

BAYESIAN NETWORKS

CHAPTER 14.1–4

Outline

- ◇ Syntax
- ◇ Semantics
- ◇ Exact inference by enumeration
- ◇ Exact inference by variable elimination

Bayesian networks

A simple, graphical notation for conditional independence assertions and hence for compact specification of full joint distributions

Syntax:

- a set of nodes, one per variable

- a directed, acyclic graph (link \approx “directly influences”)

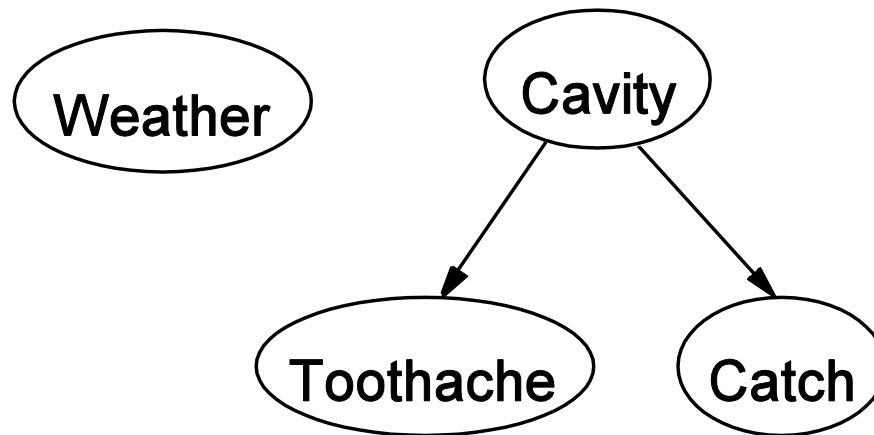
- a conditional distribution for each node given its parents:

$$P(X_i | \text{Parents}(X_i))$$

In the simplest case, conditional distribution represented as a **conditional probability table** (CPT) giving the distribution over X_i for each combination of parent values

Example 1

Topology of network encodes conditional independence assertions:



Weather is independent of the other variables

Toothache and *Catch* are conditionally independent given *Cavity*

Example 2

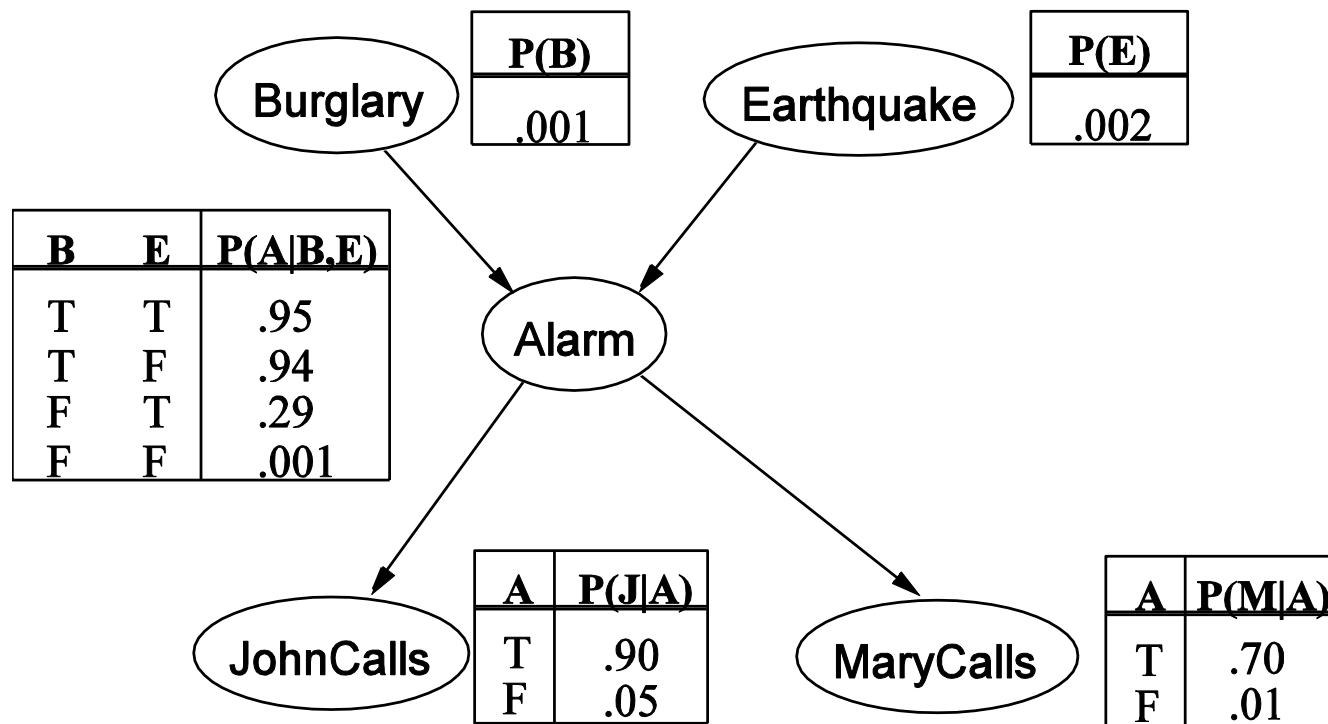
Scenario: I'm at work, neighbor John calls to say my alarm is ringing, but neighbor Mary doesn't call. Sometimes it's set off by minor earthquakes. Is there a burglar?

Variables: *Burglar*, *Earthquake*, *Alarm*, *JohnCalls*, *MaryCalls*

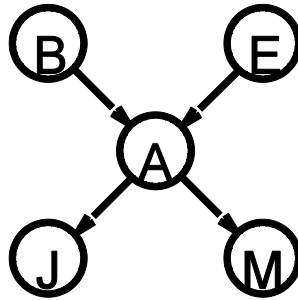
Network topology reflects “causal” knowledge:

- A burglar can set the alarm off
- An earthquake can set the alarm off
- The alarm can cause Mary to call
- The alarm can cause John to call

Example 2 contd.



Compactness



A CPT for Boolean X_i with k Boolean parents has 2^k rows for the combinations of parent values

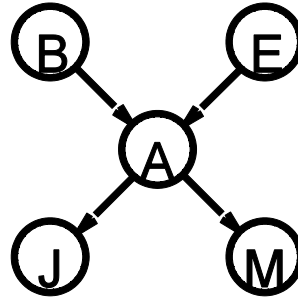
Each row requires one number p for $X_i = \text{true}$
(the number for $X_i = \text{false}$ is just $1 - p$)

If each variable has no more than k parents,
the complete network requires $O(n \cdot 2^k)$ numbers

I.e., grows linearly with n , vs. $O(2^n)$ for the full joint distribution

For burglary net, $1 + 1 + 4 + 2 + 2 = 10$ numbers (vs. $2^5 - 1 = 31$)

Global semantics



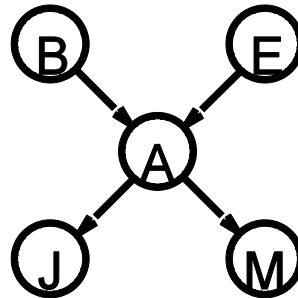
Global semantics defines the full joint distribution as the product of the local conditional distributions:

$$P(x_1, \dots, x_n) = \prod_{i=1}^n P(x_i | \text{parents}(X_i))$$

e.g., $P(j \wedge m \wedge a \wedge \neg b \wedge \neg e)$

=

Global semantics



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e.g., $P(j \wedge m \wedge a \wedge \neg b \wedge \neg e)$

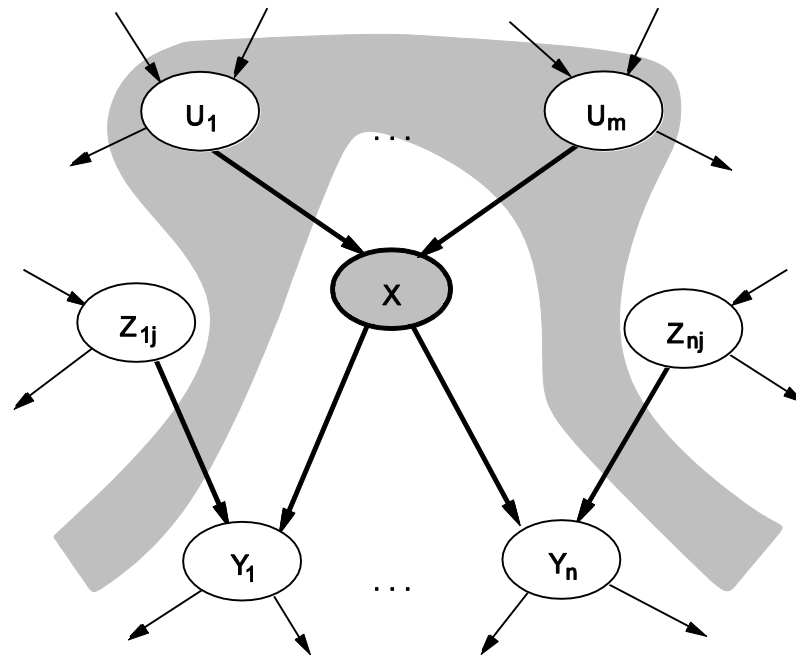
$$= P(j|a)P(m|a)P(a|\neg b, \neg e)P(\neg b)P(\neg e)$$

$$= 0.9 \times 0.7 \times 0.001 \times 0.999 \times 0.998$$

$$\approx 0.00063$$

Local semantics

Local semantics: each node is conditionally independent of its nondescendants given its parents



Constructing Bayesian networks

Need a method such that a series of locally testable assertions of conditional independence guarantees the required global semantics

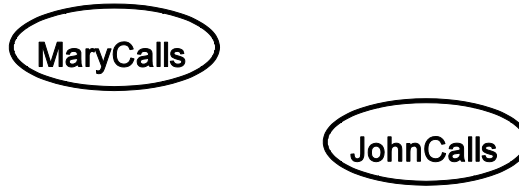
1. Choose an ordering of variables X_1, \dots, X_n
2. For $i = 1$ to n
 - add X_i to the network
 - select parents from X_1, \dots, X_{i-1} such that
$$\mathbf{P}(X_i | \text{Parents}(X_i)) = \mathbf{P}(X_i | X_1, \dots, X_{i-1})$$

This choice of parents guarantees the global semantics:

$$\begin{aligned}\mathbf{P}(X_1, \dots, X_n) &= \prod_{i=1}^n \mathbf{P}(X_i | X_1, \dots, X_{i-1}) \quad (\text{chain rule}) \\ &= \prod_{i=1}^n \mathbf{P}(X_i | \text{Parents}(X_i)) \quad (\text{by construction})\end{aligned}$$

Example

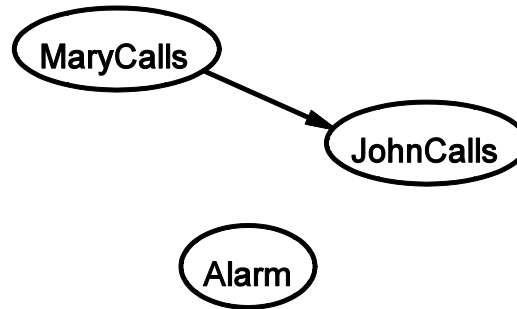
Suppose we choose the ordering M, J, A, B, E



$$P(J|M) = P(J)?$$

Example

Suppose we choose the ordering M, J, A, B, E

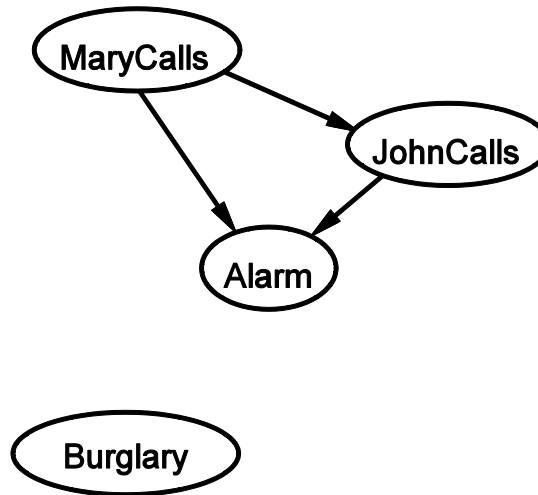


$P(J|M) = P(J)$? No

$P(A|J, M) = P(A|J)$? $P(A|J, M) = P(A)$?

Example

Suppose we choose the ordering M, J, A, B, E



$P(J|M) = P(J)$? No

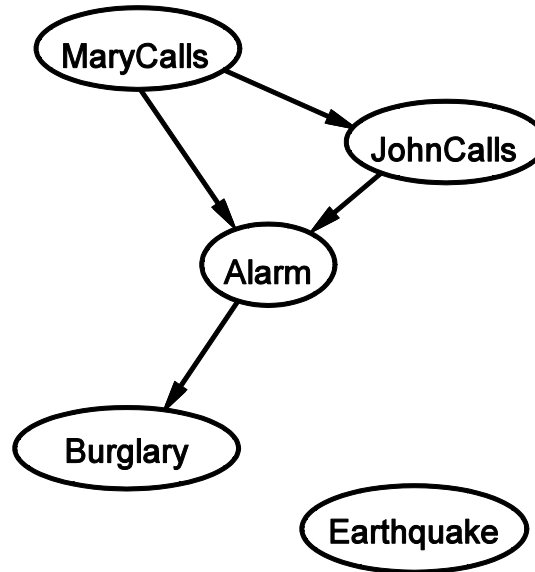
$P(A|J, M) = P(A|J)$? $P(A|J, M) = P(A)$? No

$P(B|A, J, M) = P(B|A)$?

$P(B|A, J, M) = P(B)$?

Example

Suppose we choose the ordering M, J, A, B, E



$P(J|M) = P(J)$? No

$P(A|J, M) = P(A|J)$? $P(A|J, M) = P(A)$? No

$P(B|A, J, M) = P(B|A)$? Yes

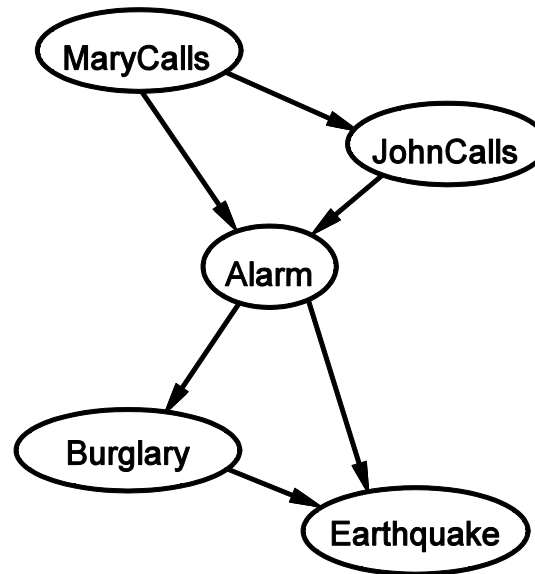
$P(B|A, J, M) = P(B)$? No

$P(E|B, A, J, M) = P(E|A)$?

$P(E|B, A, J, M) = P(E|A, B)$?

Example

Suppose we choose the ordering M, J, A, B, E



$P(J|M) = P(J)$? No

$P(A|J, M) = P(A|J)$? $P(A|J, M) = P(A)$? No

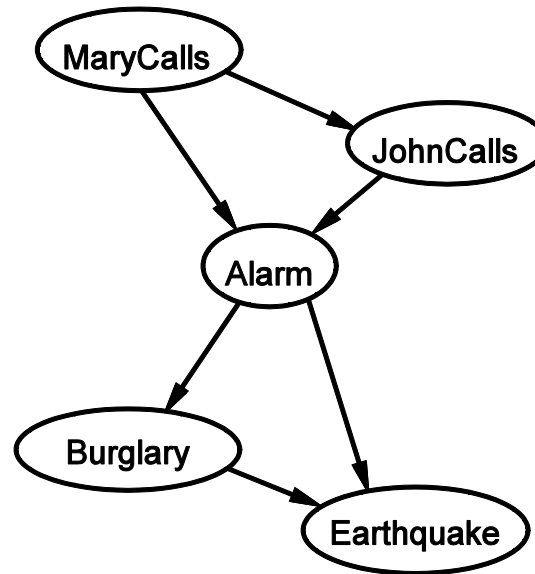
$P(B|A, J, M) = P(B|A)$? Yes

$P(B|A, J, M) = P(B)$? No

$P(E|B, A, J, M) = P(E|A)$? No

$P(E|B, A, J, M) = P(E|A, B)$? Yes

Example contd.



Deciding conditional independence is hard in noncausal directions
(symptoms \rightarrow causes)

Causal models (causes \rightarrow symptoms) and conditional independence
seem easier for humans!

Assessing conditional probabilities is hard in noncausal directions

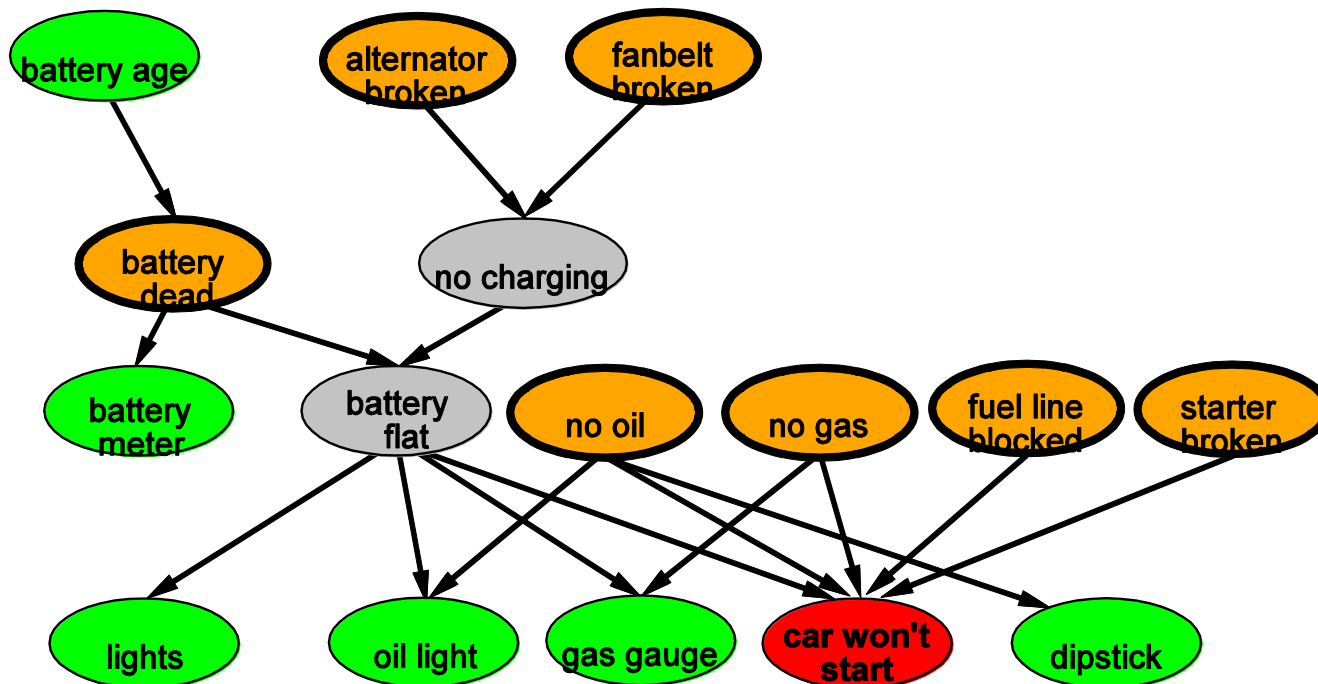
Network is less compact: $1 + 2 + 4 + 2 + 4 = 13$ numbers needed

Example: Car diagnosis

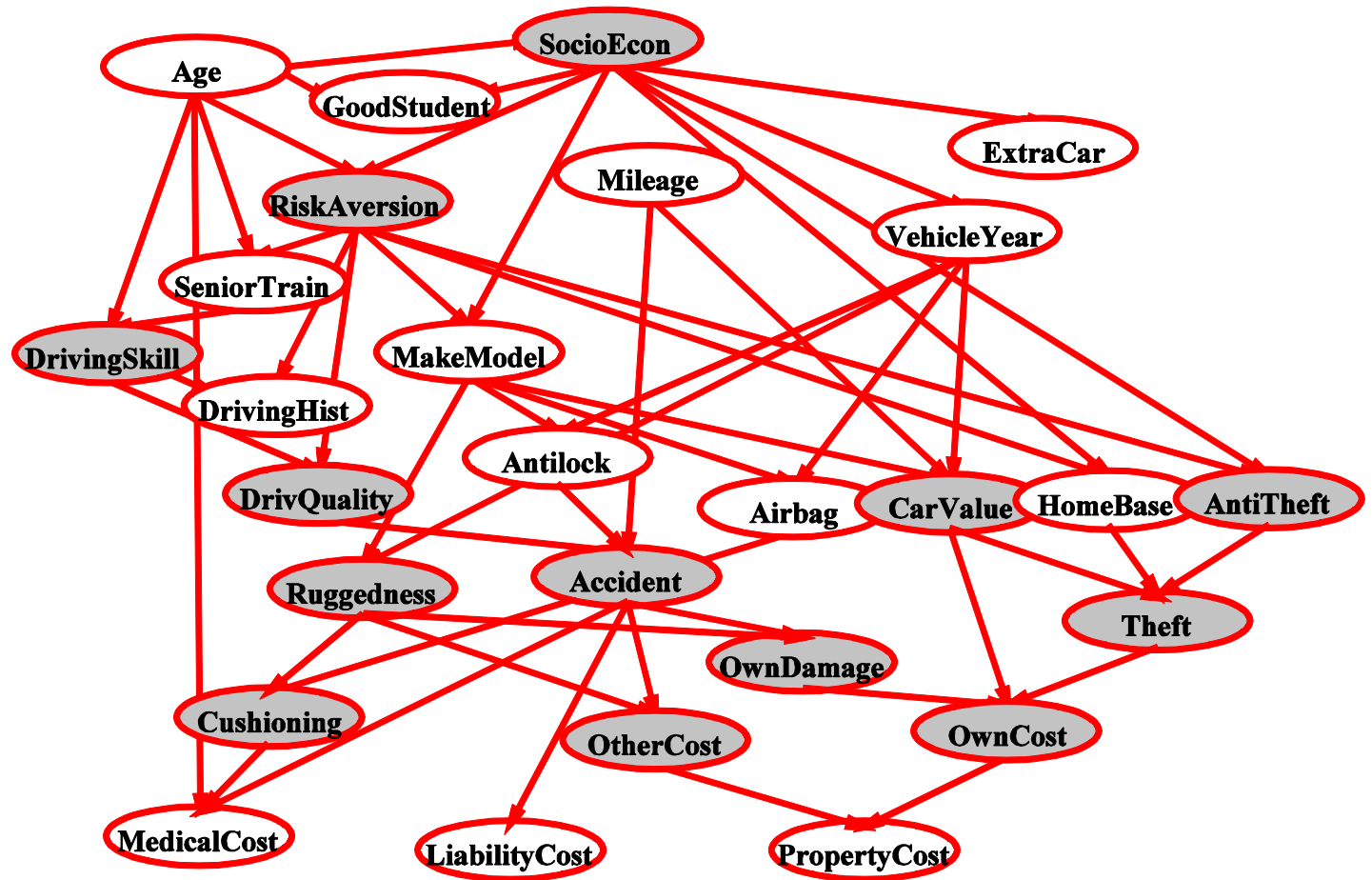
Initial evidence: car won't start

Testable variables (green), “broken, so fix it” variables (orange)

Hidden variables (gray) ensure sparse structure, reduce parameters



Example: Car insurance



Inference tasks

Simple queries: compute posterior marginal $\mathbf{P}(X_i|\mathbf{E} = E)$

e.g., $P(\text{NoGas} | \text{Gauge} = \text{empty}, \text{Lights} = \text{on}, \text{Starts} = \text{false})$

Conjunctive queries: $\mathbf{P}(X_i, X_j | \mathbf{E} = E) = \mathbf{P}(X_i | \mathbf{E} = E) \mathbf{P}(X_j | X_i, \mathbf{E} = E)$

Value of information: which evidence to seek next?

Sensitivity analysis: which probability values are most critical?

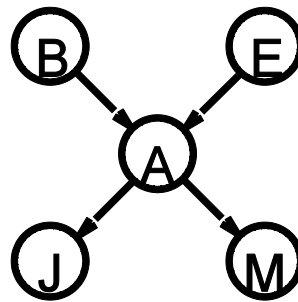
Explanation: why do I need a new starter motor?

We focus on **simple** and **conjunctive** queries

Inference by enumeration

Slightly intelligent way to sum out variables from the joint without actually constructing its explicit representation

Simple query on the burglary network:



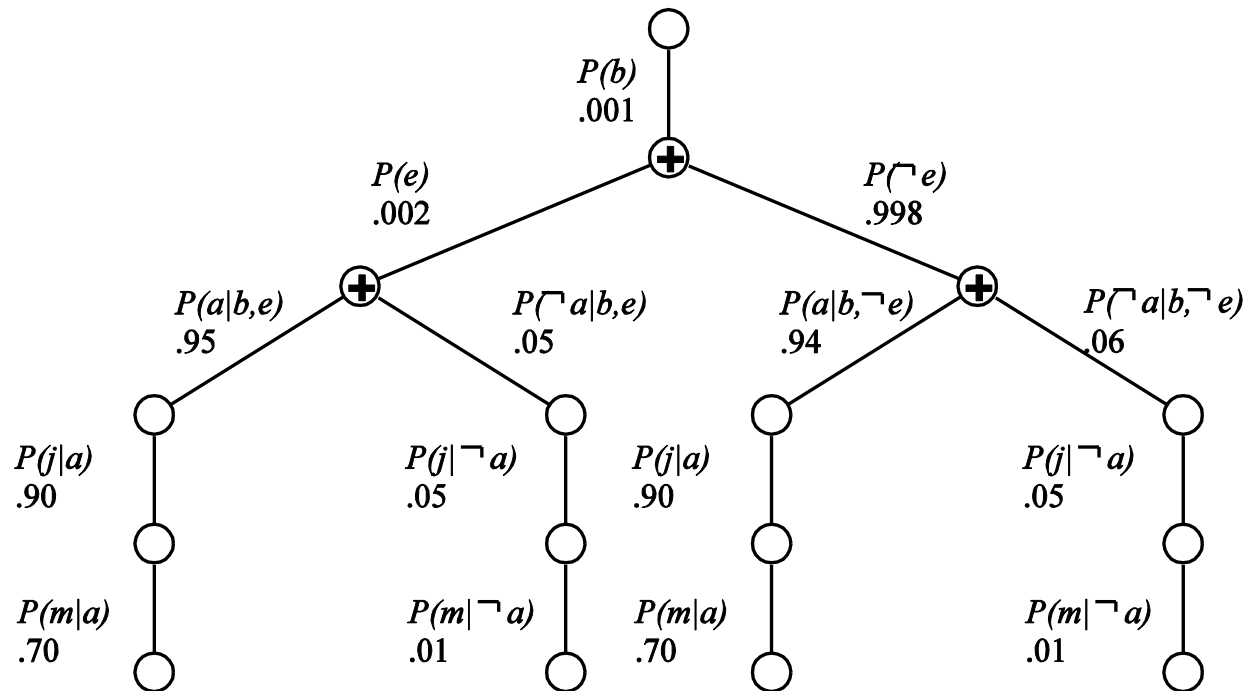
$$\begin{aligned} & \mathbf{P}(B|j, m) \\ &= \mathbf{P}(B, j, m) / P(j, m) \\ &= \alpha \mathbf{P}(B, j, m) \\ &= \alpha \sum_e \sum_a \mathbf{P}(B, e, a, j, m) \end{aligned}$$

Rewrite full joint entries using product of CPT entries:

$$\begin{aligned} & \mathbf{P}(B|j, m) \\ &= \alpha \sum_e \sum_a \mathbf{P}(B) P(e) \mathbf{P}(a|B, e) P(j|a) P(m|a) \\ &= \alpha \mathbf{P}(B) \sum_e P(e) \sum_a \mathbf{P}(a|B, e) P(j|a) P(m|a) \end{aligned}$$

Recursive depth-first enumeration: $O(n)$ space, $O(d^n)$ time

Evaluation tree



Enumeration is inefficient: repeated computation
 e.g., computes $P(j|a)P(m|a)$ for each value of e

Inference by variable elimination

Variable elimination: carry out summations right-to-left, storing intermediate results (**factors**) to avoid recomputation

$$\begin{aligned} \mathbf{P}(B|j, m) &= \alpha \underbrace{\mathbf{P}(B)}_B \underbrace{\sum_e P(e)}_{\bar{E}} \underbrace{\sum_a \mathbf{P}(a|B, e)}_A \underbrace{P(j|a)}_J \underbrace{P(m|a)}_M \\ &= \alpha \mathbf{P}(B) \sum_e P(e) \sum_a \mathbf{P}(a|B, e) P(j|a) f_M(a) \\ &= \alpha \mathbf{P}(B) \sum_e P(e) \sum_a \mathbf{P}(a|B, e) f_J(a) f_M(a) \\ &= \alpha \mathbf{P}(B) \sum_e P(e) \sum_a f_A(a, b, e) f_J(a) f_M(a) \\ &= \alpha \mathbf{P}(B) \sum_e P(e) f_{\bar{A}JM}(b, e) \text{ (sum out } A) \\ &= \alpha \mathbf{P}(B) f_{\bar{E}\bar{A}JM}(b) \text{ (sum out } E) \\ &= \alpha f_B(b) \times f_{\bar{E}\bar{A}JM}(b) \end{aligned}$$

Variable elimination: Basic operations

Summing out a variable from a product of factors:

move any constant factors outside the summation

add up submatrices in pointwise product of remaining factors

$$\sum_x f_1 \times \cdots \times f_k = f_1 \times \cdots \times f_i \sum_x f_{i+1} \times \cdots \times f_k = f_1 \times \cdots \times f_i \times f_{\bar{X}}$$

assuming f_1, \dots, f_i do not depend on X

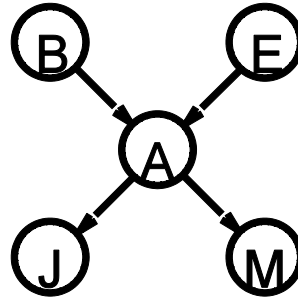
Pointwise product of factors f_1 and f_2 :

$$\begin{aligned} f_1(x_1, \dots, x_j, y_1, \dots, y_k) \times f_2(y_1, \dots, y_k, z_1, \dots, z_l) \\ = f(x_1, \dots, x_j, y_1, \dots, y_k, z_1, \dots, z_l) \end{aligned}$$

e.g., $f_1(a, b) \times f_2(b, c) = f(a, b, c)$

Irrelevant variables

Consider the query $P(\text{JohnCalls} | \text{Burglary} = \text{true})$



$$P(J|b) = \alpha P(b) \sum_e P(e) \sum_a P(a|b, e) P(J|a) \sum_m P(m|a)$$

Sum over m is identically 1; M is **irrelevant** to the query

Thm 1: Y is irrelevant unless $Y \in \text{Ancestors}(\{X\} \cup \mathcal{E})$

Here, $X = \text{JohnCalls}$, $\mathcal{E} = \{\text{Burglary}\}$, and
 $\text{Ancestors}(\{X\} \cup \mathcal{E}) = \{\text{Alarm}, \text{Earthquake}\}$
so MaryCalls is irrelevant

Summary

Bayes nets provide a natural representation for (causally induced) conditional independence

Topology + CPTs = compact representation of joint distribution

Generally easy for (non)experts to construct

Exact inference by enumeration

Exact inference by variable elimination

Examples of skills expected:

- ◇ Formulate a belief network for a given problem domain
- ◇ Derive expression for joint probability distribution for given belief network
- ◇ Use inference by enumeration to answer a query about simple or conjunctive queries on a given belief network