Targeted learning with right-censored data using the state learner

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Targeted or debiased machine learning*

Low-dimensional target parameter

$$\Psi \colon \mathcal{P} o \mathbb{R}, \quad \text{such that} \quad \Psi(P) = \tilde{\Psi}(
u_1(P), \dots,
u_B(P)),$$

for high-dimensional nuisance parameters ν_1,\ldots,ν_B .

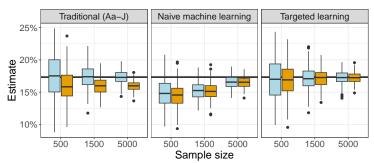
^{*[}van der Laan and Rose, 2011, Chernozhukov et al., 2018]

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Adapted from Figure 4 in [Munch et al., 2023].

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Examples of estimands

Available data
$$O=(X,\tilde{T},\tilde{D})\sim P\in\mathcal{P}$$
, where
$$X=W\in\mathbb{R}^d \text{ or } X=(W,A)\in\mathbb{R}^d\times\{0,1\},$$
 $\tilde{T}=T\wedge C$ $\tilde{D}=\mathbb{1}\{T\leq C\}D,\quad D=1 \text{ or } D\in\{1,2\}.$

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$$Q(T > t) \stackrel{(!)}{=} \mathbb{E}_P[e^{-\Lambda_P(t|X)}], \quad (T, X) \sim Q,$$

where

$$\Lambda_P(\mathrm{d}t\mid x)=P(\tilde{T}\in\mathrm{d}t,\tilde{D}=1\mid \tilde{T}\geq t,X=x).$$

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Use
$$\{(T^a,D^a):a\in\{0,1\}\}\sim Q$$
, to denote potential outcomes.

$$Q(T^a \leq t, D^a = 1) \stackrel{(!)}{=} \mathbb{E}_P \left[\int_0^t e^{-[\Lambda_{1,P} + \Lambda_{2,P}](u|a,W)} \Lambda_{1,P}(\mathrm{d}u \mid a, W) \right],$$

$$\Lambda_{d,P}(\mathrm{d}t\mid a,w)=P(\tilde{T}\in\mathrm{d}t,\tilde{D}=d\mid \tilde{T}\geq t,A=a,W=w).$$

For (!) to hold we need both $C \perp T \mid X$ and causal assumptions.

Targeted learning with super learning

$$\Psi(P) = \mathbb{E}_P \left[\int_0^t e^{-[\Lambda_{1,P} + \Lambda_{2,P}](u|a,W)} \Lambda_{1,P}(\mathrm{d}u \mid a,W) \right]$$

can be written as

$$\Psi(P) = \tilde{\Psi}(\Lambda_{1,P}, \Lambda_{2,P}, P_W).$$

$$\tilde{\Psi}(\hat{\Lambda}_{1,n},\hat{\Lambda}_{2,n},\mathbb{P}_n) \quad + \quad \frac{\mathsf{Targeting/debiasing step}}{\mathsf{using } \hat{\Gamma}_n \mathsf{ and } \hat{\pi}_n} \longrightarrow \quad \hat{\Psi}_n^*$$

Asymptotic valid inference and $\mathit{O}_{P}(n^{-1/2})$ convergence for $\hat{\Psi}_{n}^{*}$ if

$$\|\hat{\nu}_n - \nu\|_{P,2} = o_P(n^{-1/4}), \quad \text{for all } \hat{\nu}_n \in \{\hat{\Lambda}_{1,n}, \hat{\Lambda}_{2,n}, \hat{\Gamma}_n, \hat{\pi}_n\}.$$

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Attempt to achieve this using a super learner.

Super learning[†]

$$\mathcal{D}_n = \boxed{O_1|O_2|} \cdots$$

Learner
$$\mathcal{D}_n \longmapsto a(\mathcal{D}_n) = \hat{\nu}_n$$

Library $\mathcal{A} = \{a_1, a_2, \dots, a_M\}$
Loss function $\mathcal{V} \times \mathcal{O} \ni (\nu, O) \longmapsto L(\nu, O) \in \mathbb{R}$

Discrete
$$SL = \hat{a}_n = \underset{a \in \mathcal{A}}{\operatorname{argmin}} \frac{1}{K} \sum_{k=1}^K \frac{1}{|\mathcal{D}_n^k|} \sum_{Q \in \mathcal{D}_n^k} L(a(\mathcal{D}_n^{-k}), Q_i),$$

[†]Stone [1974], Geisser [1975], Wolpert [1992], Breiman [1996], van der Laan et al. [2007]

Super learning[†]

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Super learning[†]

$$\mathcal{D}_n^{-2} = \boxed{O_1 |O_2|}$$

$$\mathcal{D}_n^2 = \boxed{ }$$

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$$\mathcal{D}_n \longmapsto a(\mathcal{D}_n) = \hat{\nu}_n$$

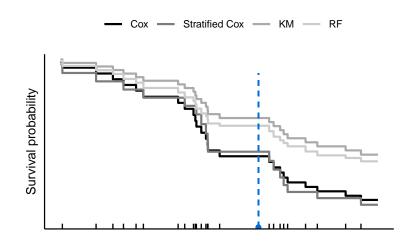
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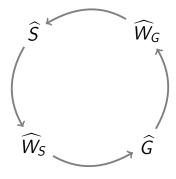
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Evaluating performance in hold-out folds is a challenge with right-censored data

The negative log-likelihood is unsuited for super learning

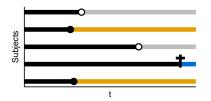


IPCW and pseudo-outcome require pre-specified censoring estimator



The state learner: Model all 'states' of the observed data

$$\textit{N(t)} = \mathbb{1}\{\tilde{\textit{T}} \leq t, \tilde{\textit{D}} = 1\} + 2\,\mathbb{1}\{\tilde{\textit{T}} \leq t, \tilde{\textit{D}} = 2\} - \mathbb{1}\{\tilde{\textit{T}} \leq t, \tilde{\textit{D}} = 0\}$$



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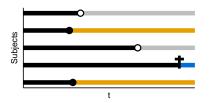


Build a super learner for the function

$$F(t, k, w, a) = P(N(t) = k \mid W = w, A = a).$$

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Build a super learner for the function

$$F(t, k, w, a) = P(N(t) = k \mid W = w, A = a).$$

$$L(F,O) = \int_0^{\tau} \sum_{i=1}^{2} \left(F(t,j,W,A) - \mathbb{1}\{N(t) = j\} \right)^2 dt.$$

Building a library for F

The formulas

$$egin{aligned} F(t,0,w,a) &= \int_0^t \left(1 - \left[\Lambda_1 + \Lambda_2 + \Gamma\right] \left(\mathrm{d} s \mid w,a\right)
ight), \ F(t,j,w,a) &= \int_0^t F(t-,0,w,a) \Lambda_j (\mathrm{d} s \mid w,a), \quad j \in \{1,2\}, \ F(t,-1,w,a) &= \int_0^t F(t-,0,w,a) \Gamma(\mathrm{d} s \mid w,a), \end{aligned}$$

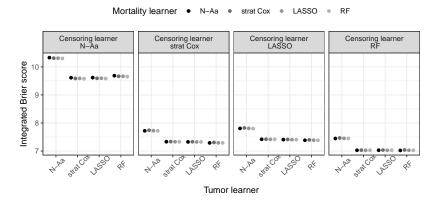
can be used to build a library for F from libraries for Λ_1 , Λ_2 , Γ ,

$$\mathcal{F}(\mathcal{A},\mathcal{B},\mathcal{C}) = \{F_{a,b,c} : a \in \mathcal{A}, b \in \mathcal{B}, c \in \mathcal{C}\}.$$

Similarly, we can obtain Λ_j and Γ from F.

Illustration with data from a prostate cancer study[‡]

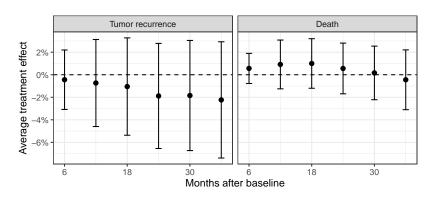
The learners selected by the state learner.



[‡]Kattan et al. [2000].

Illustration with data from a prostate cancer study[‡]

The estimated average treatment effect of hormone therapy.



[‡]Kattan et al. [2000].

Additional details

Munch and Gerds [2024] provide

- o a consistency result
- o a finite sample oracle inequality
- details for the targeting step

Prototype available at https://github.com/amnudn/statelearner.

Thank you for the attention!

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