

CENG 789 – Digital Geometry Processing

04- Mesh Data Structure and Graphics Programming

3D

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Mesh Data Structure

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- ✓ Polygon mesh: set of *polygons* embedded in 2D or 3D.
- ✓ Polygon mesh: set of *vertices, edges, and faces* embedded in 2D or 3D.
- ✓ Lets handle these vertices, edges, faces in a structured way, hence the mesh data structure.

Mesh Data Structure

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- ✓ How to store geometry & connectivity of a mesh.

3D vertex coordinates

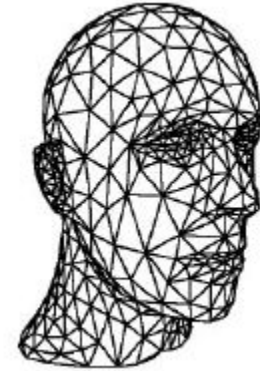
Vertex adjacency

- ✓ Attributes also stored: normal, color, texture coords, labels, etc.
- ✓ Efficient algorithms on meshes to get:
 - ✓ All vertices/edges of a face.
 - ✓ All incident vertices/edges/faces of a vertex.

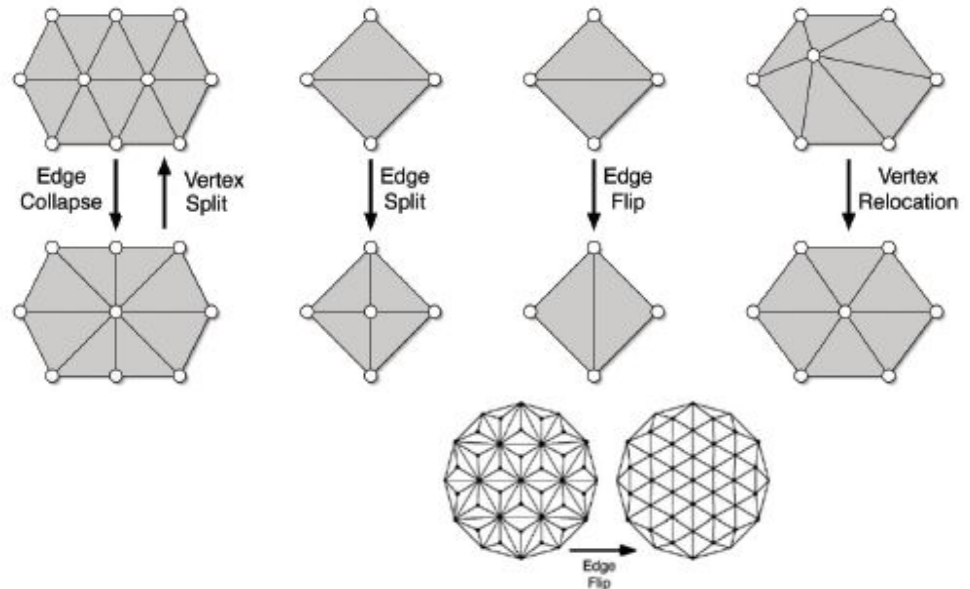
Mesh Data Structure

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- ✓ Classical queries:
 - ✓ What are the vertices of face 77?
 - ✓ Is vertex 7 adjacent to vertex 17?
 - ✓ Which edges are incident to vertex 27?
 - ✓ Which faces are incident to vertex 27?



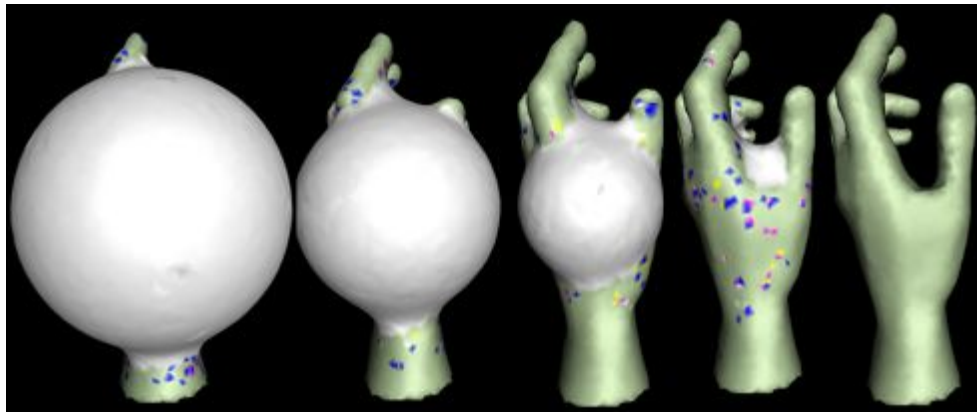
- ✓ Classical operations:
 - ✓ Remove/add vertex/face.
 - ✓ Split/collapse/flip edges.
 - ✓ Change vertex coordinates.
 - ✓ Topological vs. geometrical.



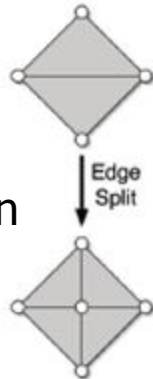
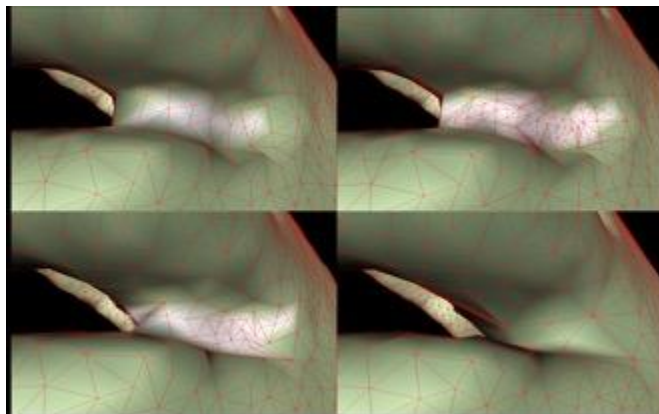
Mesh Data Structure

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- ✓ Applications of edge split:
- ✓ Increase resolution to catch details in 3D reconstruction
 - ✓ Paper: Shape from silhouette using topology-adaptive mesh deformation



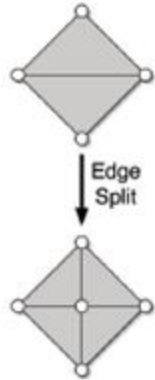
- ✓ Split short edge if midpoint is OUT:



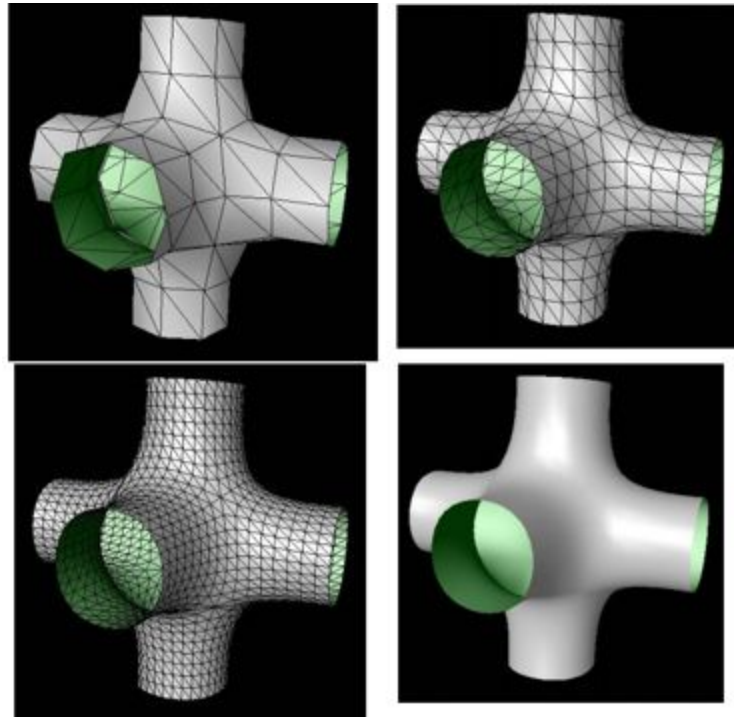
Mesh Data Structure

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- ✓ Applications of edge split:
- ✓ Increase resolution for smoother surfaces: Subdivision Surfaces
 - ✓ Loop subdivision



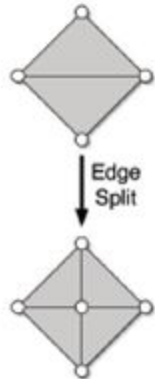
- ✓ 32 (original) to 1628 vertices in 3 iterations:



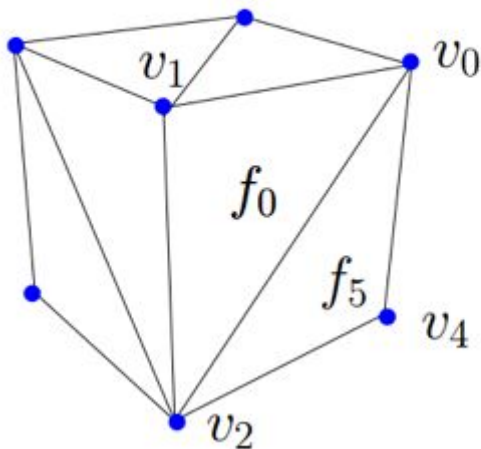
Mesh Data Structure

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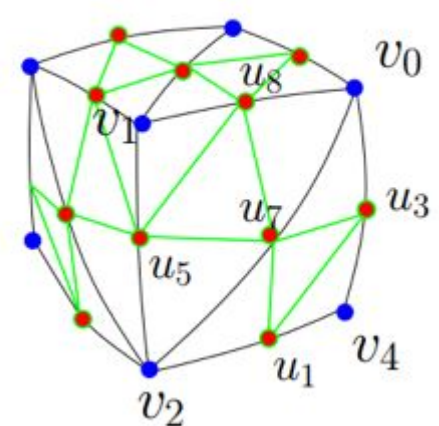
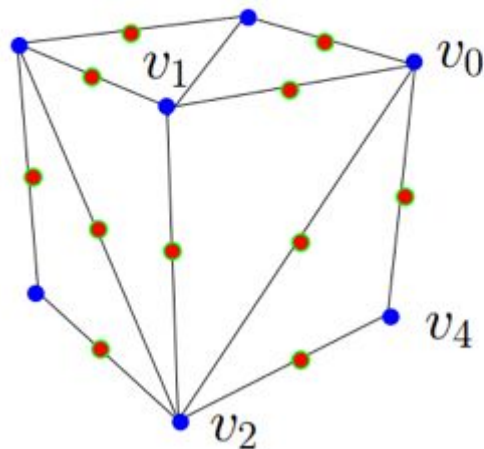
- ✓ Applications of edge split:
- ✓ Increase resolution for smoother surfaces: Subdivision Surfaces
 - ✓ Loop subdivision
 - ✓ Updating the topology (connectivity)



split all edges, by inserting a midpoint



subdivide each face into 4 triangles

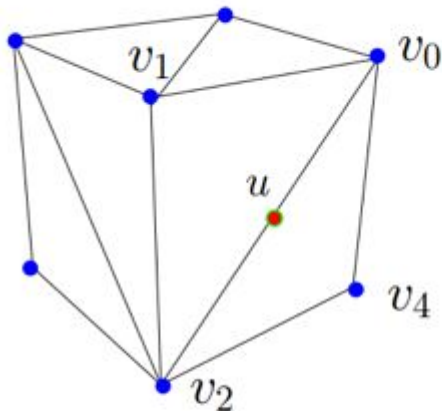


Mesh Data Structure

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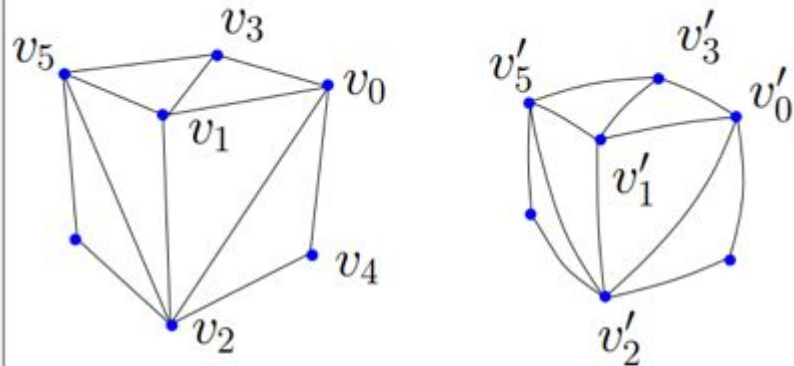
- ✓ Applications of edge split:
- ✓ Increase resolution for smoother surfaces: Subdivision Surfaces
 - ✓ Loop subdivision
 - ✓ Updating the geometry (coordinates)

First compute edge points u_k



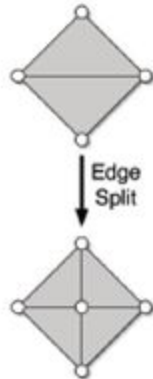
$$u = \frac{3}{8}v_0 + \frac{3}{8}v_2 + \frac{1}{8}v_1 + \frac{1}{8}v_4$$

Compute new locations v'_i of initial vertices



$$v'_i = (1 - \alpha d)v_i + \alpha \sum_{j=1}^d v_{i_j}$$

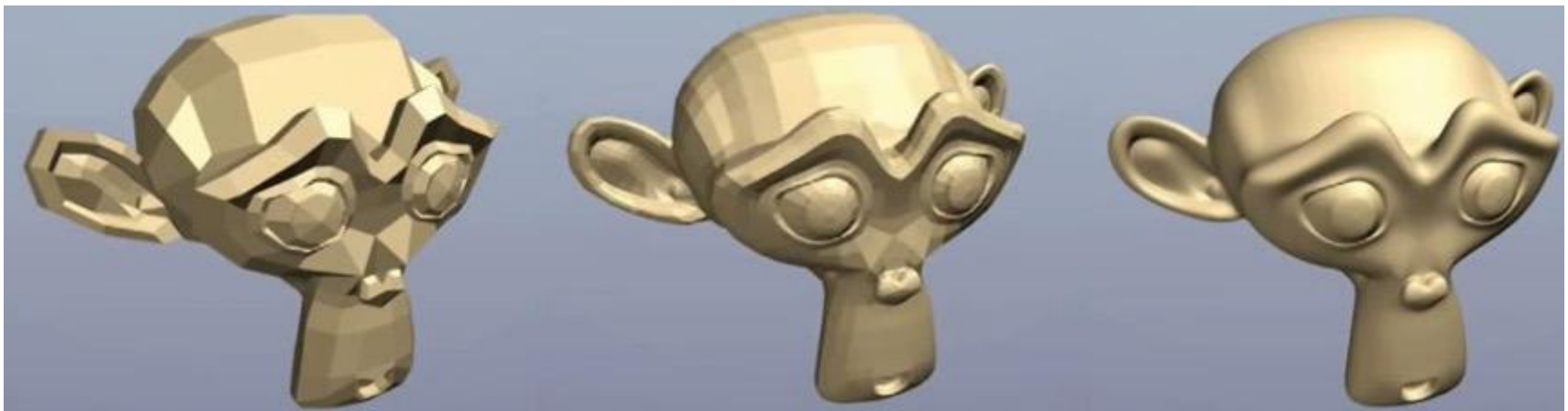
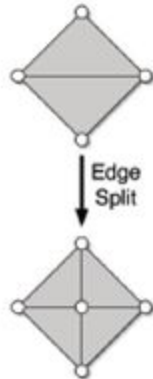
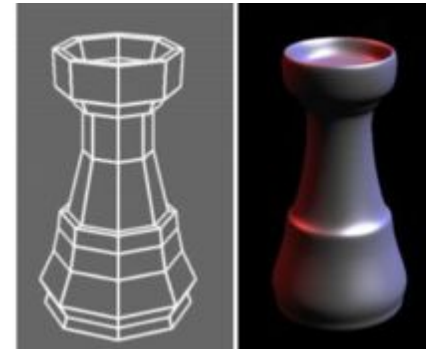
d is the degree of vertex v_i
 v_{i_j} is the j -th neighbor of v_i

$$\begin{cases} \alpha = \frac{3}{16}, & \text{if } d = 3 \\ \alpha = \frac{3}{8d}, & \text{if } d > 3 \end{cases}$$


Mesh Data Structure

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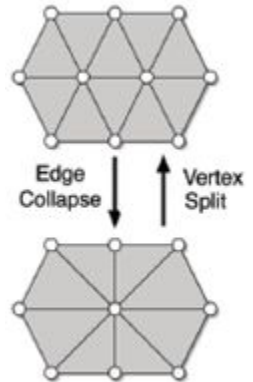
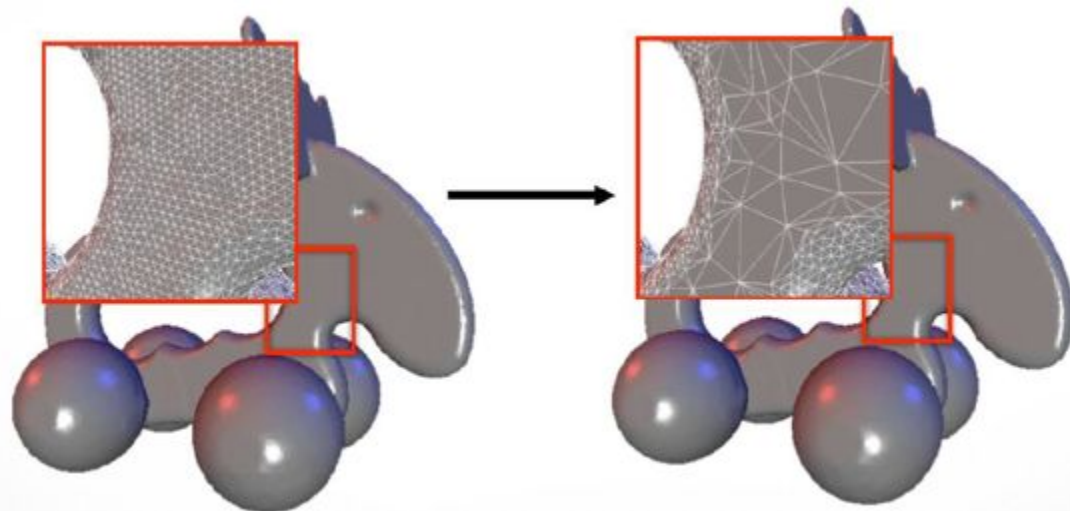
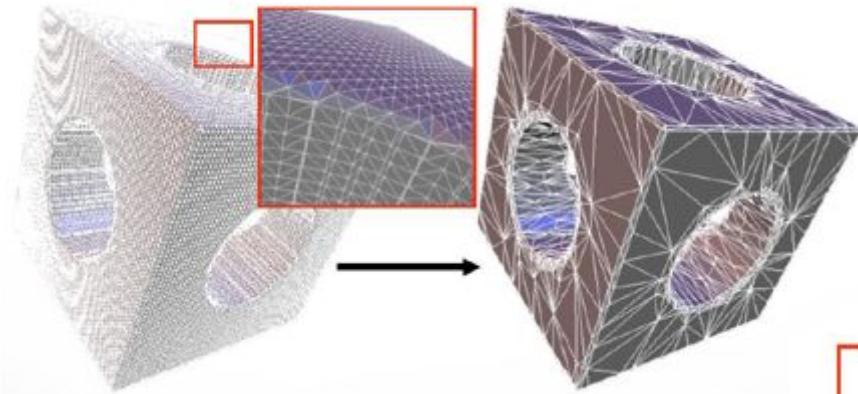
- ✓ Applications of edge split:
- ✓ Increase resolution for smoother surfaces: Subdivision Surfaces
 - ✓ Loop subdivision (best for triangle meshes)
 - ✓ Catmull-Clark subdivision (quad meshes)
 - ✓ Butterfly subdivision
 - ✓ Doo-Sabin subdivision
 - ✓ $\sqrt{3}$ -subdivision
- ✓ More on this in the Subdivision lecture later in semester.



Mesh Data Structure

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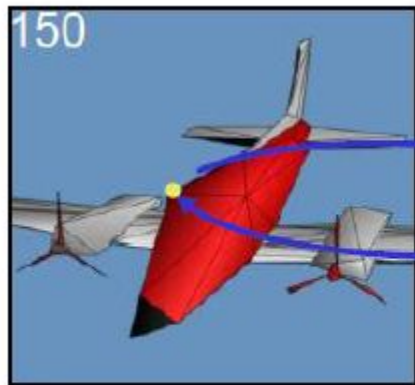
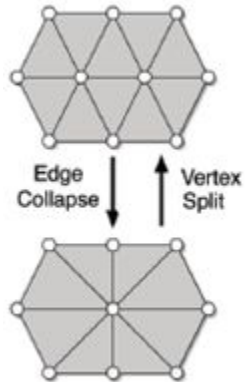
- ✓ Applications of edge collapse:
- ✓ Decrease resolution for efficiency
 - ✓ Detail-preserving



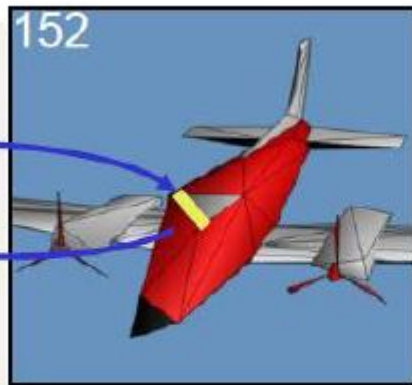
Mesh Data Structure

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- ✓ Applications of edge collapse:
- ✓ Decrease resolution for efficiency
 - ✓ Detail-oblivious (level-of-detail)



M^0



M^1



... M^{175} ...

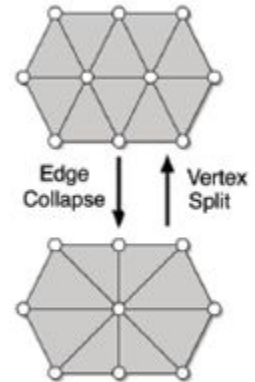
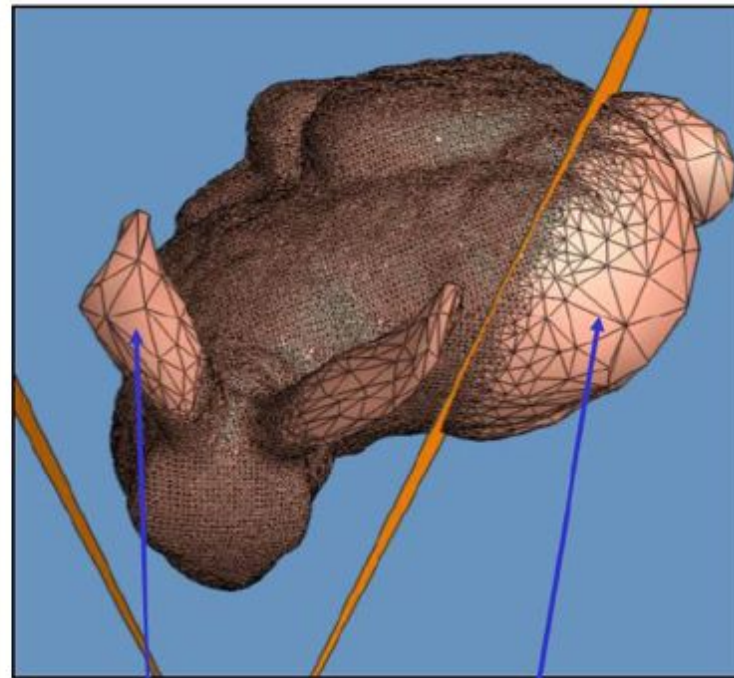
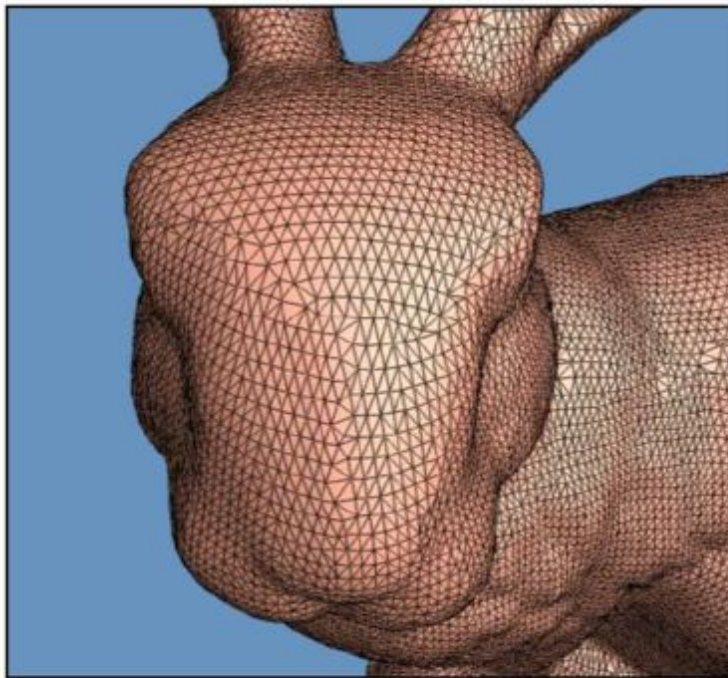


M^n

Mesh Data Structure

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- ✓ Applications of edge collapse:
- ✓ Decrease resolution for efficiency
 - ✓ Detail-oblivious (view-dependent rendering)



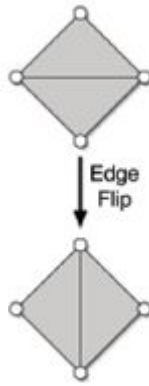
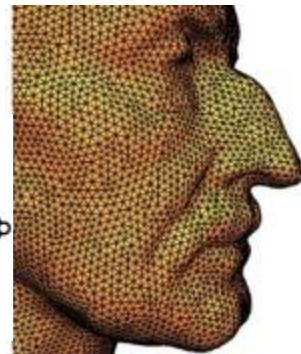
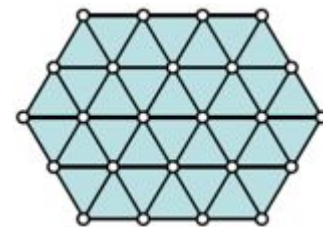
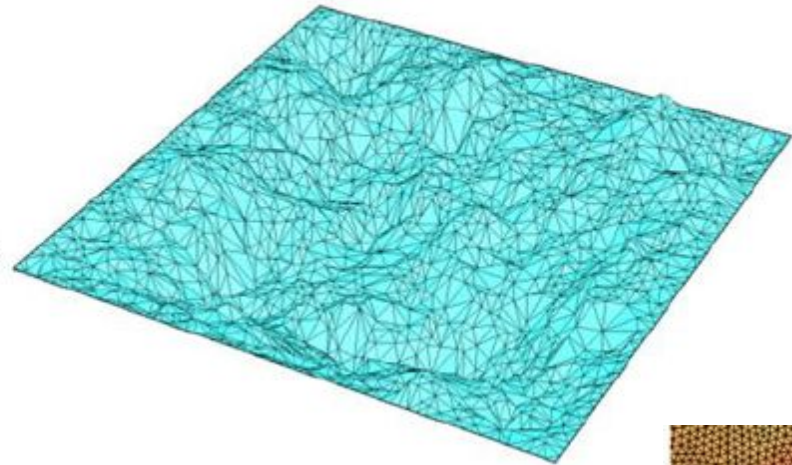
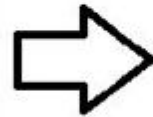
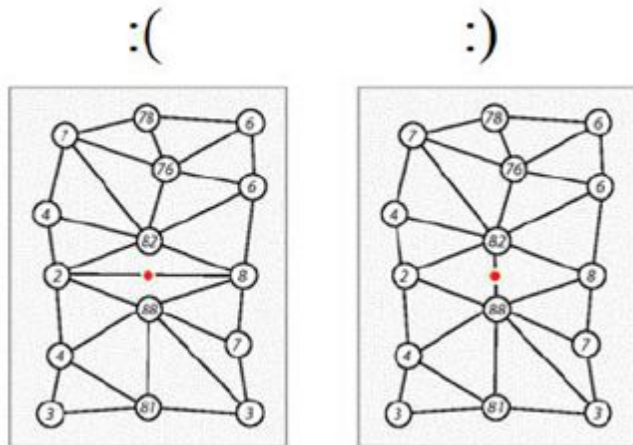
too high

too far right

Mesh Data Structure

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- ✓ Applications of edge flip:
- ✓ Better triangulations, e.g., w/ less skinny triangles
- ✓ Finite element modeling, simulations, terrain construction



Face-Based Data Structures

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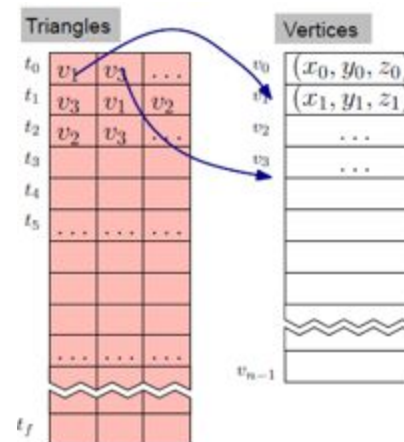
- ✓ One way to implement a mesh data structure is through faces.
- ✓ Face-Set data structure. //aka polygon soup `cos no connectivity info.

Triangles								
x_{11}	y_{11}	z_{11}	x_{12}	y_{12}	z_{12}	x_{13}	y_{13}	z_{13}
x_{21}	y_{21}	z_{21}	x_{22}	y_{22}	z_{22}	x_{23}	y_{23}	z_{23}
...				
x_{F1}	y_{F1}	z_{F1}	x_{F2}	y_{F2}	z_{F2}	x_{F3}	y_{F3}	z_{F3}

a are replicated.

- ✓ Indexed face-set data structure (obj, off, ply formats). **Better!!!!**

Vertices	Triangles
x_1 y_1 z_1	i_{11} i_{12} i_{13}
...	...
x_v y_v z_v	...
	...
	...
	i_{F1} i_{F2} i_{F3}



Face-Based Data Structures

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- ✓ My base code implements Indexed face-set data structure
- ✓ See <http://www.ceng.metu.edu.tr/~ys/ceng789-dgp/MyDemo.zip>

```
struct Triangle
{
    int idx; //tris[idx] is this triangle
    int v1i, v2i, v3i; //triangle formed by verts[v1i]-verts[v2i]-verts[v3i]
    float area, * normal; //direction

    Triangle(int i, int a, int b, int c) : idx(i), v1i(a), v2i(b), v3i(c) {};
};

struct Vertex
{
    int idx; //verts[idx]
    float* coords, //coords[0] ~ x coord, ..
        * normal; //direction

    vector< int > trilest;
    vector< int > edgelist;
    vector< int > vertlist;

    Vertex(int i, float* c) : idx(i), coords(c) {};
};

struct Edge
{
    int idx; //edges[idx]
    int v1i, v2i;
    float length;

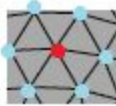
    Edge(int i, int a, int b, float l) : idx(i), v1i(a), v2i(b), length(l) {};
};
```

```
class Mesh
{
public:
    vector< Triangle* > tris;
    vector< Vertex* > verts;
    vector< Edge* > edges;

    void loadOff(char* fName);
    void createCube(float sl);
private:
    void addVertex(float* c);
    void addTriangle(int v1i, int v2i, int v3i);
    void addEdge(int v1i, int v2i);
    bool makeVertsNeighbors(int v, int w);
};
```

Edge-Based Data Structures

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- ✓ Another way to implement a mesh data structure is through edges.
 - ✓ For explicit storage of edges.
 - ✓ Enables efficient one-ring enumeration.
- 
- ✓ Can be done with slight modifications to Indexed face-set.
 - ✓ Define an Edge struct.
 - ✓ In addition to coordinates, vertices have refs to Vertexes, Edges, Faces.
 - ✓ Begin coding to demonstrate this and introduce Open Inventor.
 - ✓ Read [Open Inventor Mentor](#) for detailed Open Inventor programming.
 - ✓ Ready-to-use mesh processing libraries and software:
 - ✓ CGAL (lib)
 - ✓ OpenMesh (lib)
 - ✓ MeshLab (sw)

3D Graphics Programming

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- ✓ We prefer a high-level object-oriented approach to 3D graphics development.
- ✓ We also prefer a programming API that brings its own 3D viewer (with trackball navigation and everything).
- ✓ Coin3D, an independent implementation of Open Inventor, fits best.
 - ✓ <https://youtu.be/lK7aoc1AO8w>
 - ✓ Inventor Mentor: http://www-evasion.imag.fr/Membres/Francois.Faure/doc/inventorMentor/sgi_html/
- ✓ The Visualization Toolkit (VTK) is a popular alternative.
 - ✓ <https://youtu.be/IgvbhyDh8r0>
 - ✓ Manual: https://www.researchgate.net/profile/William_Schroeder3/publication/200034772_The_Visualization_Toolkit_An_Object-Oriented_Approach_To_3D_Graphics/links/57dfcfa708ae1dcfea865e57/The-Visualization-Toolkit-An-Object-Oriented-Approach-To-3D-Graphics.pdf
- ✓ Other alternatives are
 - ✓ libigl: <http://libigl.github.io/libigl>
 - ✓ OpenMesh: <http://www.openmesh.org>
 - ✓ OpenSceneGraph: <https://youtu.be/1l5PAVCj2iY>

Open Inventor vs. OpenGL

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- ✓ OpenGL is not object-oriented. It is state-based, unintuitive.

```
void render()
{
    //Clear color buffer
    glClear( GL_COLOR_BUFFER_BIT );
    ////////////////////////////////////////////////// object # 1 ///////////////////////////////////
    //Reset modelview matrix STATE
    glMatrixMode( GL_MODELVIEW );
    glLoadIdentity();
    //Move to center of the screen
    glTranslatef( SCREEN_WIDTH / 2.f, SCREEN_HEIGHT / 2.f, 0.f );
    //Set color to cyan and this applies to everything that follows,
    //i.e., state-based, unintuitive, not object-oriented
    glColor3f( 0.f, 1.f, 1.f );
    glBegin( GL_QUADS );
        glVertex2f( -50.f, -50.f );
        glVertex2f( 50.f, -50.f );
        glVertex2f( 50.f, 50.f );
        glVertex2f( -50.f, 50.f );
    glEnd();
}
```

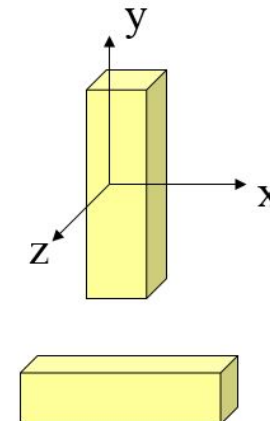
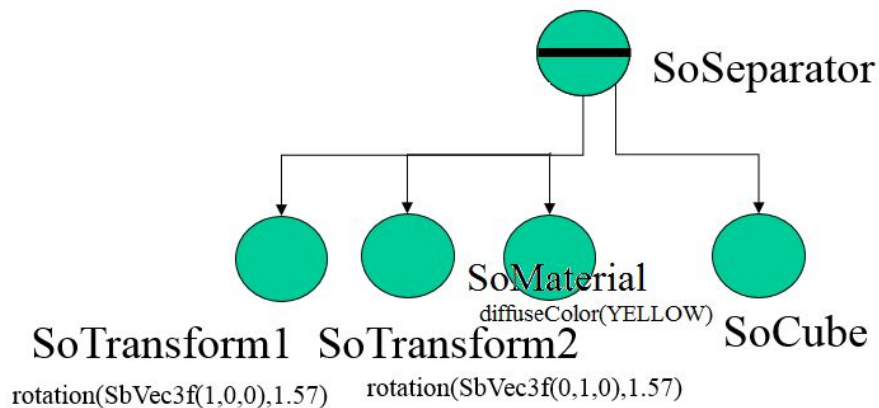
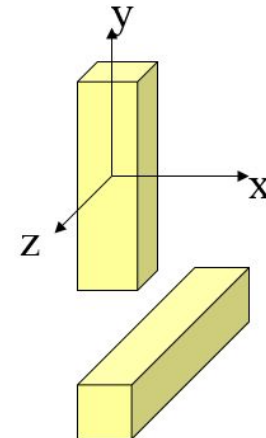
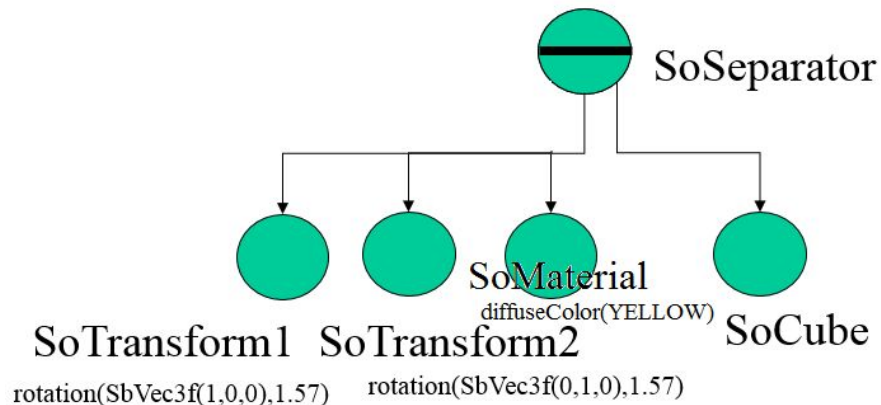
```
//////////////////////////////// object # 2 ///////////////////////////////////
//Reset modelview matrix STATE
glLoadIdentity(); //hope that current matrix mode is glMatrixMode
//to be sure set it explicitly: glMatrixMode
//Move right 1.5 units and into the screen 7.0
glTranslatef(1.5f,0.0f,-7.0f);
//change color STATE to green
glColor3f(0.0f,1.0f,0.0f);
glBegin(GL_QUADS);
    glVertex3f( 1.0f, 1.0f,-1.0f);
    glVertex3f(-1.0f, 1.0f,-1.0f);
    glVertex3f(-1.0f, 1.0f, 1.0f);
    glVertex3f( 1.0f, 1.0f, 1.0f);

    glVertex3f( 1.0f,-1.0f, 1.0f);
    glVertex3f(-1.0f,-1.0f, 1.0f);
    glVertex3f(-1.0f,-1.0f,-1.0f);
    glVertex3f( 1.0f,-1.0f,-1.0f);
glEnd();
//Update screen
glutSwapBuffers();
} //end of render()
```

Open Inventor vs. OpenGL

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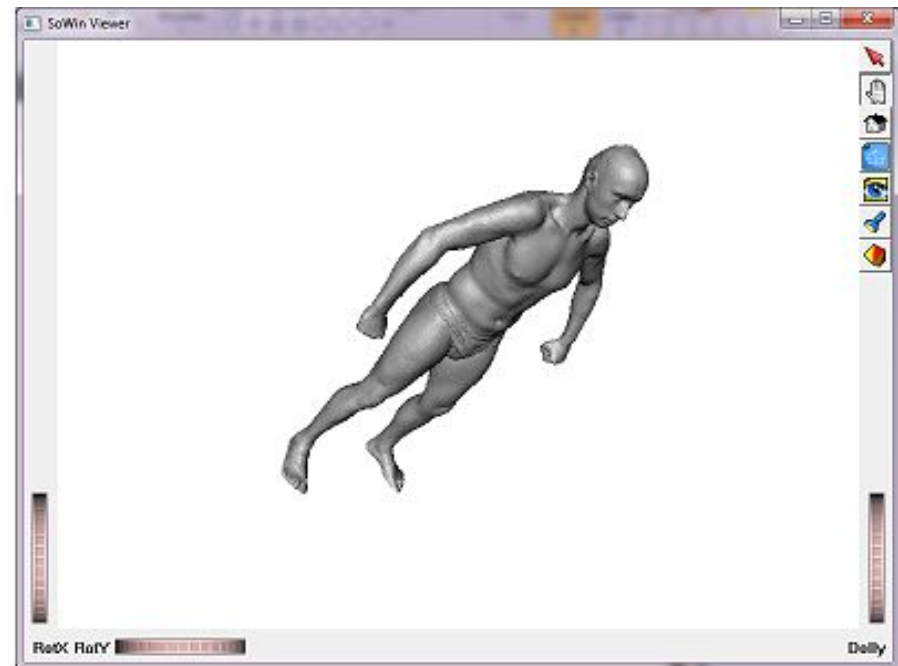
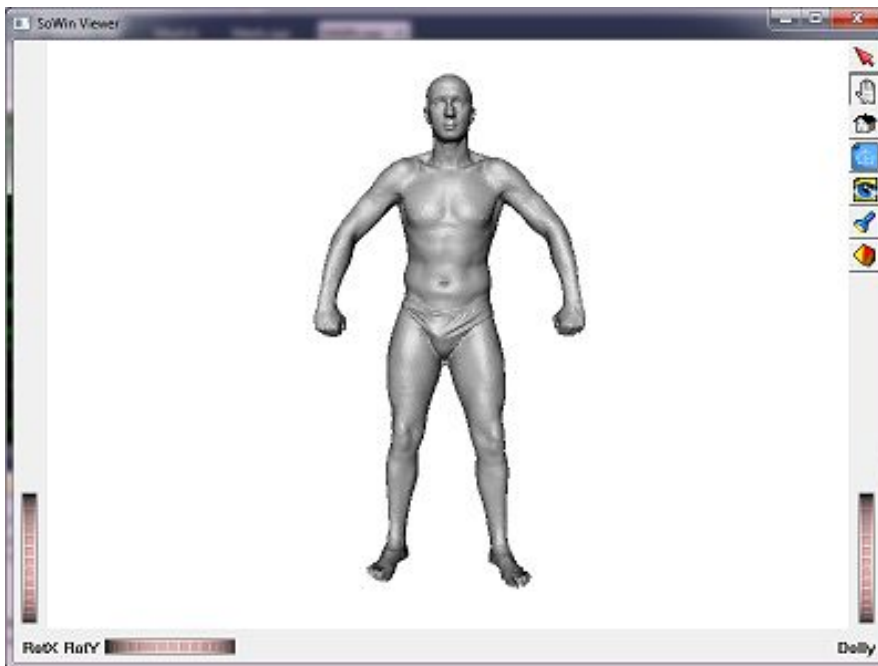
- ✓ Open Inventor is object-oriented. Everything on screen is an object (of type SoSeparator) with its own fields/attributes.



Open Inventor vs. OpenGL

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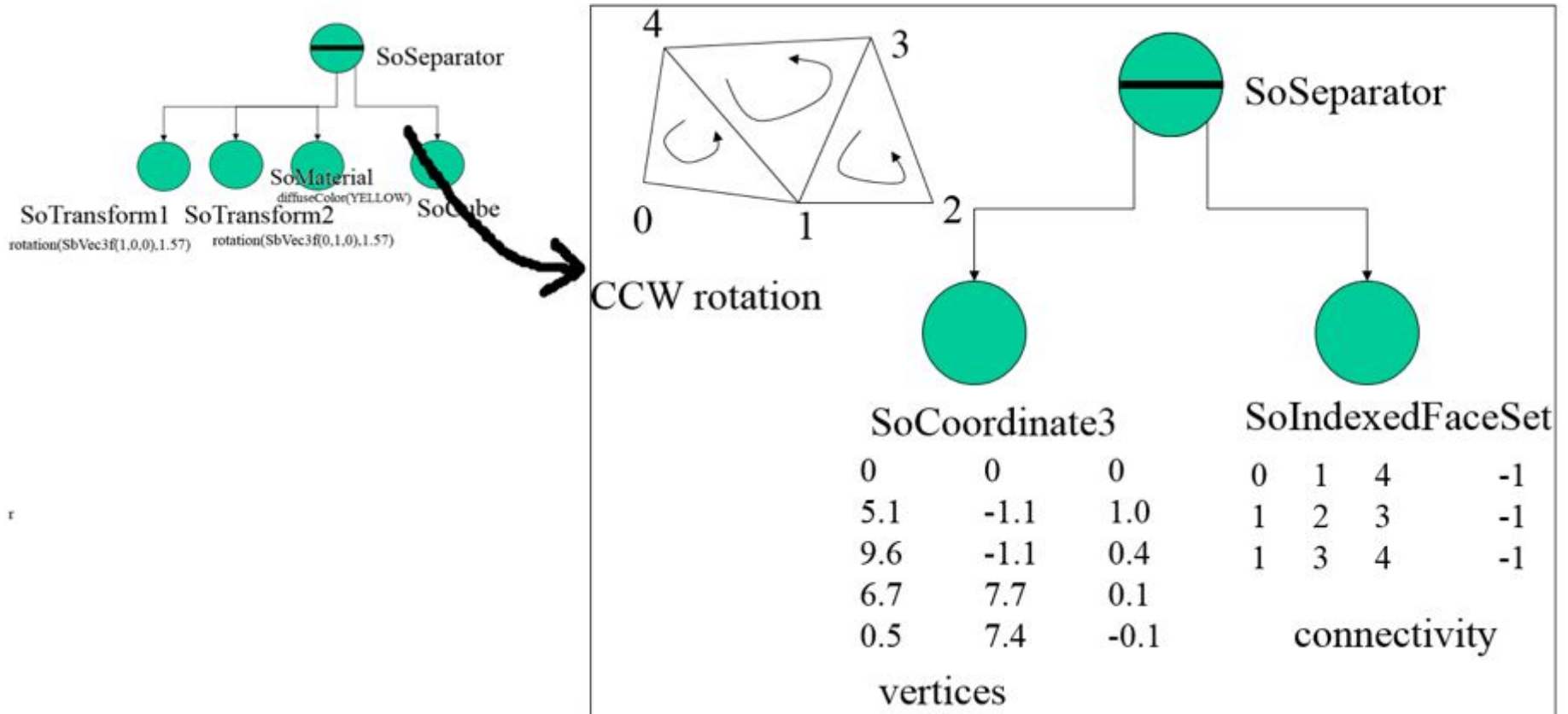
- ✓ OpenGL uses a primitive viewer, glut, where you need to implement your own trackball navigation, camera location/lookups, render modes, etc.
- ✓ Open Inventor uses an advanced viewer (SoWin Windows, SoXt Unix) with built-in trackball navigation, camera handling, render modes, etc.
- ✓ <https://youtu.be/1K7aoc1AO8w>



Open Inventor Programming

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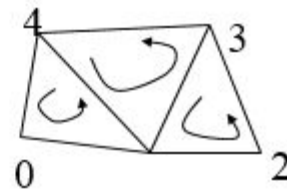
- ✓ Let's change SoCube with a more generic shape, which is a SoSeparator.



Open Inventor Programming

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✓ The code is dead simple:



```
SoSeparator *makeMyObject( ) {  
    float myVerts[5][3] = {{0.0, 0.0, 0.0}, {5.1, -1.1, 1.0}, ...};  
    int myIndex[12] = {0, 1, 4, -1, ...};
```

Get this info from
MyMesh.cpp for a
more structured code!

```
        SoSeparator *myObject = new SoSeparator;  
        SoCoordinate3 *myCoords = new SoCoordinate3;  
        myCoords->point.setValues(0, 5, myVerts);  
        myObject ->addChild(myCoords);  
        SoIndexedFaceSet *faceSet = new SoIndexedFaceSet;  
        faceSet->coordIndex.setValues(0, 12, myIndex);  
        myObject ->addChild(faceSet);  
        return myObject;
```

```
}
```

Open Inventor Programming

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- ✓ The code is dead simple.
 - ✓ You can also set myCoords and faceSet values one-by-one:

```
myCoords->point.set1Value(index, 0, 0, 0, 0);  
myCoords->point.set1Value(index, 1, 5.1, -1.1, 1.0);  
myCoords->point.set1Value(index, 2, 9.6, -1.1, 0.4);  
...  
  
faceSet->coordIndex.set1Value(index, 0, 0);  
faceSet->coordIndex.set1Value(index, 1, 1);  
faceSet->coordIndex.set1Value(index, 2, 4);  
faceSet->coordIndex.set1Value(index, 3, -1);  
...
```


Open Inventor Programming

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✓ Dead simple full code to create and render a cube.

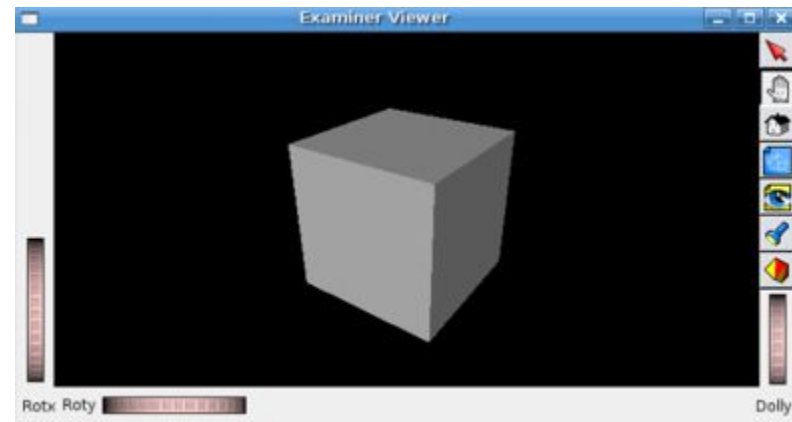
```
#include <Inventor/Qt/SoQt.h>
#include <Inventor/Qt/viewers/SoQtExaminerViewer.h>
#include <Inventor/nodes/SoSeparator.h>
#include <Inventor/nodes/SoCube.h>

int main(int argc, char ** argv)
{
    QWidget * mainwin = SoQt::init(argc, argv, argv[0]);

    SoSeparator * root = new SoSeparator;
    root->ref();
    SoCube *cube = new SoCube;
    root->addChild(cube);

    SoQtExaminerViewer * evviewer = new
    SoQtExaminerViewer(mainwin);
    evviewer->setSceneGraph(root);
    evviewer->show();
    SoQt::show(mainwin);
    SoQt::mainLoop();

    root->unref();
    delete evviewer;
    return 0;
}
```



Potential Project Topics

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- ✓ Implement all schemes in Slide 9 to generate subdivision surfaces.
- ✓ Implement paper: Progressive Meshes (Slide 11).