

Week 7 & 8 - Exercises

Max Holst Mikkelsen

Advanced Linear Algebra

Week 7 - Exercise 1

Consider the matrices

$$\begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix}, \begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{bmatrix} \in \mathbb{M}_3(\mathbb{R}).$$

Determine the rank and nullity of both matrices (considered as elements in $\text{Hom}(\mathbb{R}^3, \mathbb{R}^3)$).

For $(x, y, z) \in \mathbb{R}^3$ we have

$$\begin{pmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} x + y + z \\ x + y + z \\ x + y + z \end{pmatrix}$$
$$\begin{pmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} z \\ y \\ x \end{pmatrix}$$

Thus, if we denote the matrices by A and B respectively, we have

$$R(A) = \text{span}\{(1, 1, 1)\}$$

$$R(B) = \mathbb{R}^3$$

Hence,

$$\text{rank}(A) = \dim R(A) = 1, \quad \text{null}(A) = \dim \mathbb{R}^3 - \text{rank}(A) = 3 - 1 = 2$$

$$\text{rank}(B) = \dim R(B) = 3, \quad \text{null}(B) = 3 - 3 = 0$$

Week 7 - Exercise 2

Denote by \mathcal{P}_n the subspace in $\mathbb{R}[x]$ consisting of polynomials of degree at most n and the differentiation operator $D: \mathcal{P}_n \rightarrow \mathcal{P}_n$ sending a polynomial to its derivative. From the exercises done in week 6, it follows that D is linear [convince yourself of this]. Determine the matrix $[D]$ of D in the standard basis $\{1, x, x^2, \dots, x^n\}$.

MM853 students should be able to do this for general n , and MM562 students may, if they prefer, assume that $n = 4$.

We have

$$D(1) = 0 = 0 \cdot 1 + 0 \cdot x + 0 \cdot x^2 + \cdots + 0 \cdot x^{n-1} + 0 \cdot x^n$$

$$D(x) = 1 = 1 \cdot 1 + 0 \cdot x + 0 \cdot x^2 + \cdots + 0 \cdot x^{n-1} + 0 \cdot x^n$$

$$\vdots$$

$$D(x^n) = nx^{n-1} = 0 \cdot 1 + 0 \cdot x + 0 \cdot x^2 + \cdots + n \cdot x^{n-1} + 0 \cdot x^n$$

Thus,

$$[D] = \begin{pmatrix} 0 & 1 & 0 & 0 & \cdots & 0 \\ 0 & 0 & 2 & 0 & \cdots & 0 \\ 0 & 0 & 0 & 3 & \cdots & 0 \\ \vdots & \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & \cdots & \cdots & n \\ 0 & 0 & \cdots & \cdots & \cdots & 0 \end{pmatrix}$$

Week 7 - Exercise 3

Determine the rank and nullity of the operator D from the previous question.

We have

$$N(D) = \text{span}\{1\}$$

Thus,

$$\text{null}(D) = \dim N(D) = 1$$

$$\text{rank}(D) = \dim \mathcal{P}_n - \text{null}(D) = n + 1 - 1 = n$$

Week 7 - Exercise 4

Let U, V be vector spaces over \mathbb{F} and let $A \in \text{Hom}(U, V)$. Show that if $U_0 \subseteq U$ is a subspace then $A(U_0)$ is a subspace in V .

We have $0 \in U_0$ and thus $0 = A(0) \in A(U_0)$. Now, let $A(u), A(v) \in A(U_0)$ and $\alpha \in \mathbb{F}$. Then $u + v \in U_0$ and thus

$$A(u) + A(v) = A(u + v) \in A(U_0)$$

Further, $\alpha u \in U_0$ and thus

$$\alpha A(u) = A(\alpha u) \in A(U_0)$$

Hence, $A(U_0)$ is a subspace of V .

Week 7 - Exercise 5

Consider the real vector space \mathbb{R}^3 with its standard basis $B := \{(1, 0, 0), (0, 1, 0), (0, 0, 1)\}$.

- (a) Show that $B' := \{(1, 0, 0), (1, 1, 0), (1, 1, 1)\}$ is also a basis.
- (b) Consider the map $T: \mathbb{R}^3 \rightarrow \mathbb{R}^3$ given by $T(x_1, x_2, x_3) = (2x_1 - x_2, x_2 + x_3, 4x_3)$. Show that $T \in \text{End}(\mathbb{R}^3)$ and determine the matrix $[T]_B$ and $[T]_{B'}$ in $M_3(\mathbb{R})$ representing T in B and B' , respectively. Also, determine the matrix representing $T^2 := T \circ T$ in the basis B .

I did not cover page 19 in the lecture, so the exercise is intended to be done without these tools. See below for a slightly smarter way.

- (a) Since $\dim \mathbb{R}^3 = 3$ and $|B'| = 3$, it suffices to show that B' is linearly independent. Let $\alpha_1, \alpha_2, \alpha_3 \in \mathbb{R}$ and assume that

$$\alpha_1(1, 0, 0) + \alpha_2(1, 1, 0) + \alpha_3(1, 1, 1) = (0, 0, 0)$$

This corresponds to the following set of equations:

$$\alpha_1 + \alpha_2 + \alpha_3 = 0$$

$$\alpha_2 + \alpha_3 = 0$$

$$\alpha_3 = 0$$

From the third equation we have $\alpha_3 = 0$. Then the second equation yields $\alpha_2 = 0$. Inserting in the first equation, we obtain $\alpha_1 = 0$. Hence, B' is linearly independent, and B' is a basis for \mathbb{R}^3 .

Week 7 - Exercise 5 - continued

Consider the real vector space \mathbb{R}^3 with its standard basis $B := \{(1, 0, 0), (0, 1, 0), (0, 0, 1)\}$.

- (a) Show that $B' := \{(1, 0, 0), (1, 1, 0), (1, 1, 1)\}$ is also a basis.
- (b) Consider the map $T: \mathbb{R}^3 \rightarrow \mathbb{R}^3$ given by $T(x_1, x_2, x_3) = (2x_1 - x_2, x_2 + x_3, 4x_3)$. Show that $T \in \text{End}(\mathbb{R}^3)$ and determine the matrix $[T]_B$ and $[T]_{B'}$ in $M_3(\mathbb{R})$ representing T in B and B' , respectively. Also, determine the matrix representing $T^2 := T \circ T$ in the basis B .

I did not cover page 19 in the lecture, so the exercise is intended to be done without these tools. See below for a slightly smarter way.

(b) We have

$$T(1, 0, 0) = (2, 0, 0) = 2 \cdot (1, 0, 0) + 0 \cdot (0, 1, 0) + 0 \cdot (0, 0, 1)$$

$$T(0, 1, 0) = (-1, 1, 0) = -1 \cdot (1, 0, 0) + 1 \cdot (0, 1, 0) + 0 \cdot (0, 0, 1)$$

$$T(0, 0, 1) = (0, 1, 4) = 0 \cdot (1, 0, 0) + 1 \cdot (0, 1, 0) + 4 \cdot (0, 0, 1)$$

Thus,

$$[T]_B = \begin{pmatrix} 2 & -1 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 4 \end{pmatrix}$$

Week 7 - Exercise 5 - continued

Consider the real vector space \mathbb{R}^3 with its standard basis $B := \{(1, 0, 0), (0, 1, 0), (0, 0, 1)\}$.

- (a) Show that $B' := \{(1, 0, 0), (1, 1, 0), (1, 1, 1)\}$ is also a basis.
- (b) Consider the map $T: \mathbb{R}^3 \rightarrow \mathbb{R}^3$ given by $T(x_1, x_2, x_3) = (2x_1 - x_2, x_2 + x_3, 4x_3)$. Show that $T \in \text{End}(\mathbb{R}^3)$ and determine the matrix $[T]_B$ and $[T]_{B'}$ in $M_3(\mathbb{R})$ representing T in B and B' , respectively. Also, determine the matrix representing $T^2 := T \circ T$ in the basis B .

I did not cover page 19 in the lecture, so the exercise is intended to be done without these tools. See below for a slightly smarter way.

(b) We have

$$T(T(1, 0, 0)) = T(2, 0, 0) = (4, 0, 0)$$

$$T(T(0, 1, 0)) = T(-1, 1, 0) = (-3, 1, 0)$$

$$T(T(0, 0, 1)) = T(0, 1, 4) = (-1, 5, 16)$$

Thus,

$$[T^2]_B = \begin{pmatrix} 4 & -3 & -1 \\ 0 & 1 & 5 \\ 0 & 0 & 16 \end{pmatrix}$$

Note that

$$[T]_B^2 = [T^2]_B$$

Week 7 - Exercise 5 - continued

Consider the real vector space \mathbb{R}^3 with its standard basis $B := \{(1, 0, 0), (0, 1, 0), (0, 0, 1)\}$.

- (a) Show that $B' := \{(1, 0, 0), (1, 1, 0), (1, 1, 1)\}$ is also a basis.
- (b) Consider the map $T: \mathbb{R}^3 \rightarrow \mathbb{R}^3$ given by $T(x_1, x_2, x_3) = (2x_1 - x_2, x_2 + x_3, 4x_3)$. Show that $T \in \text{End}(\mathbb{R}^3)$ and determine the matrix $[T]_B$ and $[T]_{B'}$ in $M_3(\mathbb{R})$ representing T in B and B' , respectively. Also, determine the matrix representing $T^2 := T \circ T$ in the basis B .

I did not cover page 19 in the lecture, so the exercise is intended to be done without these tools. See below for a slightly smarter way.

(b) We have

$$T(1, 0, 0) = (2, 0, 0) = 2 \cdot (1, 0, 0) + 0 \cdot (1, 1, 0) + 0 \cdot (1, 1, 1)$$

$$T(1, 1, 0) = (1, 1, 0) = 0 \cdot (1, 0, 0) + 1 \cdot (1, 1, 0) + 0 \cdot (1, 1, 1)$$

$$T(1, 1, 1) = (1, 2, 4) = -1 \cdot (1, 0, 0) + (-2) \cdot (1, 1, 0) + 4 \cdot (1, 1, 1)$$

Thus,

$$[T]_{B'} = \begin{pmatrix} 2 & 0 & -1 \\ 0 & 1 & -2 \\ 0 & 0 & 4 \end{pmatrix}$$

Week 7 - Exercise 6

Let U, V, W be finite dimensional vector spaces equipped with fixed bases B_U, B_V and B_W . Let $A \in \text{Hom}(U, V)$ and $B \in \text{Hom}(V, W)$ be given and consider the composition $B \circ A \in \text{Hom}(U, W)$. Show that the matrix $[B \circ A]$ representing $B \circ A$ equals the matrix product $[B] \cdot [A]$ of the two matrices representing A and B , respectively.

Hint: one may start by considering the case $\dim(U) = \dim(V) = \dim(W) = 2$, and then generalize from there (or simply choose to believe that it works in general).

Let us consider $\dim(U) = \dim(V) = \dim(W) = 2$. We denote the basis vectors by $B_U = \{u_1, u_2\}$, $B_V = \{v_1, v_2\}$, $B_W = \{w_1, w_2\}$ and the entries of the matrices by

$$[A] = \begin{pmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{pmatrix}, \quad [B] = \begin{pmatrix} b_{11} & b_{12} \\ b_{21} & b_{22} \end{pmatrix}$$

Now,

$$\begin{aligned} A(u_1) &= a_{11}v_1 + a_{21}v_2, & A(u_2) &= a_{12}v_1 + a_{22}v_2 \\ B(v_1) &= b_{11}w_1 + b_{21}w_2, & B(v_2) &= b_{12}w_1 + b_{22}w_2 \end{aligned}$$

Then

$$\begin{aligned} B(A(u_1)) &= a_{11}B(v_1) + a_{21}B(v_2) \\ &= a_{11}(b_{11}w_1 + b_{21}w_2) + a_{21}(b_{12}w_1 + b_{22}w_2) \\ &= (a_{11}b_{11} + a_{21}b_{12})w_1 + (a_{11}b_{21} + a_{21}b_{22})w_2 \end{aligned}$$

Week 7 - Exercise 6 - continued

$$[A] = \begin{pmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{pmatrix}, \quad [B] = \begin{pmatrix} b_{11} & b_{12} \\ b_{21} & b_{22} \end{pmatrix}$$

$$A(u_1) = a_{11}v_1 + a_{21}v_2, \quad A(u_2) = a_{12}v_1 + a_{22}v_2$$

$$B(v_1) = b_{11}w_1 + b_{21}w_2, \quad B(v_2) = b_{12}w_1 + b_{22}w_2$$

Then

$$\begin{aligned} B(A(u_1)) &= a_{11}B(v_1) + a_{21}B(v_2) \\ &= a_{11}(b_{11}w_1 + b_{21}w_2) + a_{21}(b_{12}w_1 + b_{22}w_2) \\ &= (a_{11}b_{11} + a_{21}b_{12})w_1 + (a_{11}b_{21} + a_{21}b_{22})w_2 \end{aligned}$$

and

$$\begin{aligned} B(A(u_2)) &= a_{12}B(v_1) + a_{22}B(v_2) \\ &= a_{12}(b_{11}w_1 + b_{21}w_2) + a_{22}(b_{12}w_1 + b_{22}w_2) \\ &= (a_{12}b_{11} + a_{22}b_{12})w_1 + (a_{12}b_{21} + a_{22}b_{22})w_2 \end{aligned}$$

Thus,

$$[BA] = \begin{pmatrix} a_{11}b_{11} + a_{21}b_{12} & a_{12}b_{11} + a_{22}b_{12} \\ a_{11}b_{21} + a_{21}b_{22} & a_{12}b_{21} + a_{22}b_{22} \end{pmatrix} = [B] \cdot [A]$$

Week 8 - Exercise 1

Consider again the bases B and B' for \mathbb{R}^3 introduced above as well as the operator $T \in \text{End}(\mathbb{R}^3)$. Determine the transition matrix (a.k.a. basis change matrix) P from B' to B and use it to determine $[T]_{B'}$ from $[T]_B$.

$$B := \{(1, 0, 0), (0, 1, 0), (0, 0, 1)\}. \quad B' := \{(1, 0, 0), (1, 1, 0), (1, 1, 1)\}$$

Since

$$(1, 0, 0) = 1 \cdot (1, 0, 0) + 0 \cdot (0, 1, 0) + 0 \cdot (0, 0, 1)$$

$$(1, 1, 0) = 1 \cdot (1, 0, 0) + 1 \cdot (0, 1, 0) + 0 \cdot (0, 0, 1)$$

$$(1, 1, 1) = 1 \cdot (1, 0, 0) + 1 \cdot (0, 1, 0) + 1 \cdot (0, 0, 1)$$

we have

$$P = \begin{pmatrix} 1 & 1 & 1 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{pmatrix}$$

Then

$$[T]_{B'} = P^{-1}[T]_B P = \begin{pmatrix} 1 & -1 & 0 \\ 0 & 1 & -1 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 2 & -1 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 4 \end{pmatrix} \begin{pmatrix} 1 & 1 & 1 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{pmatrix} = \begin{pmatrix} 2 & 0 & -1 \\ 0 & 1 & -2 \\ 0 & 0 & 4 \end{pmatrix}$$

Week 8 - Exercise 2

Consider the complex vector space $M_2(\mathbb{C})$ of 2×2 complex matrices and denote by Tr the usual trace (mapping a matrix to the sum of its diagonal elements). Show that $\text{Tr} \in (M_2(\mathbb{C}))'$ and determine a basis for the nullspace $N(\text{Tr})$ and the quotient $M_2(\mathbb{C})/N(\text{Tr})$.

Let $\begin{pmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{pmatrix}, \begin{pmatrix} b_{11} & b_{12} \\ b_{21} & b_{22} \end{pmatrix} \in M_2(\mathbb{C})$ and let $\lambda \in \mathbb{C}$. Then

$$\begin{aligned} & \text{Tr} \left(\lambda \begin{pmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{pmatrix} + \begin{pmatrix} b_{11} & b_{12} \\ b_{21} & b_{22} \end{pmatrix} \right) \\ &= \text{Tr} \begin{pmatrix} \lambda a_{11} + b_{11} & \lambda a_{12} + b_{12} \\ \lambda a_{21} + b_{21} & \lambda a_{22} + b_{22} \end{pmatrix} \\ &= \lambda a_{11} + b_{11} + \lambda a_{22} + b_{22} \\ &= \lambda(a_{11} + a_{22}) + (b_{11} + b_{22}) \\ &= \lambda \text{Tr} \begin{pmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{pmatrix} + \text{Tr} \begin{pmatrix} b_{11} & b_{12} \\ b_{21} & b_{22} \end{pmatrix} \end{aligned}$$

Thus, $\text{Tr} \in (M_2(\mathbb{C}))'$.

Week 8 - Exercise 2 - continued

Consider the complex vector space $\mathbb{M}_2(\mathbb{C})$ of 2×2 complex matrices and denote by Tr the usual trace (mapping a matrix to the sum of its diagonal elements). Show that $\text{Tr} \in (\mathbb{M}_2(\mathbb{C}))'$ and determine a basis for the nullspace $N(\text{Tr})$ and the quotient $\mathbb{M}_2(\mathbb{C})/N(\text{Tr})$.

We have

$$\begin{aligned} N(\text{Tr}) &= \left\{ \begin{pmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{pmatrix} \in \mathbb{M}_2(\mathbb{C}) : a_{11} = -a_{22} \right\} \\ &= \text{span} \left\{ \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}, \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix} \right\} \end{aligned}$$

Note that a basis for $\mathbb{M}_2(\mathbb{C})$ is given by

$$B(\mathbb{M}_2(\mathbb{C})) = \left\{ \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}, \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix} \right\}$$

Thus, it follows from Theorem 2.14 that a basis for the quotient $\mathbb{M}_2(\mathbb{C})/N(\text{Tr})$ is given by

$$B(\mathbb{M}_2(\mathbb{C})/N(\text{Tr})) = \left\{ \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} + N(\text{Tr}) \right\}$$

Week 8 - Exercise 3 (Halmos §14, exercise 3)

3. Suppose that for each x in \mathcal{O} the function y is defined by

$$(a) \ y(x) = \int_{-1}^{+2} x(t) \, dt,$$

$$(b) \ y(x) = \int_0^x (x(t))^2 \, dt,$$

$$(c) \ y(x) = \int_0^1 t^2 x(t) \, dt,$$

$$(d) \ y(x) = \int_0^1 x(t^2) \, dt,$$

$$(e) \ y(x) = \frac{dx}{dt},$$

$$(f) \ y(x) = \left. \frac{d^2 x}{dt^2} \right|_{t=1}.$$

In which of these cases is y a linear functional?

(a) Let $x_1, x_2 \in \mathbb{R}[t]$ and $\lambda \in \mathbb{R}$. Then

$$\begin{aligned} y(\lambda x_1 + x_2) &= \int_{-1}^2 (\lambda x_1 + x_2)(t) \, dt = \int_{-1}^2 (\lambda x_1(t) + x_2(t)) \, dt \\ &= \lambda \int_{-1}^2 x_1(t) \, dt + \int_{-1}^2 x_2(t) \, dt = \lambda y(x_1) + y(x_2) \end{aligned}$$

Thus, y is a linear functional.

(b) y is not a linear functional since for example,

$$y(2 \cdot 1) = \int_0^2 2^2 \, dt = 4 \int_0^2 dt \neq 2 \int_0^2 dt = 2y(1)$$

(c) Let $x_1, x_2 \in \mathbb{R}[t]$ and $\lambda \in \mathbb{R}$. Then

$$y(\lambda x_1 + x_2) = \int_0^1 t^2 ((\lambda x_1 + x_2)(t)) \, dt = \lambda \int_0^1 t^2 x_1(t) \, dt + \int_0^1 t^2 x_2(t) \, dt = \lambda y(x_1) + y(x_2)$$

Thus, y is a linear functional.

Week 8 - Exercise 3 (Halmos §14, exercise 3) - continued

3. Suppose that for each x in \mathcal{O} the function y is defined by

(a) $y(x) = \int_{-1}^{+2} x(t) dt,$

(b) $y(x) = \int_0^2 (x(t))^2 dt,$

(c) $y(x) = \int_0^1 t^2 x(t) dt,$

(d) $y(x) = \int_0^1 x(t^2) dt,$

(e) $y(x) = \frac{dx}{dt},$

(f) $y(x) = \frac{d^2x}{dt^2} \Big|_{t=1}.$

In which of these cases is y a linear functional?

(d) Let $x_1, x_2 \in \mathbb{R}[t]$ and $\lambda \in \mathbb{R}$. Then

$$y(\lambda x_1 + x_2) = \int_0^1 (\lambda x_1 + x_2)(t^2) dt = \lambda \int_0^1 x_1(t^2) dt + \int_0^1 x_2(t^2) dt = \lambda y(x_1) + y(x_2)$$

Thus, y is a linear functional.

(e) y is not a linear functional since it is not even a map into the scalars ($\frac{dx}{dt}$ is not a complex number).

(f) Let $x_1, x_2 \in \mathbb{R}[t]$ and $\lambda \in \mathbb{R}$. Then

$$y(\lambda x_1 + x_2) = \frac{d^2(\lambda x_1 + x_2)}{dt^2} \Big|_{t=1} = \lambda \frac{d^2 x_1}{dt^2} \Big|_{t=1} + \frac{d^2 x_2}{dt^2} \Big|_{t=1} = \lambda y(x_1) + y(x_2)$$

Thus, y is a linear functional.

Week 8 - Exercise 4 (Halmos §14, exercise 5)

5. If y is a non-zero linear functional on a vector space \mathcal{U} , and if α is an arbitrary scalar, does there necessarily exist a vector x in \mathcal{U} such that $[x, y] = \alpha$?

Note that we are asked to show that y is surjective. From Week 7 - Exercise 4 we know that $R(y)$ is a subspace of \mathbb{F} . Hence $\dim R(y) \leq \dim \mathbb{F} = 1$, and since y is non-zero, it then follows that $\dim R(y) = 1 = \dim \mathbb{F}$. Thus, $R(y) = \mathbb{F}$ which means that y is surjective.

Week 8 - Exercise 5

5. (if time permits) Consider again the bases B and B' for \mathbb{R}^3 defined above, and denote by $\{y'_1, y'_2, y'_3\}$ the dual basis of B' . Write y'_1, y'_2 and y'_3 in terms of the basis B ; i.e. as $y'_1(x_1, x_2, x_3) = \dots$ and similarly for y'_2 and y'_3 .

$$B := \{(1, 0, 0), (0, 1, 0), (0, 0, 1)\}. \quad B' := \{(1, 0, 0), (1, 1, 0), (1, 1, 1)\}$$

For $(x_1, x_2, x_3) \in \mathbb{R}^3$ we note that

$$(x_1, x_2, x_3) = (x_1 - x_2) \cdot (1, 0, 0) + (x_2 - x_3) \cdot (1, 1, 0) + x_3 \cdot (1, 1, 1)$$

Thus,

$$y'_1(x_1, x_2, x_3) = x_1 - x_2$$

$$y'_2(x_1, x_2, x_3) = x_2 - x_3$$

$$y'_3(x_1, x_2, x_3) = x_3$$