# Week 11 & 12 - Exercises

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Advanced Linear Algebra

1. Check, if you have not already done so, that the dot-product  $\mathbb{R}^n \times \mathbb{R}^n \to \mathbb{R}$  is bilinear.

Let 
$$x=(x_1,\ldots,x_n)$$
,  $y=(y_1,\ldots,y_n), z=(z_1,\ldots,z_n)\in\mathbb{R}^n$  and  $\alpha,\beta\in\mathbb{R}$ . Then

$$x \cdot (\alpha y + \beta z) = (x_1, \dots, x_n) \cdot (\alpha y_1 + \beta z_1, \dots, \alpha y_n + \beta z_n)$$

$$= \alpha x_1 y_1 + \beta x_1 z_1 + \dots + \alpha x_n y_n + \beta x_n z_n$$

$$= \alpha (x_1 y_1 + \dots + x_n y_n) + \beta (x_1 z_1 + \dots + x_n z_n)$$

$$= \alpha (x \cdot y) + \beta (x \cdot z)$$

Linearity in the first argument is proved similarly.

- 2. Work through Example 4.2 (2) in the lecture notes. If you prefer, you may assume that n=m=2. What is the connection between this example and the dot-product exercise above?
  - (2) Let  $X = \mathcal{F}^m$  and  $Y = \mathcal{F}^n$ , and consider vectors in  $x \in X$  and  $y \in Y$  as columns. Let **B** be an  $m \times n$  matrix with elements  $b_{ij} \in \mathcal{F}$ . Then

$$B(x,y) := x^t \mathbf{B} y = \sum_{i,j} \alpha_i b_{ij} \beta_j$$

defines a bilinear form on  $X \times Y$ . Here  $(\alpha_i)$  and  $(\beta_j)$  are the coordinates of x and y.

Let  $x=(x_1,\ldots,x_m)\in\mathcal{F}^m$  and  $y=(y_1,\ldots,y_n),z=(z_1,\ldots,z_n)\in\mathcal{F}^n$  and  $\alpha,\beta\in\mathcal{F}$ . Then

$$B(x, \alpha y + \beta z) = \sum_{i,j} x_i b_{ij} (\alpha y_j + \beta z_j) = \sum_{i,j} x_i b_{ij} \alpha y_j + \sum_{i,j} x_i b_{ij} \beta z_j$$
$$= \alpha \sum_{i,j} x_i b_{ij} y_j + \beta \sum_{i,j} x_i b_{ij} z_j = \alpha B(x, y) + \beta B(x, z)$$

Linearity in the first argument is proved similarly. If m=n and  $b_{ij}=1$  for i=j and  $b_{ij}=0$  for  $i\neq j$  (i.e if B is the identity matrix) then the bilinear form B reduces to the dot-product from the previous exercise.

3. (Halmos, §25, exercise 1) Let  $\{e_1, e_2\}$  and  $\{e_1, e_2, e_3\}$  denote the standard basis for  $\mathbb{R}^2$  and  $\mathbb{R}^3$ , and consider  $x = (1, 1) \in \mathbb{R}^2$  and  $y = (1, 1, 1) \in \mathbb{R}^3$ . Determine the coordinates of  $x \otimes y \in \mathbb{R}^2 \otimes \mathbb{R}^3$  with respect to the basis  $\{e_i \otimes e_j \mid i = 1, 2; j = 1, 2, 3\}$ .

We have

$$x \otimes y = (e_1 + e_2) \otimes (e_1 + e_2 + e_3)$$
  
=  $e_1 \otimes e_1 + e_1 \otimes e_2 + e_1 \otimes e_3 + e_2 \otimes e_1 + e_2 \otimes e_2 + e_2 \otimes e_3$ 

Thus,  $x \otimes y$  has the coordinates (1,1,1,1,1,1) with respect to the given basis.

- 4. (Function spaces) Let X be a finite set<sup>1</sup> and consider the space  $\mathcal{F}(X)$  consisting of all functions  $f: X \to \mathbb{C}$ .
  - (a) If you have not already done so, check that \(\mathcal{F}(X)\) is a vector space with respect to the coordinate-wise operations \((f+g)(x):=f(x)+g(x)\) and \((\alpha \cdot f)(x)=\alpha f(x).\)
  - (b) For a fixed  $x_0 \in X$  consider the *Dirac mass* at  $x_0$ ; i.e. the function given by

$$\delta_{x_0}(x) := \begin{cases} 1 & \text{if } x = x_0 \\ 0 & \text{if } x \neq x_0 \end{cases}$$

Show that  $\{\delta_x \mid x \in X\}$  is a basis for  $\mathcal{F}(X)$ .

- (c) Let Y be another finite set and show that  $\mathcal{F}(X)\otimes\mathcal{F}(Y)$  is isomorphic to  $\mathcal{F}(X\times Y)$ .

  Hint: consider the natural bases for the two spaces in question and build a map that maps one to the other and then extend by linearity.
- (a) This follows from the fact that  $\mathbb C$  is a vector space.
- (b) We write  $X = \{x_1, \dots, x_n\}$ . Given an  $f \in \mathcal{F}(X)$  we have

$$f = f(x_1)\delta_{x_1} + \cdots + f(x_n)\delta_{x_n}$$

Thus,  $\mathcal{F}(X) = \text{span}\{\delta_x : x \in X\}$ . Now, let  $\alpha_1, \dots, \alpha_n \in \mathbb{C}$  and assume that

$$\alpha_1 \delta_{x_1} + \dots + \alpha_n \delta_{x_n} = 0$$

Then for all  $i \in \{1, ..., n\}$  we have

$$\alpha_i = \alpha_1 \delta_{x_1}(x_i) + \dots + \alpha_i \delta_{x_i}(x_i) + \dots + \alpha_n \delta_{x_n}(x_i) = 0$$

Thus,  $\{\delta_x : x \in X\}$  is linearly independent and consequently a basis for  $\mathcal{F}(X)$ .

- 4. (Function spaces) Let X be a finite set<sup>1</sup> and consider the space  $\mathcal{F}(X)$  consisting of all functions  $f:X\to\mathbb{C}$ .
  - (a) If you have not already done so, check that \( \mathcal{T}(X) \) is a vector space with respect to the coordinate-wise operations \( (f+g)(x) := f(x) + g(x) \) and \( (\alpha \cdot f)(x) = \alpha f(x). \)
  - (b) For a fixed  $x_0 \in X$  consider the *Dirac mass* at  $x_0$ ; i.e. the function given by

$$\delta_{x_0}(x) := \begin{cases} 1 & \text{if } x = x_0 \\ 0 & \text{if } x \neq x_0 \end{cases}$$

Show that  $\{\delta_x \mid x \in X\}$  is a basis for  $\mathcal{F}(X)$ .

- (c) Let Y be another finite set and show that F(X)⊗F(Y) is isomorphic to F(X × Y). Hint: consider the natural bases for the two spaces in question and build a map that maps one to the other and then extend by linearity.
- (c) From (b) we know that  $\{\delta_{(x,y)}:x\in X,y\in Y\}$  is a basis for  $\mathcal{F}(X\times Y)$  and that  $\{\delta_x\otimes\delta_y:x\in X,y\in Y\}$  is a basis for  $\mathcal{F}(X)\otimes\mathcal{F}(Y)$ . We define the map  $\varphi\colon\mathcal{F}(X)\otimes\mathcal{F}(Y)\to\mathcal{F}(X\times Y)$  given on the basis by  $\varphi(\delta_x\otimes\delta_y)=\delta_{(x,y)}$  and extend by linearity. Since  $\varphi$  is a bijection from the basis of  $\mathcal{F}(X)\otimes\mathcal{F}(Y)$  to the basis of  $\mathcal{F}(X\times Y)$ , it follows from Lemma 2.7 that  $\varphi$  is an isomorphism.

5. (Slice maps) Let U, V be finite dimensional vector spaces over a common field  $\mathcal{F}$  and let  $f \in U'$  be given. Show that there exists a linear map  $T \colon U \otimes V \to V$  with the property that  $T(u \otimes v) = f(u)v$  for all  $u \in U$  and  $v \in V$ . The map T is often denoted  $f \otimes I$  and is called the *slice map* associated with f

We fix bases  $\{u_1,\ldots,u_n\}$  and  $\{v_1,\ldots,v_m\}$  for U and V respectively. Then  $\{u_i\otimes v_j:i\in\{1,\ldots,n\},j\in\{1,\ldots,m\}\}$  is a basis for  $U\otimes V$ . We define  $T\colon U\otimes V\to V$  given on the basis by  $T(u_i\otimes v_j)=f(u_i)v_j$  and extend by linearity. To see that this map T has the desired property, we let  $u=\sum_{i=1}^n\alpha_iu_i\in U$  and  $v=\sum_{j=1}^m\beta_jv_j\in V$ . Then

$$T(u \otimes v) = T\left(\sum_{i=1}^{n} \alpha_{i} u_{i} \otimes \sum_{j=1}^{m} \beta_{j} v_{j}\right) = T\left(\sum_{i=1}^{n} \sum_{j=1}^{m} (\alpha_{i} \beta_{j})(u_{i} \otimes v_{j})\right)$$

$$= \sum_{i=1}^{n} \sum_{j=1}^{m} \alpha_{i} \beta_{j} T(u_{i} \otimes v_{j}) = \sum_{i=1}^{n} \sum_{j=1}^{m} \alpha_{i} \beta_{j} f(u_{i}) v_{j}$$

$$= f\left(\sum_{j=1}^{n} \alpha_{i} u_{i}\right) \sum_{j=1}^{m} \beta_{j} v_{j} = f(u) v$$

6. (A non-commutativity result) Let V be a finite dimensional vector space and consider the tensor product  $V \otimes V$ . For  $x,y \in V \setminus \{0\}$ , show that if x and y are linearly independent then  $x \otimes y \neq y \otimes x$ .

Hint: use Theorem 3.11 together with the exercise on slice maps.

We define the subspace  $U:=\operatorname{span}\{x\}$  of V. Since x,y are linearly independent, we have  $y\notin U$ . Then by Theorem 3.11, there is an  $f\in V'$  such that  $f(y)\neq 0$  and  $f|_U=0$ . Now, we consider the slice map T associated with f from Exercise 5. Then

$$T(x \otimes y) = f(x)y = 0$$

and

$$T(y\otimes x)=f(y)x\neq 0$$

Hence,  $x \otimes y \neq y \otimes x$ .

7. (A commutativity result) Let U,V be finite dimensional vector spaces over a common field  $\mathbb{F}$ . Show that  $U\otimes V\simeq V\otimes U$  by providing an explicit isomorphism.

We fix bases  $\{u_1,\ldots,u_n\}$  and  $\{v_1,\ldots,v_m\}$  for U and V respectively. Then  $\{u_i\otimes v_j:i\in\{1,\ldots,n\},j\in\{1,\ldots,m\}\}$  and  $\{v_j\otimes u_i:i\in\{1,\ldots,n\},j\in\{1,\ldots,m\}\}$  are bases for  $U\otimes V$  and  $V\otimes U$  respectively. We define  $\varphi\colon U\otimes V\to V\otimes U$  given on the basis elements by  $\varphi(u_i\otimes v_j)=v_j\otimes u_i$  and extend by linearity. Since  $\varphi$  is a bijection from the basis of  $U\otimes V$  to the basis of  $V\otimes U$ , it follows that  $\varphi$  is an isomorphism.

1. If you have not done so already, determine a basis for  $\mathbb{R}^2$  consisting of eigenvectors for  $\begin{pmatrix} 2 & 0 \\ 0 & 0 \end{pmatrix}$ 

We determine the eigenvalues by solving the characteristic equation:

$$0 = \begin{vmatrix} 2 - \lambda & 0 \\ 0 & -\lambda \end{vmatrix} = \lambda(\lambda - 2)$$

Thus, the eigenvalues are 0 and 2. Observe that

$$\begin{pmatrix} 2 & 0 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix} = 2 \cdot \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

and

$$\begin{pmatrix} 2 & 0 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} 0 \\ 1 \end{pmatrix} = 0 \cdot \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

Thus, the standard basis vectors for  $\mathbb{R}^2$  are eigenvectors for the matrix.

2. Consider the trivial example vector space  $V = \{0\}$ , which I made a point out of excluding in the lecture. What is  $\operatorname{End}(V)$ ? What is the minimal polynomial for the (there is only one) operator in  $\operatorname{End}(V)$ ? And why does this operator not have any eigenvectors?

Note that  $\operatorname{End}(V)$  only contains the identity operator  $I\colon V\to V$  given by I(0)=0. Now, if  $p(X)=\alpha$  is a constant polynomial then  $p(I)=\alpha I=0$ . Thus, the minimal polynomials for I are the constant polynomials. The operator I cannot have any eigenvectors as eigenvectors by definition are non-zero.

3. Consider the endomorphisms

$$\begin{pmatrix} 1 & 0 \\ 0 & 2 \end{pmatrix} \in \mathbb{M}_2(\mathbb{R}) = \operatorname{End}(\mathbb{R}^2) \quad \text{ and } \quad \begin{pmatrix} 1 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 2 \end{pmatrix} \in \mathbb{M}_3(\mathbb{R}) = \operatorname{End}(\mathbb{R}^3),$$

and determine their minimal polynomials.

We consider

$$A = \begin{pmatrix} 1 & 0 \\ 0 & 2 \end{pmatrix}, \quad B = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 2 \end{pmatrix}$$

and let  $p(X) = \alpha_0 + \alpha_1 X + \cdots + \alpha_n X^n \in \mathbb{R}[X]$ . We have

$$A^n = \begin{pmatrix} 1^n & 0 \\ 0 & 2^n \end{pmatrix}$$

and consequently

$$p(A) = \alpha_0 I + \alpha_1 A + \dots + \alpha_n A^n$$

$$= \begin{pmatrix} \alpha_0 + \alpha_1 1 + \alpha_2 1^2 + \dots + \alpha_n 1^n & 0 \\ 0 & \alpha_0 + \alpha_1 2 + \alpha_2 2^2 + \dots + \alpha_n 2^n \end{pmatrix}$$

Thus, p(A) = 0 if and only if 1 and 2 are roots of p(X) if and only if p(X) = (X-1)(X-2)q(X). It follows the minimal polynomials for A are of the form C(X-1)(X-2). Note that repeated diagonal entries do not change this argument. Thus, B has the same minimal polynomials as A.

4. Drawing on your experience from the previous exercise, determine the minimal polynomial of an arbitrary diagonal matrix?

Let  $A \in \mathbb{M}_n(\mathbb{R})$  be a diagonal matrix and let  $\lambda_1, \ldots, \lambda_m$  for an  $m \leq n$  be the distinct diagonal entries of A. Then the minimal polynomials of A are of the form

$$p(X) = C(X - \lambda_1)(X - \lambda_2) \cdots (X - \lambda_m)$$