



Juan Rojas <rojas70@gmail.com>

Controller

RamirezAlpizarIxchel <ixchel.ramiresuarupi-saru@aist.go.jp>

Mon, Sep 28, 2015 at 4:28 PM

To: Juan Rojas <rojas70@gmail.com>

Cc: 原田研介 <kensuke.harada@aist.go.jp>

Hello Juan,

I am sorry for the late reply.

As my position controller is part of a package with other programs I made that depend on other packages I made, I change it to be standalone so you do not need any other packages.

The problem is that because of what I am doing now, in this laptop I had to installed Ros Hydro, and my baxter packages are all configured with Ros Groovy so I cannot check if they will compile without errors (I checked the files, there should be no problem)

I just need one file that I could not find in the laptop I brought but I think it may be in the USB I have at home.

I will send you the package files tomorrow, as well as how you can use it with the force controller.

Best Regards,

Ixchel G. RAMIREZ ALPIZAR

Postdoctoral Researcher

Manipulation Research Group,

Intelligent Systems Research Institute,

National Institute of Advanced Industrial Science and Technology (AIST)

E-mail: ixchel.ramiresuarupi-saru@aist.go.jp

From: Juan Rojas <rojas70@gmail.com>

Sent: Thursday, September 24, 2015 3:41

To: RamirezAlpizarIxchel

Cc: 原田研介

Subject: Re: Controller

Ixchel,

I'll start testing your code today (though next week I will be in IROS).

I would appreciate if you could also send me the position control loop code that you mentioned in your email as an additional tool or code to consider.

Thanks for your support.

Juan

Dr. Juan Rojas
GDUT Associate Research Professor
School of Mechatronics (Electro-Mechanical Eng)
GuangDong University of Technology
<http://ss.sysu.edu.cn/~Rojas>



Dr. Juan Rojas. SYSU Assistant Professor.

Dr. Juan Rojas is an Assistant Professor in Robotics at the School of Software in Sun Yat-Sen University. His current reserach interests lie in:

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<http://jdgctxy.gdut.edu.cn/>

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