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Introduction



- Most of the numerical schemes used to solve the PDEs are based on finite differences.
- ► In this method, the derivatives appearing in the equation and the boundary conditions are replaced by their finite-difference approximations.
- ► Then the given equation is changed to a difference equation which is solved by iterative procedures.

Introduction



- ► Recall that A *partial differential equation* is a differential equation involving more than one independent variable, so that the derivatives occurring in it are partial derivatives.
- Partial differential equations has many applications in physics, chemistry and biology.
- ► These equations are used to describe physical/biological phenomena such as sound, heat, electrostatics, electrodynamics, fluid/blood flow or elasticity.
- ► Most of these problems can be formulated as second-order partial differential equations.
- Only some of the partial differential equations can be solved analytically and in most cases, we depend on the numerical solution of PDEs.

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Classification of second order PDEs



► The general linear PDE of the second order in two independent variables is of the form:

$$A\frac{\partial^2 u}{\partial x^2} + B\frac{\partial^2 u}{\partial x \partial y} + C\frac{\partial^2 u}{\partial y^2} + D\frac{\partial u}{\partial x} + E\frac{\partial u}{\partial y} + Fu = G$$

where A, B, C, D, E, F and G are functions of x and y.

► The above equation can also be written as

$$Au_{xx} + Bu_{xy} + Cu_{yy} + Du_x + Eu_y + Fu = G$$
 (1)

- ▶ Depending on the values of these coefficients the above equation is classified into one of the three following types:
 - ▶ Elliptic: if $B^2 4AC < 0$.
 - ▶ Hyperbolic: if $B^2 4AC > 0$,
 - **Parabolic:** if $B^2 4AC = 0$.

PDE Classification



The partial differential equation

$$xu_{xx} + u_{yy} = 0$$

is

- ightharpoonup elliptic if x > 0,
- ightharpoonup hyperbolic if x < 0,
- ightharpoonup parabolic if x = 0.

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Well-posed and ill-posed problems



The region on which the PDE defined plays an important role in the classification of PDEs. In the study of PDEs, usually three types of problems arise:

▶ **Dirchlet's problem:** Given a continuous function *f* on the boundary *C* of a region *R*, to find a function *u* satisfying the Laplace equation in *R* i.e., to find *u* such that

$$u_{xx} + u_{yy} = 0 \text{ in } R$$

$$u = f \text{ on } C$$
(2)

Numerical Methods for Solving PDE



In the present analysis we restrict ourselves to three simple particular cases of Eq. (1), namely

Laplace Equation:

$$u_{xx} + u_{yy} = 0$$

Wave Equation:

$$c^2 u_{xx} - u_{tt} = 0$$

Heat Conduction Equation:

$$u_{xx} - u_t = 0$$

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Well-posed and ill-posed problems



Cauchy's problem:

$$u_{tt} - u_{xx} = 0 \text{ for } t > 0$$

$$u(x, 0) = f(x)$$

$$u_t(x, 0) = g(x)$$
(3)

$$u_t - u_{xx} = 0 \text{ for } t > 0$$

$$u(x, 0) = f(x)$$

$$(4)$$

The above problems are all well-posed i.e., posses unique solutions.

Well-posed and ill-posed problems



- ▶ The problems which are not well-posed are called ill-posed problems.
- ▶ In contrast to ODE, the form of a PDE is always connected with a particular type of associated conditions. Thus, the problem of Laplace's equation with Cauchy boundary conditions defined by

$$u_{xx} + u_{yy} = 0 \text{ in } R$$

$$u(x,0) = f(x)$$

$$u_{y}(x,0) = g(x)$$

$$(5)$$

is an ill-posed problem.

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Finite-difference approximations to derivatives



- We write u(x, y) = u(ih, jk) as simply $u_{i,j}$.
- ► Then we have the finite difference approximations for the partial derivatives in *x*—direction are:

$$\begin{split} u_{x} &= \frac{u_{i+1,j} - u_{i,j}}{h} + O(h) \\ u_{x} &= \frac{u_{i,j} - u_{i-1,j}}{h} + O(h) \\ u_{x} &= \frac{u_{i+1,j} - u_{i-1,j}}{2h} + O(h^{2}) \\ \text{and} \\ u_{xx} &= \frac{u_{i-1,j} - 2u_{i,j} + u_{i+1,j}}{h^{2}} + O(h^{2}) \end{split}$$

where
$$u_{i,j} = u(ih, jk) = u(x, y)$$
.

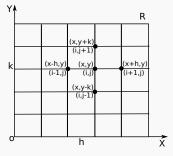
Finite-difference approximations to derivatives



- ► Consider a rectangular region *R* in the *xy*−plane.
- ▶ Divide this region into a rectangular mesh of sides $\Delta x = h$ and $\Delta y = k$ by drawing the set of lines

$$x = ih, i = 0, 1, 2, ...$$
 and $y = jk, j = 0, 1, 2, ...$

as shown in the figure.



► The points of intersection of the dividing lines are called *mesh points*, *nodal points*, or *grid points*.

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Finite-difference approximations to derivatives



➤ Similarly we have the finite difference approximations for the partial derivatives in y—direction are:

$$\begin{aligned} u_y &= \frac{u_{i,j+1} - u_{i,j}}{k} + O(k) \\ u_y &= \frac{u_{i,j} - u_{i,j-1}}{k} + O(k) \\ u_y &= \frac{u_{i,j+1} - u_{i,j-1}}{2k} + O(k^2) \\ \text{and} \\ u_{yy} &= \frac{u_{i,j-1} - 2u_{i,j} + u_{i,j+1}}{k^2} + O(k^2) \end{aligned}$$

where
$$u_{i,j} = u(ih, jk) = u(x, y)$$
.

Elliptic PDEs



► The Laplace's equation:

$$\nabla^2 u = \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} = 0$$

▶ and the Poisson's equation:

$$\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} = f(x, y)$$

are examples of elliptic partial differential equations.

- Laplace's equation arises in steady-state flow and potential problems.
- Poisson's equation arises in fluid mechanics, electricity, magnetism and torsion problems.
- ▶ Poisson's equation is generalization of Laplace's equation.

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Numerical Solution of Laplace's equation



The above formula can also be written as

$$u_{i,j} = \frac{1}{4} \left(u_{i-1,j-1} + u_{i+1,j-1} + u_{i+1,j+1} + u_{i-1,j+1} \right) \tag{8}$$

and called diagonal five-point formula.

By applying the above five-point standard formula at each mesh-point, we arrive at linear equations in the pivotal values i, j.

Once all the u_i (i = 1, 2, 3, ...) are computed, their accuracy can be improved by any of the iterative methods described below.

Numerical Solution of Laplace's equation



Substituting the finite difference of u_{xx} and u_{yy} in the Laplace equation $u_{xx} + u_{yy} = o$, we obtain

$$\frac{1}{h^2}\left(u_{i+1,j}-2u_{i,j}+u_{i-1,j}\right)+\frac{1}{k^2}\left(u_{i,j+1}-2u_{i,j}+u_{i,j-1}\right)=0\tag{6}$$

If h = k, then we have

$$u_{i,j} = \frac{1}{4} \left(u_{i+1,j} + u_{i-1,j} + u_{i,j+1} + u_{i,j-1} \right) \tag{7}$$

i.e., the value of *u* at any point is the mean of its values at the four neighbouring points. This is called the *standard five-point formula*.

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Numerical Solution of Laplace's equation



Jacobi's Method: Let $u_{i,j}^{(n)}$ denotes the *n*th iterative value of $u_{i,j}$. An iterative procedure to solve five-point standard formula is given by

$$u_{i,j}^{(n+1)} = \frac{1}{4} \left(u_{i-1,j}^{(n)} + u_{i+1,j}^{(n)} + u_{i,j-1}^{(n)} + u_{i,j+1}^{(n)} \right)$$
(9)

Gauss-Seidel Method: In this method we use the latest iterative values available and scans the mesh points systematically from left to right along the successive rows. The iterative formula is:

$$u_{i,j}^{(n+1)} = \frac{1}{4} \left(u_{i-1,j}^{(n+1)} + u_{i+1,j}^{(n)} + u_{i,j-1}^{(n+1)} + u_{i,j+1}^{(n)} \right)$$
 (10)

Numerical Solution of Poisson's equation



Exercise Problem



► The Poisson's equation can be solved numerically by using the standard 5— point formula given by

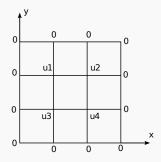
$$u_{i-1,i} + u_{i+1,i} + u_{i,i+1} + u_{i,i-1} - 4u_{i,i} = h^2 f(ih, jh).$$

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Solution



The mesh formulation by taking h = 1 is shown in the below figure:



The standard 5—point formula for the given equation is given by

$$u_{i-1,j} + u_{i+1,j} + u_{i,j+1} + u_{i,j-1} - 4u_{i,j} = -10(i^2 + j^2 + 10)$$
 (*).

Example

Solve the partial differential equation

$$\nabla^2 u = -10(x^2 + y^2 + 10)$$

over the square with sides x = 0 = y, x = 3 = y with u = 0 on the boundary and with mesh length h = k = 1.

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Solution



For u_1 , we have i = 1, j = 2 and therefore, (*) gives

$$0 + u_2 + 0 + u_3 - 4u_1 = -10(1 + 4 + 10)$$

Therefore,

$$u_1 = \frac{1}{4}(u_2 + u_3 + 150) \tag{1}$$

For u_2 , we have i = 2, j = 2 and therefore, (*) gives

$$u_1 + 0 + 0 + u_4 - 4u_2 = -10(4 + 4 + 10)$$

Therefore,

$$u_2 = \frac{1}{4}(u_1 + u_4 + 180) \tag{2}$$

Solution



For u_3 , we have i = 1, j = 1 and therefore, (*) gives

$$0 + u_4 + u_1 + 0 - 4u_3 = -10(1 + 1 + 10)$$

Therefore,

$$u_3 = \frac{1}{4}(u_1 + u_4 + 120) \tag{3}$$

For u_4 , we have i = 2, j = 1 and therefore, (*) gives

$$u_3 + O + u_2 + O - 4u_4 = -10(4 + 1 + 10)$$

Therefore,

$$u_4 = \frac{1}{4}(u_2 + u_3 + 150) \tag{4}$$

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Parabolic Equations



► The one-dimensional heat conduction equation

$$\frac{\partial u}{\partial t} = c^2 \frac{\partial^2 u}{\partial x^2}$$

(where c^2 is the diffusivity of the substance (cm²/sec)) is a well-known example of parabolic PDE.

▶ The solution of this equation is a temperature function u(x, t) which is defined for $x \in [0, 1]$ and for $t \in [0, \infty)$.

Solution



Equations (1) and (4) shows that $u_1 = u_4$. Thus, the above equations reduce to

$$u_1 = \frac{1}{4}(u_2 + u_3 + 150)$$

$$u_2 = \frac{1}{2}(u_1 + 90)$$

$$u_3 = \frac{1}{2}(u_1 + 60)$$

Now, solving the above equations by Gauss-Seidel iteration method, we obtain

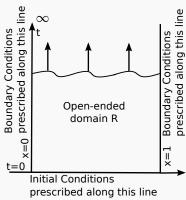
$$u_1 = 75, u_2 = 82.5, u_3 = 67.5, u_4 = 75.$$

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Parabolic Equations



➤ The solution is not defined in a closed domain but advances in an open-ended region from initial values, satisfying the prescribed boundary conditions.



Explicit Numerical Scheme to Solve Heat Equation

- VIT-AP 24
- ► Consider a recatngular mesh in the xt—space with spacing h along *x*−direction and *k* along *t*−direction.
- ▶ Denoting a mesh point (x, t) = (ih, jk) as simply i, j we have

$$\begin{split} \frac{\partial u}{\partial t} &= \frac{u_{i,j+1} - u_{i,j}}{k} \\ \text{and } \frac{\partial^2 u}{\partial x^2} &= \frac{u_{i,j-1} - 2u_{i,j} + u_{i+1,j}}{h^2} \end{split}$$

▶ substituting this in the above Heat equation, we obtain

$$u_{i,j+1} = \alpha u_{i-1,j} + (1-2\alpha)u_{i,j} + \alpha u_{i+1,j}$$

where $\alpha = \frac{kc^2}{h^2}$ is the mesh ratio parameter.

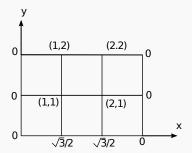
- \triangleright The above formula relates the functions values at two time levels i + 1and j and is therfore, called a 2-level formula.
- ► This is also called **Schmidt explicit formula** and is valid only for $0 < \alpha \leq \frac{1}{2}$.

Solution



Here $c^2=1$ and $h=\frac{1}{3}$, $k=\frac{1}{36}$. Therefore, $\alpha=\frac{kc^2}{h^2}=\frac{1}{4}$. Given initial condition is $u(x,0)=\sin\pi x$ for $0\leq x\leq 1$. Therefore,

 $u_{1,0}=\sin\frac{\pi}{3}=\frac{\sqrt{3}}{2}$ and $u_{2,0}=\sin\frac{2\pi}{3}=\frac{\sqrt{3}}{2}$. Since, u(0,t)=u(1,t)=0, we have all the boundary values are zero. Thus, the mesh can be pictorially represented as follows:



Exercise Problems



Example

Solve the equation

$$\frac{\partial u}{\partial t} = \frac{\partial^2 u}{\partial x^2}$$

subject to the conditions $u(x, 0) = \sin \pi x$, $0 \le x \le 1$; u(0, t) = u(1, t) = 0. Carry out computations for two levels taking $h = \frac{1}{3}, k = \frac{1}{36}$.

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Solution



Now, Schmidt's formula get reduces to

$$u_{i,j+1} = \frac{1}{4} \left[u_{i-1,j} + 2u_{i,j} + u_{i+1,j} \right].$$

To find $u_{1,1}$: Here i = 1, j = 0. So,

$$u_{1,1} = \frac{1}{4} \left[u_{0,0} + 2u_{1,0} + u_{2,0} \right]$$
$$= \frac{1}{4} \left(0 + 2 \times \frac{\sqrt{3}}{2} + \frac{\sqrt{3}}{2} \right) = 0.65$$

Solution



To find $u_{2,1}$: Here i = 2, j = 0. So,

$$u_{2,1} = \frac{1}{4} \left[u_{1,0} + 2u_{2,0} + u_{3,0} \right]$$
$$= \frac{1}{4} \left(\frac{\sqrt{3}}{2} + 2 \times \frac{\sqrt{3}}{2} + 0 \right) = 0.65$$

To find $u_{1,2}$: Here i = 1, j = 1. So,

$$u_{1,2} = \frac{1}{4} \left[u_{0,1} + 2u_{1,1} + u_{2,1} \right]$$
$$= \frac{1}{4} \left(0 + 2 \times 0.65 + 0.65 \right) = 0.49$$

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Crank-Nicolson Implicit Scheme to Solve Parabolic Equations

Consider the heat conduction equation

$$\frac{\partial u}{\partial t} = c^2 \frac{\partial^2 u}{\partial x^2}$$

Using the approximations

$$\frac{\partial u}{\partial t} = \frac{u_{i,j+1} - u_{i,j}}{k}$$

(as in the previous case). We replace $\frac{\partial^2 u}{\partial x^2}$ by average of its finite-difference approximations on the j^{th} and $(j+1)^{\text{th}}$ rows. Thus,

$$\frac{\partial^2 u}{\partial x^2} = \frac{1}{2} \left(\frac{u_{i-1,j} - 2u_{i,j} + u_{i+1,j}}{h^2} + \frac{u_{i-1,j+1} - 2u_{i,j} + u_{i+1,j+1}}{h^2} \right)$$

Solution



To find $u_{2,2}$: Here i = 2, j = 1. So,

$$u_{2,2} = \frac{1}{4} \left[u_{1,1} + 2u_{2,1} + u_{3,1} \right]$$
$$= \frac{1}{4} \left(0.65 + 2 \times 0.65 + 0 \right) = 0.49$$

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Crank-Nicolson Implicit Scheme to Solve Parabolic Equations

Substituting these in the heat equation and rearranging the terms, we obtain

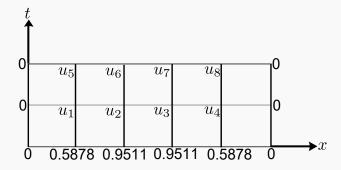
$$-\alpha u_{i-1,j+1} + (2+2\alpha)u_{i,j+1} - \alpha u_{i+1,j+1} = \alpha u_{i-1,j} + (2-2\alpha)u_{i,j} + \alpha u_{i+1,j},$$

where $\alpha = \frac{kc^2}{h^2}$. This is called *Crank-Nicolson implicit scheme* and is convergent for all values of α .

Crank-Nicolson Implicit Scheme to Solve Parabolic Equations

Example

Solve $u_t = u_{xx}$ subsect to the initial condition $u = \sin \pi x$, at t = 0 for $0 \le x \le 1$ and the boundary conditions u = 0 at x = 0 and x = 1 for t > 0. Taking h = 0.2 and k = 0.04 compute the values of u at the internal mesh points up to two time steps using Crank-Nicolson implicit scheme.



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Solution

By symmetry, we have $u_1 = u_4$, and $u_2 = u_3$. Hence, Eqs. (ii) to (v) reduce to the two equations:

$$4u_1 - u_2 = 0.9511$$
, $u_1 - 3u_2 = -1.5389$.

Solving, the above two equations we obtain $u_1 = u_4 = 0.3993$, $u_2 = u_3 = 0.6461$.

For the second time step, applying the formula (i) at the grid points u_5 , u_6 , u_7 and u_8 , we obtain

$$-4u_5 + u_6 = -0.6461$$

 $u_5 - 4u_6 + u_7 = -0.3993 - 0.6461 = -1.0454$
 $u_6 - 4u_7 + u_8 = -0.6461 - 0.3993 = -1.0454$
 $u_7 - 4u_8 = -0.6461$.

By symmetry, we have $u_5 = u_8$ and $u_6 = u_7$. Hence the above system of equations reduces to the following two equations:

$$-4u_5 + u_6 = -0.6461$$
 $u_5 - 3u_6 = -1.0454$

Solving we obtain $u_5 = u_8 = 0.2712, u_6 = u_7 = 0.4387$.

Solution

We have $c^2 = 1$, h = 0.2 and k = 0.04, So, $\alpha = \frac{kc^2}{h^2} = 1$. The Crank-Nicolson implicit scheme for $\alpha = 1$ is:

$$u_{i-1,j+1} - 4u_{i,j+1} + u_{i+1,j+1} = -u_{i-1,j} - u_{i+1,j}$$
 (i)

Applying (i) at the mesh point u_1 , (we have i = 1, j = 0) we obtain

$$0 - 4u_1 + u_2 = -0.9511 (ii)$$

C VIT-AP

Applying (i) at the mesh point u_2 , (we have i = 2, j = 0) we obtain

$$u_1 - 4u_2 + u_3 = -0.5878 - 0.9511 = -1.5389$$
 (iii)

Applying (i) at the mesh point u_3 , (we have i = 3, j = 0) we obtain

$$u_2 - 4u_3 + u_4 = -0.9511 - 0.5878 = -1.5389$$
 (iv)

Applying (i) at the mesh point u_4 , (we have i = 4, j = 0) we obtain

$$u_3 - 4u_4 + 0 = 0.9511$$
 (v)

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Crank-Nicolson Implicit Scheme to Solve Parabolic Equations

Example

WIT-AP 3

Solve the heat equation

$$\frac{\partial u}{\partial t} = \frac{\partial^2 u}{\partial x^2}$$

subject to the conditions

$$u(x, 0) = 0, \quad u(0, t) = 0, \quad u(1, t) = t$$

by taking $k = \frac{1}{8}$ and $h = \frac{1}{2}$.

Hint: The Crank-Nicolson scheme becomes

$$-u_{i-1,j+1}+6u_{i,j+1}-u_{i+1,j+1}=u_{i-1,j}+2u_{i,j}+u_{i+1,j}$$

Hyperbolic Equations



We consider the boundary-value problem defined by

$$\frac{\partial^2 \mathbf{u}}{\partial t^2} = c^2 \frac{\partial^2 \mathbf{u}}{\partial \mathbf{x}^2} \tag{11}$$

$$u(x,0) = f(x) \tag{12}$$

$$u_t(x, 0) = \phi(x) \tag{13}$$

$$u(0,t) = \psi_1(t) \tag{14}$$

$$\mathsf{u}(\mathsf{1},\mathsf{t}) = \psi_{\mathsf{2}}(\mathsf{t}) \tag{15}$$

for $0 \le t \le T$, which models the transverse vibrations of a stretched string.

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Numerical Scheme to Solve Hyperbolic Equation



Substituting, u_{xx} and u_{tt} in the equation (1) and rearranging the terms, we obtain

$$u_{i,j+1} = -u_{i,j-1} + \alpha^2 (u_{i-1,j} + u_{i+1,j}) + 2(1 - \alpha^2) u_{i,j}$$

where $\alpha = \frac{ck}{h}$.

The above formula is called *three level* difference scheme as the function values at the j^{th} and $(j-1)^{\text{th}}$ time levels are required in order to determine the values at $(j+1)^{\text{th}}$ time level. This valid for $\alpha <$ 1, which is the condition for stability.

Numerical Scheme to Solve Hyperbolic Equation



Using the finite difference approximations

$$u_{xx} = \frac{1}{h^2} (u_{i-1,j} - 2u_{i,j} + u_{i+1,j})$$

and

$$u_{tt} = \frac{1}{k^2} (i_{i,j-1} - 2u_{i,j} + u_{i,j+1}),$$

where x = ih, i = 0, 1, 2, ..., and t = jk, j = 0, 1, 2, ...

Further, $u_t(x, t)$ is approximated as

$$u_t(x,t) = \frac{u_{i,j+1} - u_{i,j-1}}{2k}$$

in particular, for $u_t(x, 0)$ we have j = 0 and that

$$u_t(x, 0) = \frac{u_{i,1} - u_{i,-1}}{2k}.$$

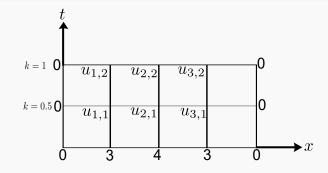
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Numerical Scheme to Solve Hyperbolic Equation



Example

Solve the BVP $u_{tt}=4u_{xx}$ subject to the conditions $u(0,t)=0=u(4,t), u_t(x,0)=0, u(x,0)=4x-x^2$, for $0\leq x\leq 4$, by taking h=1 and k=0.5. Carry out computations for two-levels.



Solution



Given h=1, k=0.5 and we have c=2. So, $\alpha=\frac{ck}{h}=1$.

Since u(o, t) = o = u(4, t) for $o \le x \le 4$, we have $u_{o,j} = u_{4,j} = o \forall j$.

Since $u_t(x, 0) = 0$, we have

$$\frac{u_{i,1} - u_{i,-1}}{2k} = 0 \implies u_{i,1} = u_{i,-1} \text{ for } j = 0$$

Finally,

$$u(x, 0) = 4x - x^2 \implies u_{i,0} = 4(ih) - (ih)^2 = 4i - i^2 \text{ (since } h = 1)$$

So,

$$u_{0,0} = 0, u_{1,0} = 3, u_{2,0} = 4, u_{3,0} = 3, u_{4,0} = 0.$$

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Solution



At the second time step i.e., t = 1, we have j = 1:

So, the equation (*) reduces to

$$u_{i,2} = -u_{i,0} + u_{i-1,1} + u_{i+1,1}$$

So,

$$u_{1,2} = -u_{1,0} + u_{0,1} + u_{2,1} = -3 + 0 + 3 = 0$$

 $u_{2,2} = -u_{2,0} + u_{1,1} + u_{3,1} = -4 + 2 + 2 = 0$

$$u_{3,2} = -u_{3,0} + u_{2,1} + u_{4,1} = -3 + 3 + 0 = 0$$

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Solution



For $\alpha=$ 1, the explicit scheme for Hyperbolic equations, get reduces to

$$u_{i,j+1} = -u_{i,j-1} + u_{i-1,j} + u_{i+1,j} \tag{*}$$

At the first time step i.e., t = 0.5, we have j = 0:

For j = 0 we have $u_{i,1} = u_{i,-1}$. So, the above equation (*) reduces to

$$u_{i,1} = -u_{i,-1} + u_{i-1,0} + u_{i+1,0} \implies u_{i,1} = \frac{1}{2}(u_{i-1,0} + u_{i+1,0})$$

So,

$$u_{1,1} = \frac{1}{2}(u_{0,0} + u_{2,0}) = \frac{1}{2}(0+4) = 2$$

$$u_{2,1} = \frac{1}{2}(u_{1,0} + u_{3,0}) = \frac{1}{2}(3+3) = 3$$

$$u_{3,1} = \frac{1}{2}(u_{2,0} + u_{4,0}) = \frac{1}{2}(4+0) = 2$$

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