# ME 536 - Design of Intelligent Machines

## Term Project - Defect Finder Camera

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Github:

https://github.com/amnessa/MECH536/tree/e4cba326a3cc35476c5539c02b752f3d 851cce0e/me\_term\_project

### Introduction & Problem Statement

- In a production line a camera system detect surface defects
- Technician reports a new defect



How It Meets Project Requirements

- Principal Component Analysis -PCA
- Clustering (K- means)
- A bit of Image Processing -(histogram equalization and resizing)
- Artificial Neural Networks ANN (VGG16 fc1 layer)

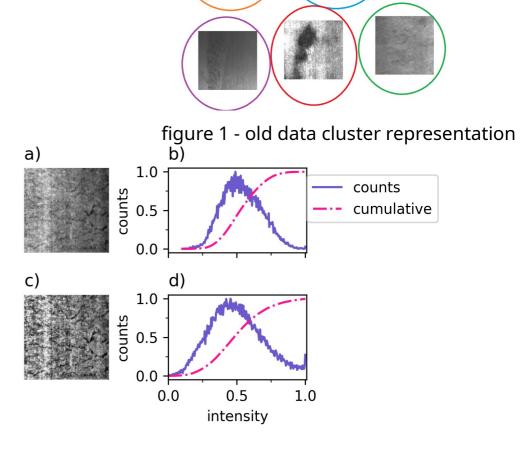
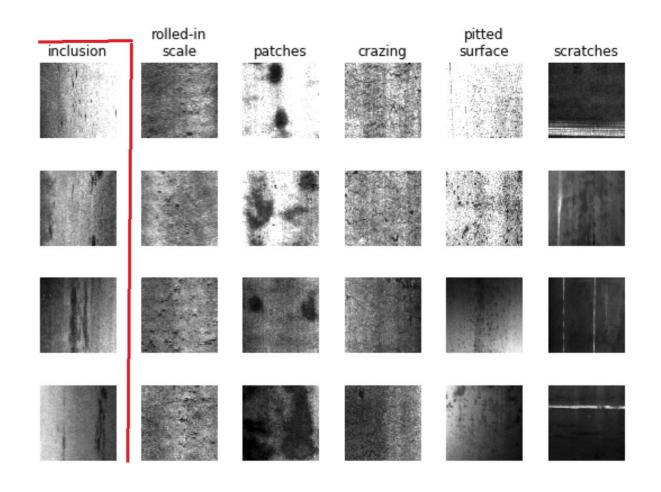


figure 2 - Histogram Equalization to spread intensities and enhance contrast

#### Data & Generation

- North East University
   Dataset for Defect Detection
  - NEU Dataset
- Histogram Equalization
- Resize
- Store



### Methods & Network Structure

- VGG16 pretrained on ImageNet
- Filter out features
- PCA 4096 -> 50 (SVD = Full)
- "Whitening in PCA so each principal component has unit variance, preventing large components from dominating."
- Result: 5 clusters

figure 3 - code part for feature extraction

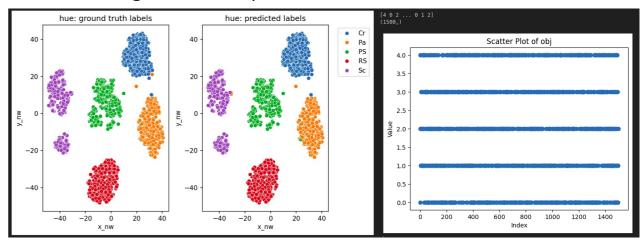


figure 4 - t-SNE and scatter plot images for cluster confirmation

## Novelty Detection Approach

- New Batch of 40 image
- Same preprocess (ANN fc1-PCA - Kmeans)
- Old cluster centers , New cluster centers
- Automatically detect the novel and cluster it

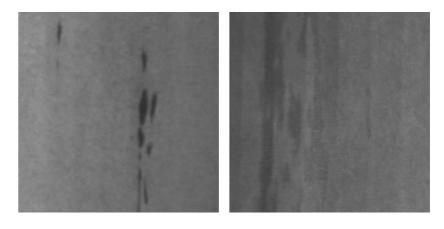


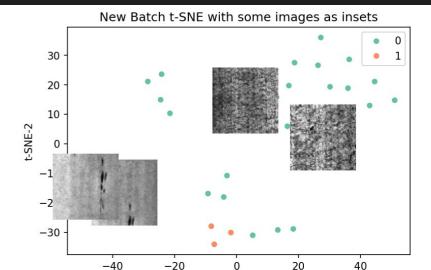
figure 5 - example new data mixed with old both are member of the same defect class in real life

### Results & Demo

```
# MAIN USAGE
    # (1) Load base data (fc1 => shape(N,4096))
    from pathlib import Path
    import pickle
10 fcl path = Path('..', 'data', 'features', 'VGG16 fcl features std.pickle')
11 with open(fc1 path, 'rb') as f:
       base data = pickle.load(f)
13 fc1 = base data['features'] # (N,4096)
16 # (2) Build PCA(4096->50) + KMeans(6) on the old data
    pca, kmeans 50d = build base pca kmeans(fc1, n components=50, k=6)
20 system = NoveltyDetectionSystem(pca, kmeans 50d)
22 # (4) Load a new batch of images (40)
23 batch dir = Path("NEU mixed batch 40")
24 batch images = sorted(batch dir.glob("*.bmp"))
   if not batch images:
       print(f"[WARNING] No images in {batch dir}!")
       print(f"Found {len(batch images)} images in new batch.")
       # Extract their fcl
       new feats 4096 = system.extract fcl batch(batch images)
       # (5) Find 2 new cluster centers from the new batch (in 50D),
             compare to old 6 centers
       system.cluster new batch 2(new feats 4096)
       # (Optional) visualize in t-SNE 2D
       system.visualize new2 tsne(new feats 4096)
```

figure 6 - calling system from main

New cluster 0: dist to old center#0 => 3.53 => Crazing New cluster 1: dist to old center#0 => 7.16 => new class



t-SNE-1

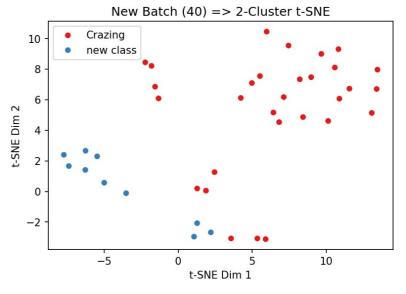


figure 7 results from testing

## Possible Improvements

- Dynamic tresholding
- Dynamic Clustering
- Synthetic generation from dataset
- Sub analysis on clustered new data
- Alternative to Kmeans

## **Ending & Questions**

Thank you for listening!



#### References

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#### **EXTRAS**

