odomSampler

import matplotlib.pyplot as plt

```
def sample(self, mu, sigma):
   tmp = [(random() * 2.0 * sigma - sigma) for x in range(12)]
   return 0.5 * sum(tmp) + mu
                                       """A Class for sampling from a gaussian normal distribution"""
class sampleFromGaussian:
```

```
sRot1 = self.dRot1 - self.sampler.sample(0, self.a1 * self.dRot1^2 + self.a2 * self.dTrans^2) sTrans = self.dTrans - self.sample(0, self.a3 * self.dTrans^2 + self.a4 * self.dRot1^2 +
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    sRot2 = self.dRot2 - self.sampler.sample(0, self.al ^* self.dRot2^{\sim}2 + self.a2 ^* self.dTrans^{\sim}2)
                                                                                                              _init__(self, odom0 = [1, 2, pi/3], odom1 = [4, 6, pi/2], pose0 = [8, 9, pi]): self.sampler = sampleFromGaussian()
                                                                                                                                                                                                                                                                                                                                                                       self.dTrans = float(sqrt((odom1[0] - odom0[0])^2 + (odom1[1] - odom0[1])^2))\\ self.dRot2 = odom1[2] - odom0[2] - self.dRot1
                                                                                                                                                                                                                                                                                                                                        - odom0[1],odom1[0] - odom0[0]))
class sampleFromOdom:
    ""A Class for sampling from an odom diff model"""
                                                                                                                                                                                                                                                                                                                                        self.dRot1 = float(atan2(odom1[1]
                                                                                                                                                                                                                                                               self.pose0 = pose0
# d[...] difference
                                                                                                                                                                                    self.odom0 = odom0
                                                                                                                                                                                                                          self.odom1 = odom1
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           self.a3 = 0.002 self.a4 = 0
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     # s[...] sample
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            self.a4 * self.dRot2^2)
                                                                                                                                                                                                                                                                                                                                                                                                                                                  # a[...] alpha
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                       self.a1 = 0.3
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               def sample(self):
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           self.a2 = 0
```

01/04/2016 10:11 AM

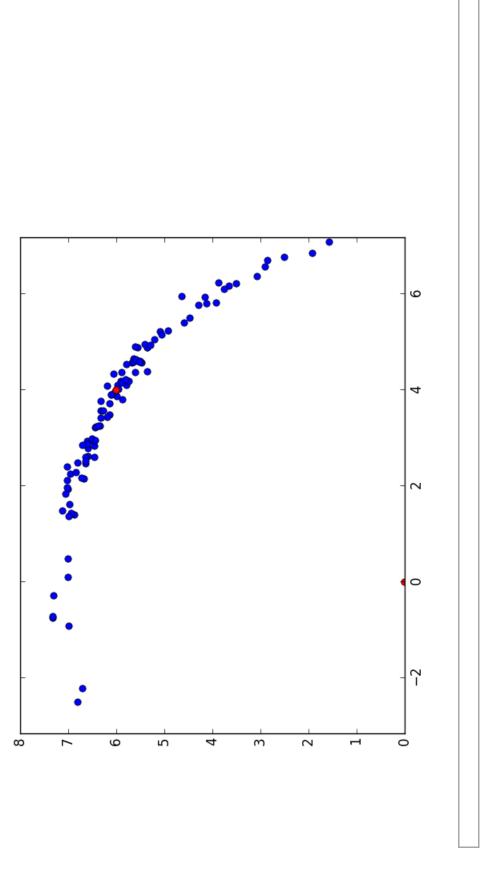
1 of 3

```
pose1 = copy(self.pose0)
pose1[0] += sTrans * cos(self.pose0[2] + sRot1)
pose1[1] += sTrans * sin(self.pose0[2] + sRot1)
pose1[2] += sRot1 + sRot2
                                                                                                                                                                 return posel
```

```
plt.plot(x,y,'bo')
plt.plot([0, 4],[0, 6],'ro')
plt.axes().set_aspect('equal', 'datalim')
plt.savefig('Histogram.png') #matplotlib has a bug, these lines force the plot to actually be drawn plt.close()
sampler = sampleFromOdom(odom0 = [0, 0, 0], odom1 = [4, 6, pi/2], pose0 = [0, 0, 0])
                                                                                                                                                                                               sampleSet.append(sampler.sample())
                                                                                                                                                                                                                              x.append(sampleSet[i][0])
y.append(sampleSet[i][1])
p.append(sampleSet[i][2])
                                                                                                                                                                for i in range(n):
                                   sampleSet = []
                                                                                                                                     [] = d
                                                                      Ⅱ
×
```

01/04/2016 10:11 AM

2 of 3



3 of 3