

INDUSTRIAL TRAINING

ARDUINO & IT'S INTERFACING WITH INTERNET OF THINGS - IOT



Presented by

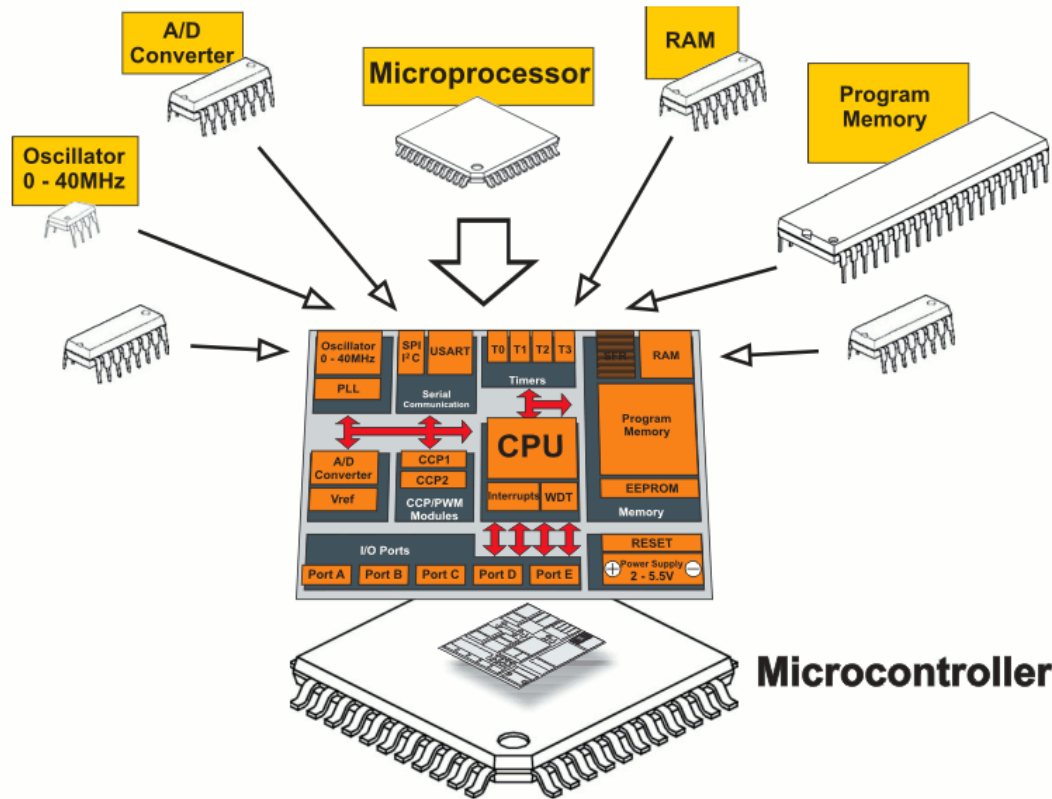
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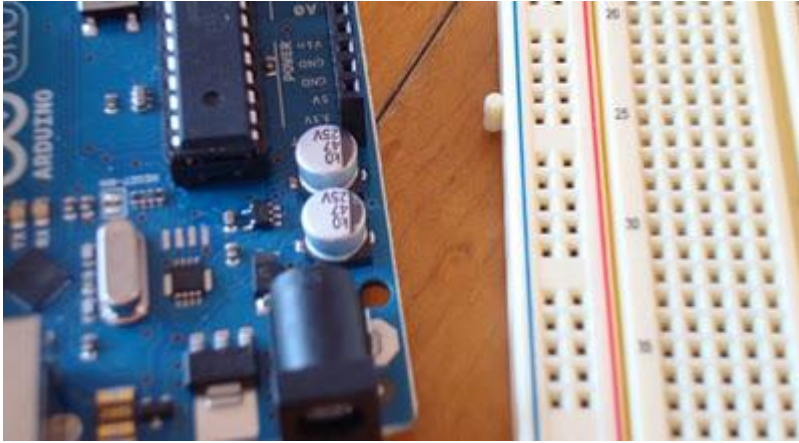
URL: www.shreejicharanelectronics.com

What is a Microcontroller



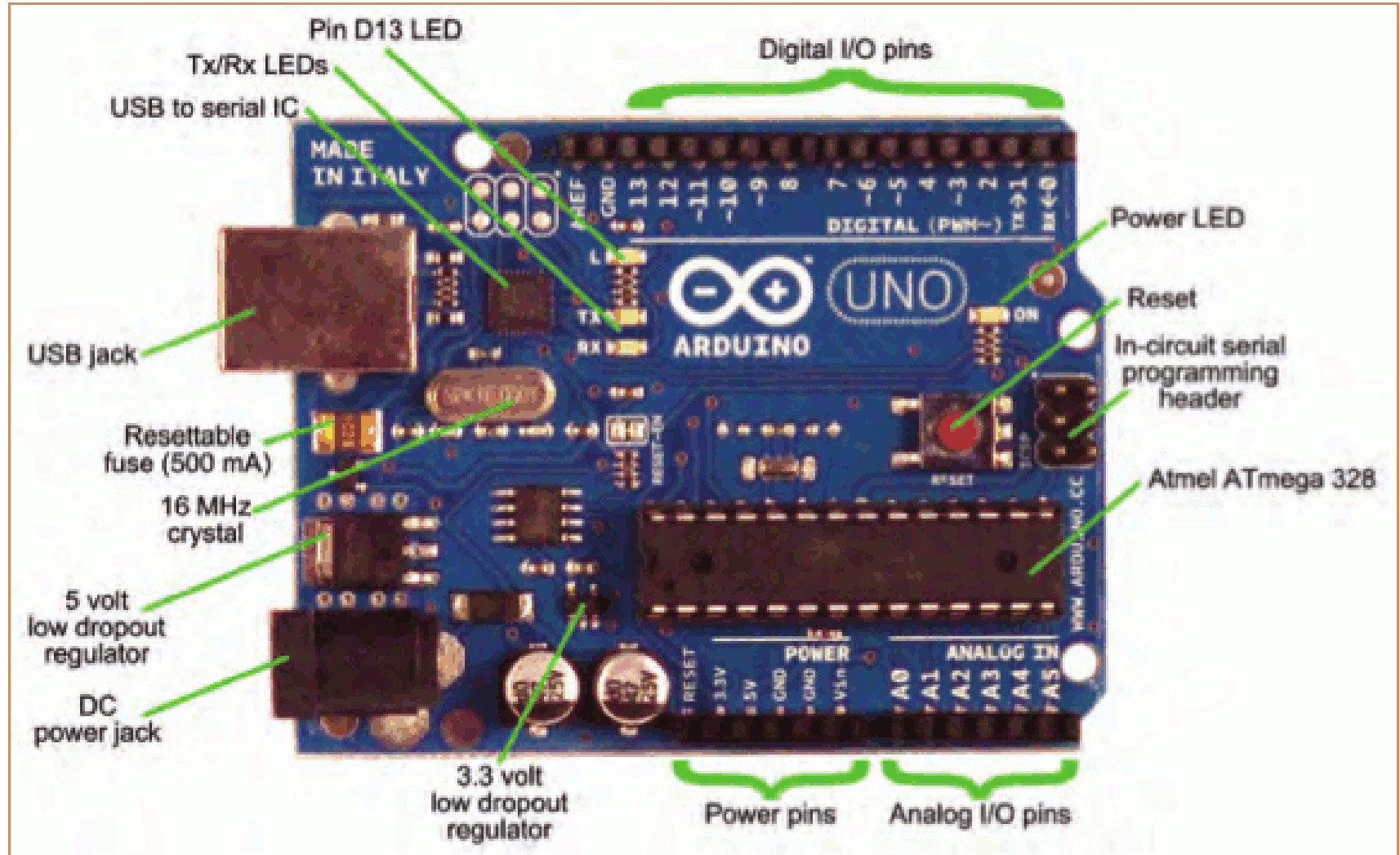
- A small computer on a single chip
 - containing a processor, memory, and input/output
- Typically "**embedded**" inside some device that they control
- A microcontroller is often small and low cost

What is a Development Board

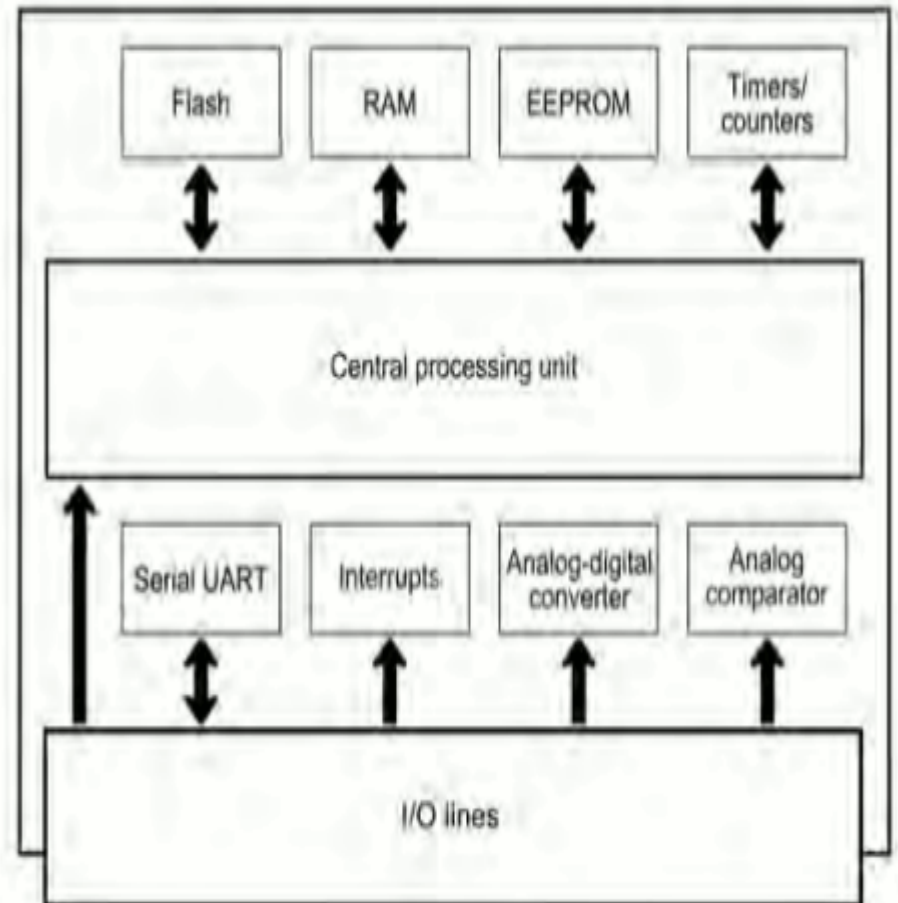
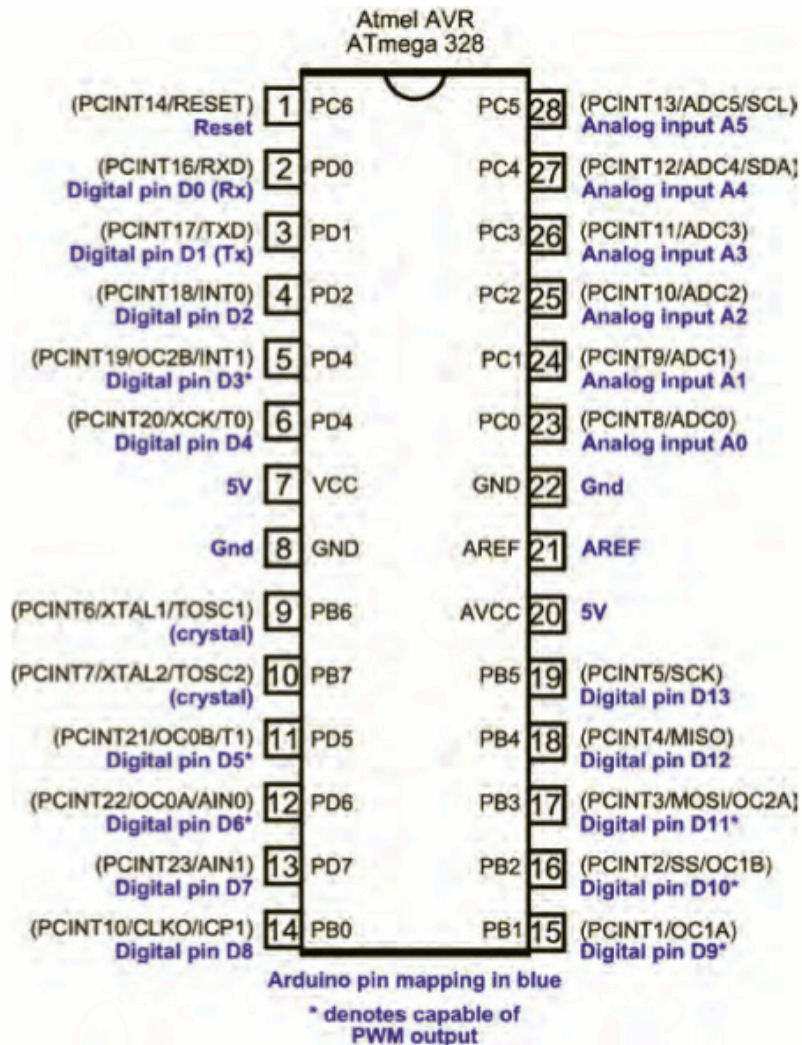


- A printed circuit board designed to facilitate work with a particular microcontroller.
- Typical components include:
 - power circuit
 - programming interface
 - basic input; usually buttons and LEDs
 - I/O pins

The Arduino Development Board



The Arduino Microcontroller: Atmel AVR Atmega 328



What is the Arduino

The word “Arduino” can mean 3 things

A physical piece of hardware



A programming environment



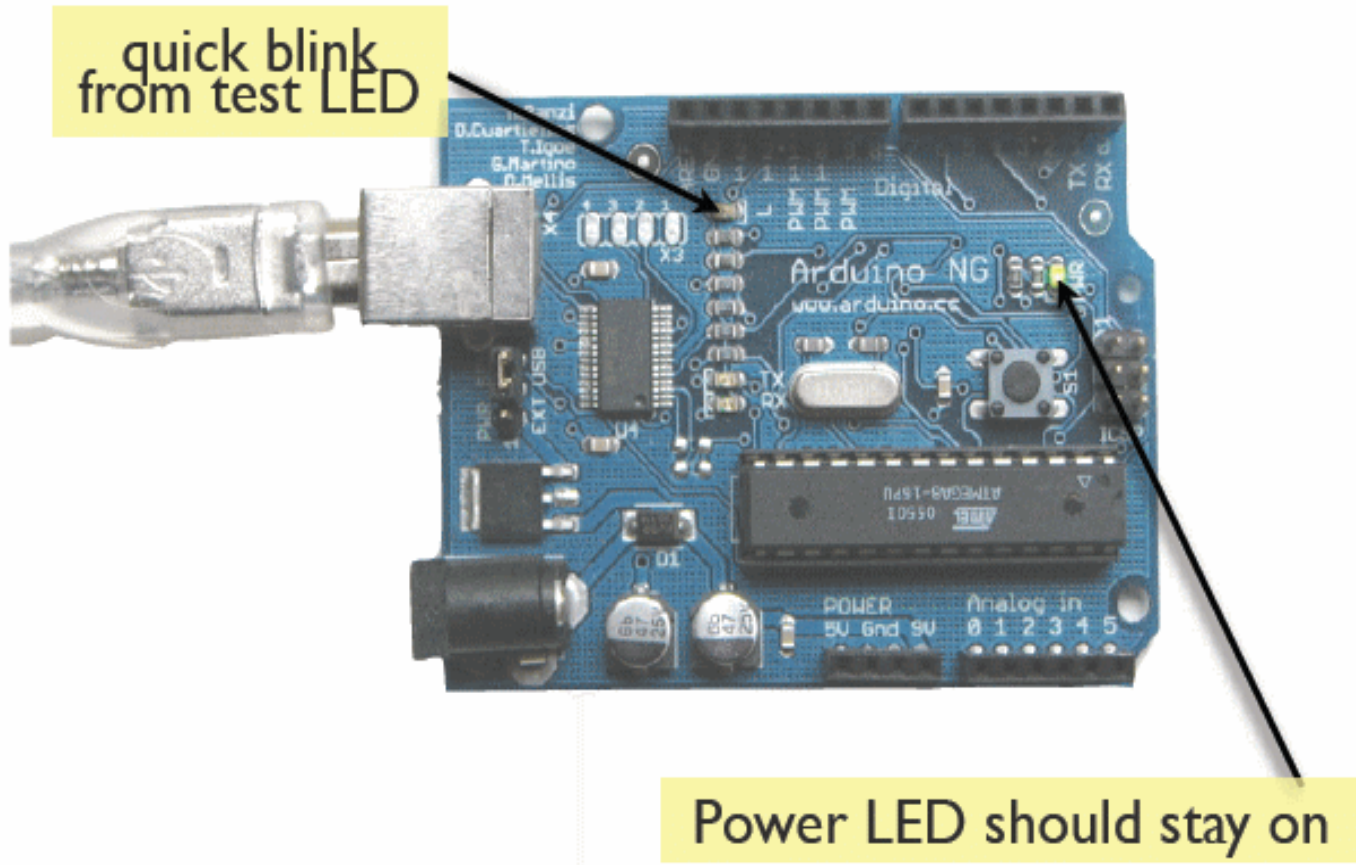
A community & philosophy



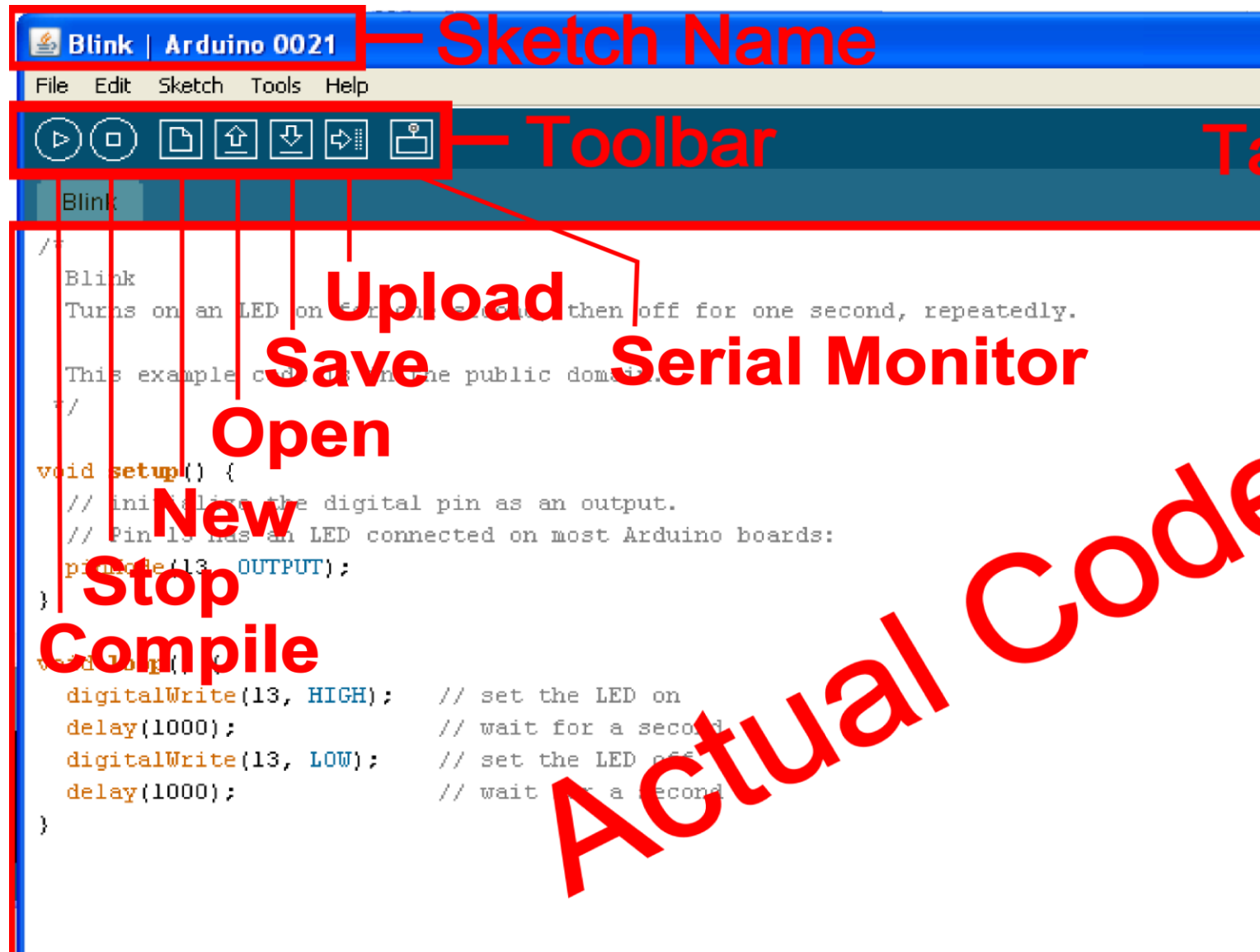
Getting Started

- Check out: <http://arduino.cc/en/Guide/HomePage>
 1. Download & install the Arduino environment (IDE)
 2. Connect the board to your computer via the UBS cable
 3. If needed, install the drivers (not needed in lab)
 4. Launch the Arduino IDE
 5. Select your board
 6. Select your serial port
 7. Open the blink example
 8. Upload the program

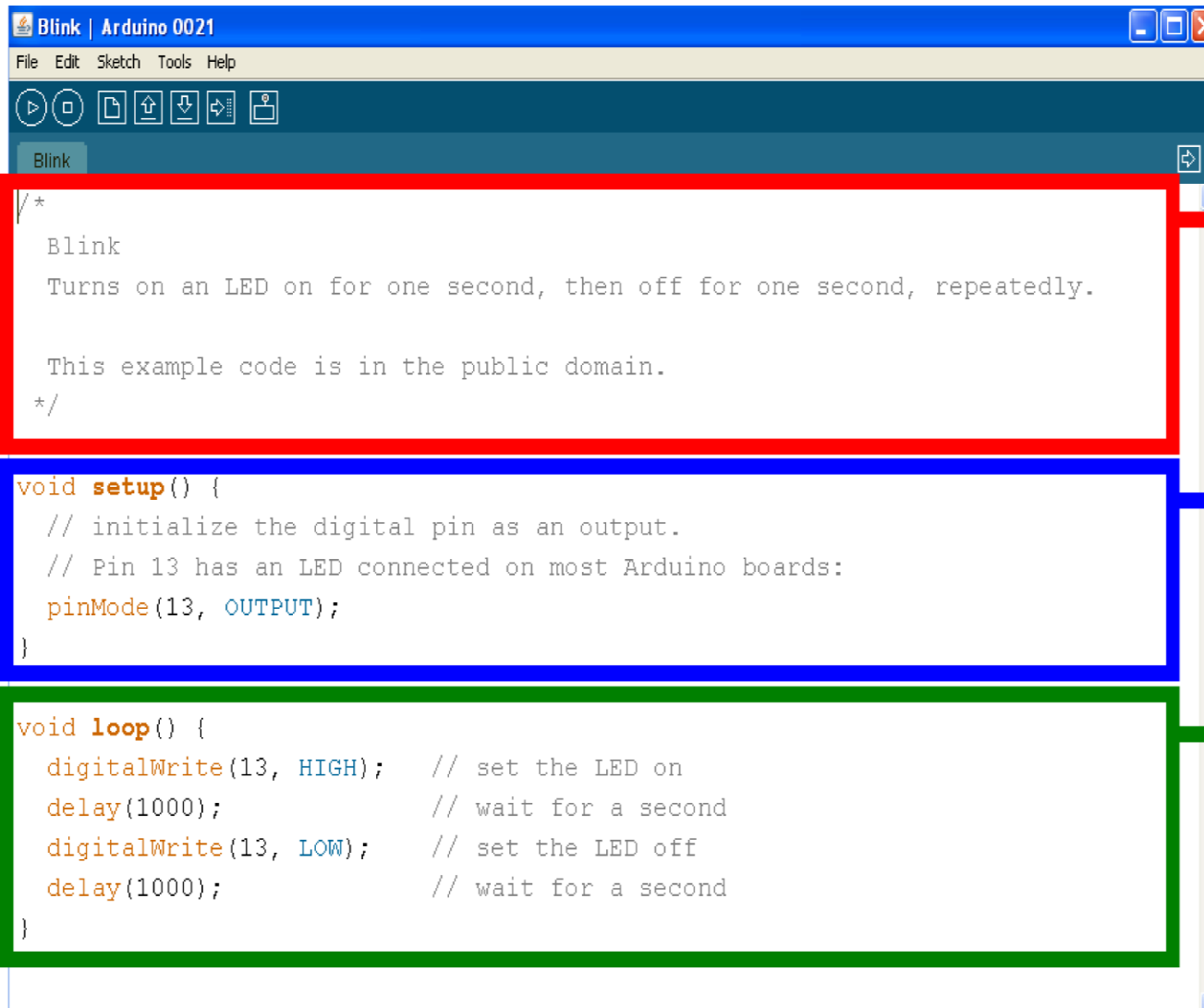
Try It: Connect the USB Cable



The Environment



Parts of the Sketch



```
Blink | Arduino 0021
File Edit Sketch Tools Help

Blink

/*
  Blink
  Turns on an LED on for one second, then off for one second, repeatedly.

  This example code is in the public domain.
  */

void setup() {
  // initialize the digital pin as an output.
  // Pin 13 has an LED connected on most Arduino boards:
  pinMode(13, OUTPUT);
}

void loop() {
  digitalWrite(13, HIGH); // set the LED on
  delay(1000);             // wait for a second
  digitalWrite(13, LOW);  // set the LED off
  delay(1000);             // wait for a second
}
```

**Comments /
Explaining
the game**

**Setup /
Stretching or
tying shoes**

**Loop /
Playing the
game**

Status Messages

Uploading worked

Size depends on complexity of your sketch

```
Done uploading.  
Binary sketch size: 1110 bytes (of a 14336 byte maximum)
```

Wrong serial port selected

```
Serial port '/dev/tty.usbserial-A4001qa8' not found. Did you select the  
java.awt.EventQueue$DispatchThread.run(EventDispatchThread.java:118)  
at  
java.awt.EventQueue$DispatchThread.run(EventDispatchThread.java:118)
```

Wrong board selected

```
Wrong microcontroller found. Did you select the right board from the T  
Binary sketch size: 000 bytes (of a 7168 byte maximum)  
avrdude: Expected signature for ATMEGA8 is 1E 93 07  
Double check chip, or use -F to override this check.
```

nerdy cryptic error messages

Using Arduino

- Write your sketch
- Press Compile button (to check for errors)
- Press Upload button to program Arduino board with your sketch

Try it out with the “Blink” sketch!

Load “File/Sketchbook/Examples/Digital/Blink”

```
void setup() {  
  pinMode(ledPin, OUTPUT); // sets t  
}  
void loop() {  
  digitalWrite(ledPin, HIGH); // sets t  
  delay(1000); // waits  
  digitalWrite(ledPin, LOW); // sets t  
  delay(1000); // waits  
}
```



compile

Done compiling.



upload

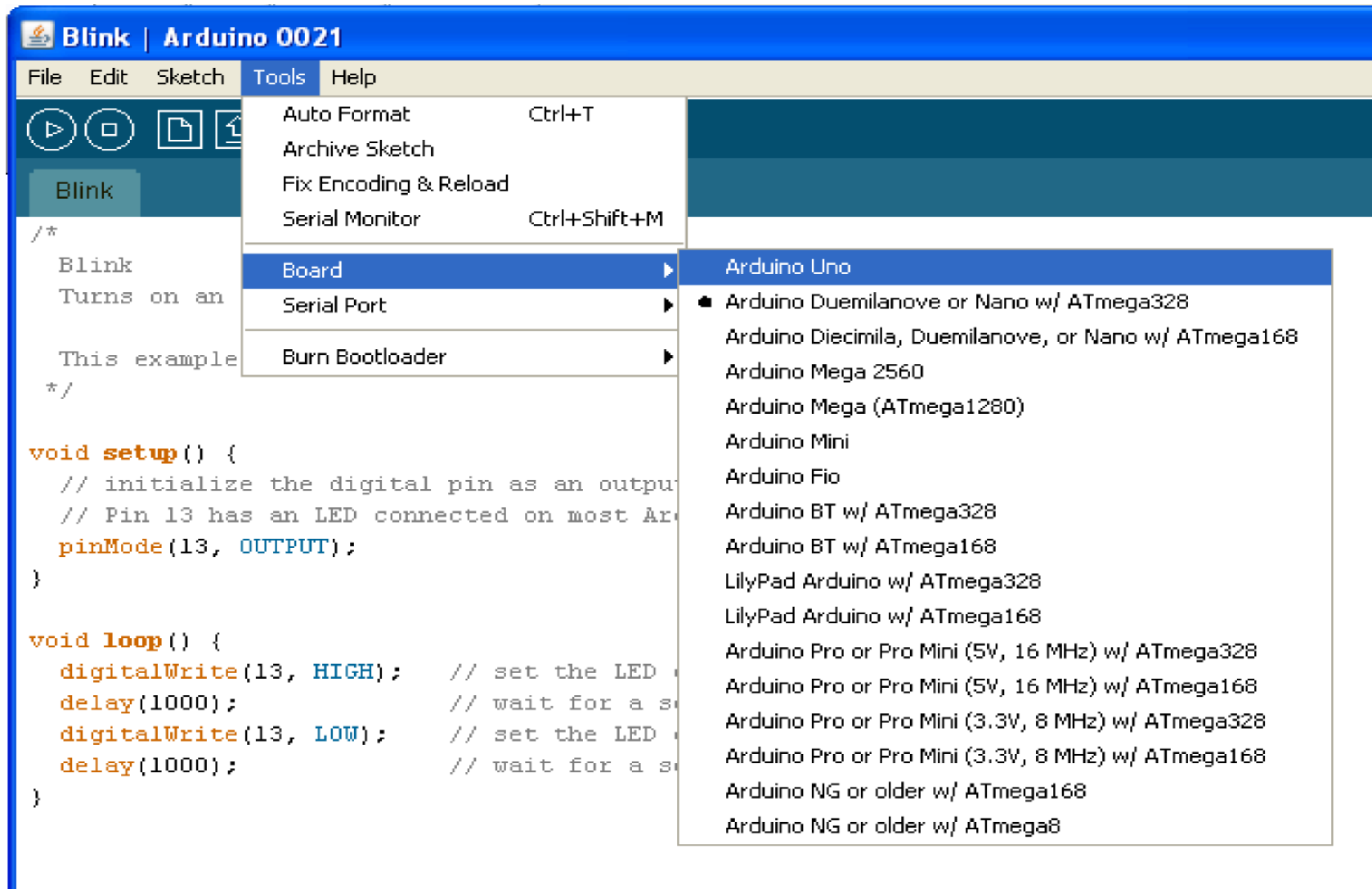


TX/RX flash

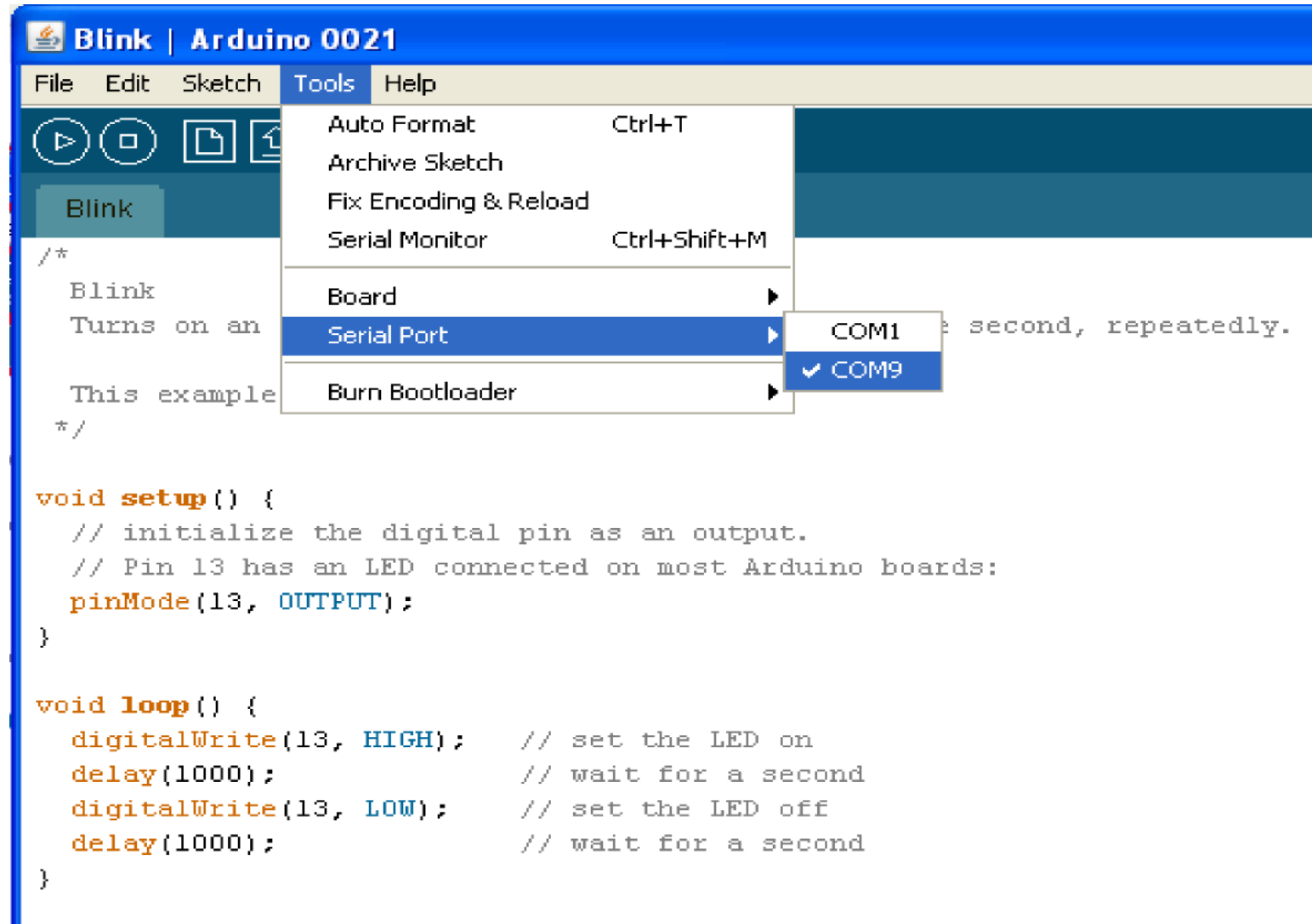


sketch runs

Board Type



Serial Port / COM Port

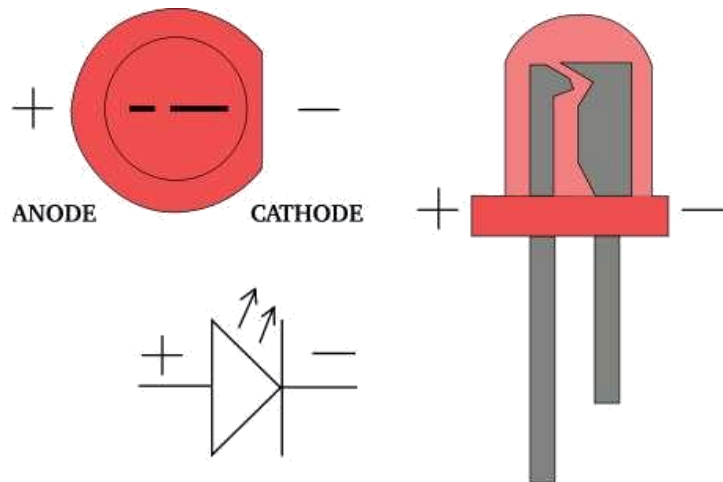


Comments

- Comments can be anywhere
- Comments created with `//` or `/*` and `*/`
- Comments do not affect code
- You may not need comments, but think about the community!
- Code is case sensitive
- Statements are commands and must end with a semi-colon
- Comments follow a `//` or begin with `/*` and end with `*/`
- loop and setup

Add an External LED to pin 13

- **File > Examples > Digital > Blink**
- LED's have polarity
 - Negative indicated by flat side of the housing and a short leg



www.instructables.com

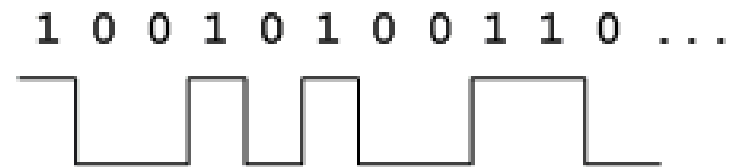
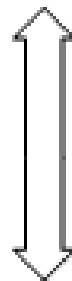
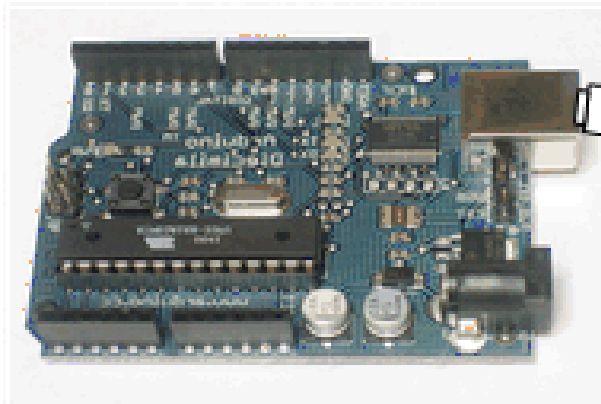


Serial Communication



Laptop

Cable



Information passes between the computer and Arduino through the USB cable. Information is transmitted as zeros ('0') and ones ('1')... also known as **bits**!

Serial Communications

- “Serial” because data is broken down into bits, each sent one after the other down a single wire.

- The single ASCII character ‘B’ is sent as:

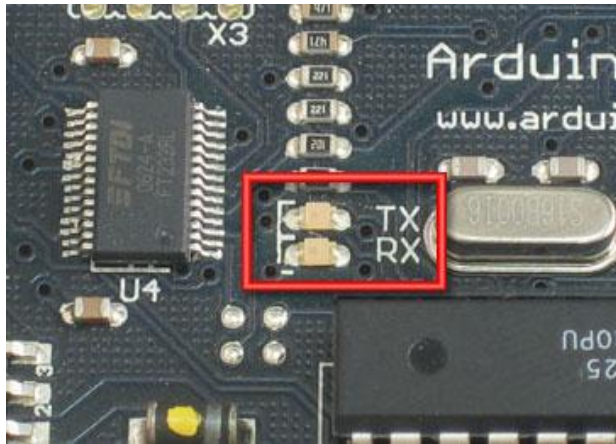
‘B’ = 0 1 0 0 0 0 1 0

= L H L L L L H L



- Toggle a pin to send data, just like blinking an LED
- You could implement sending serial data with `digitalWrite()` and `delay()`
- A single data wire needed to send data. One other to receive.

Serial Communication



- **Compiling** turns your program into binary data (ones and zeros)
- **Uploading** sends the bits through USB cable to the Arduino
- The two LEDs near the USB connector blink when data is transmitted
 - **RX** blinks when the Arduino is receiving data
 - **TX** blinks when the Arduino is transmitting data

First Program

```
/*
```

```
* Hello World!
```

```
* From www.ladyada.net
```

```
* It shows how to send data to the computer
```

```
*/
```

```
void setup()                                // run once, when the sketch starts
```

```
{
```

```
    Serial.begin(9600);                    // set up Serial library at 9600 bps
```

```
    Serial.println("Hello world!");        // prints hello with a line break
```

```
}
```

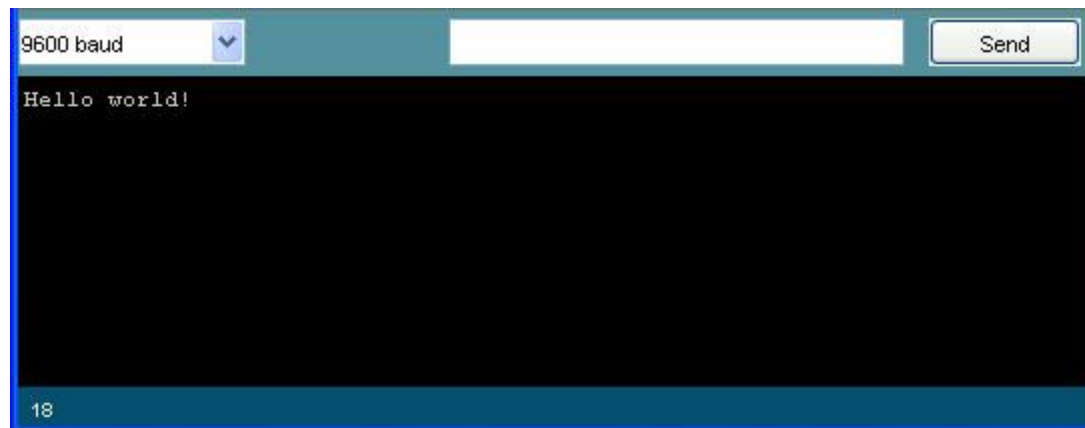
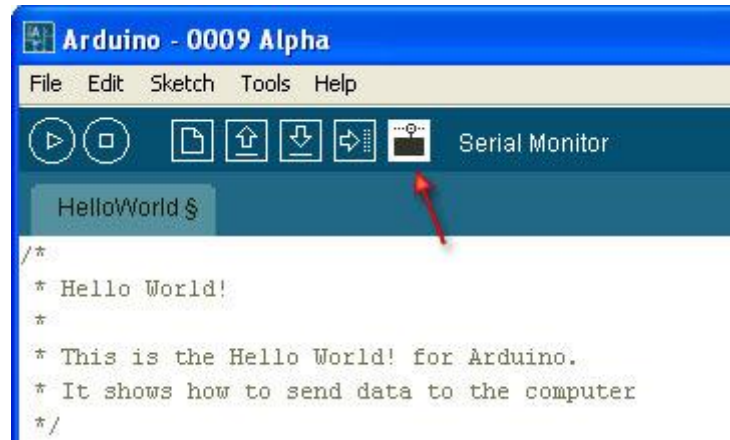
```
void loop()                                // run over and over again
```

```
{
```

```
    // do nothing!
```

```
}
```

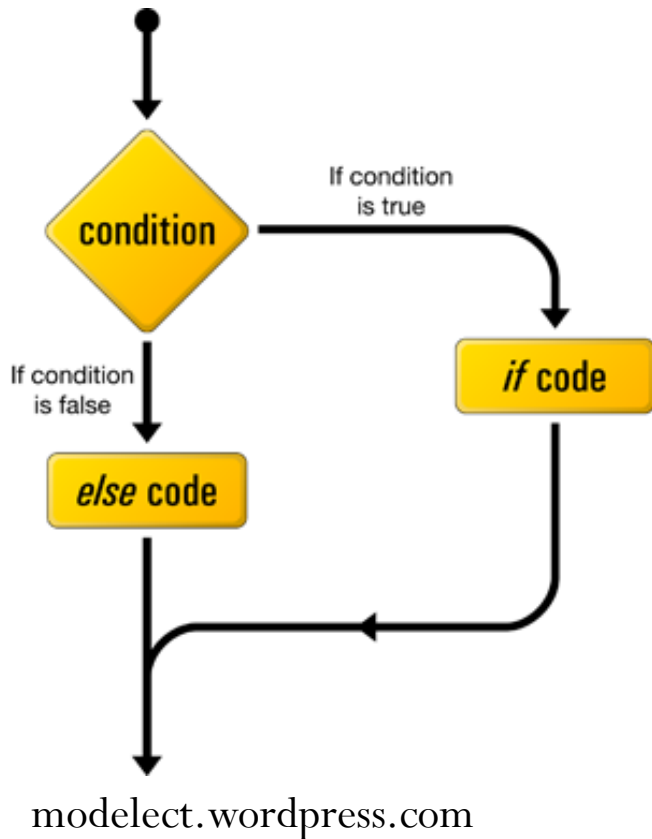
Open the Serial Monitor and Upload the Program



Embedded C Programming

- Operators
- Variables
- Setup & Loop Function
- Conditions
 - a. If... Else
- Basic Repetition
 - a. Loop
 - b. For
 - c. While
- Function

Conditional Statement



```
if (someCondition) {  
    // do stuff if the condition is true  
} else {  
    // do stuff if the condition is false  
}
```


Conditional Statement

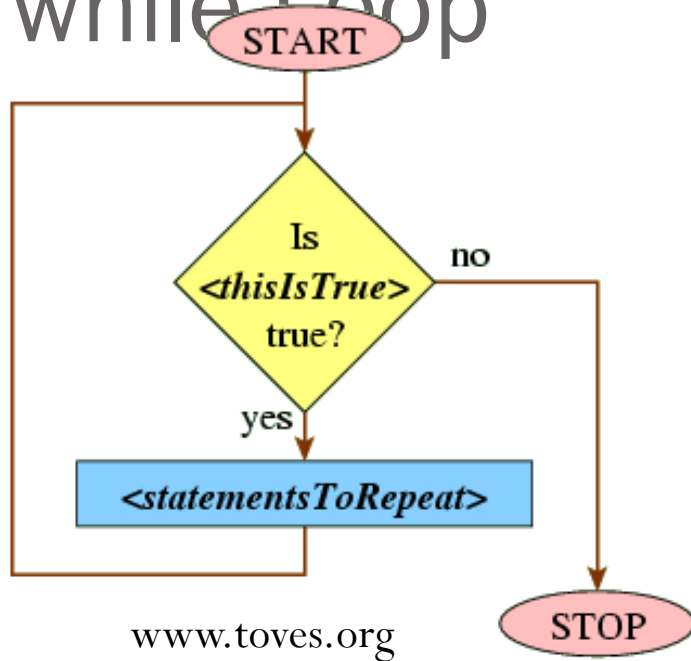
```
int printMessage = 1;
void setup()
{  Serial.begin(9600);
}

void loop()
{
  if (printMessage == 1) {
    Serial.println("Message");
    printMessage= 0;
  }
}
```

```
int printMessage = 1;
void setup()
{  Serial.begin(9600);
}

void loop()
{
  if (printMessage == 1) {
    Serial.println("Message");
    printMessage= 0;
  }
  else {
    Serial.println("NO Message");
    printMessage= 1;
  }
}
```

while Loop



```
while(expression) {  
    statement(s);  
}
```

Example

```
int var = 0;
```

```
while (var < 200) {
```

```
    // do something repetitive 200 times
```

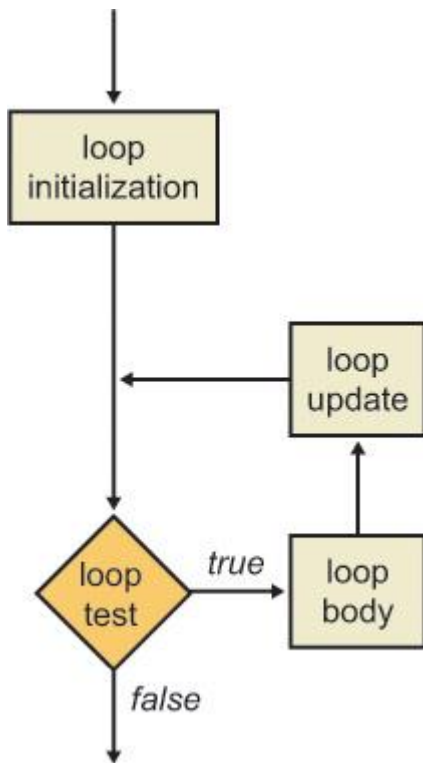
```
    var = var + 1;
```

```
}
```

while Loop

```
void setup()
{  Serial.begin(9600);
   int count = 0;
   while (count < 5) {
       Serial.println("Hello world!");
       count = count + 1;
   }
}
```

```
void loop()
{
}
```



initialisation iteration step
condition

```
for (int i = 0; i < 10; i++) {  
    // This is the loop body  
    // add your code here  
}
```

for Loop

```
void setup()
```

```
{
```

```
  Serial.begin(9600);
```

```
  for (int count = 0; count < 5; count++) {
```

```
    Serial.println("Hello world!");
```

```
  }
```

```
}
```

```
void loop()
```

```
{
```

```
}
```


Functions

- loop() and setup() are procedures
- You can create you own functions

Anatomy of a C function

Datatype of data returned,
any C datatype.

"void" If nothing is returned.

Function name

Parameters passed to
function, any C datatype.

```
int myMultiplyFunction(int x, int y){  
  int result;  
  result = x * y;  
  return result;  
}
```

Return statement,
datatype matches
declaration.

Curly braces required.

arduino.cc

```
void setup() {  
}
```

```
void loop() {  
}
```

Both setup() and loop()
have no parameters and
return no values

Functions: Example 1

```
void setup() {  
  Serial.begin(9600);  
  
  Serial.println("Before example function call.");  
  delay(1000);  
  example();  
  
  Serial.println("After example function call.");  
  delay(1000);  
}  
  
void loop() {  
}  
  
void example() {  
  Serial.println("During example function call.");  
  delay(1000);  
}
```

Function call...

...sends sketch to function.

Function starts here.

When done, sketch returns to next instruction after function call.

```
graph TD
    A[example() call in setup()] -- "Function call..." --> B[example() function start]
    B -- "...sends sketch to function." --> C[End of example() function]
    C -- "When done, sketch returns to next instruction after function call." --> D[Line following example() call in setup()]
```

Functions: Example 2

```
void setup() {  
  Serial.begin(9600);  
  
  pitch(3500);  
  Serial.println("Playing high pitch tone...");  
  delay(1000);  
  
  (5) Pass 2000 to Hz.  
  pitch(2000);  
  Serial.println("Playing lower pitch tone...");  
  delay(1000);  
}  
  
void loop()  
{  
  (6) Function  
  executes with  
  Hz = 2000  
  
  void pitch(int Hz)  
  {  
    Serial.print("Frequency = ");  
    Serial.print(Hz);  
    tone(4, Hz, 1000);  
    delay(1000);  
  }  
}
```

(1) Call sends sketch to function...

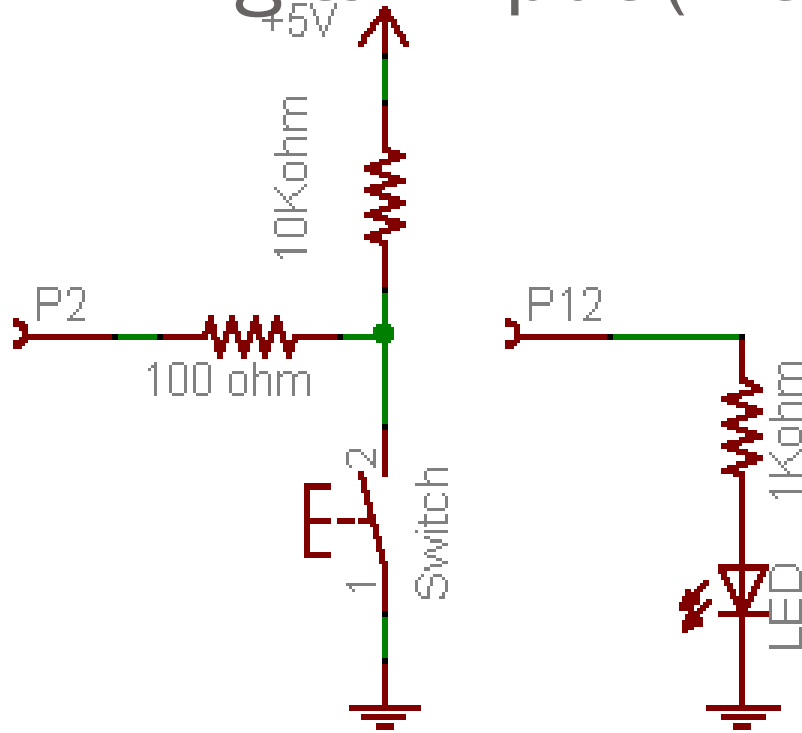
(2)...passing 3500 to Hz.

(3) Function executes with Hz = 3500.

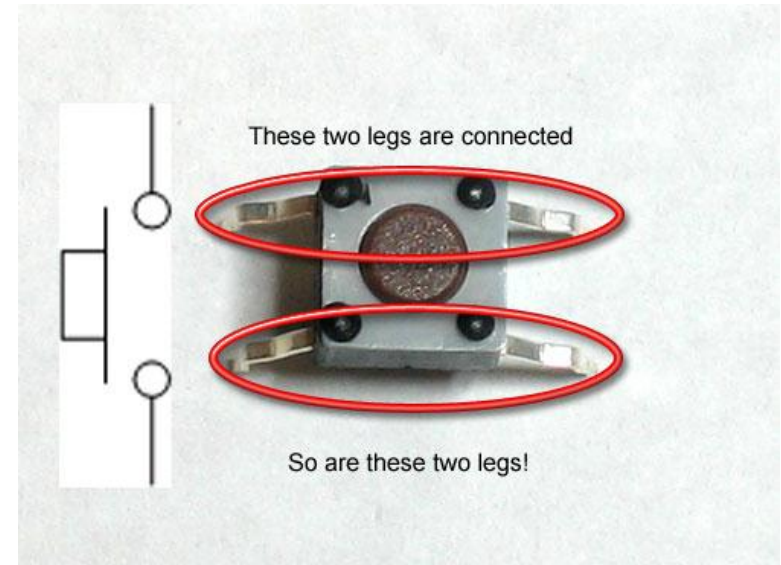
(4) No more code—return to next instruction in sketch.

The diagram illustrates the execution flow of the code. Red arrows show the sequence: from the `pitch(3500);` call in `setup()` to the `pitch` function definition, then to the `pitch(2000);` call in `setup()`, and finally to the `pitch` function definition again. A long red arrow from the closing brace of the `pitch` function points back to the `loop()` function, indicating the return path. Yellow boxes highlight the specific calls and the return instruction.

Digital Input (introducing the switch)



www.ladyada.net/



push-button switch

Create the circuit above and then run File ->
Examples -> Digital -> Button

Thank You

Embedded C Programming Fundamentals

- What is the difference between flash memory, EPROM, and EEPROM?
- What is the difference between Volatile & Non Volatile Memory?
- What are the differences between a union and a structure in C?
- What is the difference between RS232 and UART?
- Is it possible to declare struct and union one inside other? Explain with example.
- How to find the bug in code using the debugger if the pointer is pointing to an illegal value.
- What is watchdog timer?
- What is the DMA?
- What is RTOS?
- What are CAN and its uses?
- Why is CAN having 120 ohms at each end?
- Why is CAN message-oriented protocol?
- What is the Arbitration in the CAN?
- Standard CAN and Extended CAN difference?
- What is the use of bit stuffing?
- How many types of IPC mechanism do you know?
- What is semaphore?
- What is the spinlock?
- Convert a given decimal number to hex.
- What is the difference between heap and stack memory?
- What is socket programming?
- How can a double pointer be useful?
- What is the difference between binary semaphore and mutex?

