## sensor

```
-observers: set<sensor_observ
-sensing: bool = false
-status: unsigned short = 0
+<<virtual>> sensing_status()
+<<virtual>> sensing(): bool
+<<virtual>> start_sensing():
+<<virtual>> stop_sensing():
+<<virtual>> toggle_sensing()
+<<virtual>> sense(): void
+attach_observer(observer:sen-
+detach_observer(observer:sen-
```

```
er>
: int
int
int
: int
: or_observer &): void
```

```
+observer_count(): int
```

## Syscall\_Se singleton

```
-FTRACE_DIR: string = /sys/ke
-TRACING_ON_FILE: string = tr
-SYS_ENTRY_DIR: string = sys_
-SYS_EXIT_DIR: string = sys_e
-EVENTS_DIR: string = events/
-TRACE_PIPE_FILE: string = tr
-CURRENT_TRACER_FILE: string
-trace_pipe_stream: fstream
-ENABLE FILE: string = enable
-<<constructor>> syscall_sens
+get_instance(): syscall_sens
+sensing status(): int
+sensing(): bool
+start_sensing(): int
+stop_sensing(): int
+toggle_sensing(): int
-set_tracer(tracer:string="no
   t tracing on/on-hoolly une
```

## nsor

```
rnel/debug/tracing/
acing_on
enter/
xit/
ace_pipe
```

= current\_tracer

or()
or &

p"): void
igned short