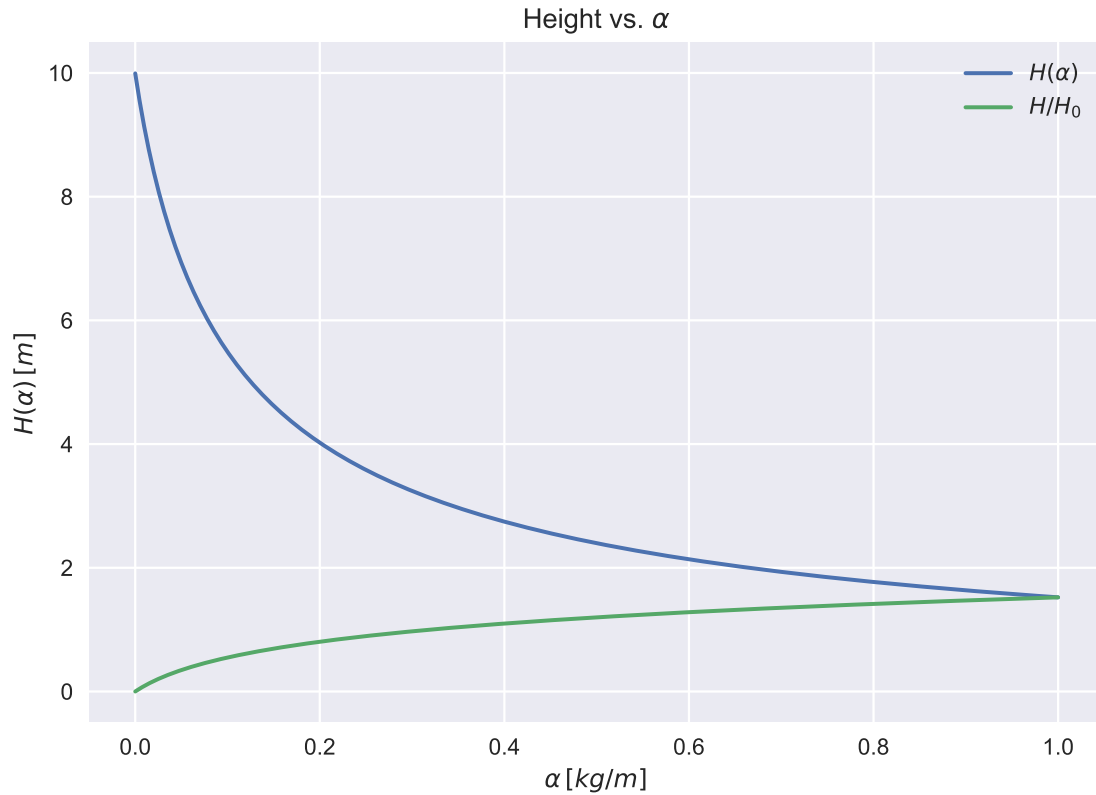
### 3.3 Plot $H(\alpha)$

Let us set up the code to graph the function  $y$  vs  $\alpha$

```
[ ]: # define constants
mass = 1
v0 = 14
alphas = np.arange(1e-10, 1, 1e-5)

# define terminal velocity
def vt(alpha, m=mass):
    return np.sqrt(m * g / alpha)
# define characteristic time
def tau(vt):
    # return np.sqrt(m / (alpha*g))
    return vt / g
# define the height
def y(alpha):
    return - mass / alpha * np.log(np.cos(np.arctan(v0 / vt(alpha))))
def y2(alpha):
    return - np.log(np.cos(np.arctan(v0 / vt(alpha))))

plt.plot(alphas, y(alphas), label=r'$H(\alpha)$')
plt.plot(alphas, y2(alphas), label=r'$H/H_0$')
plt.legend()
plt.xlabel(r'$\alpha$, [kg/m]$')
plt.ylabel(r'$H(\alpha)$, [m]$')
plt.title(r'Height vs. $\alpha$')
plt.show()
```



```
[ ]: alphas = np.arange(1e-16, 1e-5, 1e-6)
      height_res = [y(a) for a in alphas]

      pd.DataFrame({'alpha': alphas, 'Height': height_res})
```

```
[ ]:
      alpha      Height
0  1.000000e-16  9.992007
1  1.000000e-06  9.993119
2  2.000000e-06  9.993019
3  3.000000e-06  9.992919
4  4.000000e-06  9.992819
5  5.000000e-06  9.992720
6  6.000000e-06  9.992620
7  7.000000e-06  9.992520
8  8.000000e-06  9.992420
9  9.000000e-06  9.992320
```

### 3.4 Without resistance

Let us consider the case when  $\alpha \rightarrow 0$ . From the previous table we see that the object approaches the height  $10m$ , for no effect of air drag.