Homework 2 (Due: 10/15/2018)

COEN 281, Fall 2018 Professor Marwah

The objective of this HW is to implement k-NN and cross-validation to find the best value of k for a binary classification task. The task to diagnose breast cancer based on 30 numeric features. However, to keep things simple, we will only use two of those features. The output is binary: 0 benign, 1 malignant. In all there are 569 examples, which we will split into training and test sets. There are no missing values.

```
In [56]: # Load the data set
    import numpy as np
    import sklearn.datasets
    dat = sklearn.datasets.load_breast_cancer()
```

In [57]: # uncomment the following and run it to get a description of the data set
print(dat.DESCR)

Breast Cancer Wisconsin (Diagnostic) Database

Notes

_ _ _ _

Data Set Characteristics:

:Number of Instances: 569

:Number of Attributes: 30 numeric, predictive attributes and the class

:Attribute Information:

- radius (mean of distances from center to points on the perimeter)
- texture (standard deviation of gray-scale values)
- perimeter
- area
- smoothness (local variation in radius lengths)
- compactness (perimeter^2 / area 1.0)
- concavity (severity of concave portions of the contour)
- concave points (number of concave portions of the contour)
- symmetry
- fractal dimension ("coastline approximation" 1)

The mean, standard error, and "worst" or largest (mean of the three largest values) of these features were computed for each image, resulting in 30 features. For instance, field 3 is Mean Radius, fiel

d

13 is Radius SE, field 23 is Worst Radius.

- class:
 - WDBC-Malignant
 - WDBC-Benign

:Summary Statistics:

	=====	=====
	Min	Max
	=====	=====
radius (mean):	6.981	28.11
texture (mean):	9.71	39.28
perimeter (mean):	43.79	188.5
area (mean):	143.5	2501.0
<pre>smoothness (mean):</pre>	0.053	0.163
compactness (mean):	0.019	0.345
<pre>concavity (mean):</pre>	0.0	0.427
concave points (mean):	0.0	0.201
symmetry (mean):	0.106	0.304
fractal dimension (mean):	0.05	0.097
radius (standard error):	0.112	2.873
texture (standard error):	0.36	4.885
perimeter (standard error):	0.757	21.98
area (standard error):	6.802	542.2
smoothness (standard error):	0.002	0.031
compactness (standard error):	0.002	0.135
concavity (standard error):	0.0	0.396
concave points (standard error):	0.0	0.053
symmetry (standard error):	0.008	0.079
fractal dimension (standard error):	0.001	0.03

```
radius (worst):
                                7.93
                                      36.04
                                12.02 49.54
texture (worst):
perimeter (worst):
                                50.41 251.2
area (worst):
                                185.2 4254.0
smoothness (worst):
                                0.071 0.223
compactness (worst):
                                0.027 1.058
concavity (worst):
                                0.0
                                      1.252
                                      0.291
concave points (worst):
                                0.0
symmetry (worst):
                                0.156 0.664
fractal dimension (worst):
                                0.055 0.208
```

:Missing Attribute Values: None

:Class Distribution: 212 - Malignant, 357 - Benign

:Creator: Dr. William H. Wolberg, W. Nick Street, Olvi L. Mangasarian

:Donor: Nick Street

:Date: November, 1995

This is a copy of UCI ML Breast Cancer Wisconsin (Diagnostic) datasets. https://goo.gl/U2Uwz2

Features are computed from a digitized image of a fine needle aspirate (FNA) of a breast mass. They describe characteristics of the cell nuclei present in the image.

Separating plane described above was obtained using Multisurface Method-Tree (MSM-T) [K. P. Bennett, "Decision Tree Construction Via Linear Programming." Proceedings of the 4th Midwest Artificial Intelligence and Cognitive Science Society, pp. 97-101, 1992], a classification method which uses linear programming to construct a decision tree. Relevant features were selected using an exhaustive search in the space of 1-4 features and 1-3 separating planes.

The actual linear program used to obtain the separating plane in the 3-dimensional space is that described in: [K. P. Bennett and O. L. Mangasarian: "Robust Linear Programming Discrimination of Two Linearly Inseparable Sets", Optimization Methods and Software 1, 1992, 23-34].

This database is also available through the UW CS ftp server:

ftp ftp.cs.wisc.edu
cd math-prog/cpo-dataset/machine-learn/WDBC/

References

- W.N. Street, W.H. Wolberg and O.L. Mangasarian. Nuclear feature extraction

for breast tumor diagnosis. IS&T/SPIE 1993 International Symposium on Electronic Imaging: Science and Technology, volume 1905, pages 861-870, San Jose, CA, 1993.

- O.L. Mangasarian, W.N. Street and W.H. Wolberg. Breast cancer diagnosis

and
 prognosis via linear programming. Operations Research, 43(4), pages 570577,
 July-August 1995.
 - W.H. Wolberg, W.N. Street, and O.L. Mangasarian. Machine learning techni
ques
 to diagnose breast cancer from fine-needle aspirates. Cancer Letters 77
(1994)
 163-171.

```
In [3]: # dat is a dictionary with the data, Let's see what keys it has
    dat.keys()
Out[3]: dict_keys(['data', 'target', 'target_names', 'DESCR', 'feature_names'])
```

In [58]: # we will use two features: 'mean area' and 'mean concave points'
ix1 = np.where(dat["feature_names"] == "mean area")[0][0]
ix2 = np.where(dat["feature_names"] == "mean concave points")[0][0]

```
In [59]: | X = dat["data"][:,(ix1,ix2)]
         Y = dat["target"]
         # verify shape of X and Y
         print(X.shape, Y.shape)
         # stats of the two features
         from scipv import stats
         st = stats.describe(X)
         print("Number of points: %i" % st.nobs)
         print("range (min, max), X1: (%.2f, %.2f), X2: (%.2f, %.2f)" % (st.minmax[0][0
         ], st.minmax[1][0], st.minmax[0][1], st.minmax[1][1]))
         print("mean: %.2f, %.2f" % (st.mean[0], st.mean[1]))
         print("variance: %.2f, %f" % (st.variance[0], st.variance[1]))
         # Given the stats, is it a good idea to normalize the features?
         #yes it is as both the features are in differnt scales and as they differ by a
          lot, the feature with the higher magnitude can dominate while calculating the
          euclidian distances.
         # add code to normalize features
         print()
         print("yes it is as both the features are in differnt scales and as they diffe
         r by a lot, the feature with the higher magnitude can dominate while calculati
         ng the euclidian distances.")
         for i in range(X.shape[1]):
             X[:,i]=(X[:,i]-X[:,i].min())/(X[:,i].max()-X[:,i].min())
         #print((np.around(normalized df,3)))
```

```
(569, 2) (569,)
Number of points: 569
range (min, max), X1: (143.50, 2501.00), X2: (0.00, 0.20)
mean: 654.89, 0.05
variance: 123843.55, 0.001506
```

yes it is as both the features are in differnt scales and as they differ by a lot, the feature with the higher magnitude can dominate while calculating the euclidian distances.

```
In [60]: # split into training set / test set
#
# usually you would do the split randomly; here for deterministic results, we
assume the data
# points are already shuffled and take the first 70% as training and the rest
as test
#
nTot = X.shape[0]
nTr = int(nTot*0.7)
nTs = nTot - nTr

Xtr = X[0:nTr,]
Ytr = Y[0:nTr]

Xts = X[nTr:nTot,]
Yts = Y[nTr:nTot,]
# verify shapes
print(Xtr.shape, Ytr.shape, Xts.shape, Yts.shape)
```

(398, 2) (398,) (171, 2) (171,)

k-NN Implementation

```
In [61]: # Implement the following functions for k-NN
         # knn predict(Xtr, Ytr, Xts, k)
         # input: Xtr - training examples input features, size nXd
                  Ytr - label (can assume to be binary 0/1), size nX1
                  Xts - test examples input features, for which labels (Yts)
                        need to be predicted, size mXd
         #
                       - k for the k-NN algo
         # output: Yts - 0/1 labes for Xts, size mX1
            This function predicts the binary labels for Xts, given the training
            data Xtr, Ytr and k, using the k-NN algorithm
         import math
         import random
         def knn predict(Xtr, Ytr, Xts, k):
             # compute in two steps
             # step 1: compute dist matrix between Xts and Xtr
             dist = compute dist mat(Xtr, Xts)
             dist = np.asarray(dist)
             index sort = np.argsort(dist)
             # step 2: use the dist matrix and use k-nn to find labels for Xts
             # hint: function numpy.argsort may be useful
             # in case of a tie, pick a class randomly
             # YOUR CODE HERE
             neighbours = []
             for i in range(0, len(dist)):
                 neighbours.append([])
                 neighbours[i] = index sort[i][0:k].tolist()
                 for j in range(0, len(neighbours[i])):
                      neighbours[i][j] = Ytr[neighbours[i][j]]
             prediction = []
             for i in range(0,len(neighbours)):
                 prediction.append([])
                  count one = 0
                  count zero = 0
                 for j in range(0, k):
                      if neighbours[i][j] == 1:
                          count_one = count_one + 1
                      if neighbours[i][j] == 0:
                          count zero = count zero + 1
                  if count one > count zero:
                      res = 1
                 elif count_zero > count_one:
                      res = 0
                 else:
                      res = random.randint(0,1)
                  prediction[i].append(res)
```

```
pred = np.asarray(prediction)
    return pred
    pass
   compute dist mat(Xts, Xtr)
  input: Xts - test examples, size mXd
#
          Xtr - training examples, size nXd
#
#
  output: L2 distance matrix mXn
#
    if Xts is mXd, and Xtr is nXd, this function returns a matrix of size mXn
with the L2 distances; the (i,j)
      entry of the matrix is the L2 distance between ith test and jth training
example
def compute dist mat(Xtr, Xts):
    # use two for loops to compute the matrix
    # YOUR CODE HERE
    dist matrix = []
    for i in range(0, len(Xts)):
        dist_matrix.append([])
        for j in range(0, len(Xtr)):
            x = Xts[i][0] - Xtr[j][0];
            y = Xts[i][1] - Xtr[j][1];
            dist = math.sqrt(x**2 + y**2)
            dist_matrix[i].append(dist)
    return dist_matrix
    pass
```

Problem 1 (30 points): Fill-in code for normalizing features, and the above two functions to implement k-NN.

Problem 2 (20 points): Run your k-NN implementation on the test data set. Use k=5. Compute accuracy, recall and precision of the test data set (do not use python library functions to compute these).

recall = 0.8939393939393939

```
In [62]:
         # problem 2 solution
         predected label = knn predict(Xtr, Ytr, Xts, 5)
         predected label = predected label.flatten()
         Yts = np.asarray(Yts)
         diff accuracy = np.subtract(Yts,predected label)
         sum_accuracy = np.add(Yts,predected_label)
         unique sum, counts sum = np.unique(sum accuracy, return counts=True)
         unique diff, counts diff = np.unique(diff accuracy, return counts=True)
         true values = dict(zip(unique diff, counts diff))[0]
         total = true_values + dict(zip(unique_diff, counts_diff))[-1]+ dict(zip(unique
         diff, counts diff))[1]
         accuracy = true values/total
         precession = dict(zip(unique_sum, counts_sum))[2]/(dict(zip(unique_sum, counts
         sum))[2] + dict(zip(unique diff, counts diff))[-1])
         recall = dict(zip(unique sum, counts sum))[2]/(dict(zip(unique sum, counts sum))
         ))[2] + dict(zip(unique_diff, counts_diff))[1])
         print("accuracy = {}".format(accuracy))
         print("precession = {}".format(precession))
         print("recall = {}".format(recall))
         accuracy = 0.9122807017543859
         precession = 0.9915966386554622
```

Cross-Validation

Priblem 3 (30 points): Now we will implement 5-fold cross-validation to find the best value of k. And then using that value of k, re-run k-NN on the test data set. (This is adapted from a past Stanford cs231n assignment)

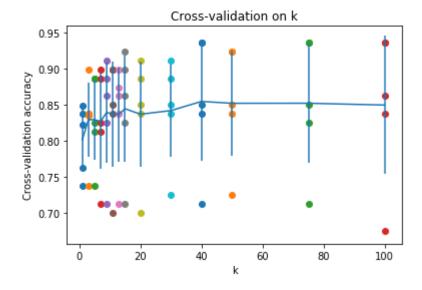
```
In [63]:
      num folds = 5
       k_choices = [1, 3, 5, 7, 9, 11, 13, 15, 20, 30, 40, 50, 75, 100]
       X train folds = []
       y train folds = []
       # TODO:
       # Split up the training data into folds. After splitting, X_train_folds and
       # y train folds should each be lists of length num folds, where
       # y train folds[i] is the label vector for the points in X train folds[i].
       # Hint: Look up the numpy array_split function.
       X train folds = np.array(np.array split(Xtr, num folds))
       y train folds = np.array(np.array split(Ytr, num folds))
       ##
       #
                                END OF YOUR CODE
       ##
       # A dictionary holding the accuracies for different values of k that we find
       # when running cross-validation. After running cross-validation,
       # k_to_accuracies[k] should be a list of length num_folds giving the different
       # accuracy values that we found when using that value of k.
       k to accuracies = {}
       ##
       # TODO:
       # Perform k-fold cross validation to find the best value of k. For each
       # possible value of k, run the k-nearest-neighbor algorithm num folds times,
       # where in each case you use all but one of the folds as training data and the
       # last fold as a validation set. Store the accuracies for all fold and all
       # values of k in the k to accuracies dictionary.
       ##
       for k in k_choices:
          for n in range(num_folds):
             test num fold set = [x for x in range(num folds) if x != n]
             x training dat = np.concatenate(X train folds[test num fold set])
```

```
y_training_dat = np.concatenate(y_train_folds[test_num_fold_set])
      predected_label = knn_predict(x_training_dat, y_training_dat, X_train_
folds[n], k)
      predected label = predected label.flatten()
      sum accuracy = np.add(y train folds[n],predected label)
      unique, counts = np.unique(sum_accuracy, return_counts=True)
      true_values = dict(zip(unique, counts))[0] + dict(zip(unique, counts))
[2]
      total = true_values + dict(zip(unique, counts))[1]
      accuracy = true values/total
      k to accuracies.setdefault(k, []).append(accuracy)
pass
#
                            END OF YOUR CODE
#
##
# Print out the computed accuracies
for k in sorted(k_to_accuracies):
   for accuracy in k to accuracies[k]:
      print('k = %d, accuracy = %f' % (k, accuracy))
```

k = 1, accuracy = 0.787500 k = 1, accuracy = 0.787500 k = 1, accuracy = 0.875000 k = 1, accuracy = 0.873418 k = 1, accuracy = 0.898734 k = 3, accuracy = 0.787500 k = 3, accuracy = 0.812500 k = 3, accuracy = 0.887500 k = 3, accuracy = 0.911392 k = 3, accuracy = 0.886076 k = 5, accuracy = 0.825000 k = 5, accuracy = 0.837500 k = 5, accuracy = 0.900000 k = 5, accuracy = 0.936709 k = 5, accuracy = 0.911392 k = 7, accuracy = 0.837500 k = 7, accuracy = 0.837500 k = 7, accuracy = 0.875000 k = 7, accuracy = 0.949367 k = 7, accuracy = 0.924051 k = 9, accuracy = 0.850000 k = 9, accuracy = 0.837500 k = 9, accuracy = 0.900000 k = 9, accuracy = 0.924051 k = 9, accuracy = 0.936709 k = 11, accuracy = 0.850000 k = 11, accuracy = 0.825000 k = 11, accuracy = 0.912500 k = 11, accuracy = 0.924051 k = 11, accuracy = 0.936709 k = 13, accuracy = 0.887500 k = 13, accuracy = 0.825000 k = 13, accuracy = 0.912500 k = 13, accuracy = 0.924051 k = 13, accuracy = 0.911392 k = 15, accuracy = 0.875000 k = 15, accuracy = 0.837500 k = 15, accuracy = 0.925000 k = 15, accuracy = 0.924051 k = 15, accuracy = 0.911392 k = 20, accuracy = 0.850000 k = 20, accuracy = 0.850000 k = 20, accuracy = 0.912500 k = 20, accuracy = 0.911392 k = 20, accuracy = 0.936709 k = 30, accuracy = 0.850000 k = 30, accuracy = 0.837500 k = 30, accuracy = 0.937500 k = 30, accuracy = 0.936709 k = 30, accuracy = 0.936709 k = 40, accuracy = 0.825000 k = 40, accuracy = 0.837500 k = 40, accuracy = 0.937500 k = 40, accuracy = 0.924051 k = 40, accuracy = 0.949367 k = 50, accuracy = 0.837500 k = 50, accuracy = 0.850000

```
k = 50, accuracy = 0.937500
k = 50, accuracy = 0.924051
k = 50, accuracy = 0.962025
k = 75, accuracy = 0.825000
k = 75, accuracy = 0.850000
k = 75, accuracy = 0.937500
k = 75, accuracy = 0.924051
k = 75, accuracy = 0.962025
k = 100, accuracy = 0.862500
k = 100, accuracy = 0.862500
k = 100, accuracy = 0.925000
k = 100, accuracy = 0.924051
k = 100, accuracy = 0.924051
```

```
In [18]:
         # plot the raw observations
         import matplotlib.pyplot as plt
         %matplotlib inline
         for k in k_choices:
             accuracies = k_to_accuracies[k]
             plt.scatter([k] * len(accuracies), accuracies)
         # plot the trend line with error bars that correspond to standard deviation
         accuracies mean = np.array([np.mean(v) for k,v in sorted(k to accuracies.items
         ())1)
         accuracies_std = np.array([np.std(v) for k,v in sorted(k_to_accuracies.items
         ())1)
         plt.errorbar(k choices, accuracies mean, yerr=accuracies std)
         plt.title('Cross-validation on k')
         plt.xlabel('k')
         plt.ylabel('Cross-validation accuracy')
         plt.show()
```



Problem 4 (20 points): Based on the cross-validation results above, choose the best value for k. Repeat problem 2 with this k (using the entire training data set).

```
In [64]:
         mean = []
         for k in sorted(k to accuracies):
             mean.append(np.mean(k_to_accuracies.get(k)))
         mean = np.asarray(mean)
         mean = np.argsort(mean)
         best k = k choices[mean[len(mean) - 1]]
         print("Best K value is {}".format(best k))
         predected label = knn predict(Xtr, Ytr, Xts, best k)
         predected label = predected label.flatten()
         Yts = np.asarray(Yts)
         diff accuracy = np.subtract(Yts,predected label)
         sum accuracy = np.add(Yts,predected label)
         unique_sum, counts_sum = np.unique(sum_accuracy, return_counts=True)
         unique diff, counts diff = np.unique(diff accuracy, return counts=True)
         true values = dict(zip(unique diff, counts diff))[0]
         total = true_values + dict(zip(unique_diff, counts_diff))[-1]+ dict(zip(unique
         diff, counts diff))[1]
         accuracy = true values/total
         precession = dict(zip(unique_sum, counts_sum))[2]/(dict(zip(unique_sum, counts
         sum))[2] + dict(zip(unique diff, counts diff))[-1])
         recall = dict(zip(unique sum, counts sum))[2]/(dict(zip(unique sum, counts sum))
         ))[2] + dict(zip(unique_diff, counts_diff))[1])
         print("accuracy = {}".format(accuracy))
         print("precession = {}".format(precession))
         print("recall = {}".format(recall))
         Best K value is 50
         accuracy = 0.9239766081871345
         precession = 0.976
         recall = 0.9242424242424242
```

Note: these extra credit problems are optional and only increase your score marginally.

Extra Credit Problem 1 (5 points): Plot decision boundaries for the best k, similar to how it is done here: http://scikit-learn.org/stable/auto_examples/neighbors/plot_classification.html (http://scikit-learn.org/stable/auto_examples/neighbors/plot_classification.html)

Extra Credit Problem 2 (5 points): In problem 1 above, re-write the compute_dist_mat() function with no loops. That may seem non-intuitive, but it is possible to compute the L2 distances using matrix operations (matrix multiplication, addition, etc.) without explicitly doing the double for loop. The advantage of using matrix operations is that they are highly optimized and enable "vectorization", and for such computations can give 10-100x speed improvements.