CENG 789 – Digital Geometry Processing

04- Mesh Data Structure and3D Graphics Programming

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- ✓ Polygon mesh: set of *polygons* embedded in 2D or 3D.
- ✓ Polygon mesh: set of *vertices, edges, and faces* embedded in 2D or 3D.
- ✓ Lets handle these vertices, edges, faces in a structured way, hence the mesh data structure.

✓ How to store geometry & connectivity of a mesh.

3D vertex coordinates

Vertex adjacency

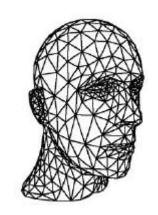
- ✓ Attributes also stored: normal, color, texture coords, labels, etc.
- ✓ Efficient algorithms on meshes to get:
 - ✓ All vertices/edges of a face.
 - ✓ All incident vertices/edges/faces of a vertex.

4 / 25

Mesh Data Structure

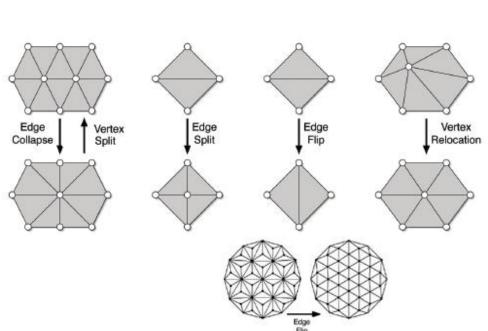
✓ Classical queries:

- ✓ What are the vertices of face 77?
- ✓ Is vertex 7 adjacent to vertex 17?
- ✓ Which edges are incident to vertex 27?
- ✓ Which faces are incident to vertex 27?

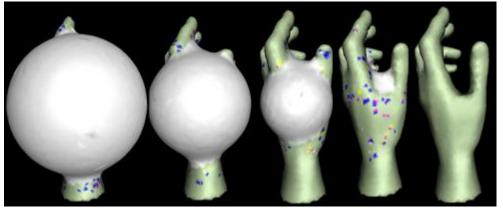


✓ Classical operations:

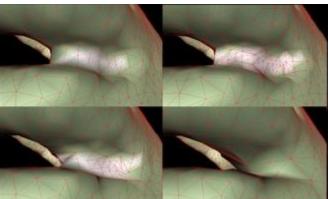
- ✓ Remove/add vertex/face.
- ✓ Split/collapse/flip edges.
- ✓ Change vertex coordinates.
- ✓ Topological vs. geometrical.



- ✓ Applications of edge split:
- ✓ Increase resolution to catch details in 3D reconstruction
 - ✓ Paper: Shape from silhouette using topology-adaptive mesh deformation

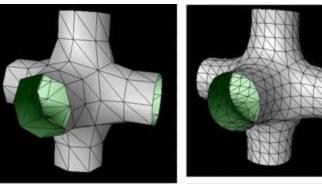


✓ Split short edge if midpoint is OUT:

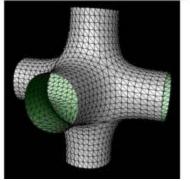


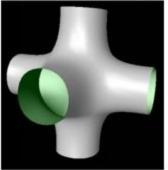
- ✓ Applications of edge split:
- ✓ Increase resolution for smoother surfaces: Subdivision Surfaces
 - ✓ Loop subdivision



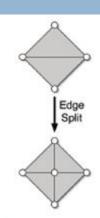


✓ 32 (original) to 1628 vertices in 3 iterations:



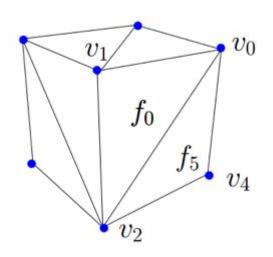


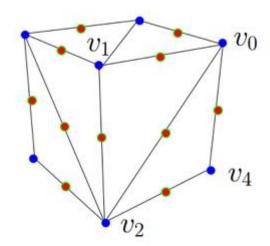
- ✓ Applications of edge split:
- ✓ Increase resolution for smoother surfaces: Subdivision Surfaces
 - ✓ Loop subdivision
 - ✓ Updating the topology (connectivity)

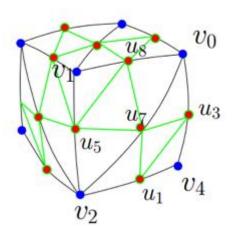


split all edges, by inserting a midpoint

subdivide each face into 4 triangles

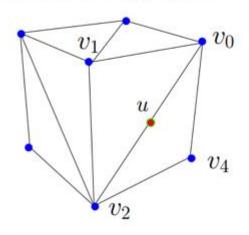






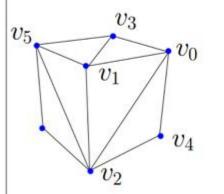
- ✓ Applications of edge split:
- ✓ Increase resolution for smoother surfaces: Subdivision Surfaces
 - √ Loop subdivision
 - ✓ Updating the geometry (coordinates)

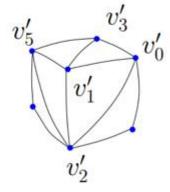
First compute edge points u_k



$$u = \frac{3}{8}v_0 + \frac{3}{8}v_2 + \frac{1}{8}v_1 + \frac{1}{8}v_4$$

Compute new locations v'_i of initial vertices





$$v_i' = (1 - \alpha d)v_i + \alpha \sum_{j=1}^d v_{i_j}$$

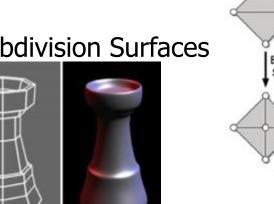
d is the *degree* of vertex v_i v_{i_j} is the j-th neighbor of v_i

$$\alpha = \frac{3}{16}$$
, if $d = 3$

$$\alpha = \frac{3}{8d}$$
, if $d > 3$

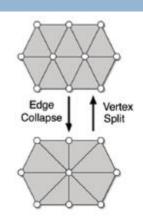
- ✓ Applications of edge split:
- ✓ Increase resolution for smoother surfaces: Subdivision Surfaces
 - ✓ Loop subdivision (best for triangle meshes)
 - ✓ Catmull-Clark subdivision (quad meshes)
 - ✓ Butterfly subdivision
 - ✓ Doo-Sabin subdivision
 - \checkmark $\sqrt{3}$ -subdivision
- ✓ More on this in the Subdivison lecture later in semester.

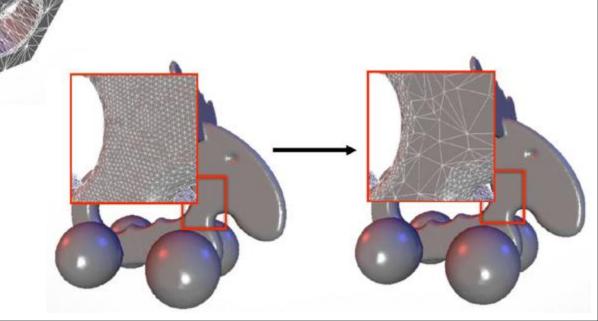




10 / 25

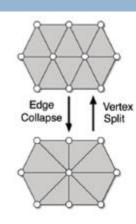
- ✓ Applications of edge collapse:
- ✓ Decrease resolution for efficiency
 - ✓ Detail-preserving

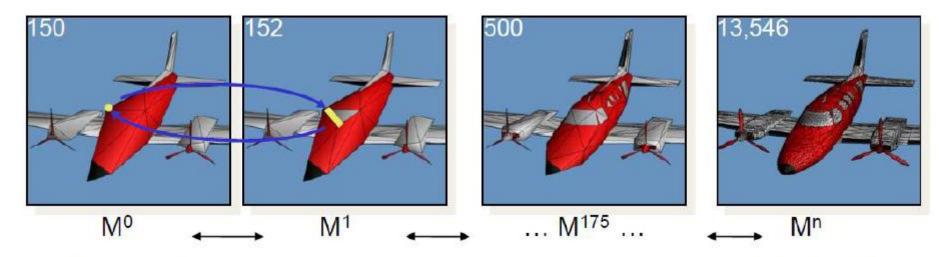




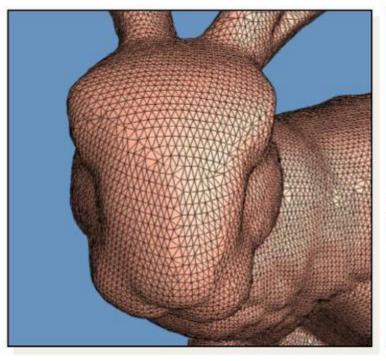
11 / 25

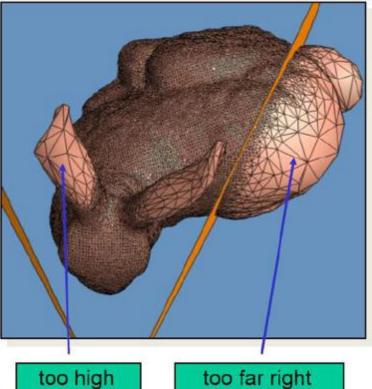
- ✓ Applications of edge collapse:
- ✓ Decrease resolution for efficiency
 - ✓ Detail-oblivious (level-of-detail)





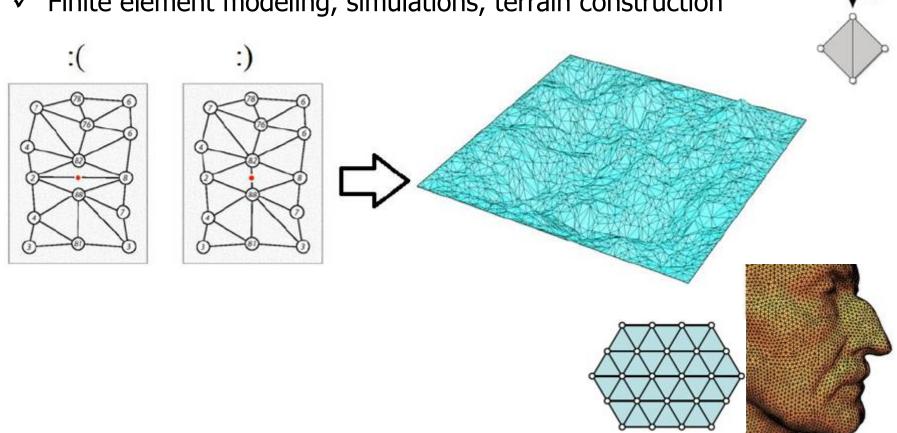
- ✓ Applications of edge collapse:
- ✓ Decrease resolution for efficiency
 - ✓ Detail-oblivious (view-dependent rendering)







- ✓ Applications of edge flip:
- ✓ Better triangulations, e.g., w/ less skinny triangles
- ✓ Finite element modeling, simulations, terrain construction



Face-Based Data Structures

- ✓ One way to implement a mesh data structure is through faces.
- ✓ Face-Set data structure. //aka polygon soup 'cos no connectivity info.

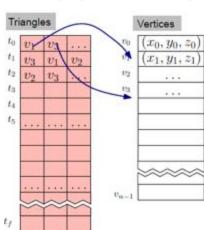
Triangles								
X ₁₁	У11	Z ₁₁	X ₁₂	У12	Z ₁₂	X13	У 13	Z ₁₃
X21	Y 21	Z ₂₁	X22	У22	Z ₂₂	X23	У 23	Z ₂₃
	• • •						•••	
XF1	УF1	Z _{F1}	XF2	y _{F2}	Z _{F2}	X _{F3}	Угз	Z _{F3}

//vertices and associated data are replicated.

✓ Indexed face-set data structure (obj, off, ply formats). *Better!!!!*

Vertices					
x_1 y_1 z_1					
x _v y _v z _v					

Triangles					
i ₁₁ i ₁₂ i ₁₃					
• • •					
•••					
• • •					
i _{F1} i _{F2} i _{F3}					



Face-Based Data Structures

- ✓ My base code implements Indexed face-set data structure
- ✓ See http://www.ceng.metu.edu.tr/~ys/ceng789-dgp/MyDemo.zip

```
struct Triangle
    int idx; //tris[idx] is this triangle
    int v1i, v2i, v3i; //triangle formed by verts[v1i]-verts[v2i]-verts[v3i]
    float area, * normal; //direction
    Triangle(int i, int a, int b, int c) : idx(i), v1i(a), v2i(b), v3i(c) {};
};
Istruct Vertex
    int idx; //verts[idx]
    float* coords, //coords[0] ~ x coord, ...
         * normal; //direction
    vector< int > triList;
    vector< int > edgeList;
    vector< int > vertList;
    Vertex(int i, float* c) : idx(i), coords(c) {};
};
struct Edge
    int idx; //edges[idx]
    int v1i, v2i;
    float length;
    Edge(int i, int a, int b, float 1) : idx(i), v1i(a), v2i(b), length(l) {};
};
```

```
class Mesh
{
public:
    vector< Triangle* > tris;
    vector< Vertex* > verts;
    vector< Edge* > edges;

    void loadOff(char* fName);
    void createCube(float sl);
private:
    void addVertex(float* c);
    void addTriangle(int v1i, int v2i, int v3i);
    void addEdge(int v1i, int v2i);
    bool makeVertsNeighbors(int v, int w);
};
```

Edge-Based Data Structures

- ✓ Another way to implement a mesh data structure is through edges.
- ✓ For explicit storage of edges.
 - ✓ Enables efficient one-ring enumeration.



- ✓ Can be done with slight modifications to Indexed face-set.
 - ✓ Define an Edge struct.
 - ✓ In addition to coordinates, vertices have refs to Vertexes, Edges, Faces.
 - ✓ Begin coding to demonstrate this and introduce Open Inventor.
 - ✓ Read Open Inventor Mentor for detailed Open Inventor programming.
- ✓ Ready-to-use mesh processing libraries and software:
 - ✓ CGAL (lib)
 - ✓ OpenMesh (lib)
 - ✓ MeshLab (sw)

3D Graphics Programming

- ✓ We prefer a high-level object-oriented approach to 3D graphics development.
- ✓ We also prefer a programming API that brings its own 3D viewer (with trackball navigation and everything).
- ✓ Coin3D, an independent implementation of Open Inventor, fits best.
 - √ https://youtu.be/lK7aoc1AO8w
 - ✓ Inventor Mentor: http://www-evasion.imag.fr/Membres/Francois.Faure/doc/inventorMentor/sgi_html/
- ✓ The Visualization Toolkit (VTK) is a popular alternative.
 - √ https://youtu.be/IgvbhyDh8r0
 - Manual: https://www.researchgate.net/profile/William_Schroeder3/publication/200034772 The Visualization Toolkit An Object-Oriented Approach To 3D Graphics/Inks/57dfcfa708ae1dcfea865e57/The-Visualization-Toolkit-An-Object-Oriented-Approach-To-3D-Graphics.pdf
- ✓ Other alternatives are
 - ✓ libigl: http://libigl.github.io/libigl
 - ✓ OpenMesh: http://www.openmesh.org
 - ✓ OpenSceneGraph: https://youtu.be/1|5PAVCj2iY

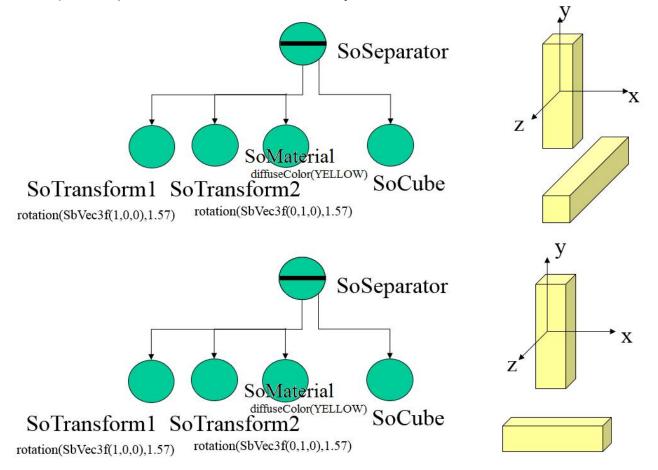
Open Inventor vs. OpenGL

✓ OpenGL is not object-oriented. It is state-based, unintuitive.

```
void render()
                                                                      //Reset modelview matrix STATE
                                                                      glLoadIdentity(); //hope that current matrix mode is glMatrixM
   //Clear color buffer
                                                                                     //to be sure set it explicitly: glMatrixMode
   glClear ( GL COLOR BUFFER BIT );
                                                                     //Move right 1.5 units and into the screen 7.0
   glTranslatef(1.5f,0.0f,-7.0f);
   //Reset modelview matrix STATE
                                                                     //change color STATE to green
   glMatrixMode ( GL MODELVIEW );
                                                                     glColor3f(0.0f,1.0f,0.0f);
   glLoadIdentity();
                                                                     glBegin (GL QUADS);
                                                                         glVertex3f( 1.0f, 1.0f, -1.0f);
   //Move to center of the screen
                                                                         glVertex3f(-1.0f, 1.0f,-1.0f);
   glTranslatef( SCREEN WIDTH / 2.f, SCREEN HEIGHT / 2.f, 0.f )
                                                                         glVertex3f(-1.0f, 1.0f, 1.0f);
   //Set color to cyan and this applies to everything that follows,
                                                                         glVertex3f( 1.0f, 1.0f, 1.0f);
   //i.e., state-based, unintuitive, not object-oriented
   glColor3f( 0.f, 1.f, 1.f);
                                                                         glVertex3f( 1.0f,-1.0f, 1.0f);
   glBegin ( GL QUADS );
                                                                         glVertex3f(-1.0f,-1.0f, 1.0f);
       glVertex2f( -50.f, -50.f);
                                                                         glVertex3f(-1.0f,-1.0f,-1.0f);
       glVertex2f( 50.f, -50.f);
                                                                         glVertex3f( 1.0f,-1.0f,-1.0f);
       glVertex2f( 50.f, 50.f);
                                                                     glEnd();
       glVertex2f( -50.f, 50.f);
                                                                     //Update screen
   glEnd();
                                                                     glutSwapBuffers();
                                                                  } //end of render()
```

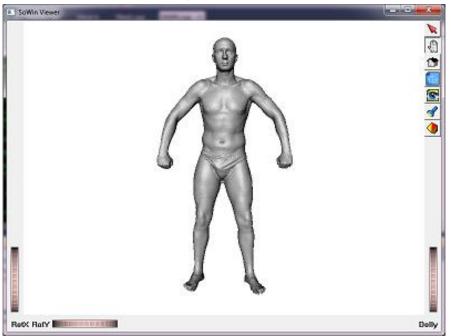
Open Inventor vs. OpenGL

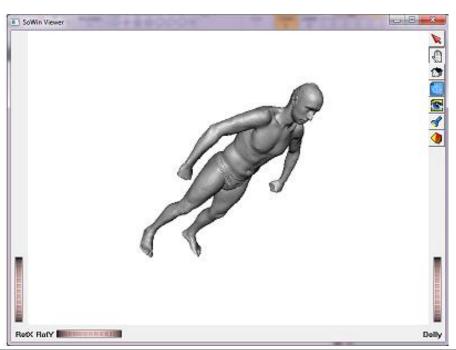
✓ Open Inventor is object-oriented. Everything on screen is an object (of type SoSeparator) with its own fields/attributes.



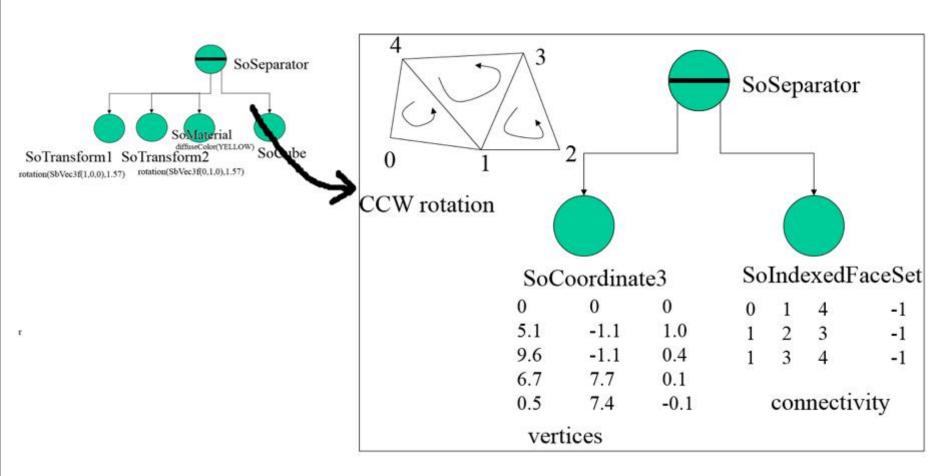
Open Inventor vs. OpenGL

- ✓ OpenGL uses a primitive viewer, glut, where you need to implement your own trackball navigation, camera location/lookups, render modes, etc.
- ✓ Open Inventor uses an advanced viewer (SoWin Windows, SoXt Unix) with built-in trackball navigation, camera handling, render modes, etc.
 - √ https://youtu.be/lK7aoc1AO8w





✓ Let's change SoCube with a more generic shape, which is a SoSeparator.



✓ The code is dead simple:

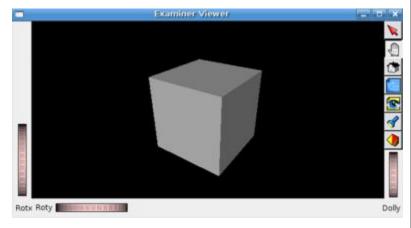
```
SoSeparator *makeMyObject() {
Get this info from
                         float myVerts[5][3] = \{\{0.0, 0.0, 0.0\}, \{5.1, -1.1, 1.0\}, ...\};
MyMesh.cpp for a
                         int myIndex[12] = \{0, 1, 4, -1, ...\};
more structured code!
                         SoSeparator *myObject = new SoSeparator;
                         SoCoordinate3 *myCoords = new SoCoordinate3;
                         myCoords->point.setValues(0, 5, myVerts);
                         myObject ->addChild(myCoords);
                         SoIndexedFaceSet *faceSet = new SoIndexedFaceSet;
                         faceSet->coordIndex.setValues(0, 12, myIndex);
                          myObject ->addChild(faceSet);
                         return myObject;
```

- ✓ The code is dead simple.
 - ✓ You can also set myCoords and faceSet values one-by-one:

```
index
myCoords->point.set1Value(0,0,0,0);
myCoords->point.set1Value(1,5.1,-1.1,1.0);
myCoords->point.set1Value(2, 9.6,-1.1,0.4);
                                   index
faceSet->coordIndex.set1Value(0,0);
faceSet->coordIndex.set1Value(1,1);
faceSet->coordIndex.set1Value(2,4);
faceSet->coordIndex.set1Value(3,-1);
```

✓ Dead simple full code to create and render a cube.

```
#include <Inventor/Qt/SoQt.h>
#include <Inventor/Qt/viewers/SoQtExaminerViewer.h>
#include <Inventor/nodes/SoSeparator.h>
#include <Inventor/nodes/SoCube.h>
int main(int argc, char ** argv)
  QWidget * mainwin = SoQt::init(argc, argv, argv[0]);
  SoSeparator * root = new SoSeparator;
  root->ref();
  SoCube *cube = new SoCube;
  root->addChild(cube);
  SoQtExaminerViewer * eviewer = new
SoQtExaminerViewer (mainwin);
  eviewer->setSceneGraph(root);
  eviewer->show();
  SoOt::show(mainwin);
  SoQt::mainLoop();
  root->unref();
  delete eviewer;
  return 0;
```



Potential Project Topics

25 / 25

- ✓ Implement all schemes in Slide 9 to generate subdivision surfaces.
- ✓ Implement paper: Progressive Meshes (Slide 11).