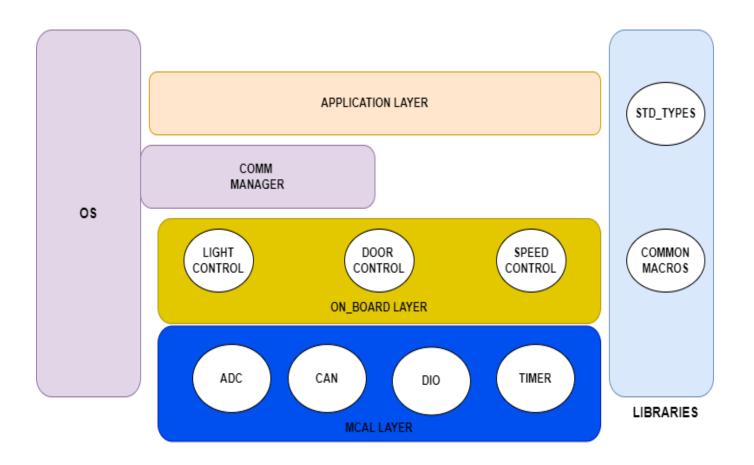
# **ECU1 Static Design**

**Ammar Hassan Abdelhakim** 

#### > ECU1 LAYERED ARCHITECTURE



## **ECU1** Consists Of 7 Modules:

- DIO
- CAN
- TIMER
- ADC
- LIGHT CONTROL
- DOOR CONTROL
- SPEED CONTROL

# **ECU1 DETAILS APIS&TYPES:**

## • DIO

#### TYPES

NAME	pinConfg		
ТҮРЕ	STRUCTURE		
RANGE	portNo	Port which pin belongs to	
	pinNo	Number of the pin in the port	
	pinDr	The direction of the pin	
	inRes	The internal resistor	
DESCRIPTION		Structure to configure each individual pin	

Name	PinDir		
TYPE	ENUM		
RANGE	INDIR	INDIR 0	
	OURDIE	1	
DESCRIPTION	Enum to hole	Enum to hold pin direction	

NAME	inResType		
TYPE	ENUM		
RANGE	PULLUP	0	
	PULLDOWN	1	
	NOA	2	
DESCRIPTION	Enum to hold	Enum to hold pin resistor	

NAME	pinStatus		
TYPE	ENUM	ENUM	
RANGE	LOW	LOW 0	
	HIGH	1	
DESCRIPTION	Enum to h	Enum to hold the status of the	
	pin		

NAME	portID		
TYPE	ENUM		
RANGE	PORTA 0		
	PORTB 1		
	PORTC 2		
	PORTD 3		
	PORTE 4		
	PORTF 5		
DESCRIPTION	Enum to hold port id	Enum to hold port id	

NAME	pinID	
TYPE	ENUM	
RANGE	PIN0	0
	PIN1	1
	PIN2	2
	PIIN3	3
	PIN4	4
	PIN5	5
	PIN6	6
	PIN7	7
DESCRIPTION	Enum to hold pin id	

<b>Function Name</b>	Dio_Init		
Parameters	Input	Input Output	
	configPtr Pointer to pin configurat data	None	
Return	none		
Description	Function to initialize	<b>Function to initialize the DIO module</b>	

<b>Function Name</b>	DIO_PIN_write		
Parameters	Input		
	pinID	Indicates the index of the pin	
	pinStatus	Indicates the status of the pin	
Return	none		
Description	<b>Function to set</b>	Function to set the level of a pin	

<b>Function Name</b>	DIO_PIN_read		
Parameters	Input	Input	
	pinID	Indicates the index	
		of the pin	
Return	pinStatus	Indicates the state	
		of the pin	
Description	Function to rea	Function to read a level of a pin	

#### • TIMER

#### TYPES

NAME	timerConfig
TYPE	STRUCTURE
RANGE	
DESCRIPTION	Sturcture holds the timer call
	back function

<b>Function Name</b>	timer_init		
Parameters	input	input	
	TimerConfig	Pointer to timer configuration data	
Return	None	None	
Description	Function to ini module	Function to initialize the timer module	

<b>Function Name</b>	timer_start	
Paramteters	Input	
	time Unit32 time in	
		seconds
Return	None	
Description	Function to start the timer	
	module	

<b>Function Name</b>	timer_stop
Parameters	None
Return	None
Description	Function to stop the timer module

#### ADC

#### TYPES

NAME	ChannelID	
ТҮРЕ	Enum	
RANGE	СН0	0
	CH1	1
	CH2	2
	CH3	3
	CH4	4
	CH5	5
	CH6	6
	CH7	7
DESCRIPTION	Enum holds ADC channels	

Function Name	ADC_init	
Parameters	None	
Return	None	
Description	Function to initialize the ADC	
	module	

Function Name	ADC_Read_CHannel	
Parameters	Input	
	CH_NO	Indicates
		channel id
Return	CH_value	The value in
		the ADC
		register
Description	Function to read the value of the	
	ADC	

# • CAN

Function Name	CAN_init	
Parameters	None	
Return	None	
Description	Function to initialize CAN	
	module	

<b>Function Name</b>	CAN_send_da	CAN_send_data	
Parameters	Input	Input	
	Unit32 data	Data that will be sent through CAN	
Return	None	None	
Description	Function to se can module	Function to send data through can module	

<b>Function Name</b>	CAN_recieve_data	
Parameters	output	
	Unint32*data	Data that will
		be received
		through CAN
Return	None	
Description	Function to receive data	
	through CAN module	

# • Light control module

#### APIS

<b>Function Name</b>	Light_control_init
Parameters	None
Return	None
Description	Function to initialize the light
	sensor

Function Name	Light_status	
Parameters	None	
Return	Unit8 state	State of light
Description	Function to return the status of	
	the light sensor	

# • Door control module

<b>Function Name</b>	Door_init
Parameters	None
Return	None
Description	Function to initialize the door
	sensor

<b>Function Name</b>	Door_status	Door_status	
Parameters	None	None	
Return	Unit8 state	State of door	
Description	Function to re	Function to return the state of	
	the door sense	the door sensor	

# • Speed control module

<b>Function Name</b>	Speed_init
Parameters	None
Return	None
Description	Function to initialize the speed
	sensor

<b>Function Name</b>	Speed_value	Speed_value	
Parameters	None	None	
Return	Unit8 value	Value of the speed sensor	
Description	Function to ge	Function to get the value of	
	the speed sen	the speed sensor	