

Validating survival models

Young Researcher Day

Anders Munch

November 25, 2021

Risk prediction model and full data

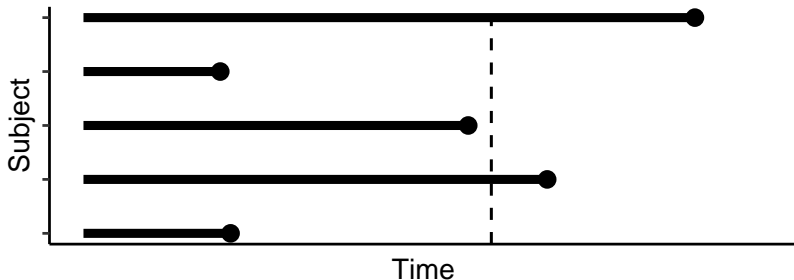
For a fixed time horizon $t \in \mathbb{R}_+$ we have

$X \in \mathbb{R}^p$ Static covariates measured at baseline ($t = 0$)

$T \in \mathbb{R}_+$ Time of event

$r(t | X) \in [0, 1]$ Risk prediction at time t given baseline covariates

$Y(t) \in \{0, 1\}$ Event status at time t , $Y(t) := \mathbb{1}\{T \leq t\}$



Risk prediction model and censored data

For a fixed time horizon $t \in \mathbb{R}_+$ we have

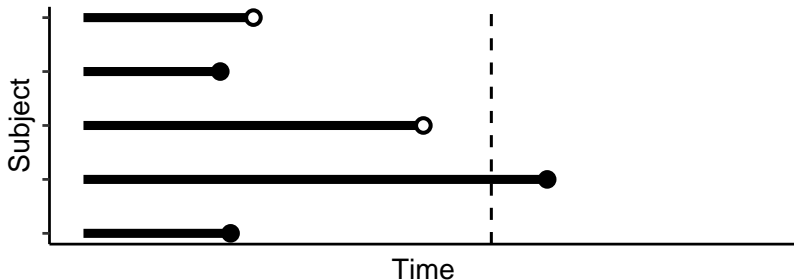
$X \in \mathbb{R}^p$ Static covariates measured at baseline ($t = 0$)

$\tilde{T} \in \mathbb{R}_+$ Observation time ($\tilde{T} := T \wedge C$)

$\Delta \in \{0, 1\}$ Event indicator ($\Delta := \mathbb{1}\{\tilde{T} = T\}$)

$r(t | X) \in [0, 1]$ Risk prediction at time t given baseline covariates

$Y(t) \in \{0, 1\}$ Is unobserved for som subjects



The Brier score

Given a (non-random) risk-prediction model $r: \mathbb{R}_+ \times \mathbb{R}^p \rightarrow [0, 1]$ we want to evaluate the performance of r at a fixed time horizon $t \in \mathbb{R}_+$. For this we use the Brier score

$$\mathbb{E} \left[\{Y(t) - r(t | X)\}^2 \right], \quad \text{with} \quad Y(t) := \mathbb{1}\{T \leq t\}.$$

Inverse probability of censoring weights (IPCW)

Let $(X, T) \sim Q$ and $(X, \tilde{T}, \Delta) \sim P$. When $T \perp\!\!\!\perp C | X$ the Brier score is identifiable from the observed data¹:

$$\mathbb{E}_Q \left[\{Y(t) - r(t | X)\}^2 \right] = \mathbb{E}_P \left[W(t) \{Y(t) - r(t | X)\}^2 \right],$$

with

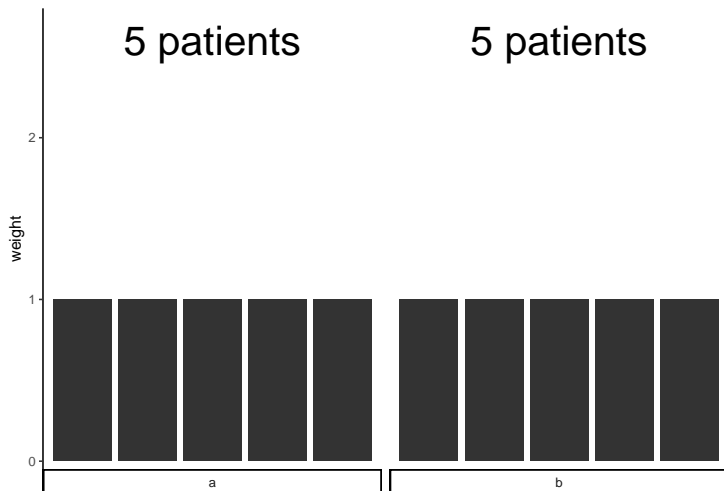
$$W(t) = \frac{\mathbb{1}(\tilde{T} > t)}{G(t | X)} + \frac{\mathbb{1}(\tilde{T} \leq t)\Delta}{G(\tilde{T} | X)},$$

and where $G(s | x) = P(C > s | X = x)$.

¹Note that $W(t)\{Y(t) - r(t | X)\}^2$ is a function of the observed data, as $Y(t)$ is observed whenever $W(t)$ is non-zero.

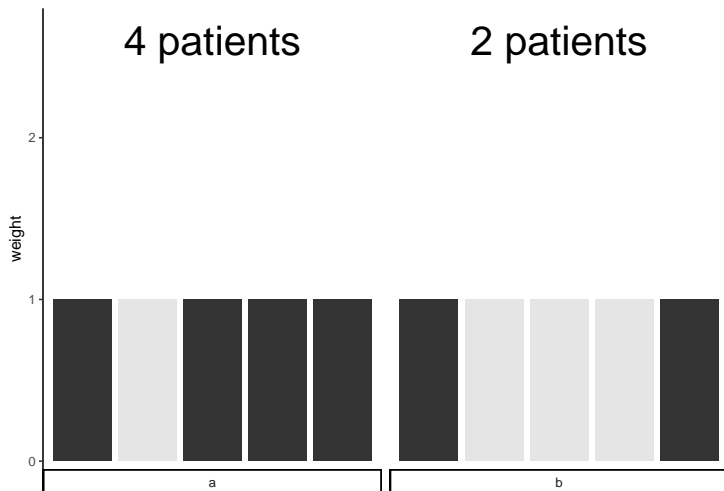
Visualizing the re-weighting

$$\mathbb{E}_Q \left[\{Y(t) - r(t | X)\}^2 \right] = \mathbb{E}_P \left[W(t) \{Y(t) - r(t | X)\}^2 \right]$$



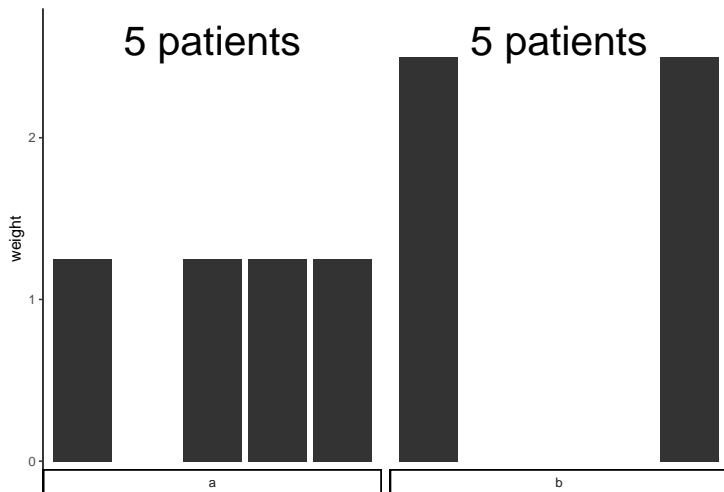
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Non-parametric estimation

By estimating the censoring distribution G we obtain the IPCW estimator

$$\widehat{W}_i(t) = \frac{\mathbb{1}(\tilde{T}_i > t)}{\widehat{G}(t | X_i)} + \frac{\mathbb{1}(\tilde{T}_i \leq t)\Delta_i}{\widehat{G}(\tilde{T}_i | X_i)}, \quad \hat{\theta}_n^t = \hat{\mathbb{P}}_n[\widehat{W}_i(t) \{Y_i(t) - r(t | X_i)\}^2]$$

Inference and efficiency under non-parametric assumptions

- Existing methods use Kaplan-Meier or Cox models to estimate the censoring distribution.
- Non-parametric, data-adaptive estimation of the censoring distribution + inference \rightarrow one-step estimators / DML / TMLE.

Data-adaptive selection of the estimator \widehat{G}

Use some kind of cross-validation to select the best \widehat{G} from a collection of candidates.

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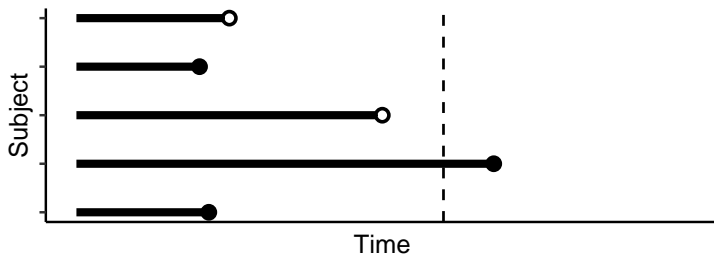
Use some kind of cross-validation to select the best \widehat{G} from a collection of candidates. **Is it obvious how to do this?**

Cross validation for survival models – the Brier score?

Brier score!

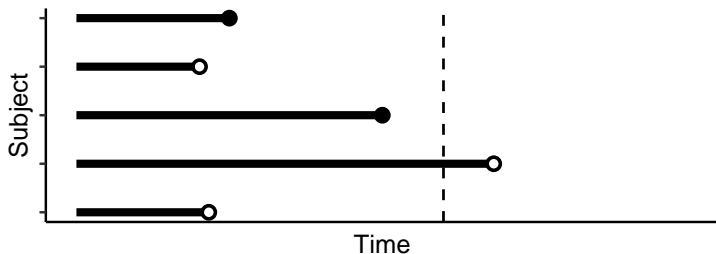
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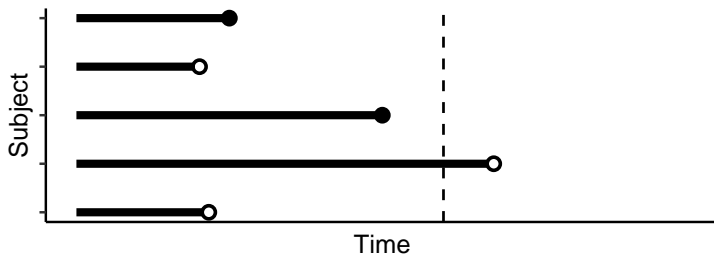
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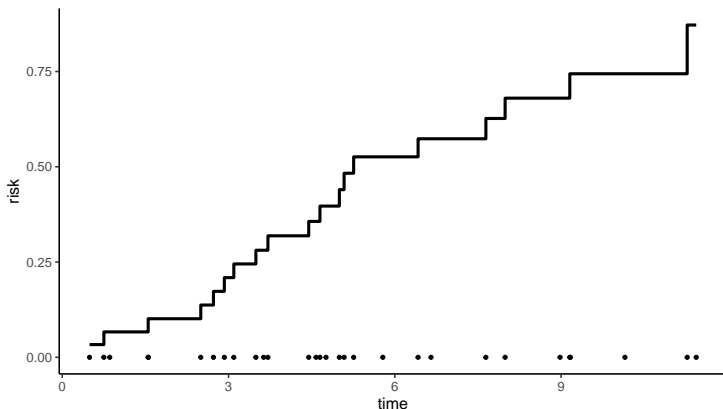
Cross validation for survival models – the Brier score?

Brier score! ... infinite regress ...



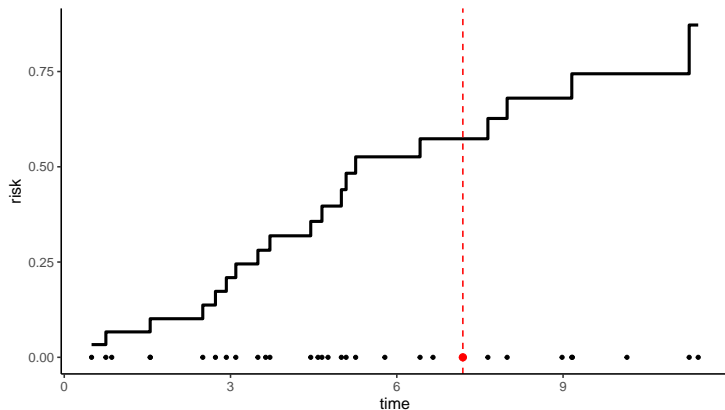
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Many common estimators of a survival function will be a discrete measure \rightarrow the likelihood will (a.s.) be 0 on any hold-out data sample.



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Summary

How should we do cross validation for general survival models when the test and train data are censored?

- Which other loss functions are sensible to use instead?
- How can these (and the risk of an estimator) be approximated with observed data?

Questions, comments, suggestions?

Thank you for listening!