



CINESTAR[®]

BUILD MANUAL

SAFETY WARNING AND DISCLAIMER

Thank you for purchasing the CineStar 8 by FreeFly Systems. The CineStar 8 is not a toy and should be operated with extreme care, as improper operation can cause serious personal injury and damage to property. The CineStar 8 should not be flown over or around people, power lines or other aircraft. It is important to always check the CineStar 8 and its components prior to operation. Always maintain a safe distance from the CineStar 8 when in use. Never attempt to touch the CineStar 8 when the propellers are moving. As with any multi-rotor helicopter, the CineStar 8 is a complex and technical machine. Novice pilots should invest sufficient time on a flight simulator and seek training from an experienced pilot prior to operation. A flight simulator is no substitute for training with an experienced pilot, particularly when it comes to learning how to safely operate the CineStar 8. Novice pilots should never fly without the supervision of an experienced pilot.

Always remove the props when you are making a change to the configuration of the CineStar 8. Always test the CineStar 8 with the props removed to make sure that the motors are spinning in the correct direction and that the motor assignment is correct with respect to your flight control board. If you have either of these wrong, the CineStar 8 will be uncontrollable and dangerous.

FreeFly Systems disclaims all warranties, whether express or implied, including but not limited to the implied warranties of merchantability and fitness for a particular purpose. FreeFly Systems does not assume any liability, whether direct or indirect, from the use of the CineStar 8. FreeFly Systems shall not be liable for any direct, indirect, special, incidental, punitive, contingent or consequential damages to persons or property caused by the CineStar 8. In no event shall FreeFly Systems be liable for personal injury up to and including death.

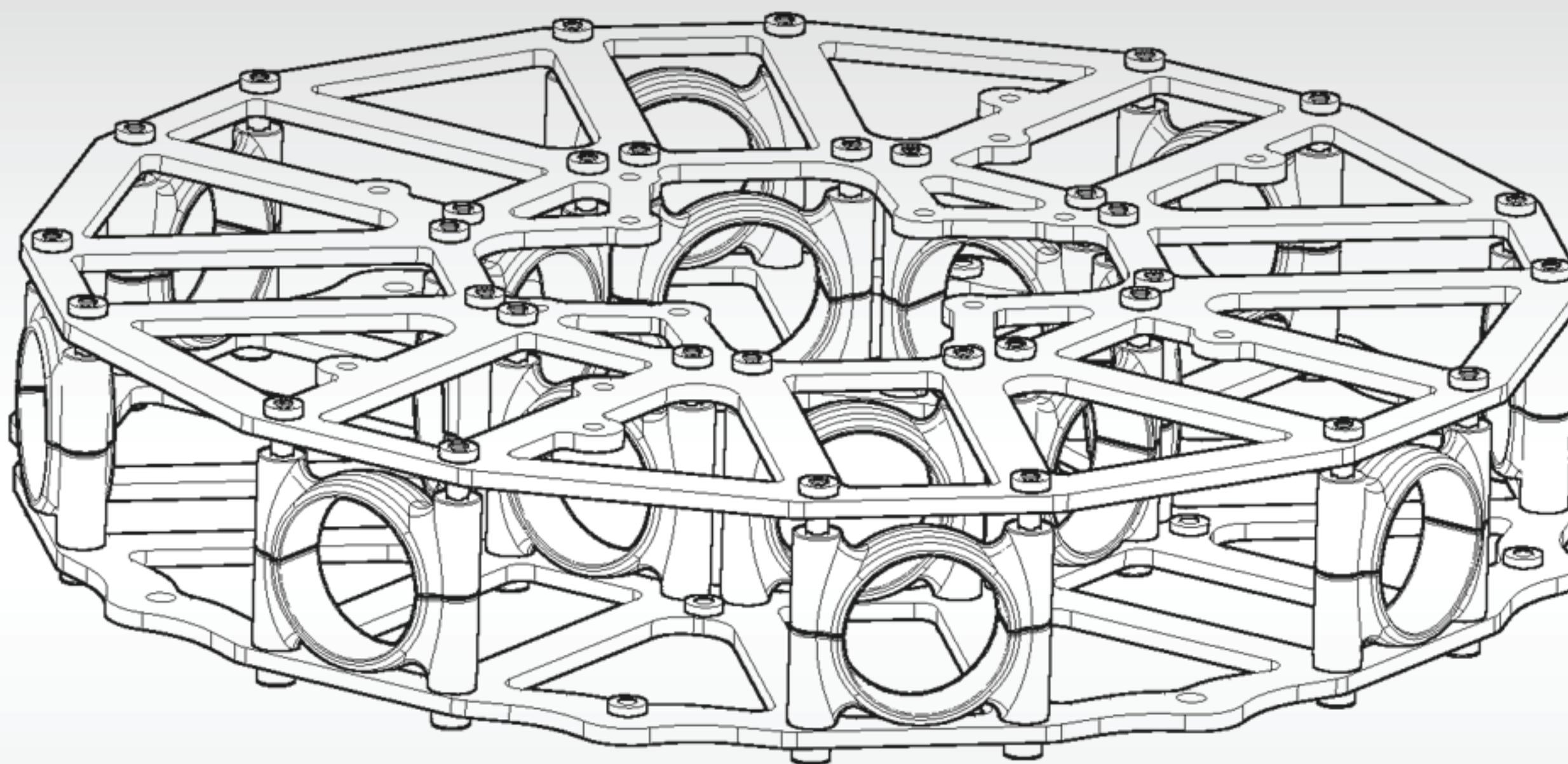
It is your responsibility to perform a full system check of the CineStar 8 prior to flight. It is your responsibility to learn how to safely operate the CineStar 8 and to adhere to all applicable rules and regulations. Fly at your own risk.

TECHNICAL FOREWORD

Below are a few tips from the designers to aid in assembly, flight and maintenance of the CineStar 8. The CineStar 8 is designed to be a professional heavy lift multi-rotor helicopter. As such, it is very important to take your time and assemble with care.

Here are a few important tips in assembling the CineStar 8:

- + Always use threadlocker on any screw going into either aluminum or steel. This will ensure that the screws will not come loose even under the vibrations encountered in flight. We recommend using “Loctite 222MS Low Strength Purple Threadlocker,” as it is intended for the small screw sizes found on the CineStar 8. It is important to use this product or a similar strength screw retainer adhesive, as stronger variations, such as Green or Red Loctite, are too strong for the small screw sizes used on the CineStar 8 and may make disassembly for repair/service impossible.
- + Be careful working with the carbon fiber booms and frame. We try to make sure that the edges on the carbon fiber are smooth and safe, but carbon can still have sharp edges which can cut your fingers and/or chafe delicate electronic wires. Any time a wire has to make a bend around the carbon fiber booms or frame, we recommend using some kind of protective sleeve (e.g., shrink tubing, nylon braid, etc.), so that the vibrations from the motors will not cause the wire to chafe on the edge of the carbon fiber. Carbon fiber is also conductive, so it is very important to make sure that all flight components are appropriately insulated.
- + Always remove the props when you are making a change to the configuration of the CineStar 8. We always recommend first testing the CineStar 8 with the props removed to make sure that the motors are spinning in the correct direction and that the motor assignment is correct with respect to your flight control board. If you have either of these wrong, the CineStar 8 will be uncontrollable and dangerous.
- + Always install your selected flight control system in accordance with the manufacturer’s instructions.

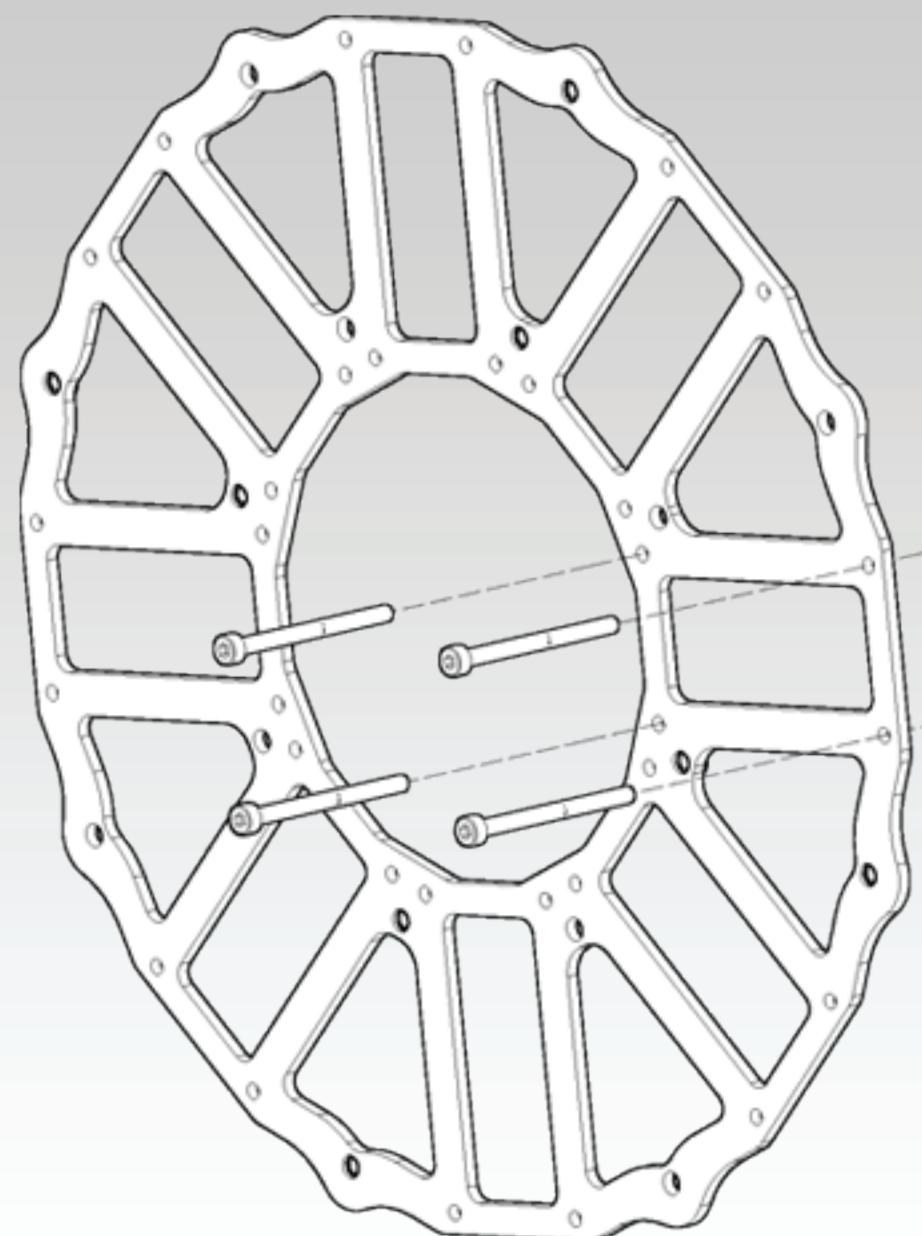


1

MAIN FRAME
MF1.1 - MF1.5

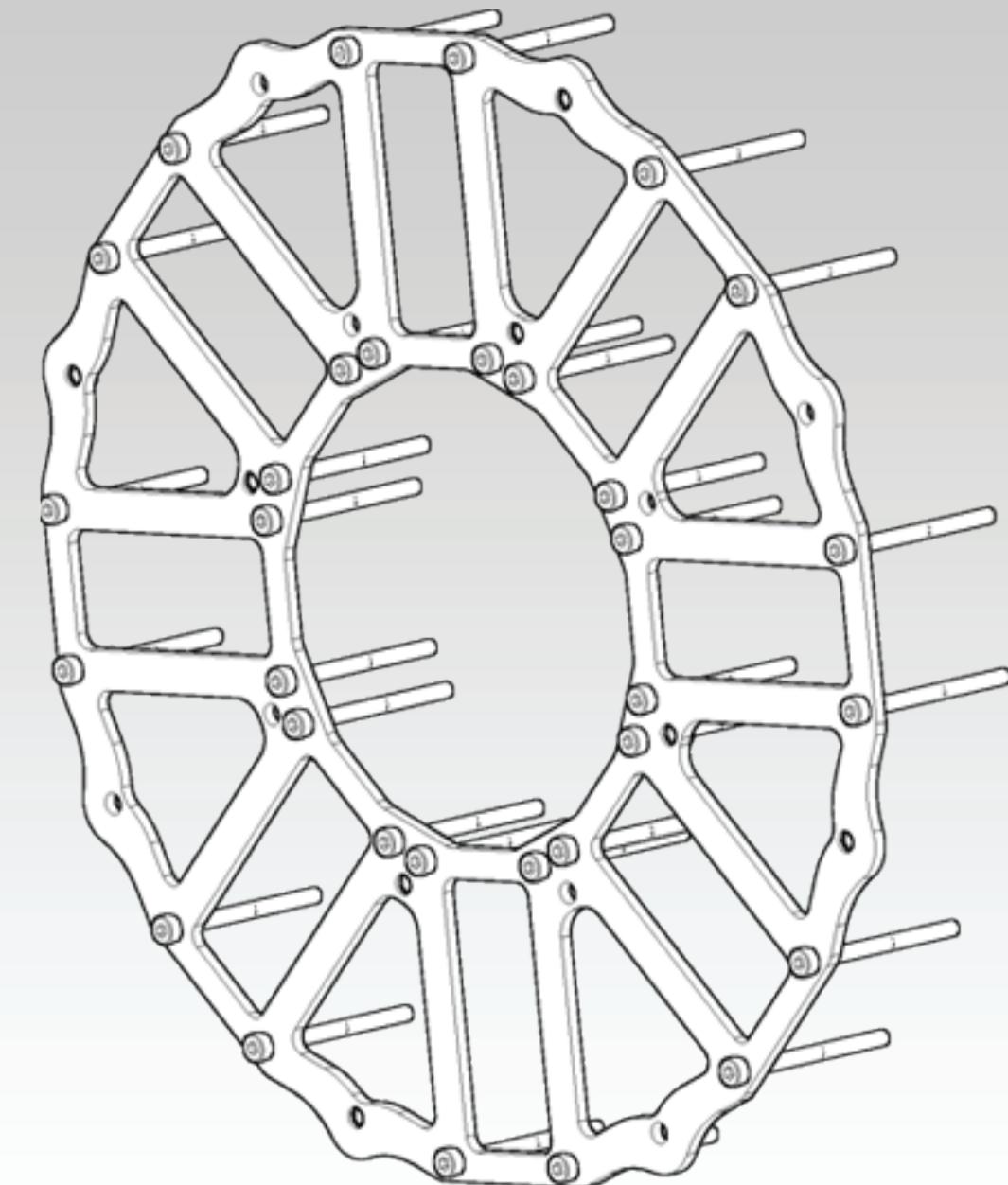
1

MF1.1 Install thirty-two (32) M3x40mm screws through the bottom frame plate. Note that the press nuts are on the backside of the bottom frame plate in the current view.



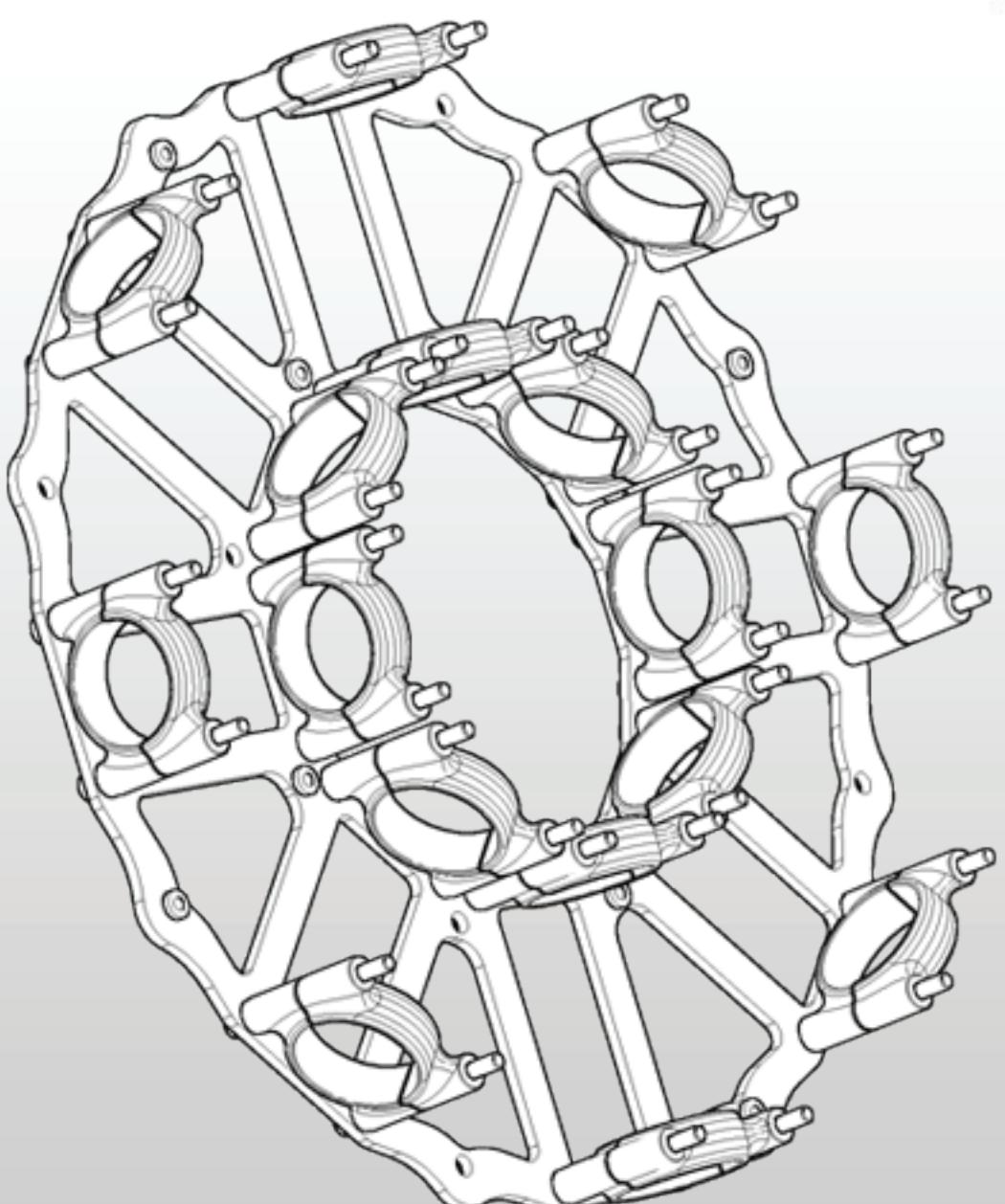
2

MF1.2 All thirty-two (32) M3x40mm screws installed.



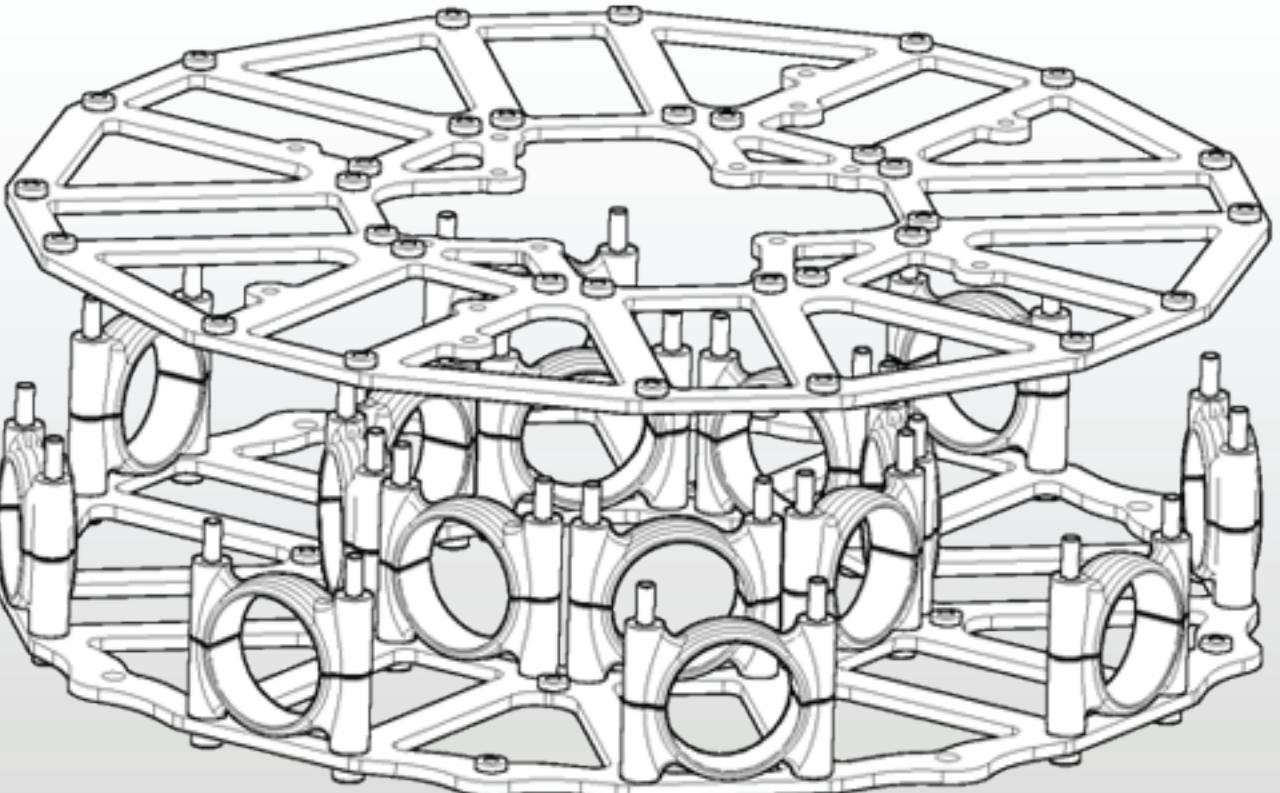
3

MF1.3 Install thirty-two (32) clamp halves onto the M3x40 screws.

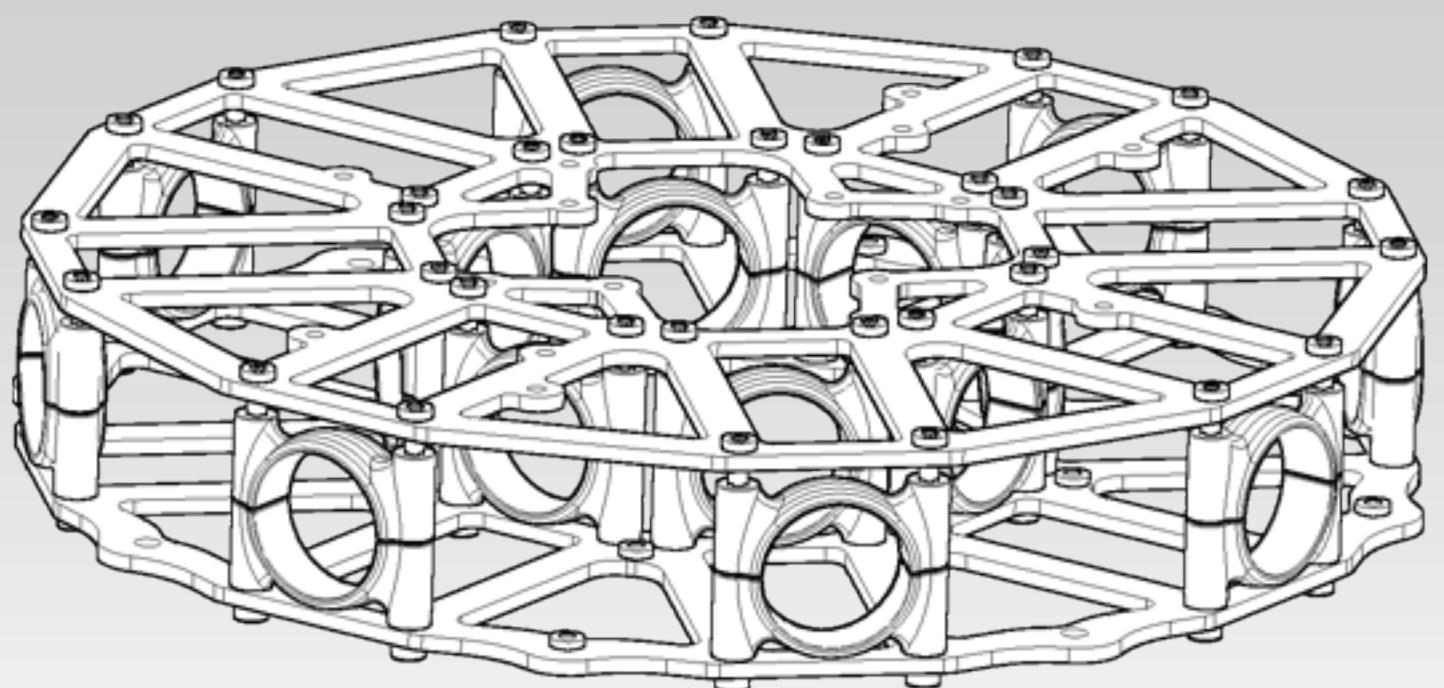


4

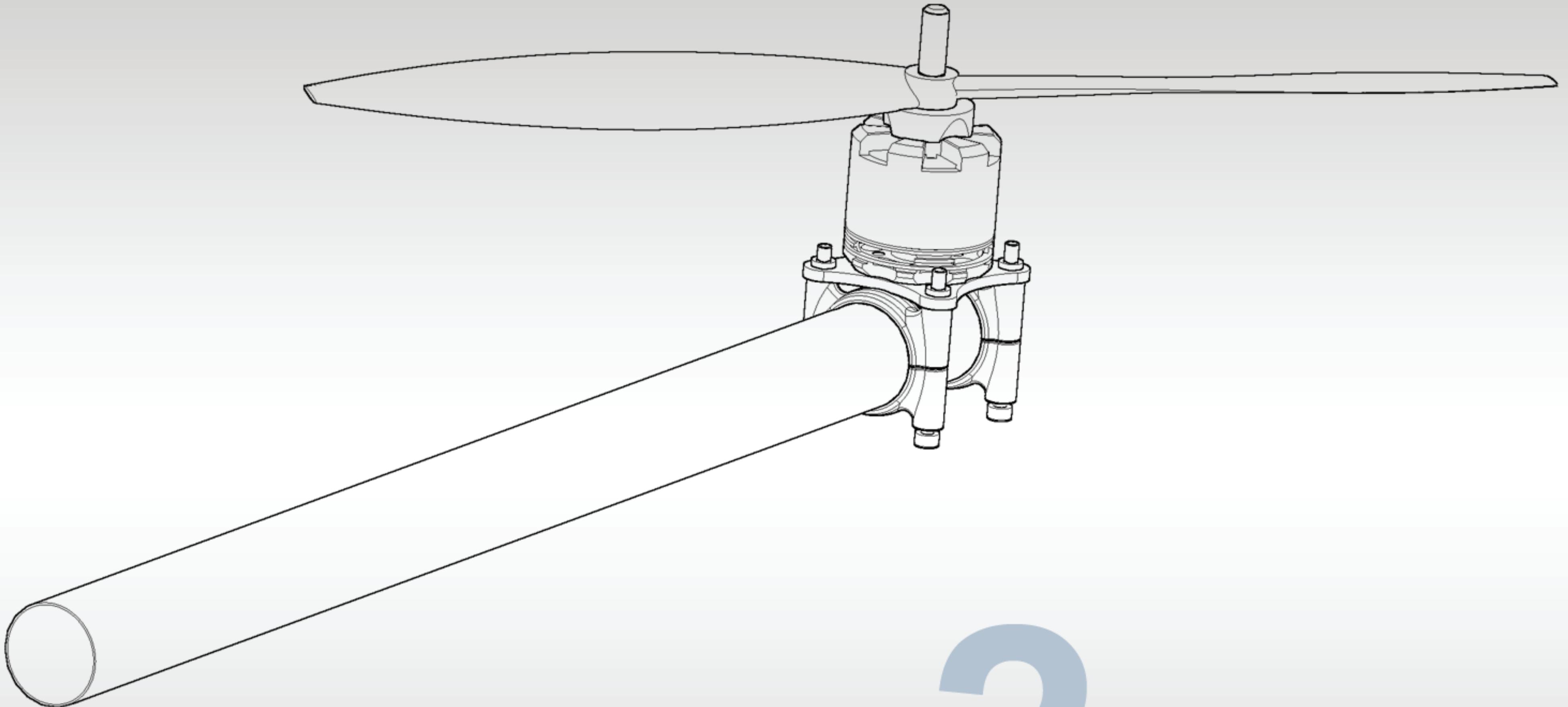
MF1.4 Thread the thirty-two (32) M3x40mm screws into the top plate just far enough so they are flush with the edge of the press nuts. Do not fully tighten, as we will need the clamps loose in order to insert the booms.



5



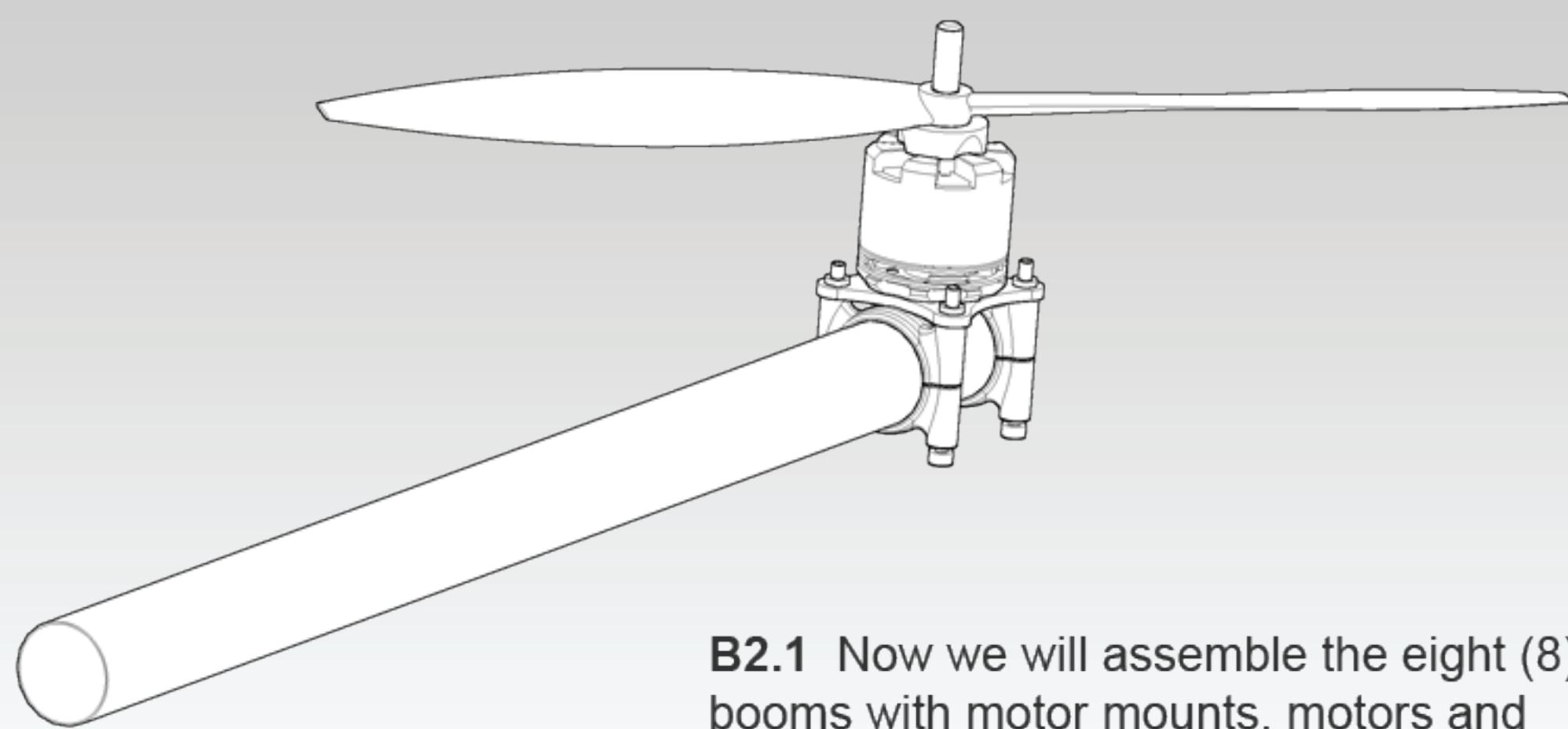
MF1.5 Assembled main frame.



2

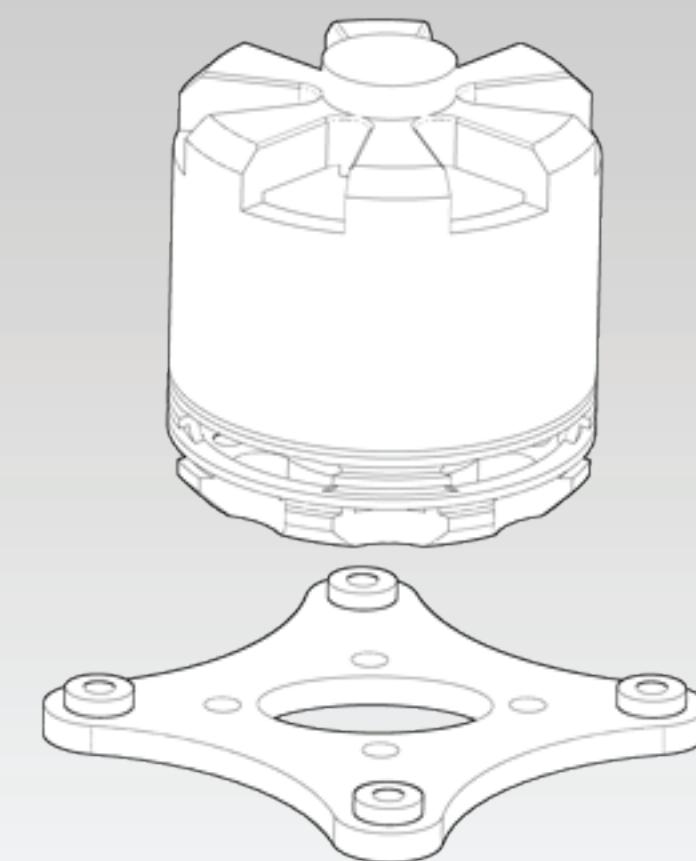
BOOM
B2.1 - B2.10

1



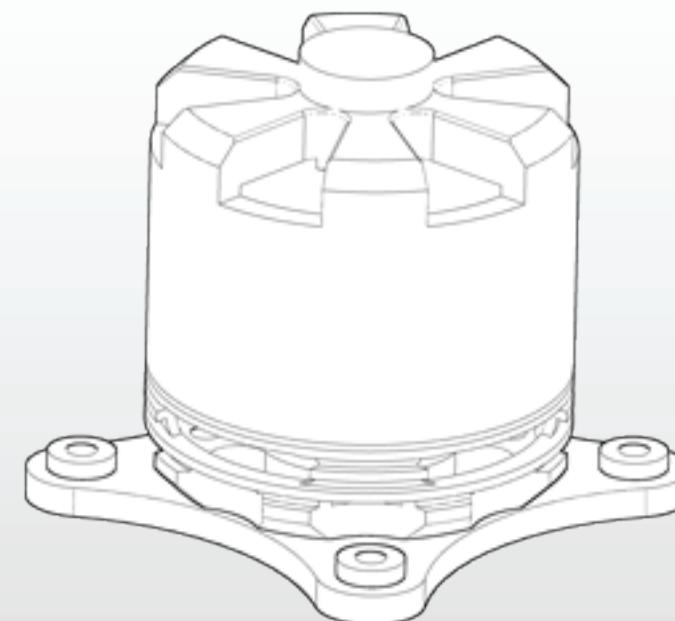
B2.1 Now we will assemble the eight (8) booms with motor mounts, motors and props.

2



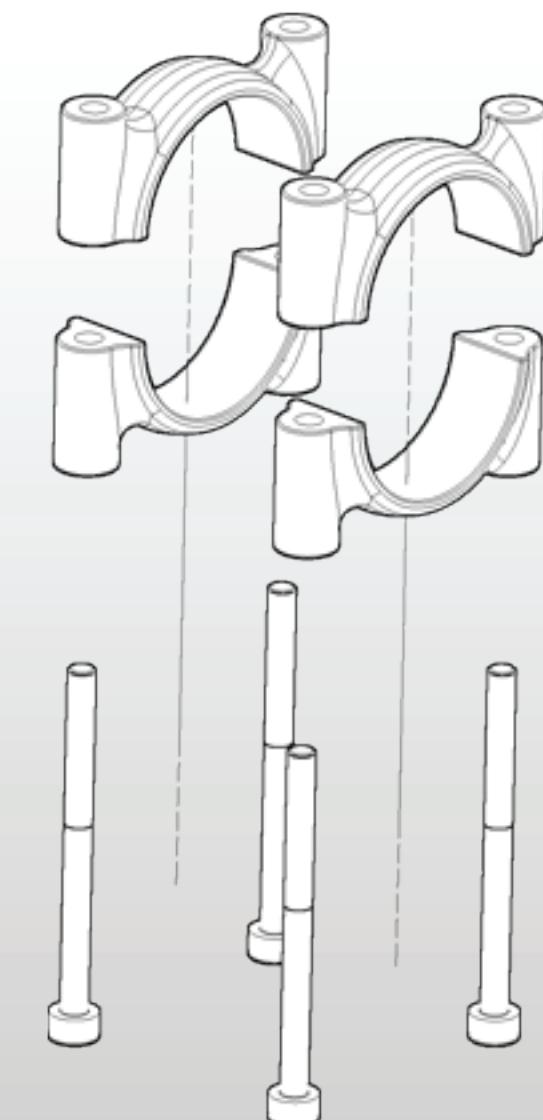
B2.2 Install motors onto the motor mount plate using M3x6 button head cap screws ("BHCS") making sure to use purple Loctite.

3



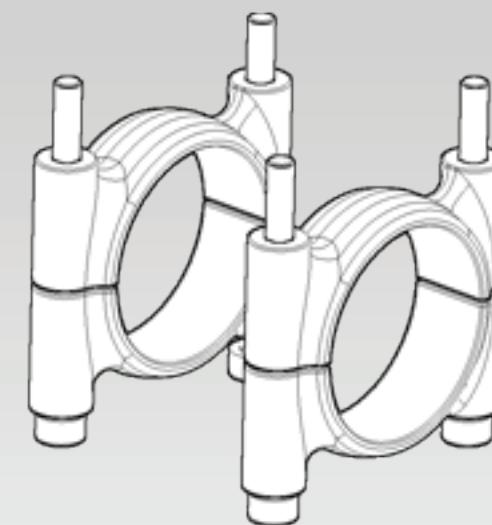
B2.3 Motor mounted to the motor mount plate.
Please observe the orientation of the press nuts.

4



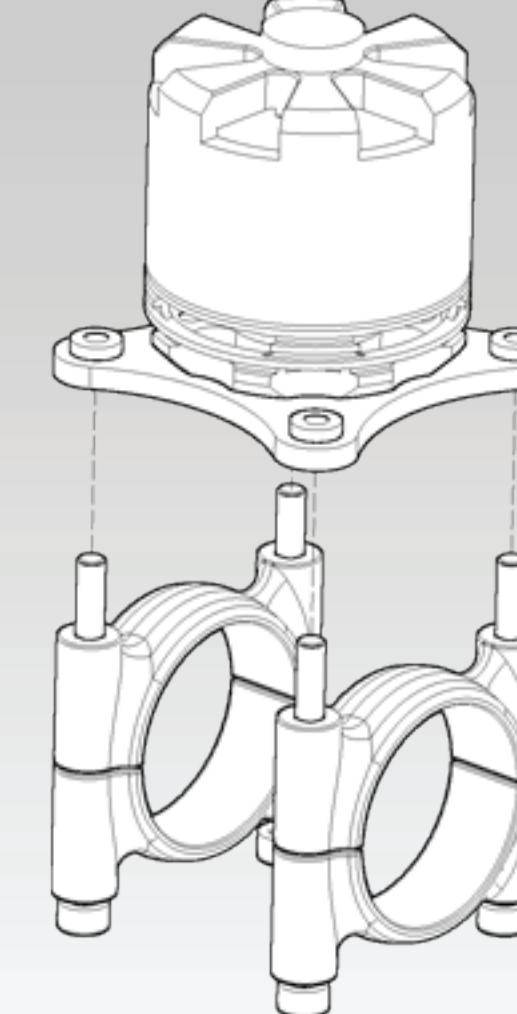
B2.4 Fit the four (4) clamp halves onto the four M3x35 screws.

5



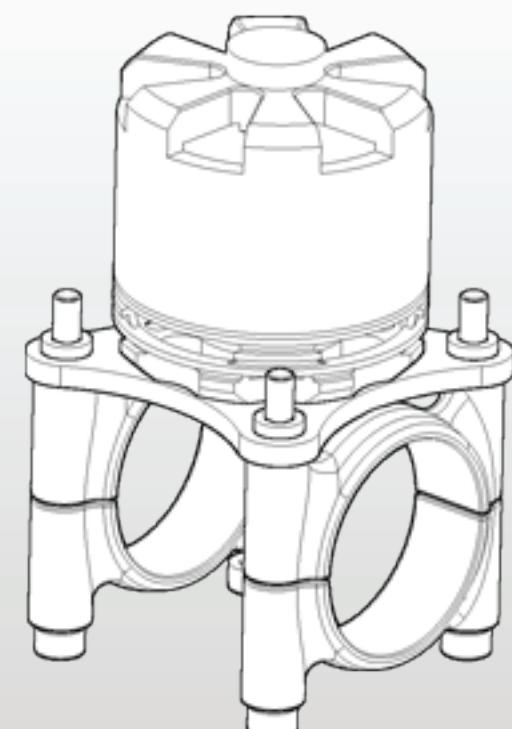
B2.5 Clamps mounted onto the M3x35 screws.

6



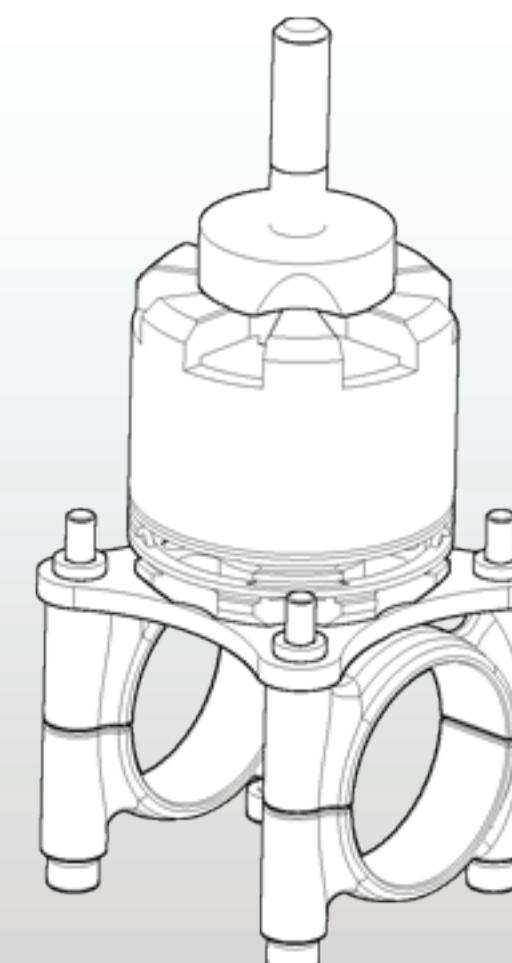
B2.6 Thread the four (4) M3x35 screws into the motor mount plate. Once again, only thread the screws until they are flush with the press nuts, as we will need the slack in the clamps to make the boom installation easier.

7



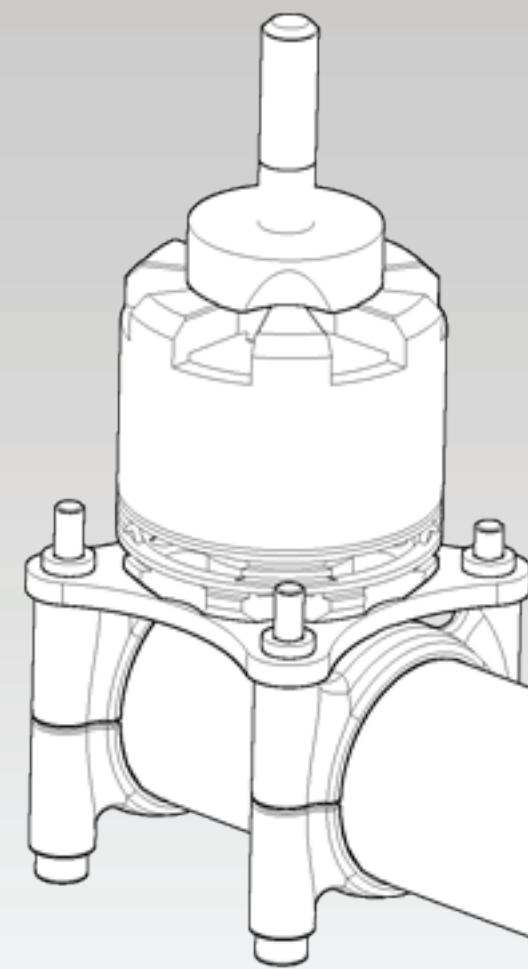
B2.7 Motor and motor mount plate installed.

8



B2.8 Install the included prop adapter onto the Quadrocopter motor.

9

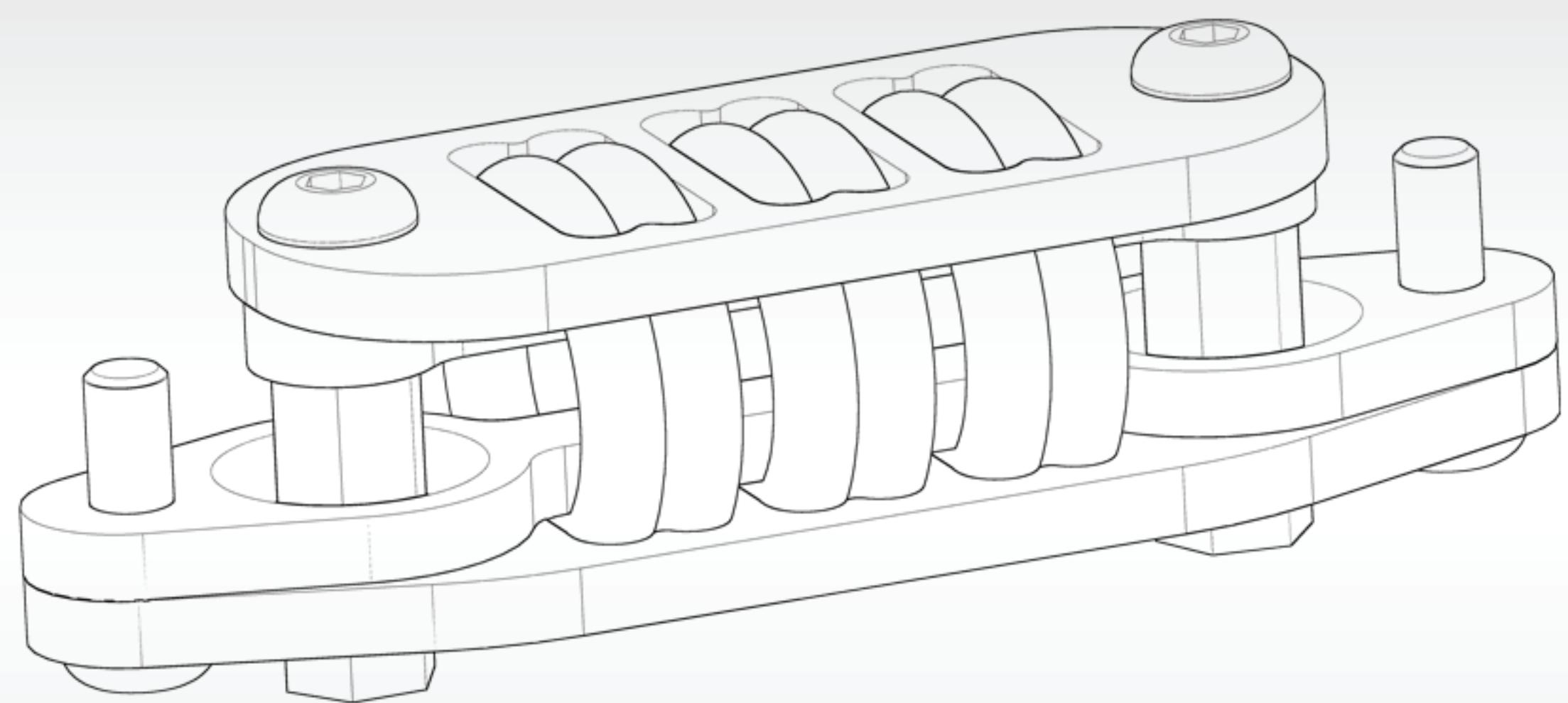


B2.9 Insert the boom into the clamps. It will take a little finessing to get the boom through the clamps, as the parts are designed to fit fairly tight. Please make sure the end of the boom is flush with the end of the clamp. Tighten the M3x35 screws to secure the boom.

10

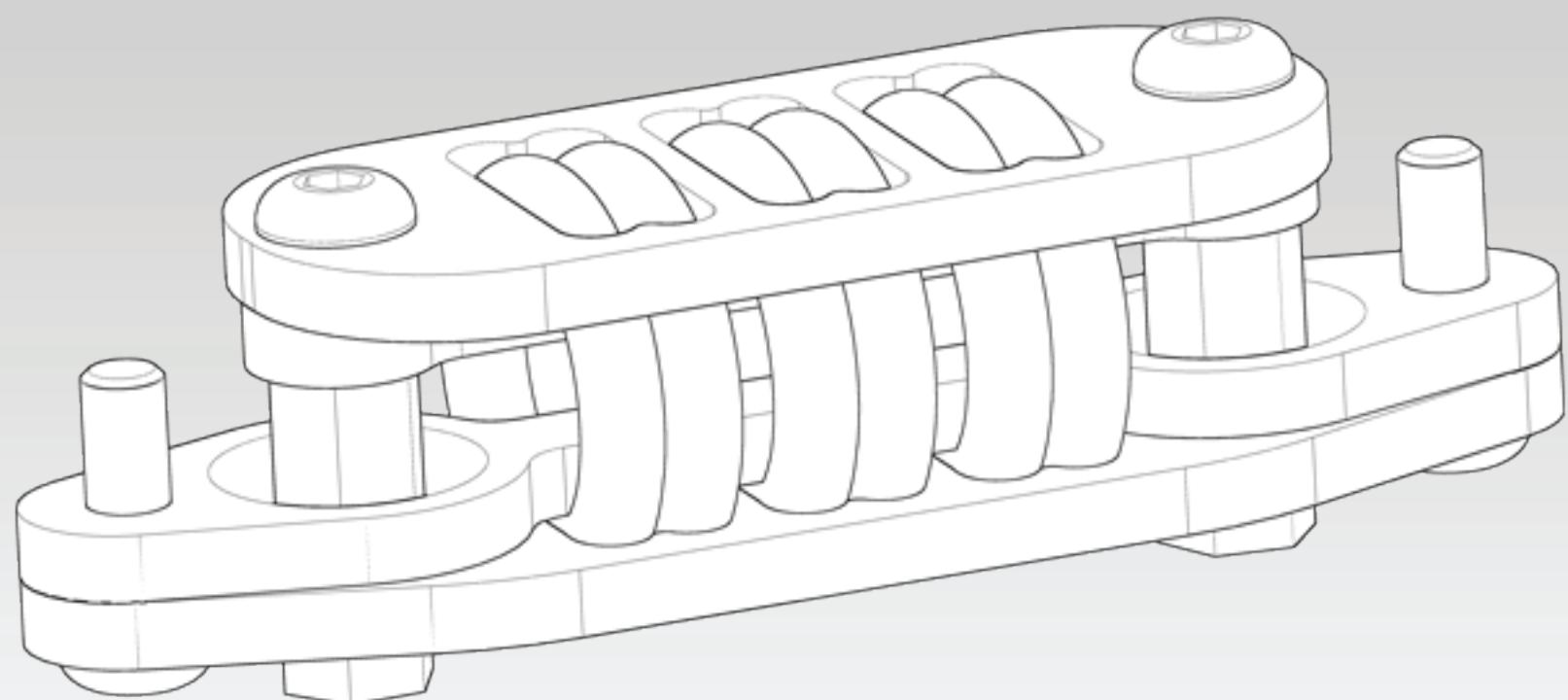


B2.10 Repeat these steps until you have all eight (8) booms fully built.



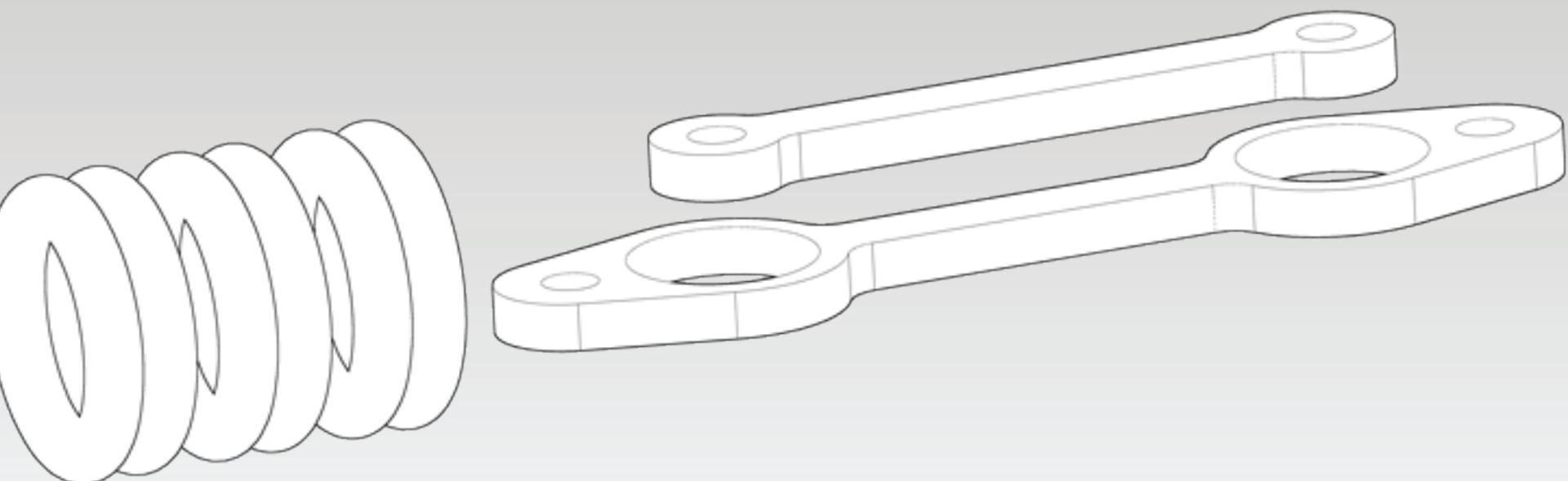
3
ISOLATOR
ISO3.1 - ISO3.13

1



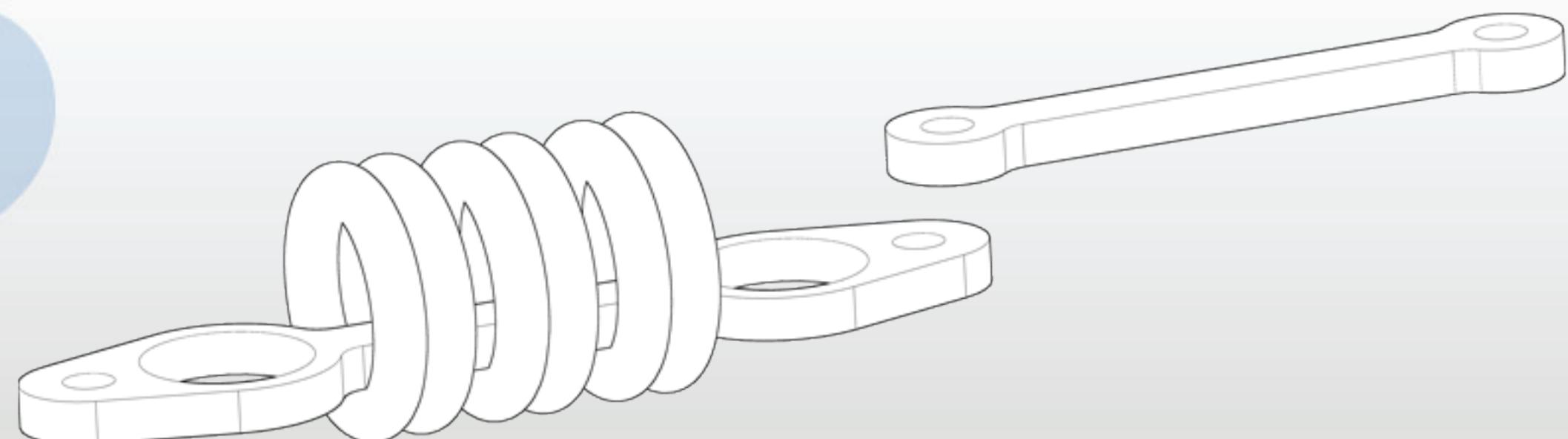
ISO3.1 We will now assemble the four (4) vibration isolators. Shown is the completed vibration isolator.

2



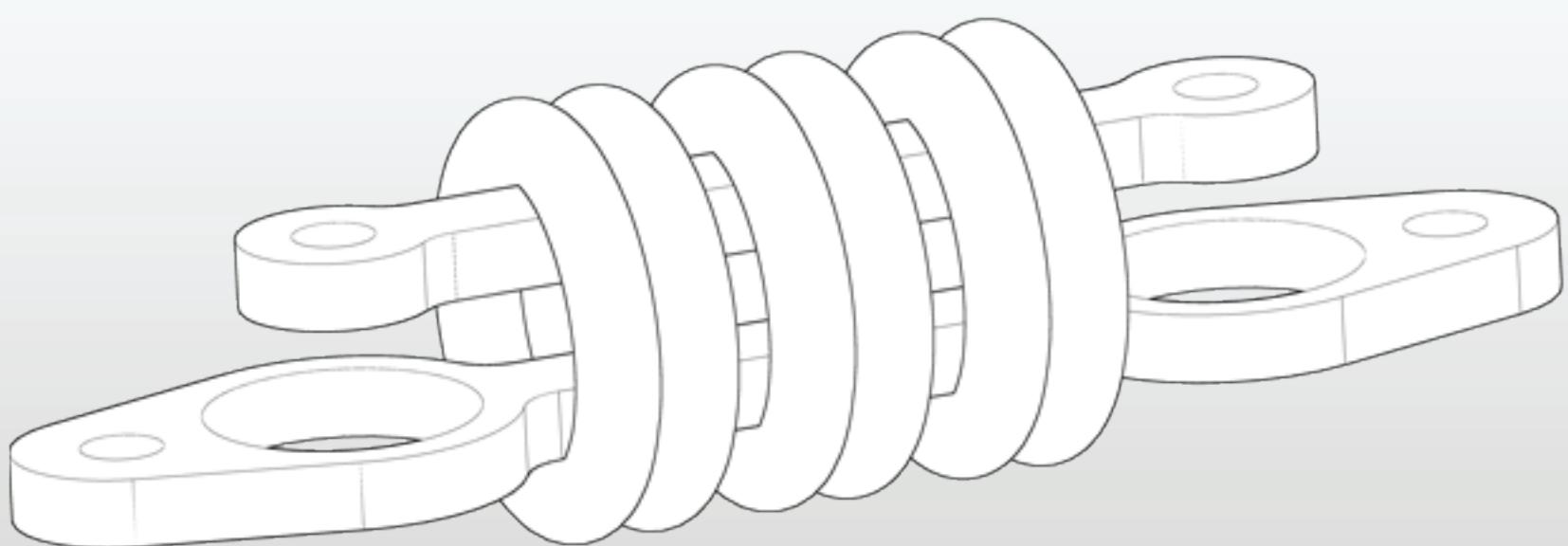
ISO3.2 Find the two (2) O-ring clamp plates.

3



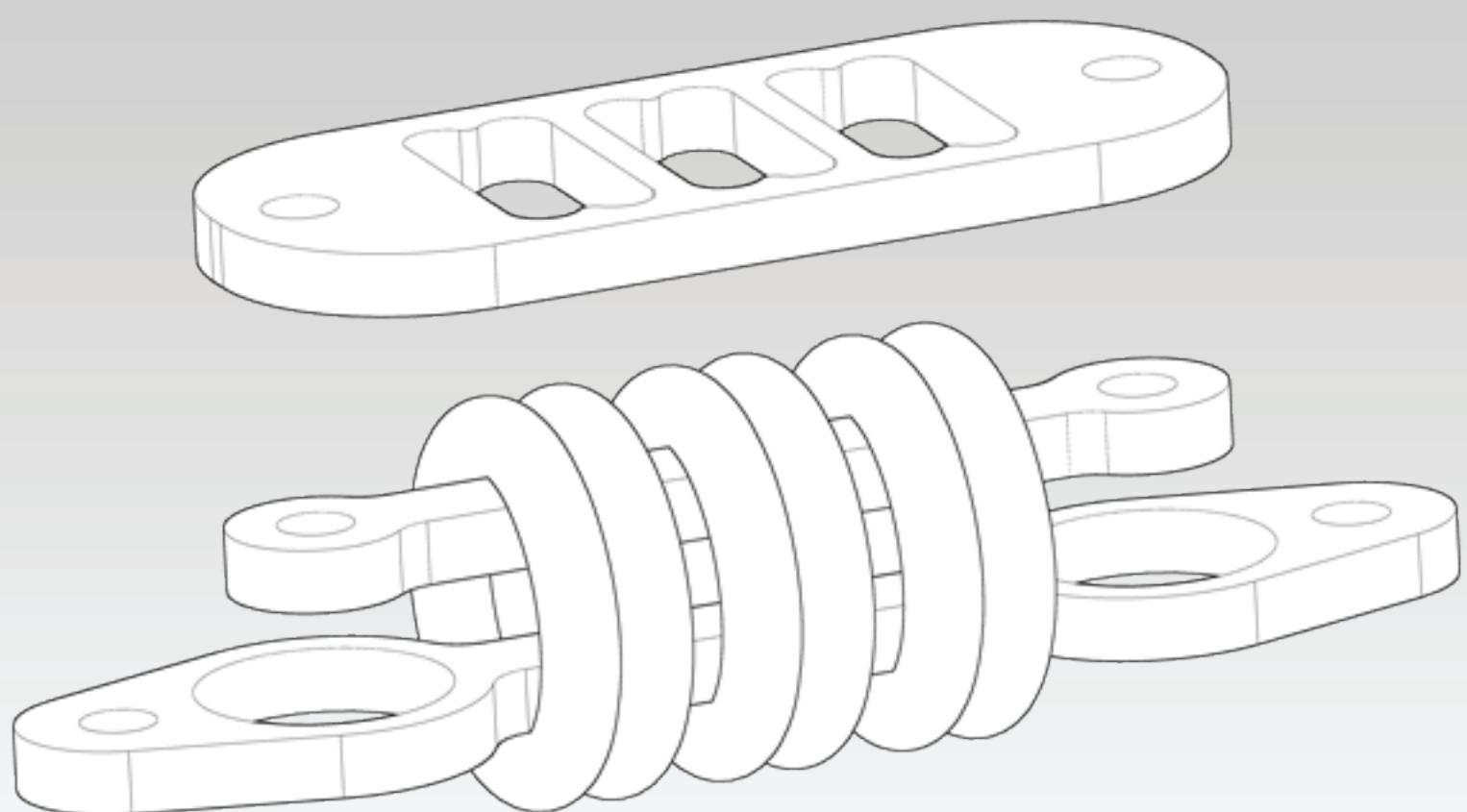
ISO3.3 Insert the bottom clamp plate through the six (6) silicone O-rings.

4



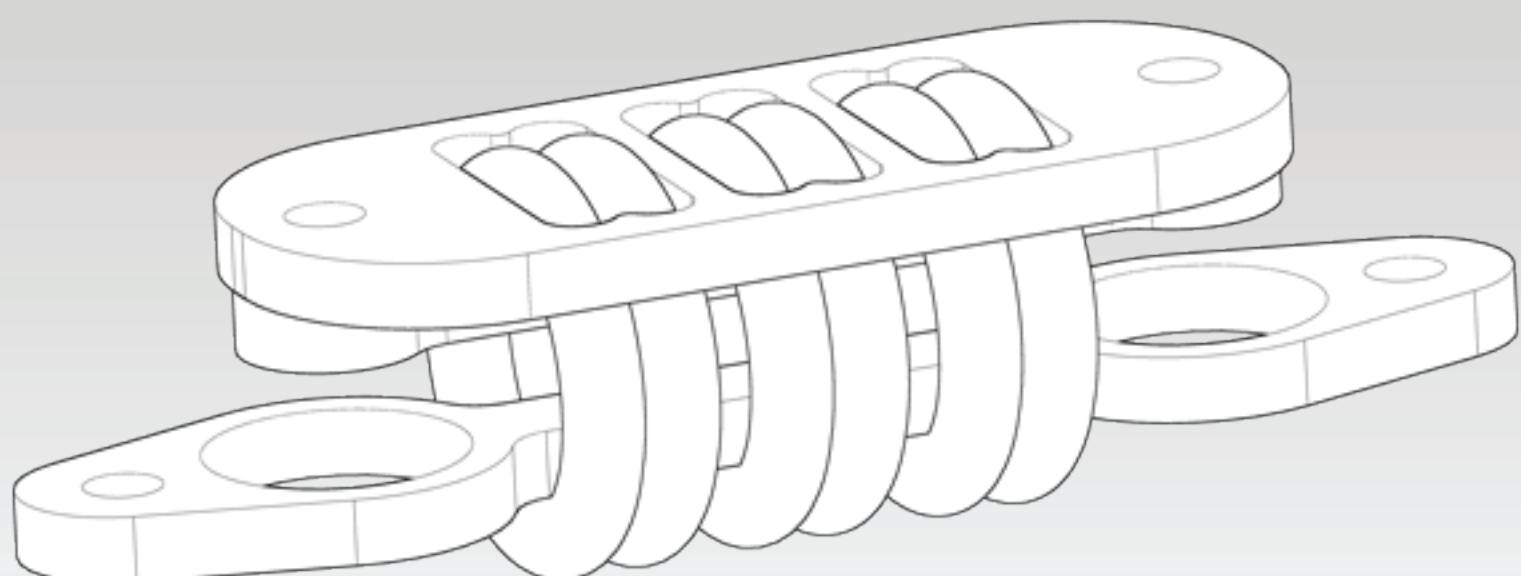
ISO3.4 Insert the top clamp plate through the six (6) silicone O-rings.

5



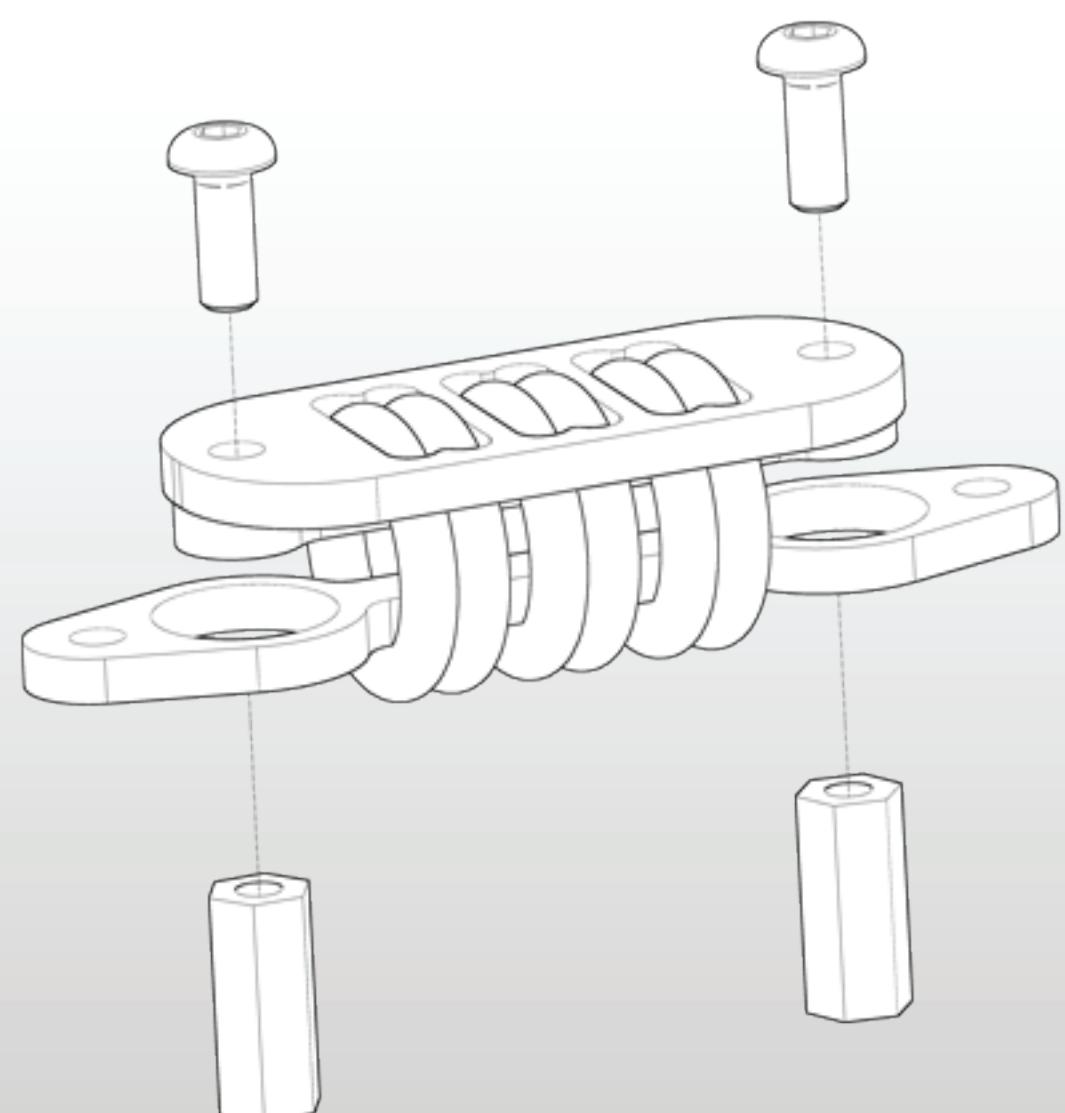
ISO3.5 Place the top isolator plate on top of the O-rings. You will need to align pairs of O-rings into the three (3) slots.

6



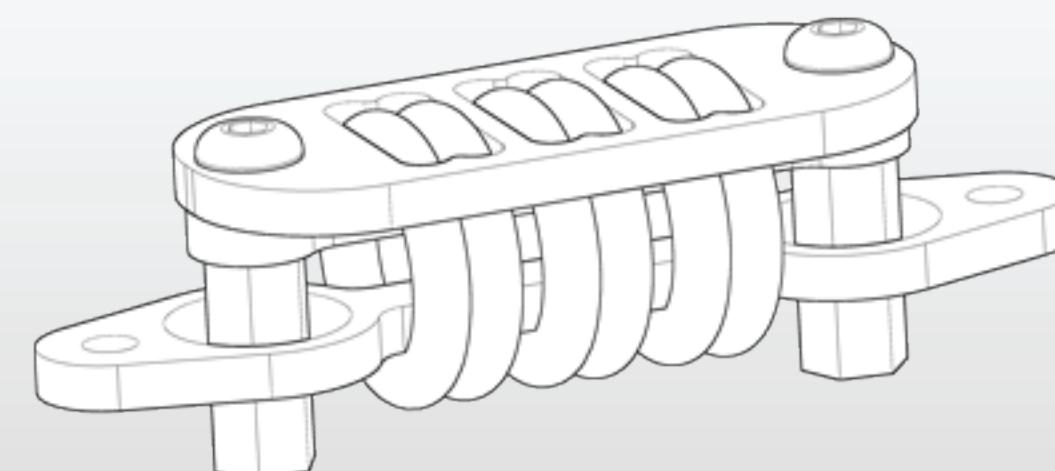
ISO3.6 Top isolator plate installed.

7



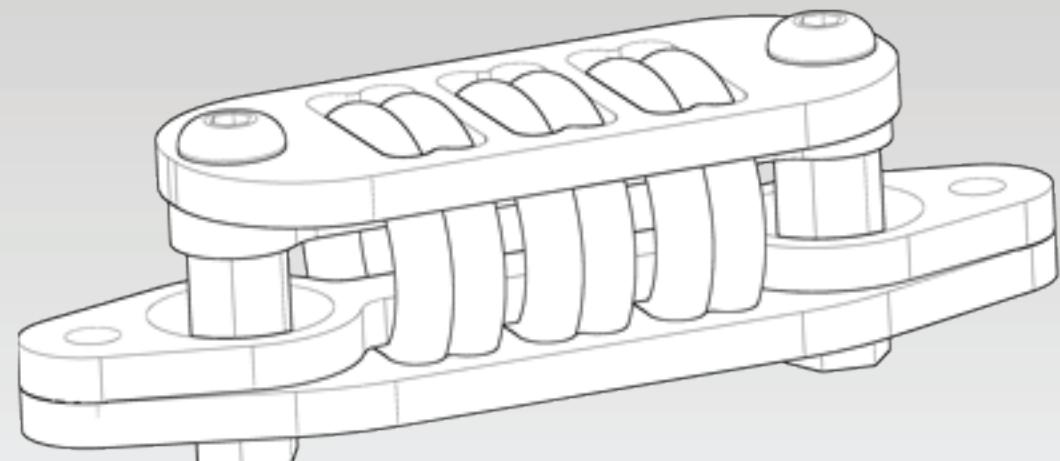
ISO3.7 Install the 12mm aluminum standoffs using M3x8 BHCS.

8



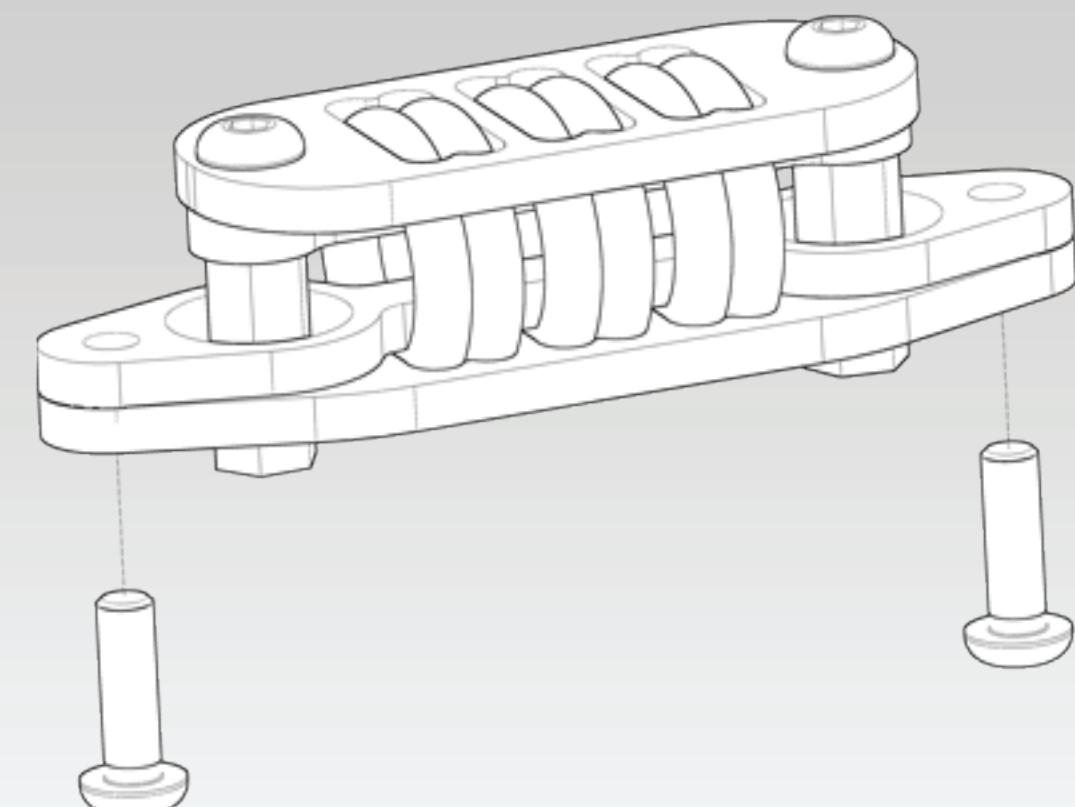
ISO3.8 12mm aluminum standoffs installed.

9



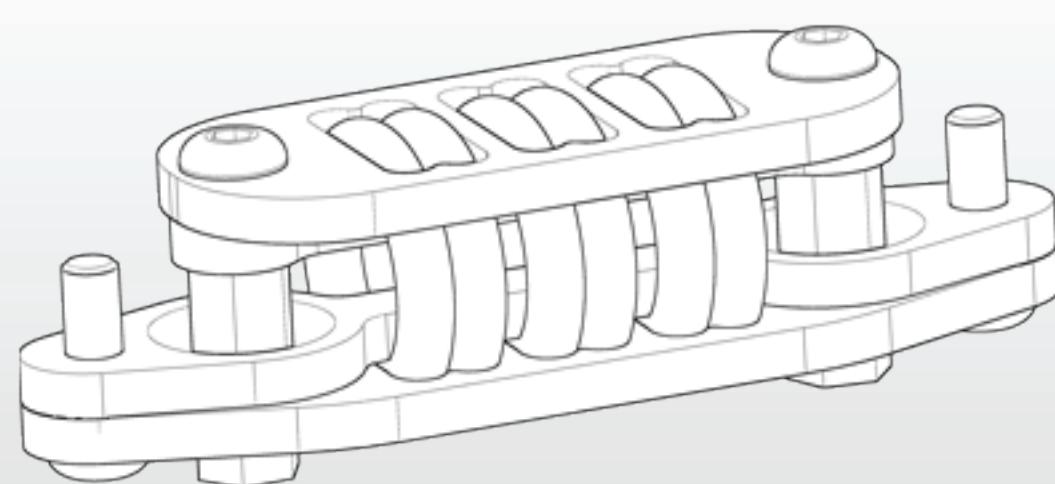
ISO3.9 Install the bottom isolator plate.

10



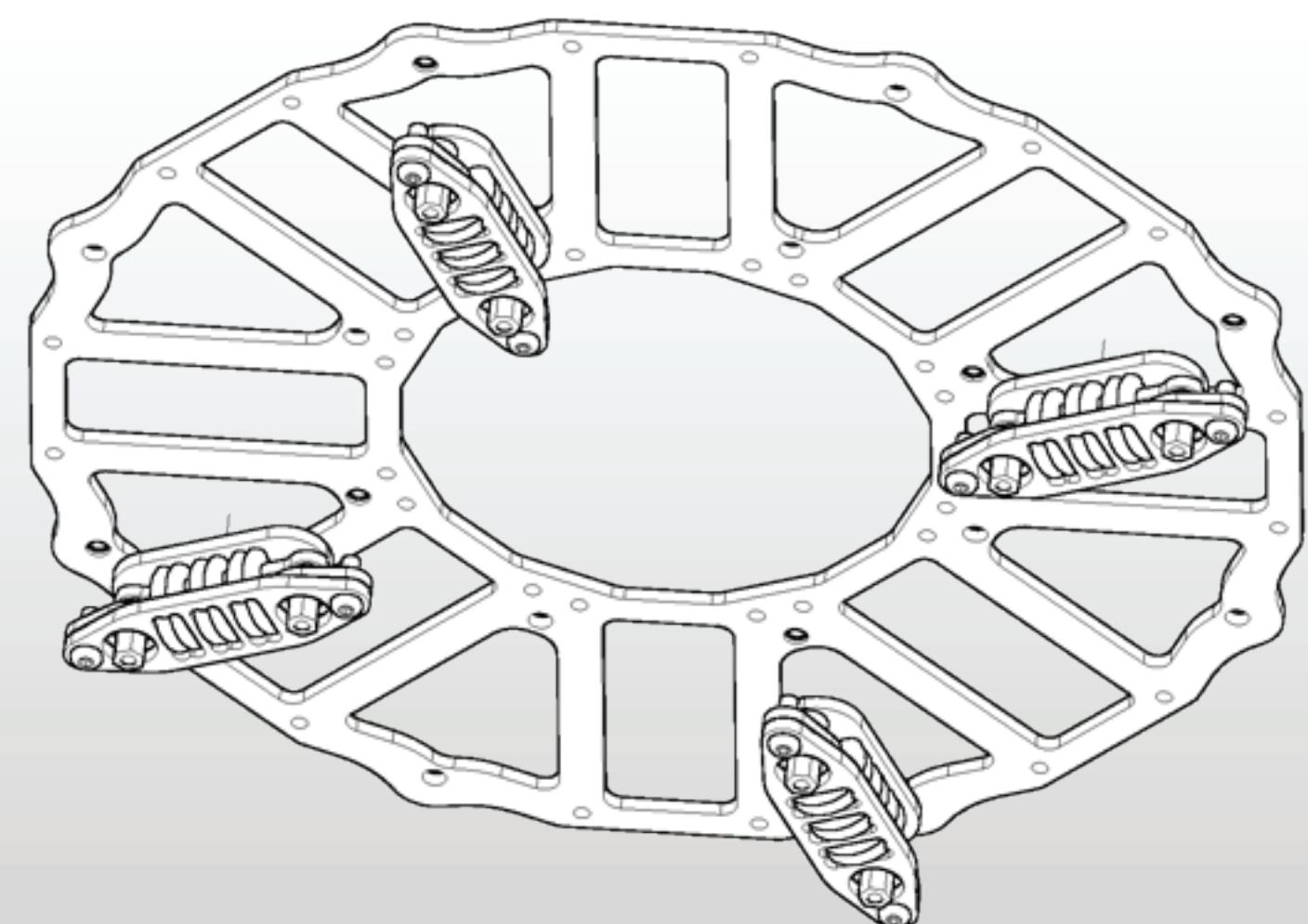
ISO3.10 Insert the M3x10 BHCS. Please note that the screws used here are M3x10 BHCS and the screws used earlier in the isolator are M3x8 BHCS.

11



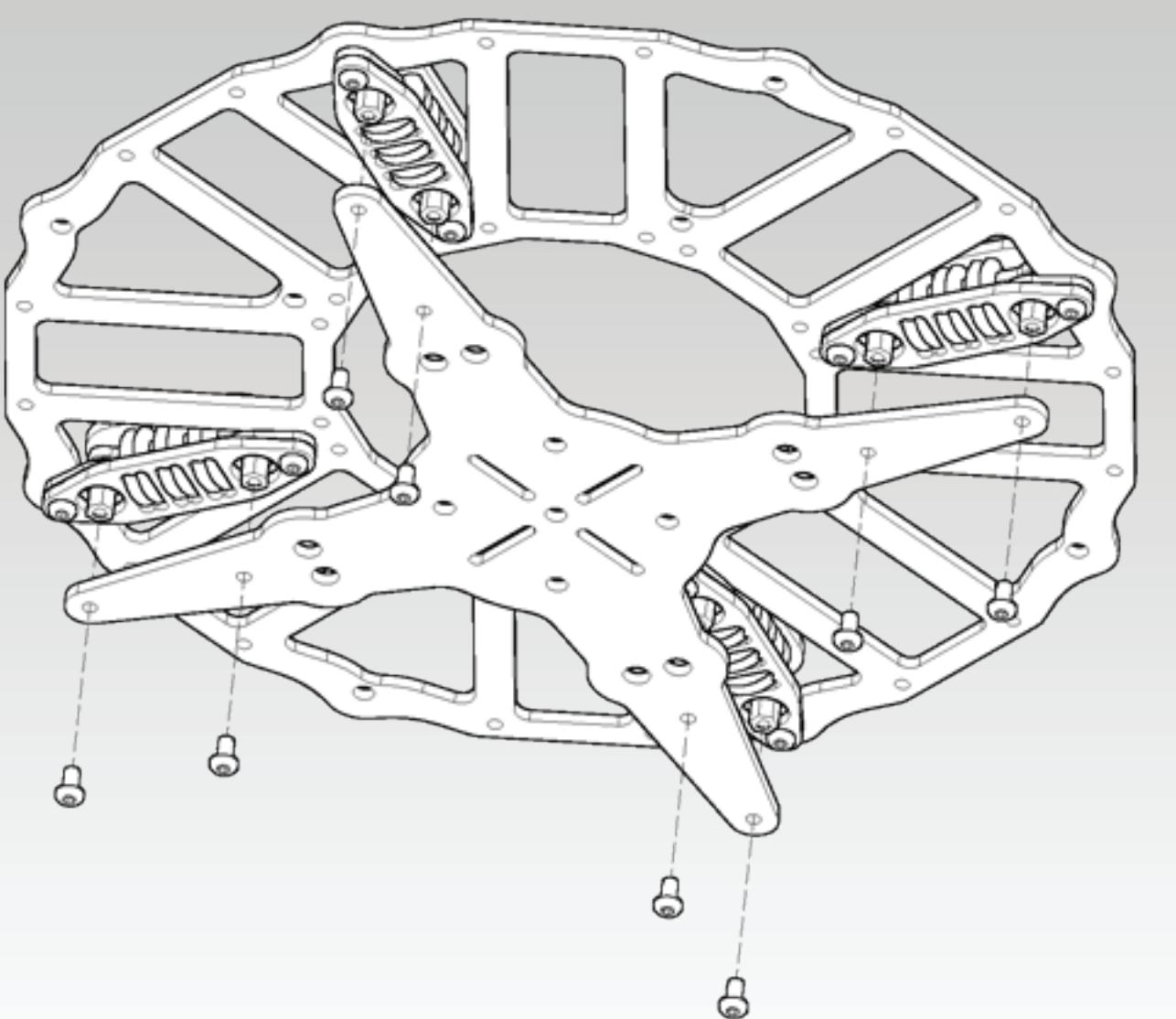
ISO3.11 M3x10 BHCS installed.

12

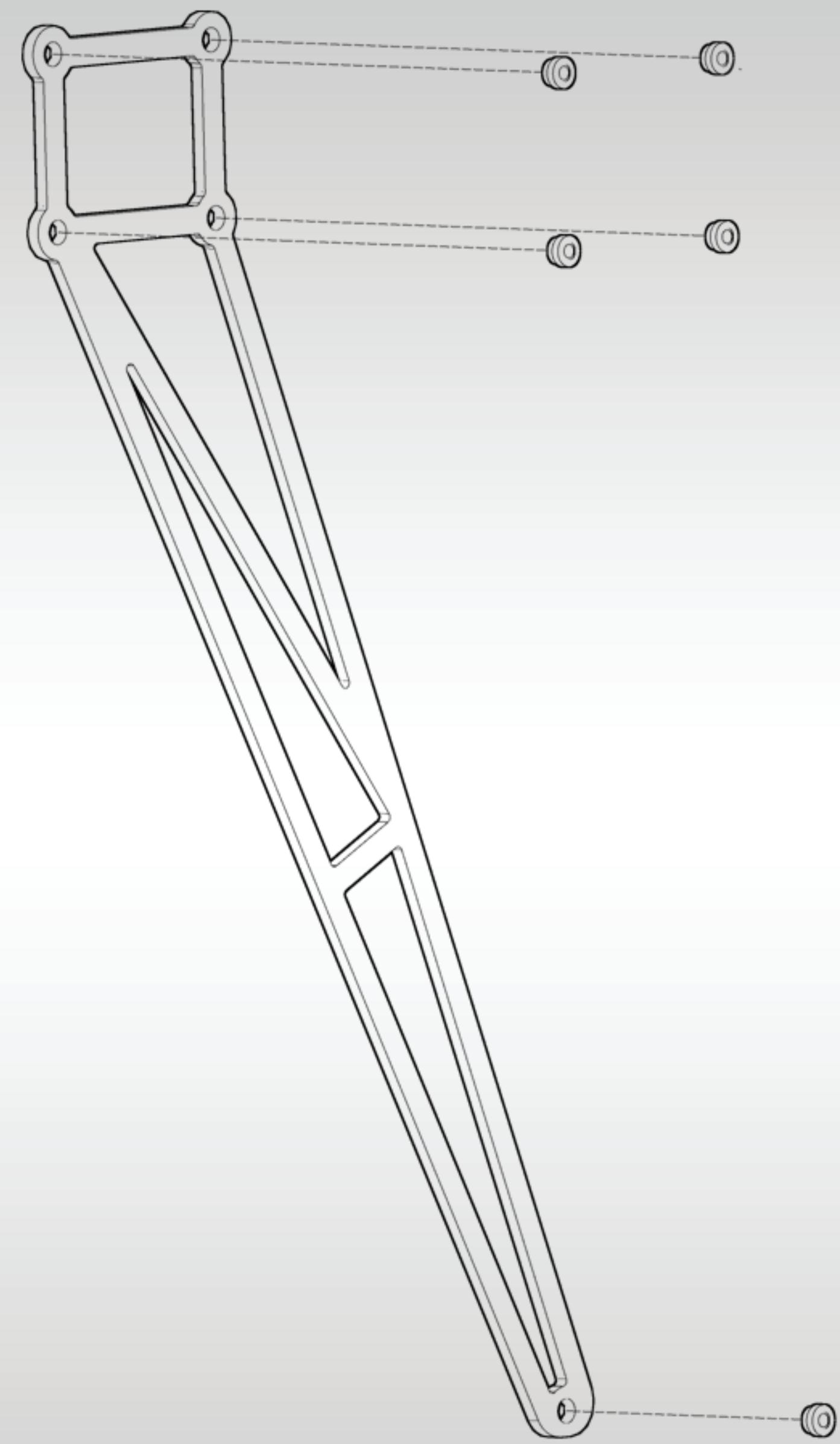


ISO3.12 Attach the four (4) completed isolators to the bottom side of the bottom frame plate by threading the M3x10 BHCS into the press nuts.

13



ISO3.13 Attach the camera mount plate to the aluminum standoffs in the vibration isolators using the eight (8) M3x6 BHCS.

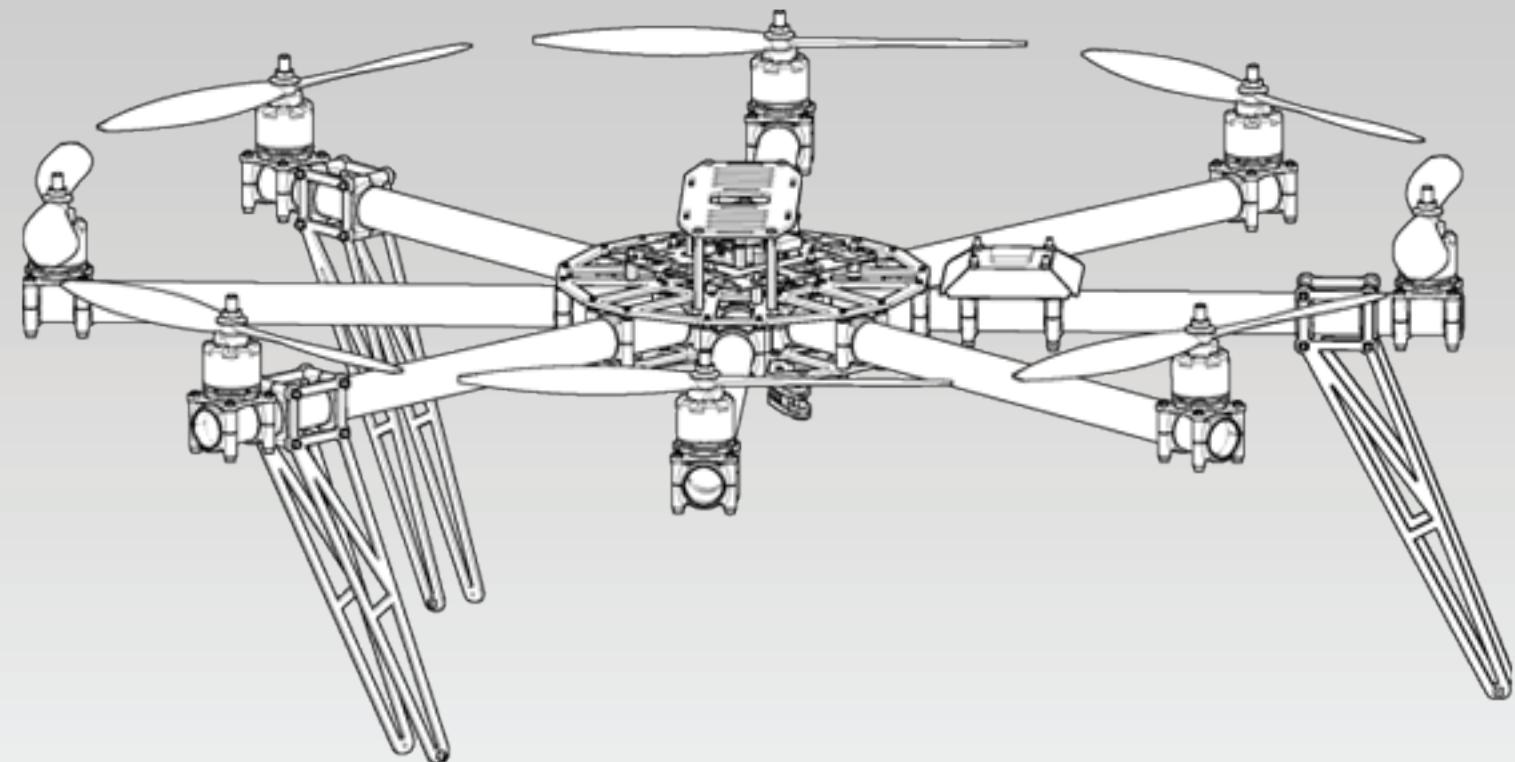


4

LANDING GEAR LEGS

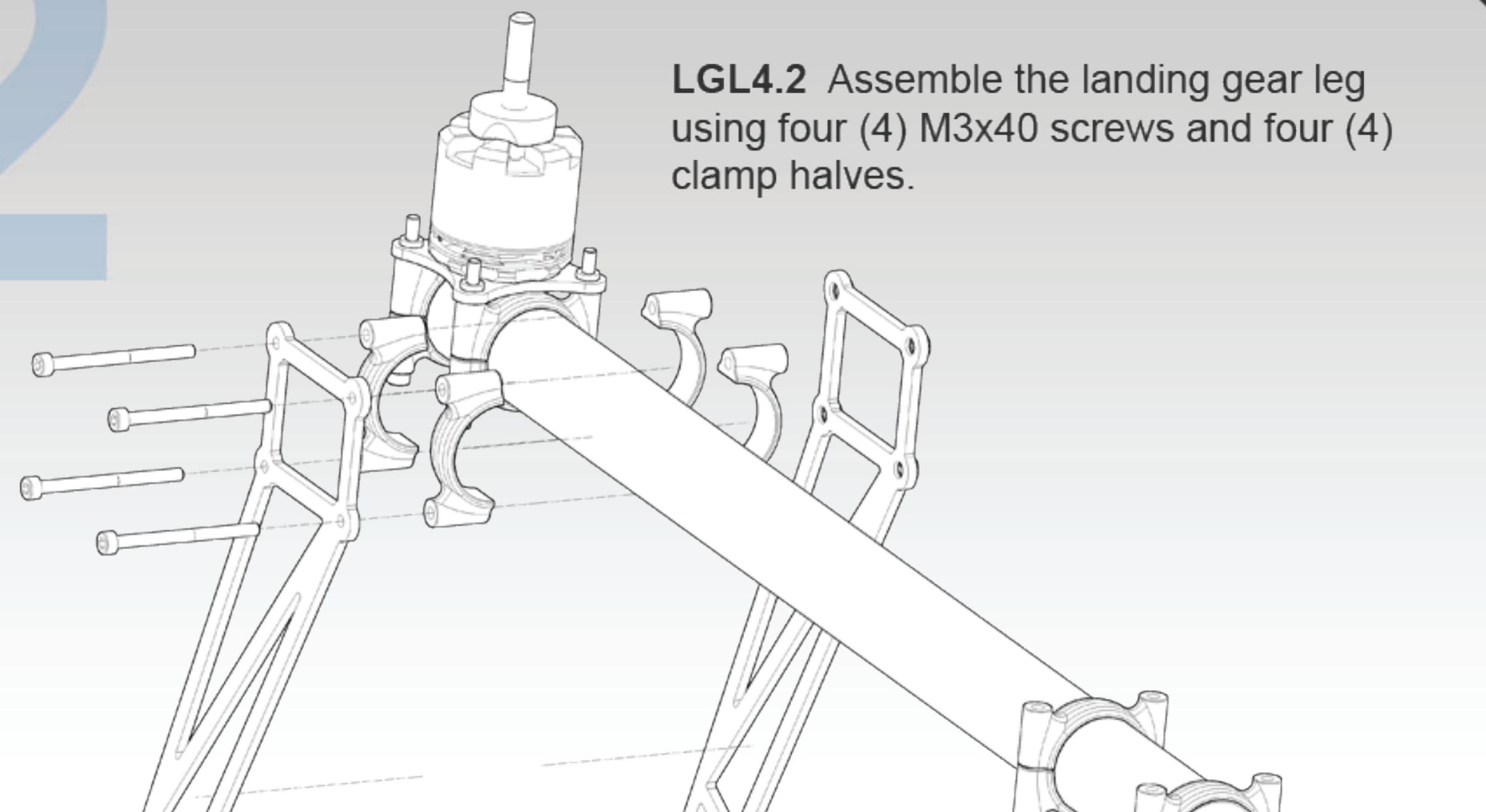
LGL4.1 - LGL4.5

1



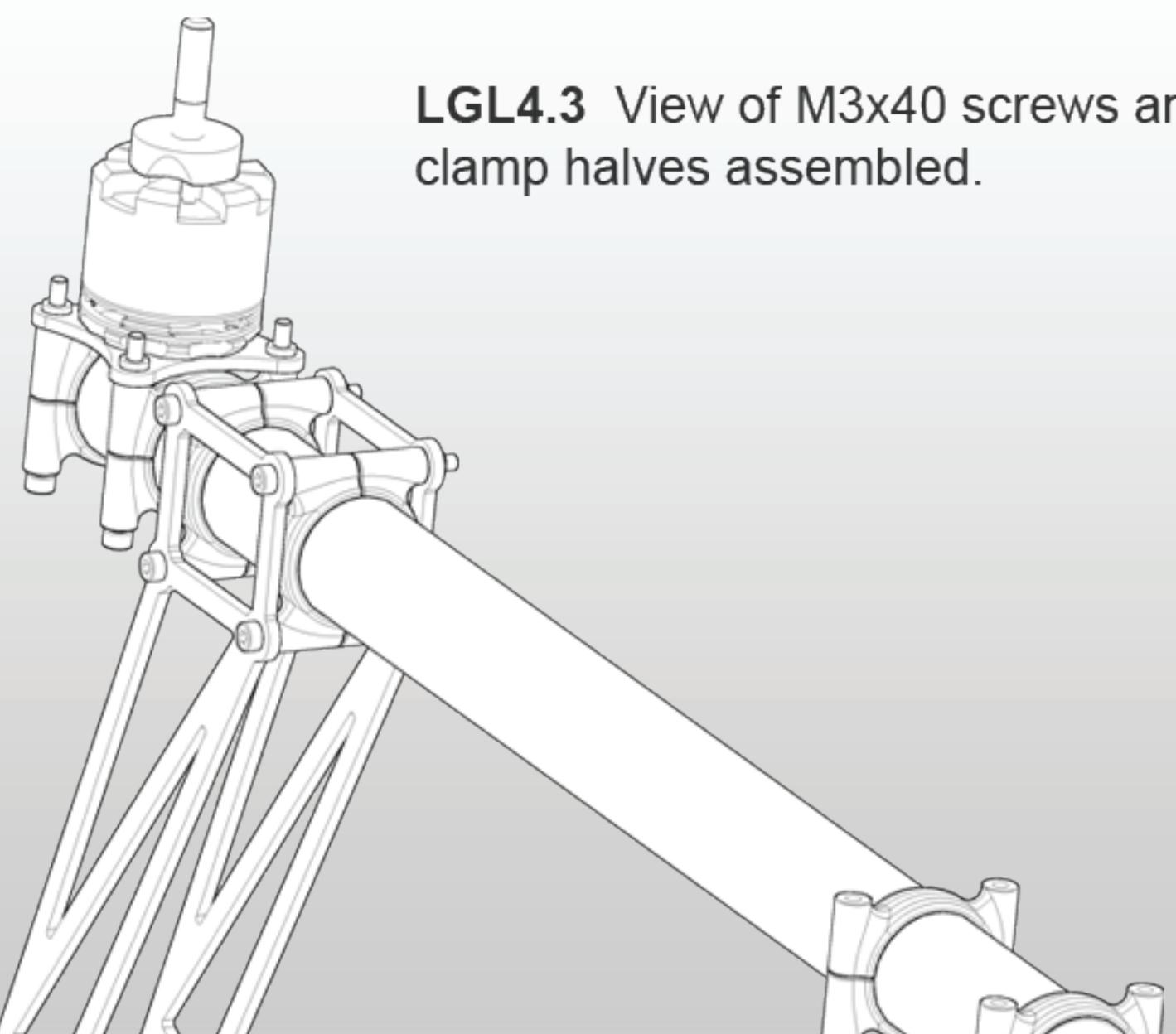
LGL4.1 Now the landing gear needs to be installed. The CineStar team usually runs the rear leg pointed outward and the front two (2) legs pointing inward. The CineStar team sets the landing gear up this way, so that there is the visual cue of the rear leg facing outward while flying. You can also mount the front legs facing outward for maximum stability on takeoff and landing.

2



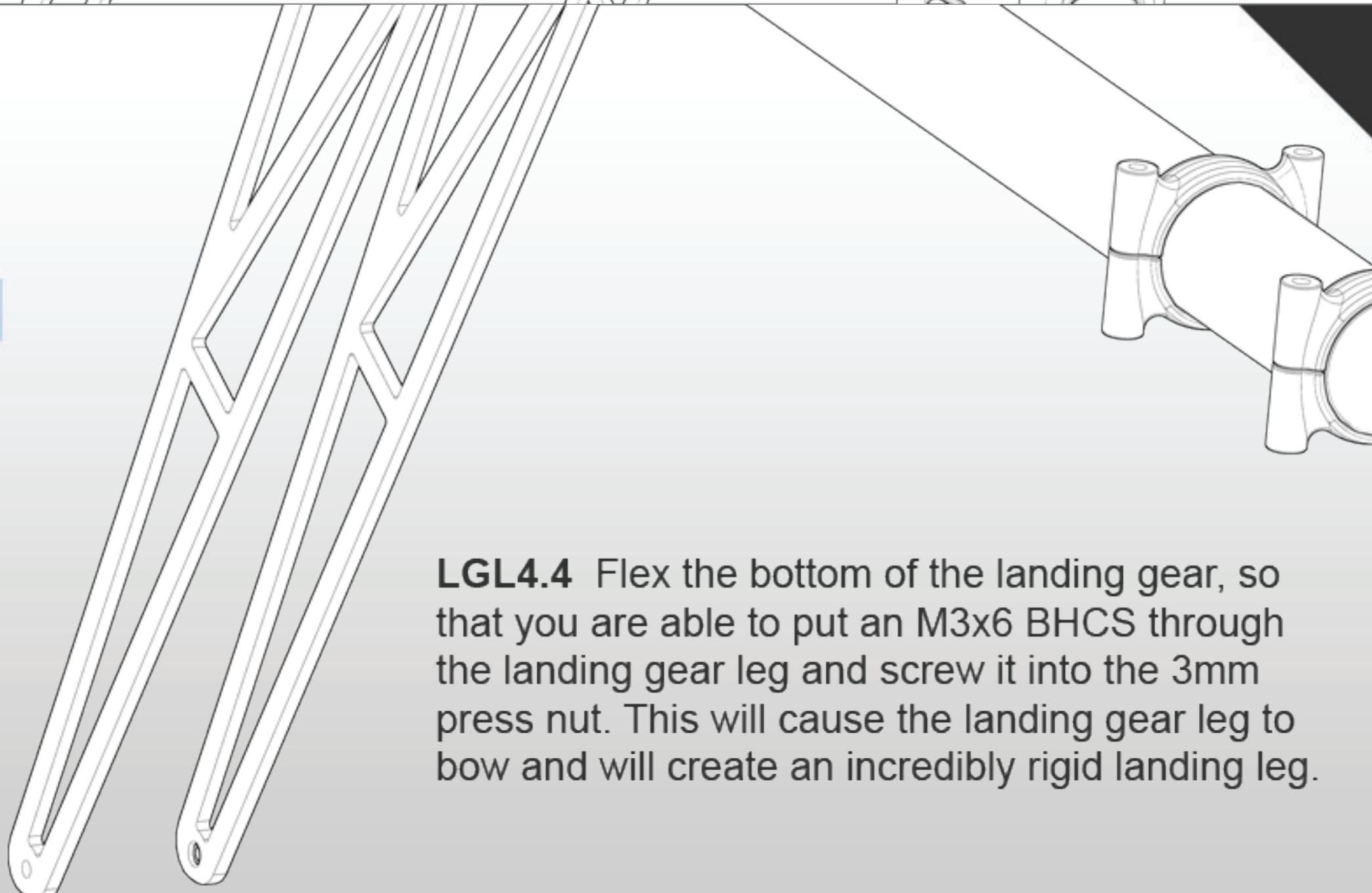
LGL4.2 Assemble the landing gear leg using four (4) M3x40 screws and four (4) clamp halves.

3



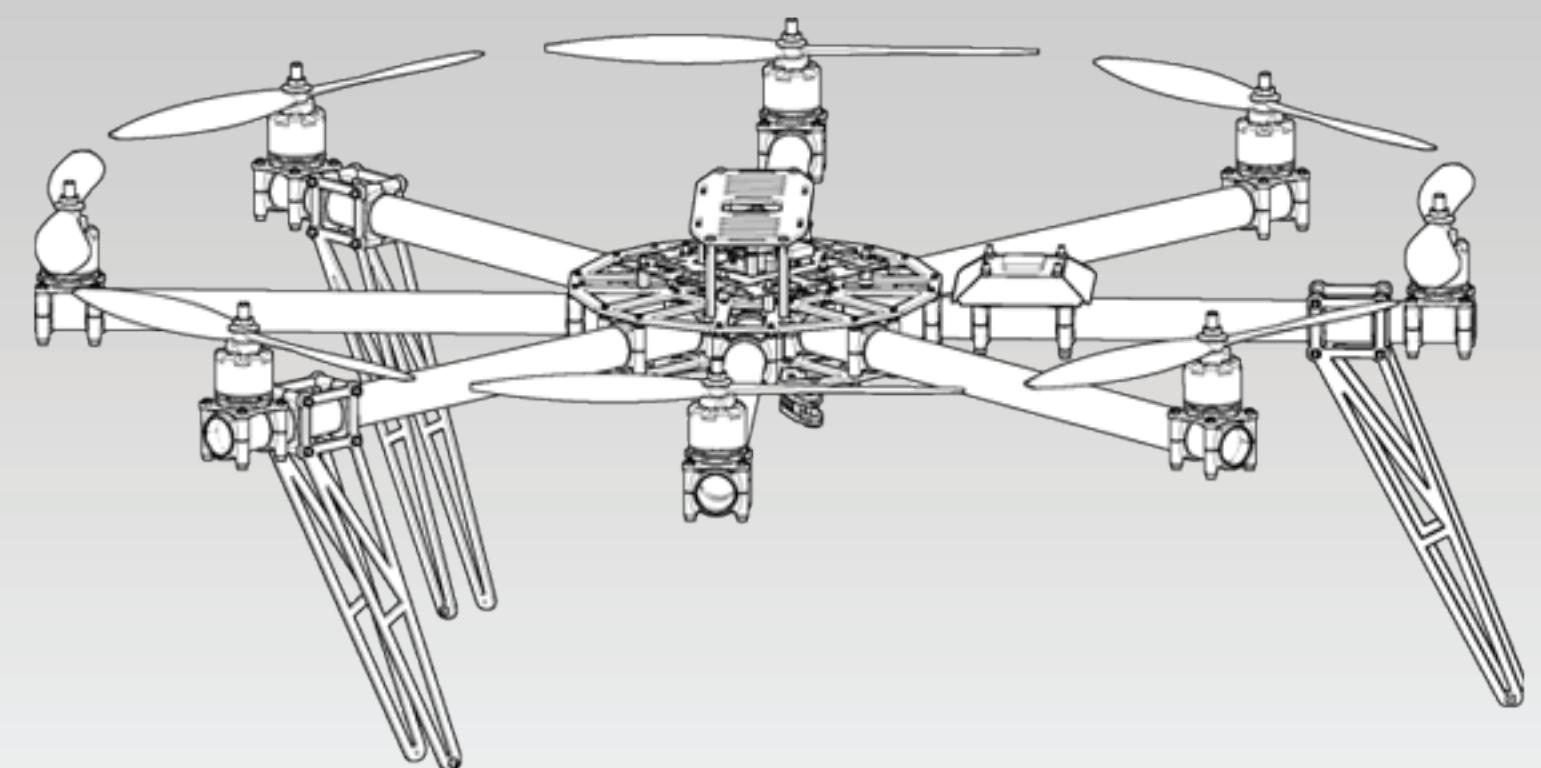
LGL4.3 View of M3x40 screws and clamp halves assembled.

4

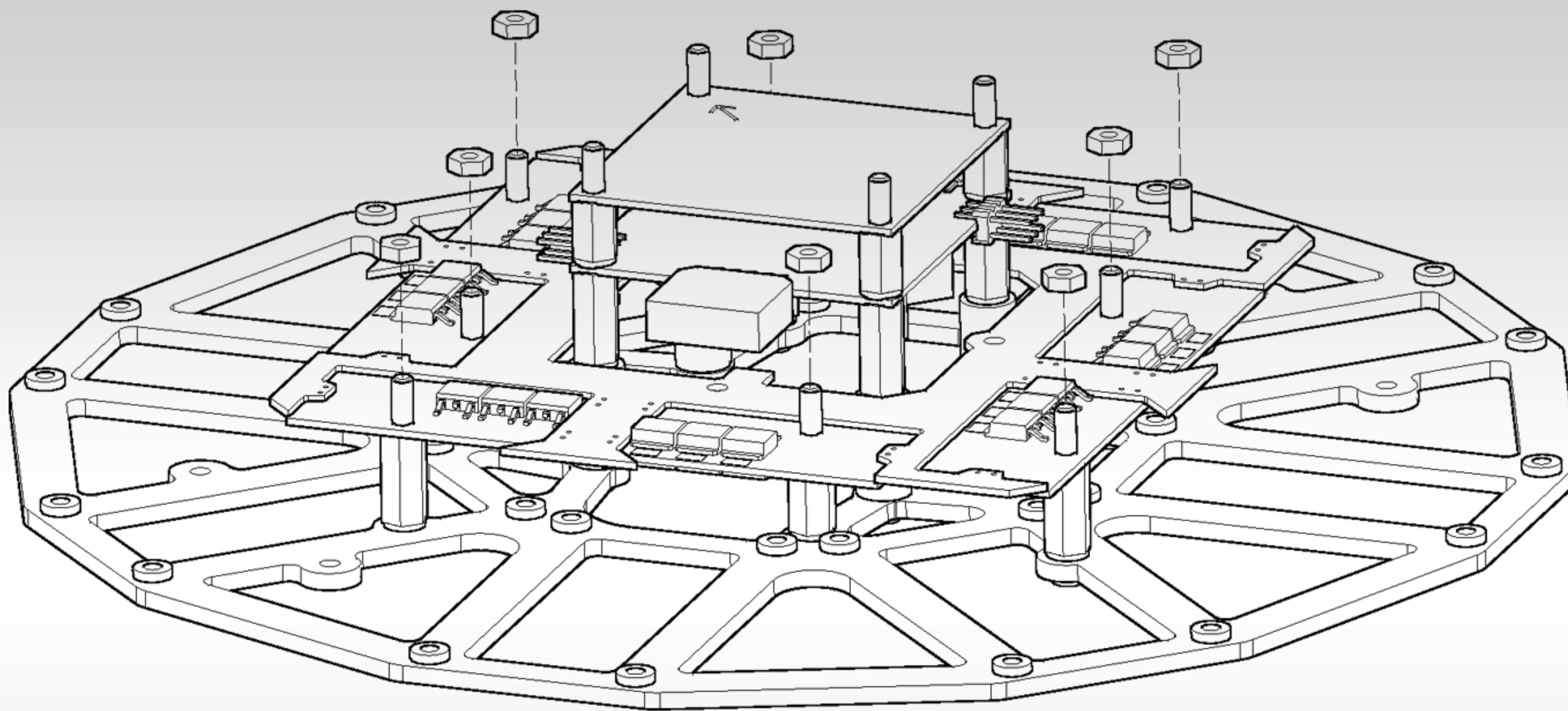


LGL4.4 Flex the bottom of the landing gear, so that you are able to put an M3x6 BHCS through the landing gear leg and screw it into the 3mm press nut. This will cause the landing gear leg to bow and will create an incredibly rigid landing leg.

5

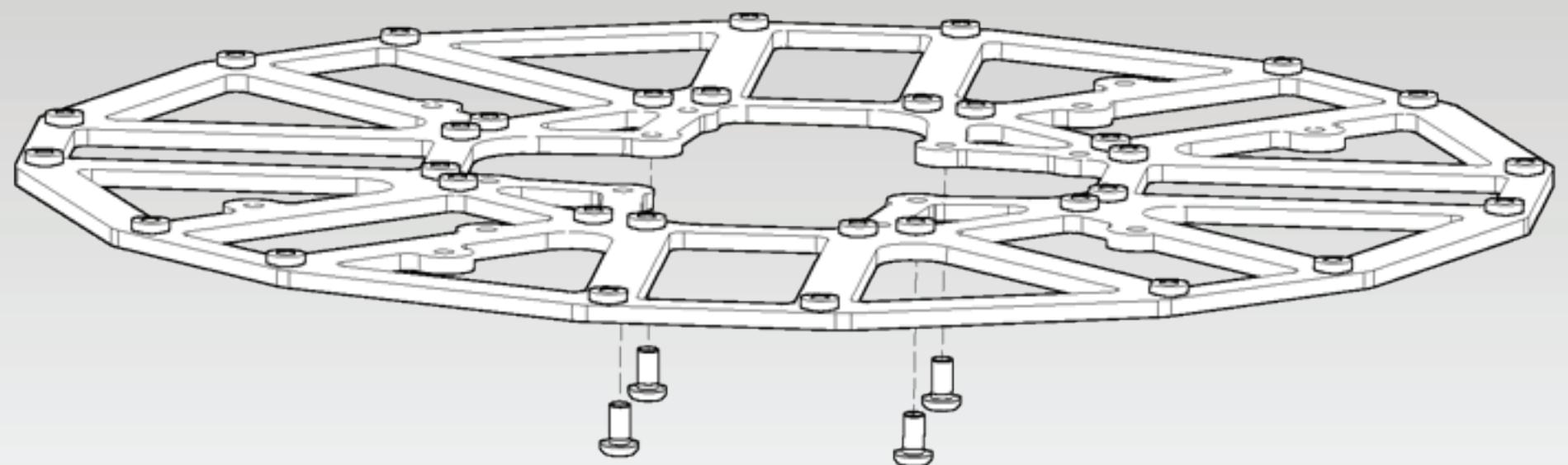


LGL4.5 Complete installation of the remaining two (2) landing gear legs.



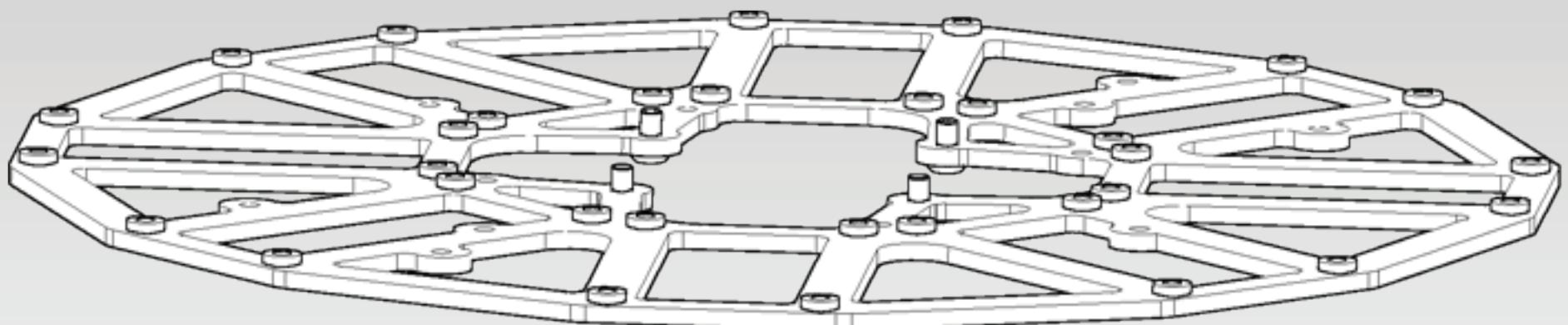
5 MK ELECTRONICS
MKE5.1 - MKE5.12

1



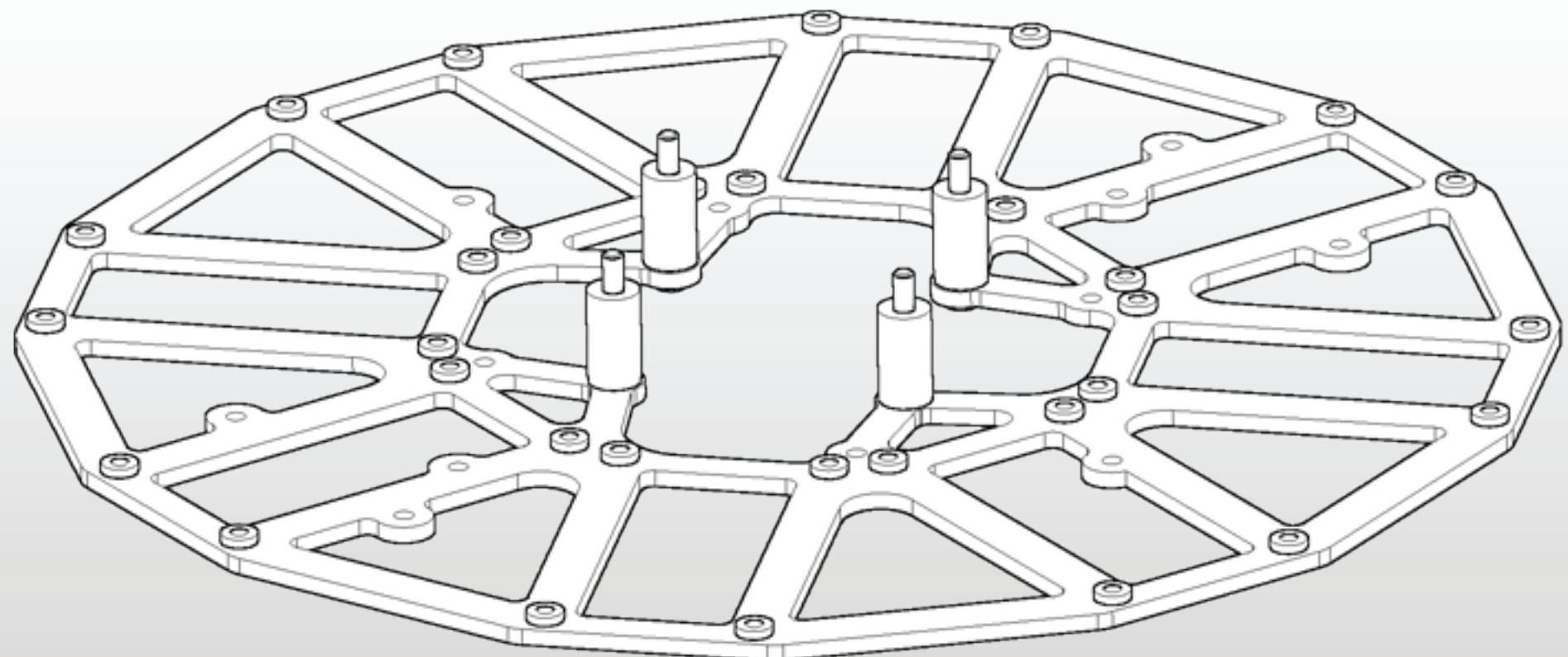
MKE5.1 Install four (4) M3x6 BHCS to hold the flight control board vibration isolators. Note only the top frame plate is shown for ease of illustration.

2



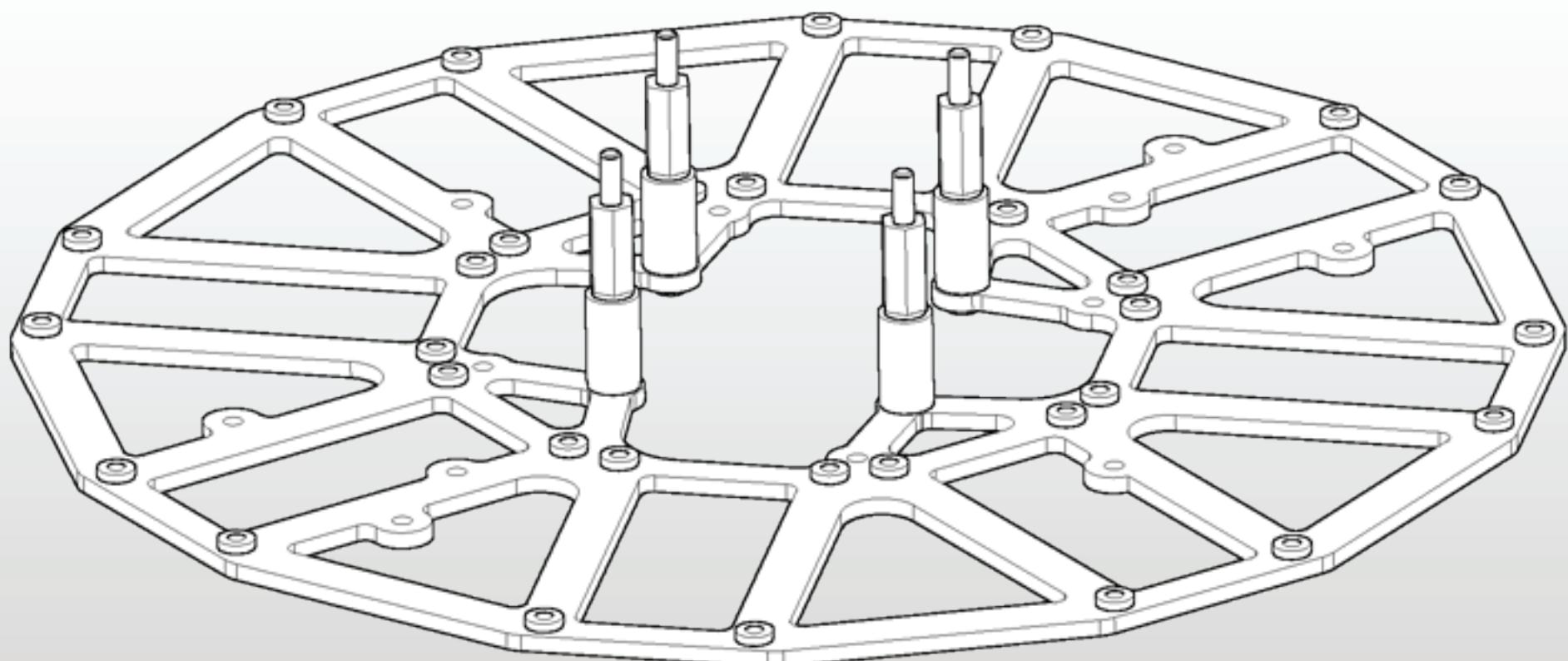
MKE5.2 View of four (4) M3x6 BHCS installed.

3



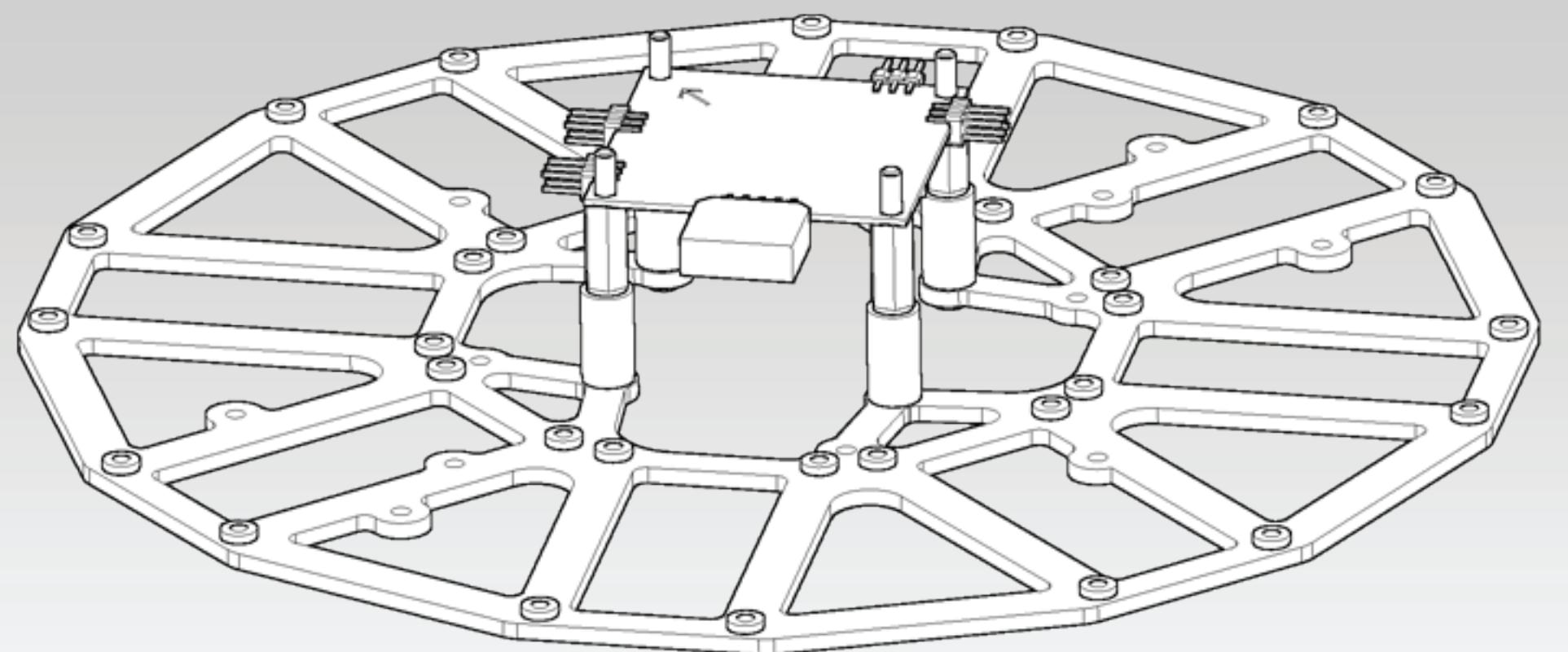
MKE5.3 Thread the MK flight control vibration isolation mounts onto the M3x6 BHCS.

4



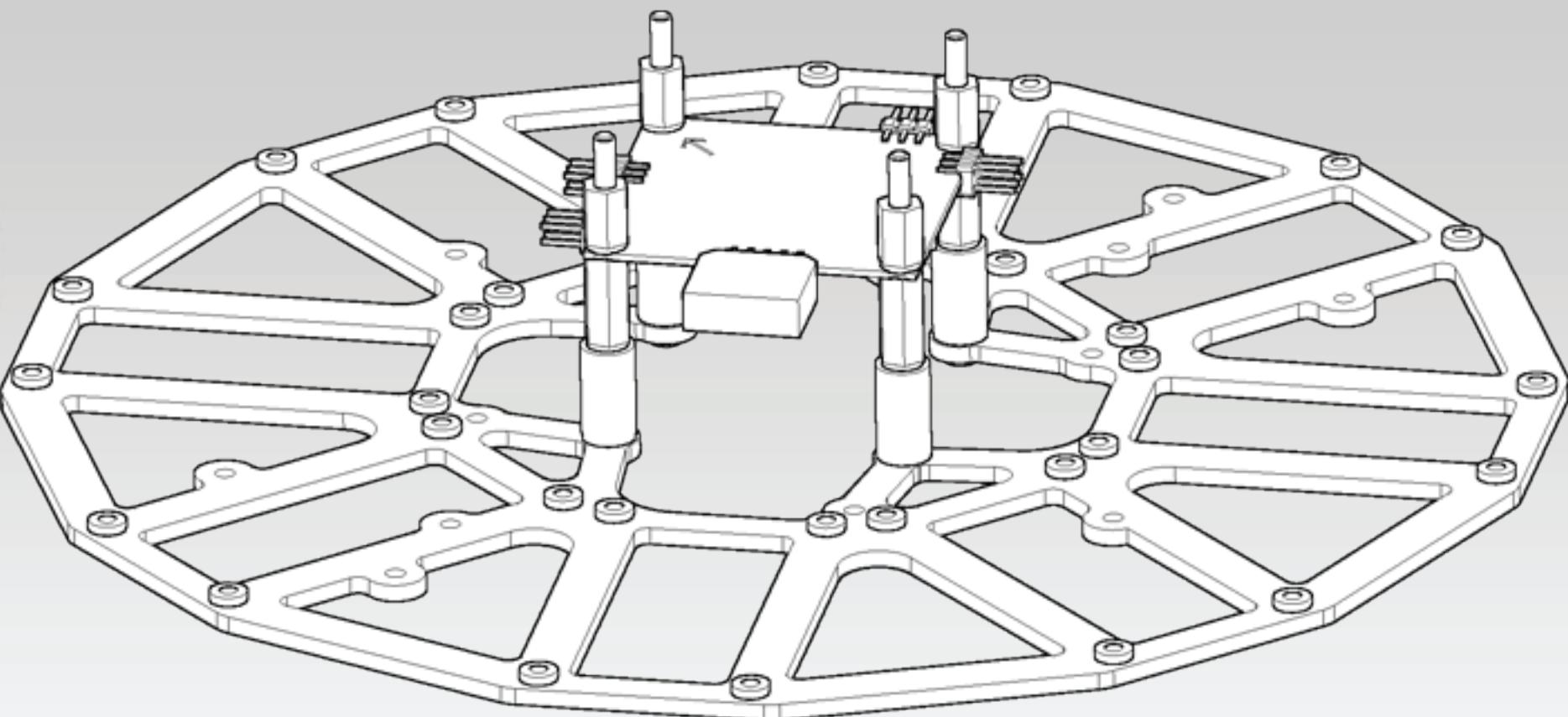
MKE5.4 Thread the four (4) 15mm nylon standoffs onto the rubber vibration isolator mounts. This will give the flight control board adequate spacing from the distribution board.

5



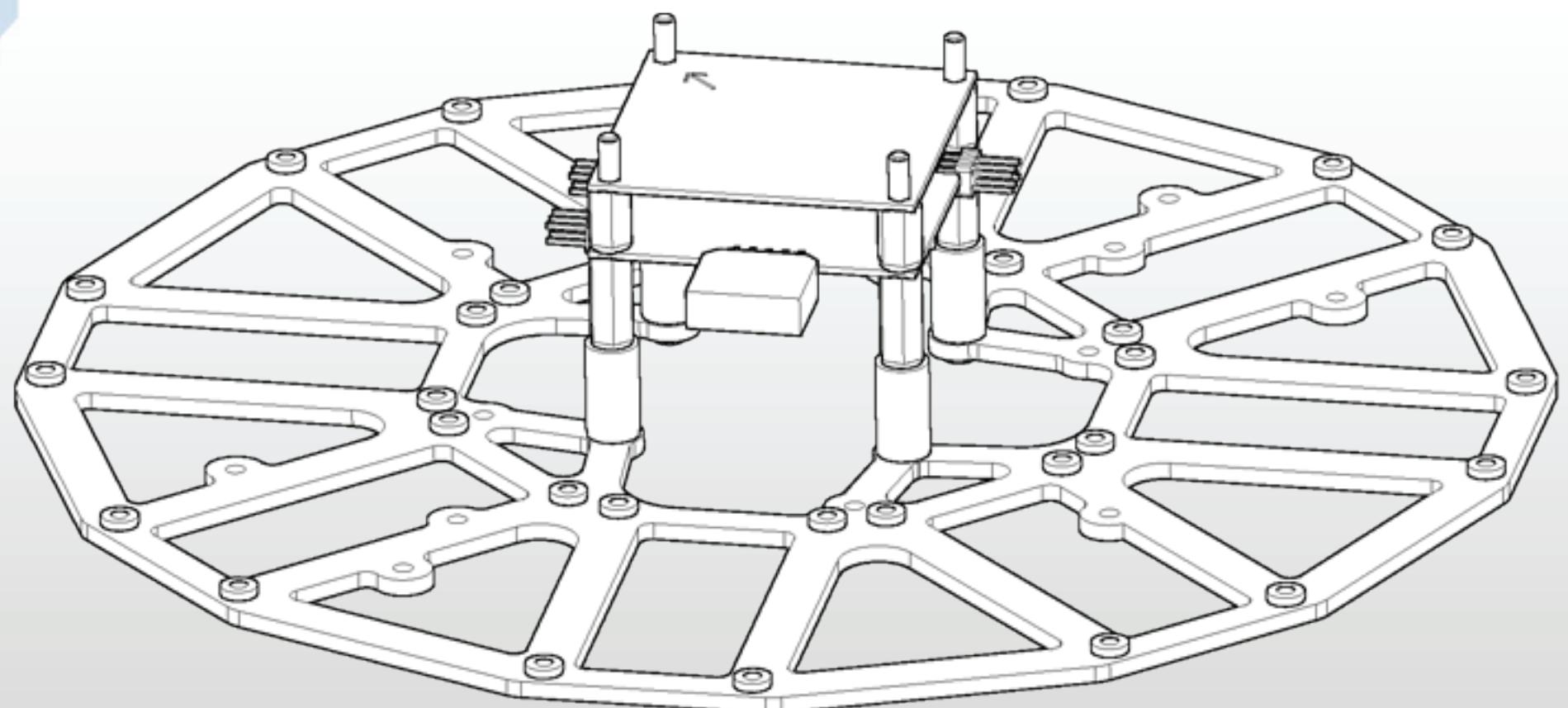
MKE5.5 Mount the flight control board onto the vibration isolation mounts being careful to observe proper orientation. The flight control board has a small arrow that should be aligned as shown in the drawing.

6



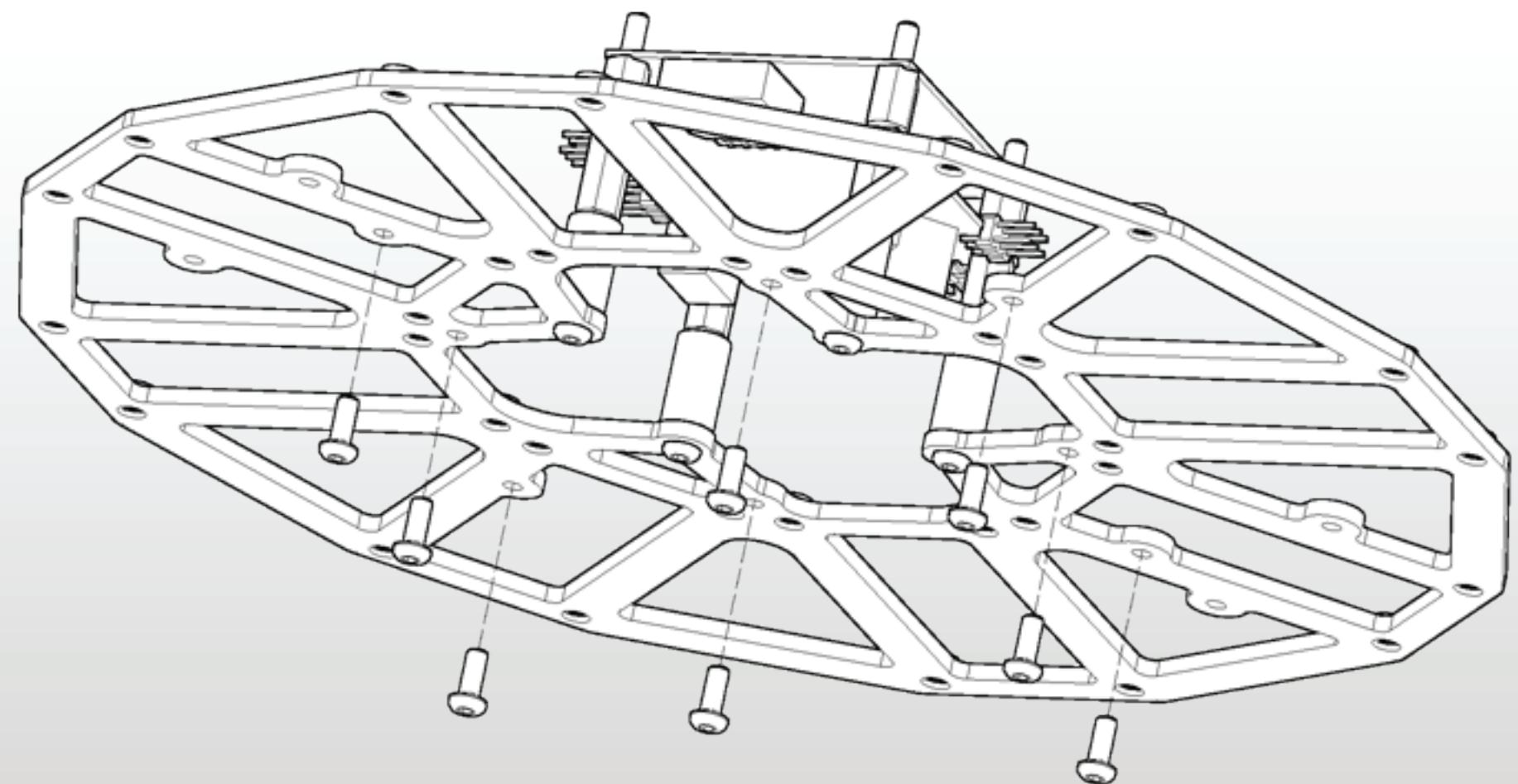
MKE5.6 Install the four (4) nylon standoffs onto the existing studs of the flight control vibration isolation mounts.

7



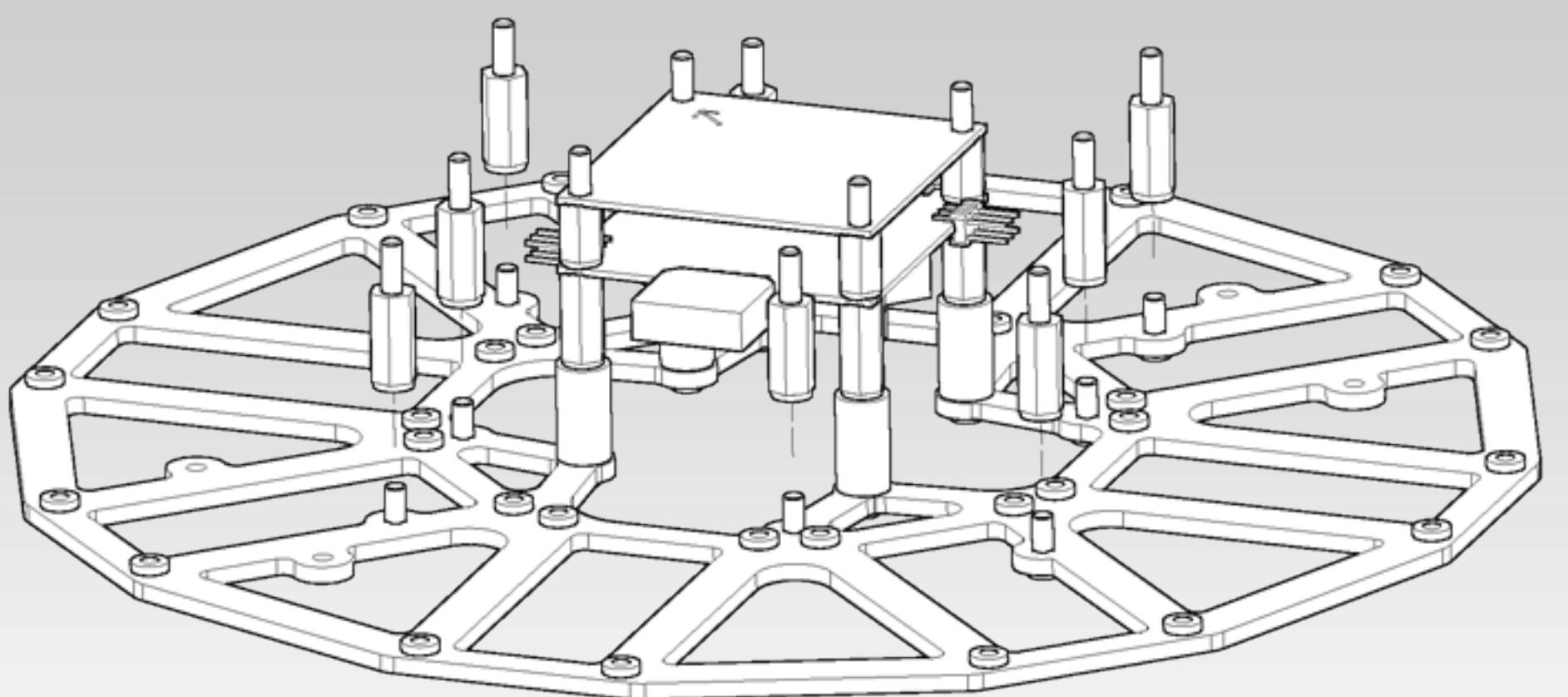
MKE5.7 Install the Navi-Ctrl board being careful again to observe proper orientation and carefully tighten the 3mm nylon nuts to secure the board.

8

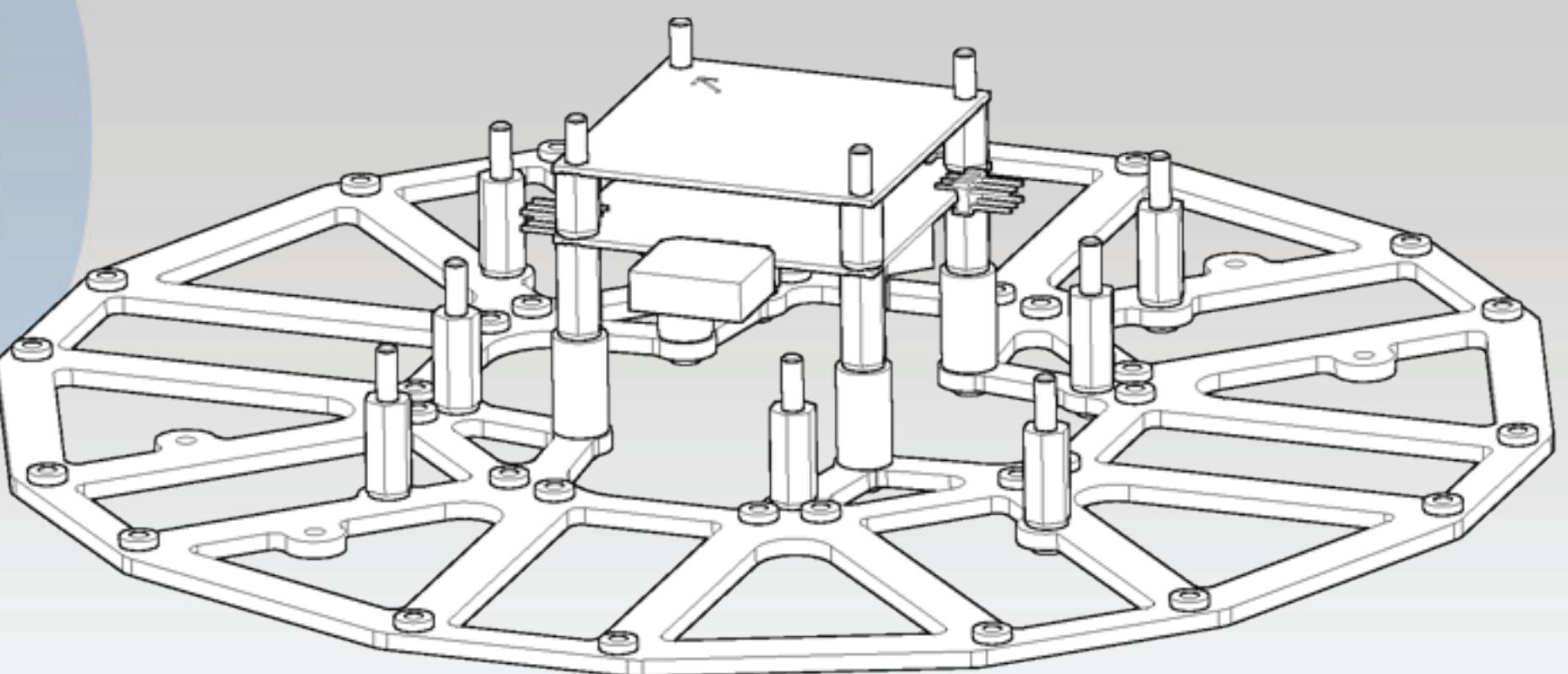


MKE5.8 Now we will install the distribution ring. Once again, for the ease of viewing, only the top frame plate is shown. Insert eight (8) M3x6 BHCS into the holes shown.

9



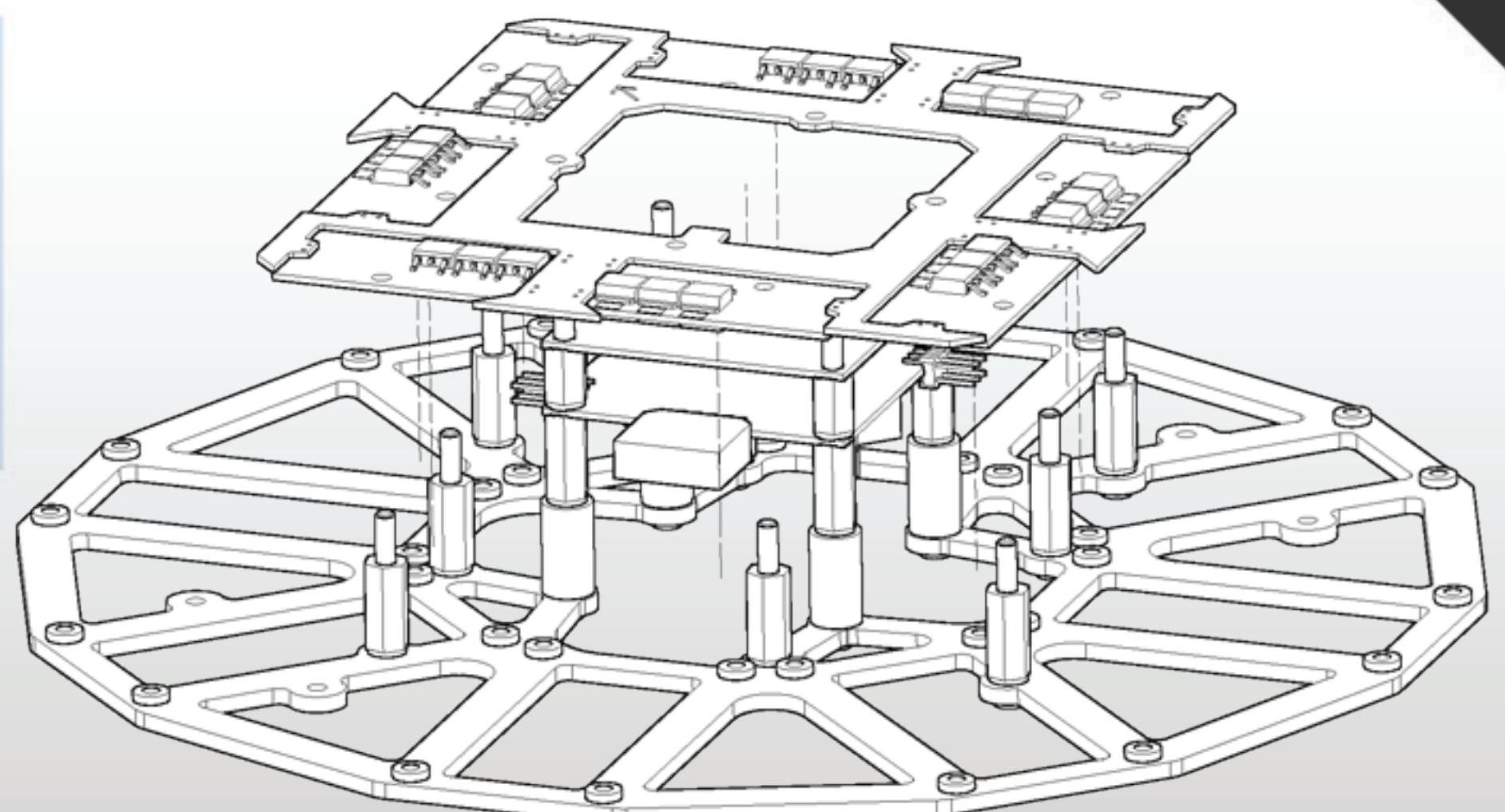
10



MKE5.9 Thread the 15mm nylon standoffs onto the M3x6 BHCS. Be careful not to strip the nylon threads.

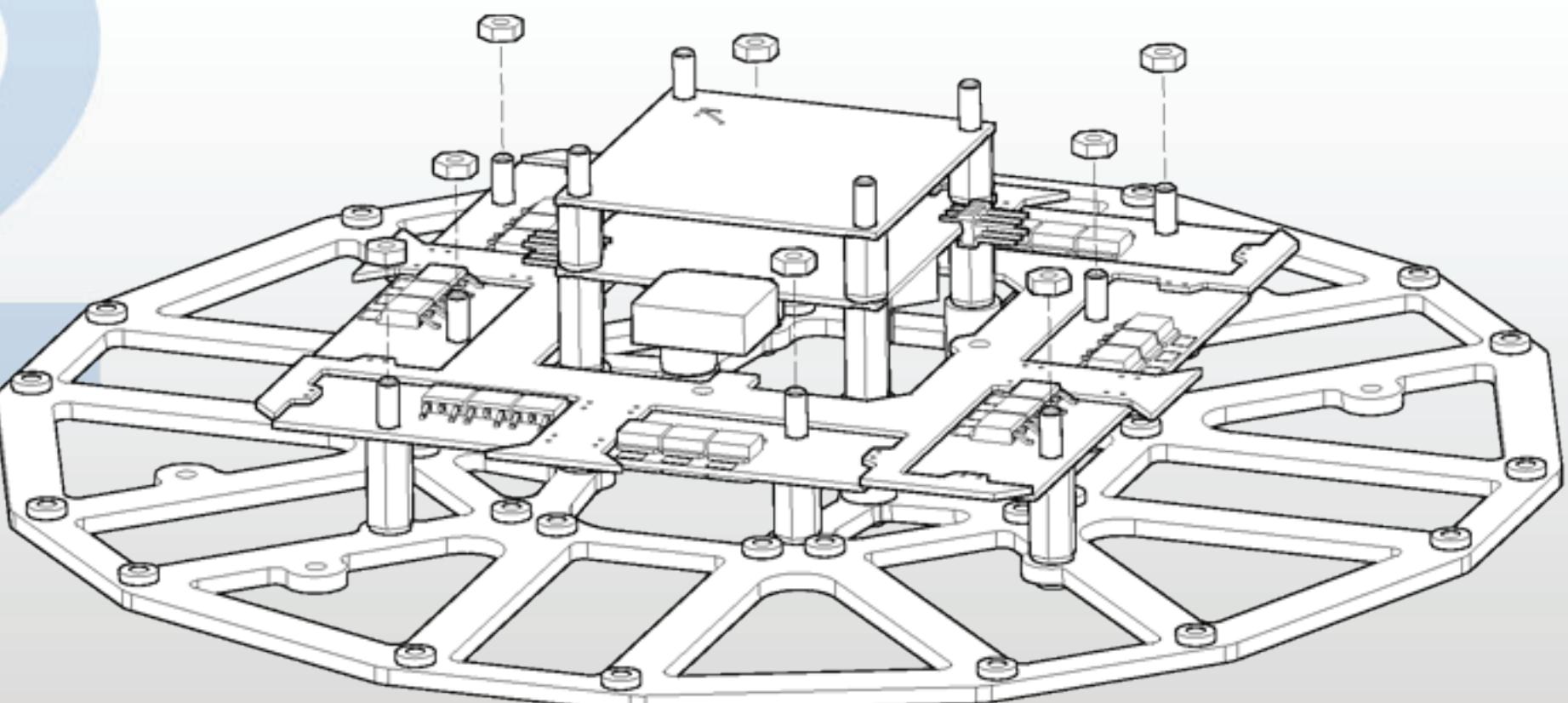
MKE5.10 Nylon standoffs installed.

11

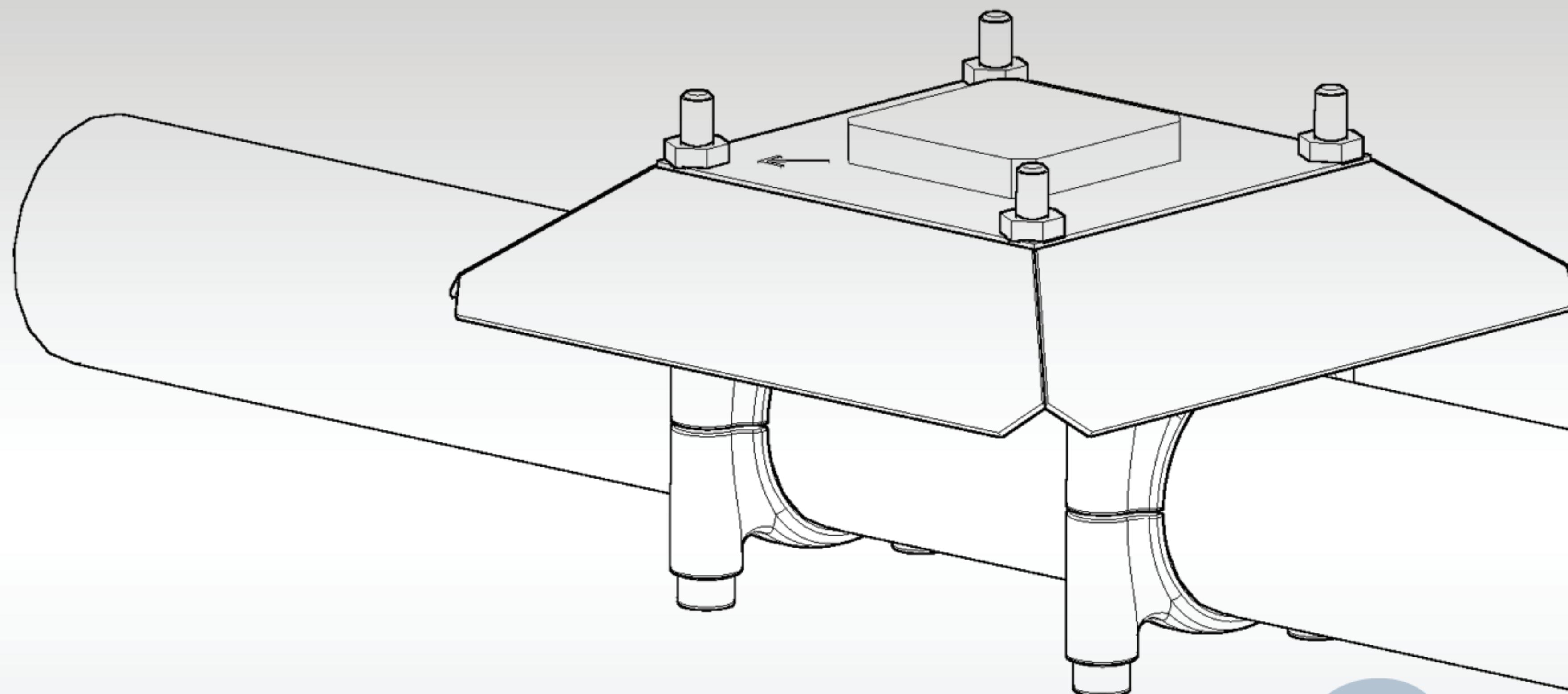


MKE5.11 Now place the MK distribution ring onto the nylon standoffs being careful not to strip the threads.

12



MKE5.12 Install the nylon nuts to retain the distribution ring.



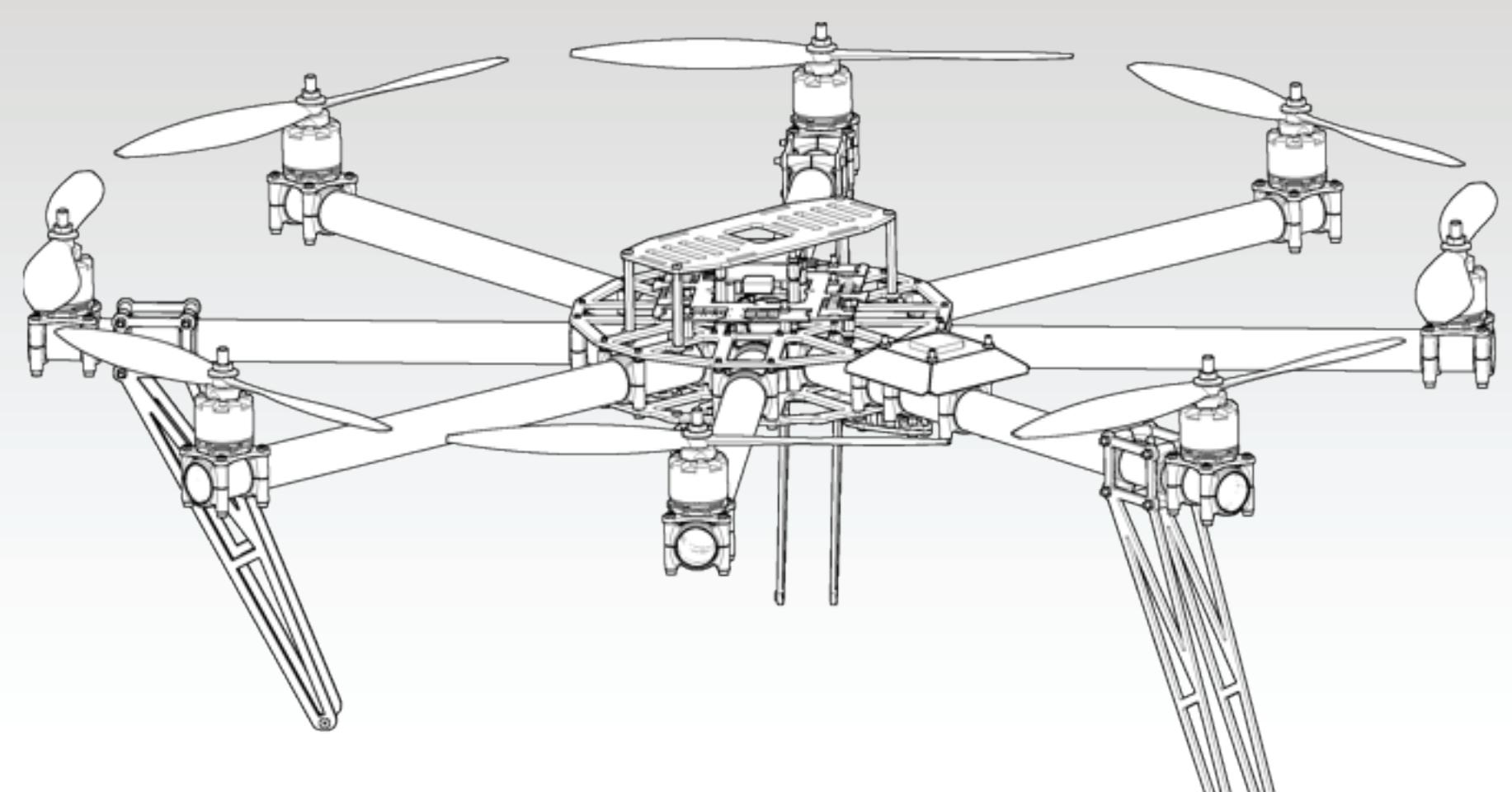
6

GPS

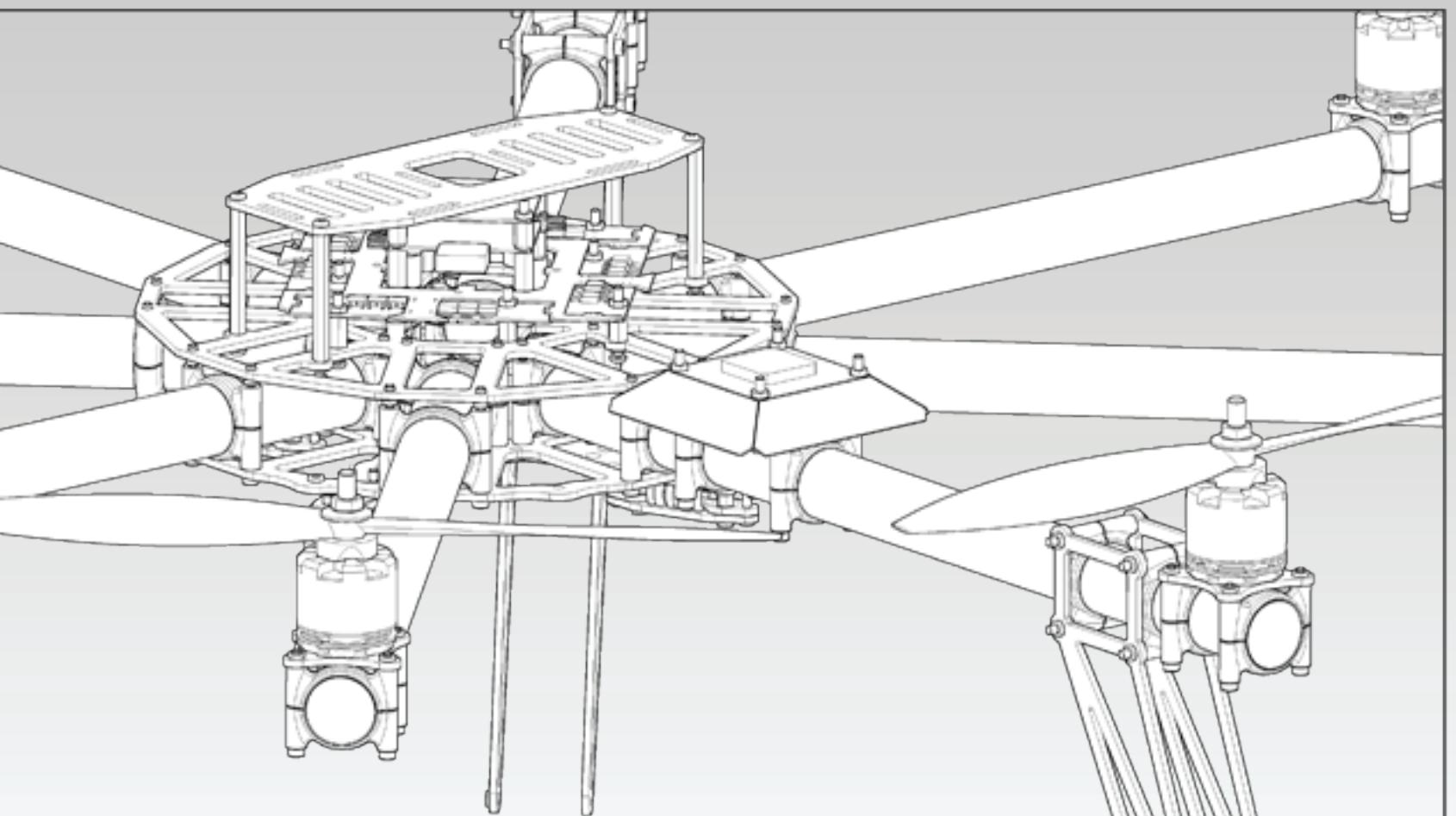
GPS6.1 - GPS6.10

1

GPS6.1 If you choose to run the MK GPS with the optional GPS shield, it will not fit in the stock mounting location. For this reason, we have included an accessory mount for the GPS shield that allows it to be mounted on the boom.

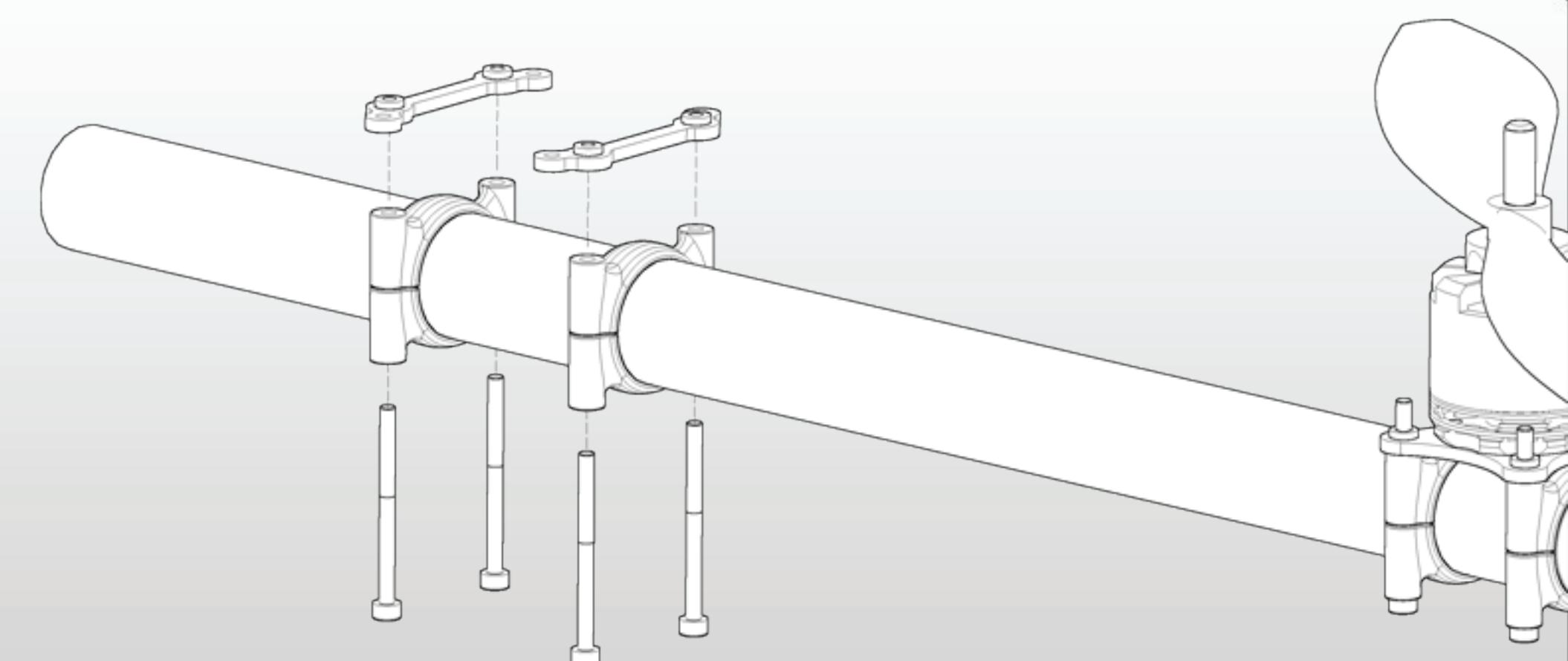


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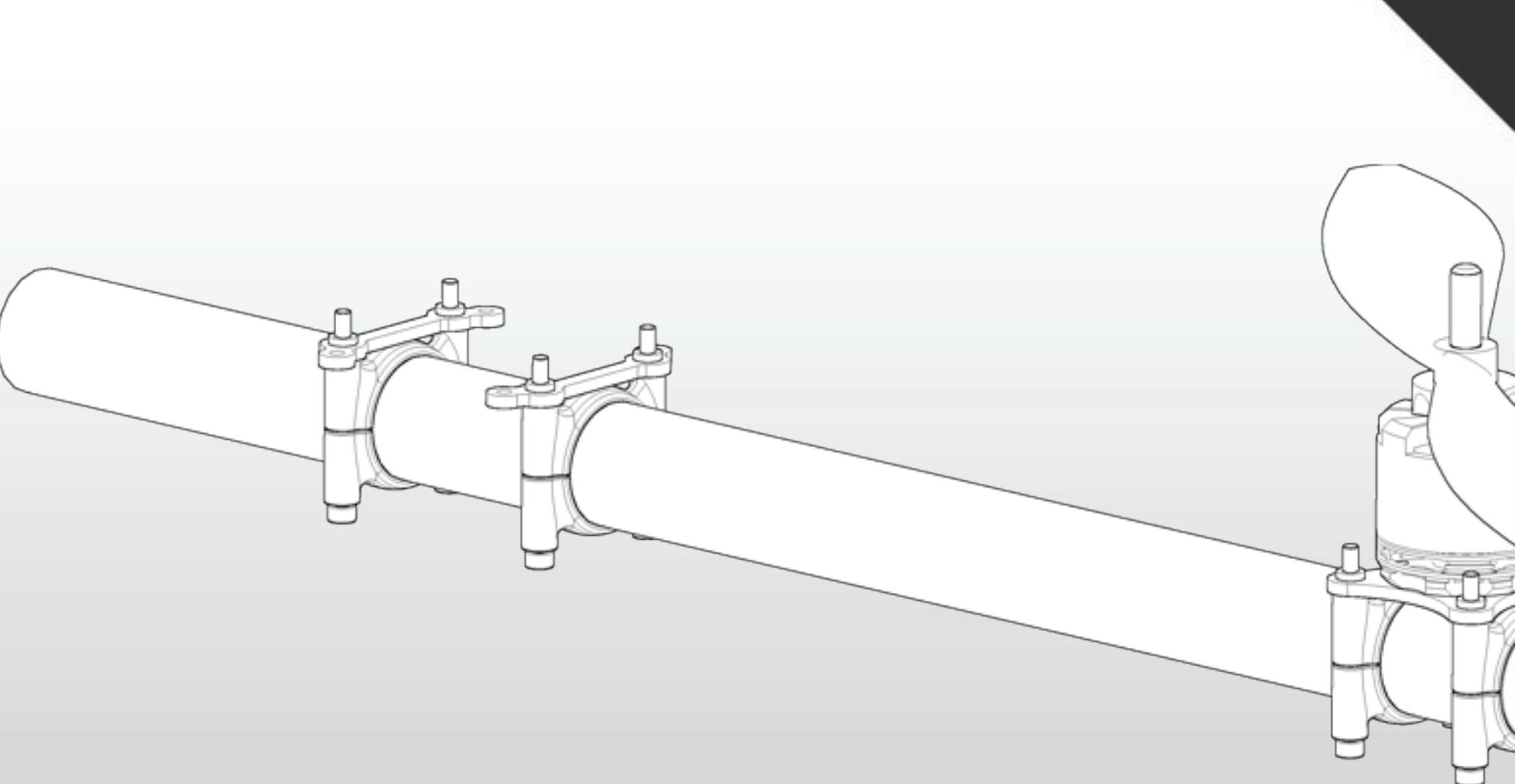
GPS6.2 Close-up of the GPS shield mounted on the accessory mount.

3



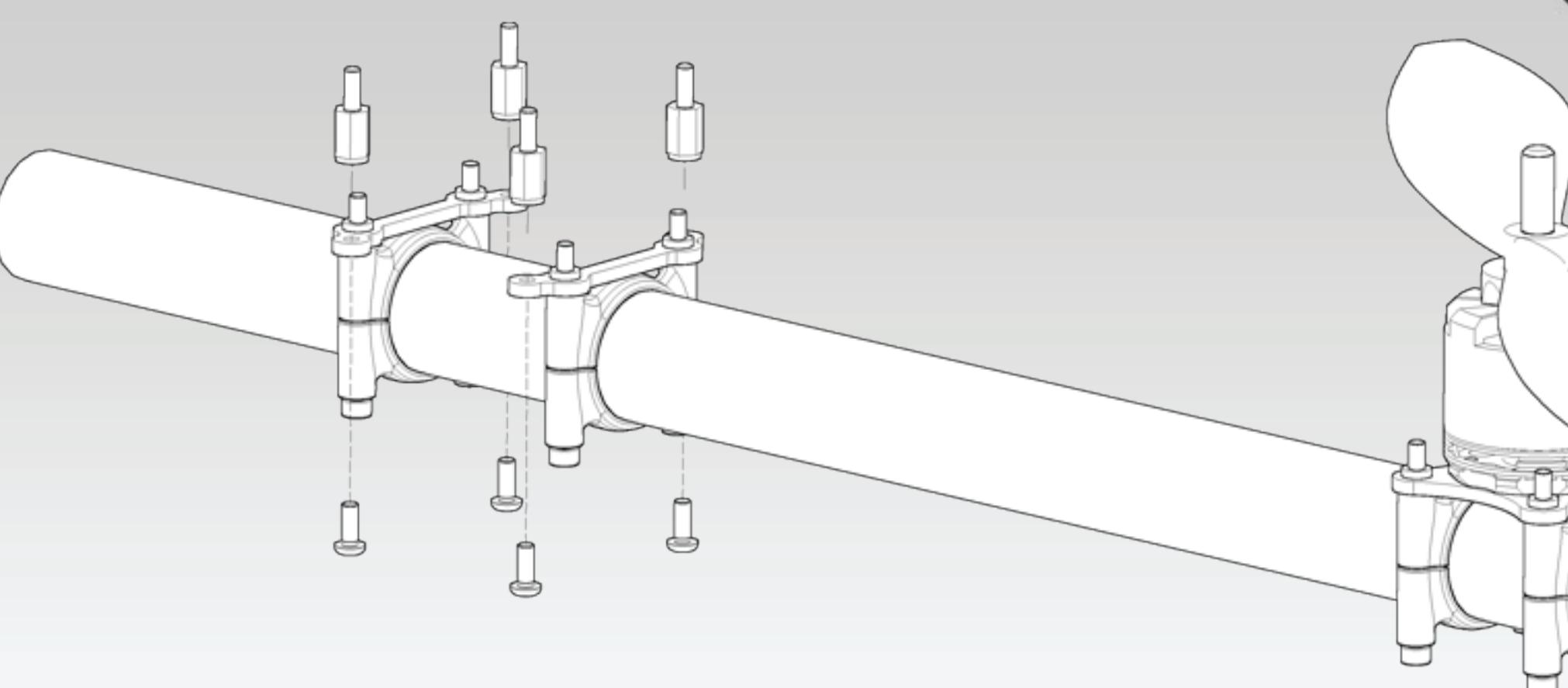
GPS6.3 Install four (4) M3x35 screws through the four(4) clamp halves into the press nuts in the GPS mount plates.

4



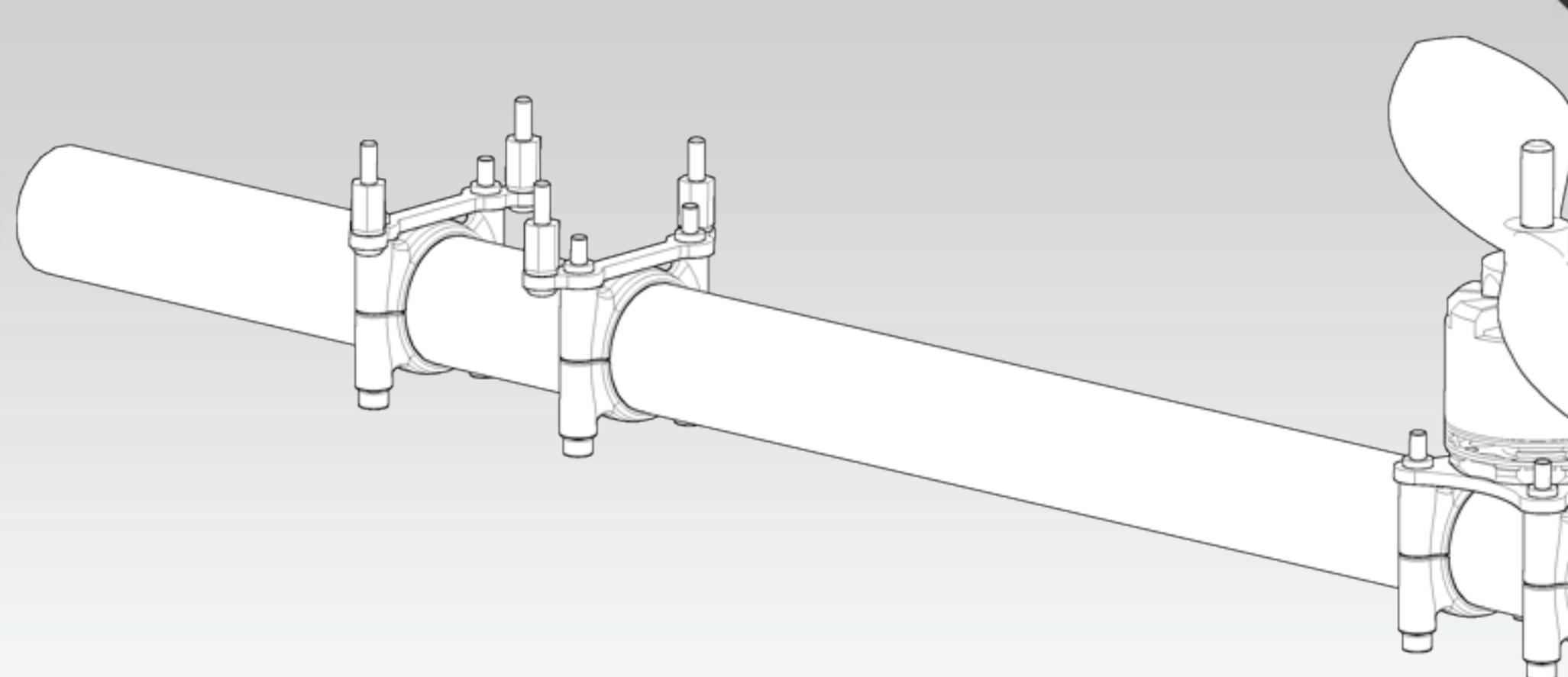
GPS6.4 GPS mount plates installed.

5



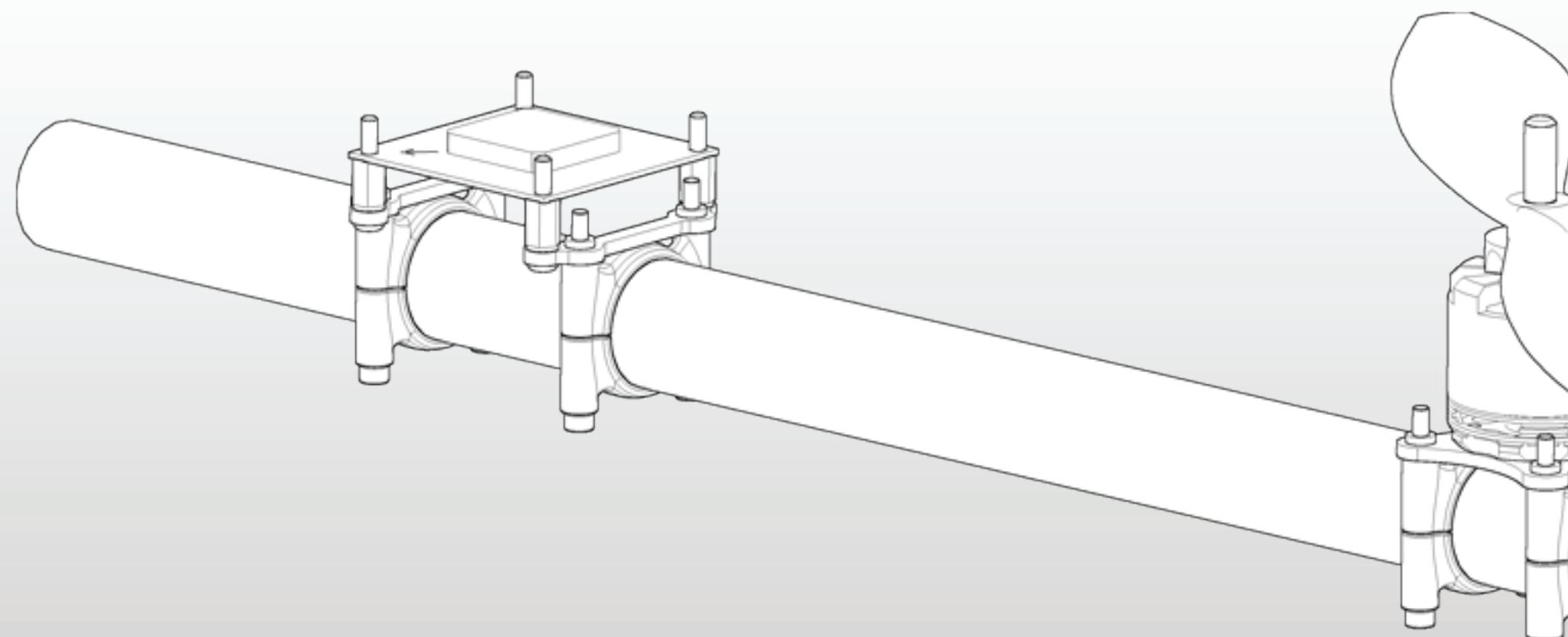
GPS6.5 Attach four (4) nylon standoffs using M3x6 BHCS.

6



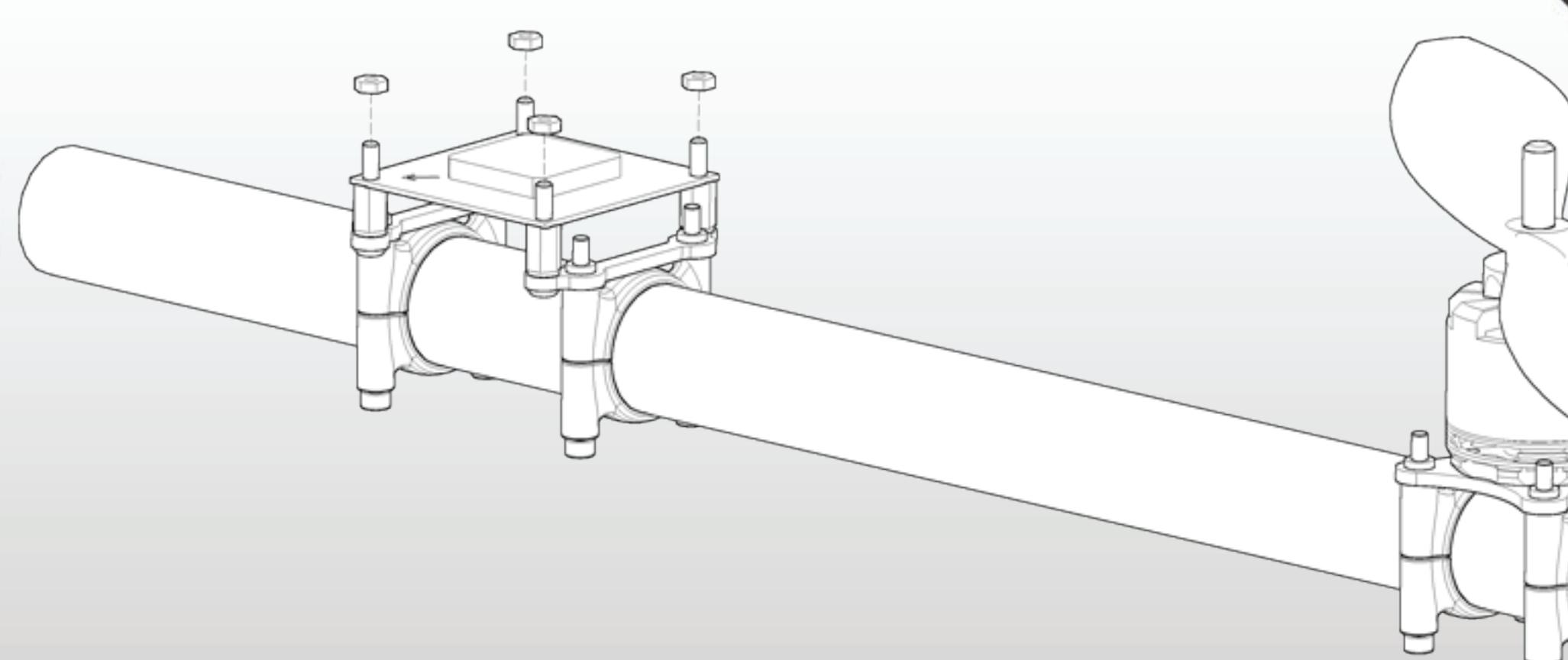
GPS6.6 Nylon standoffs installed.

7



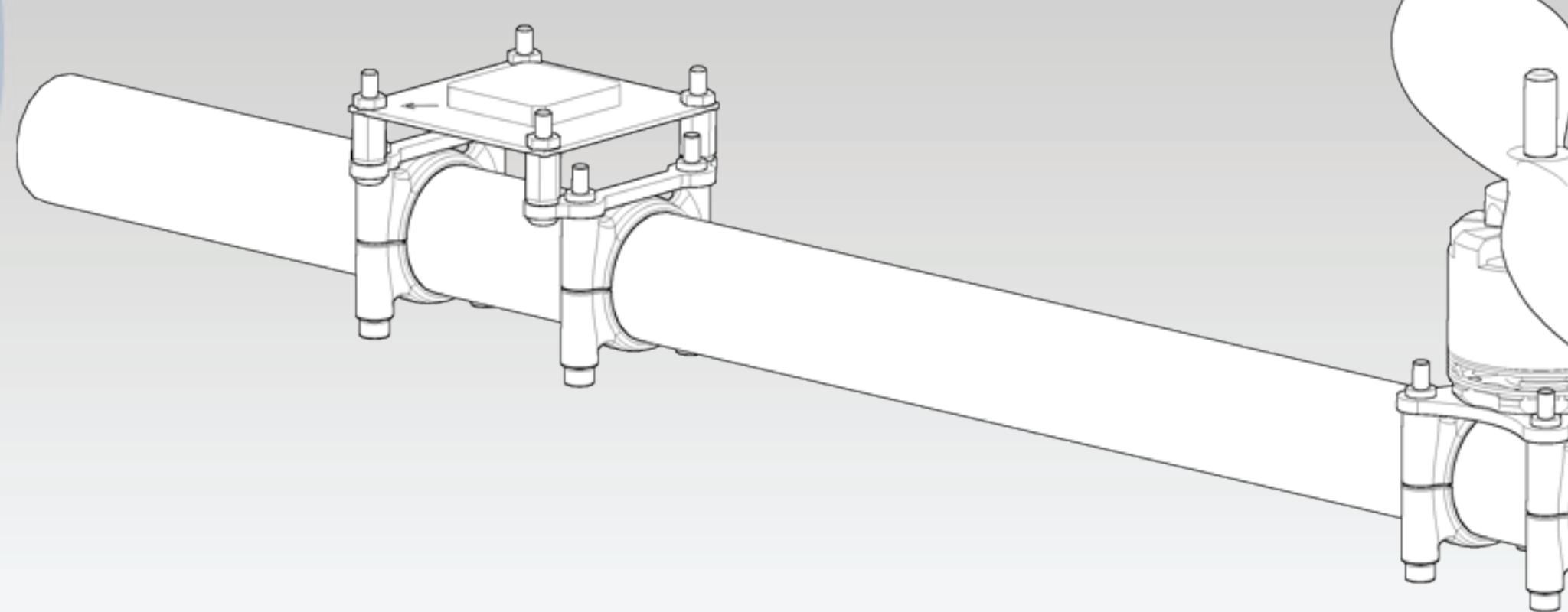
GPS6.7 Install the MK GPS board (note the GPS shield is not shown for the ease of illustration).

8



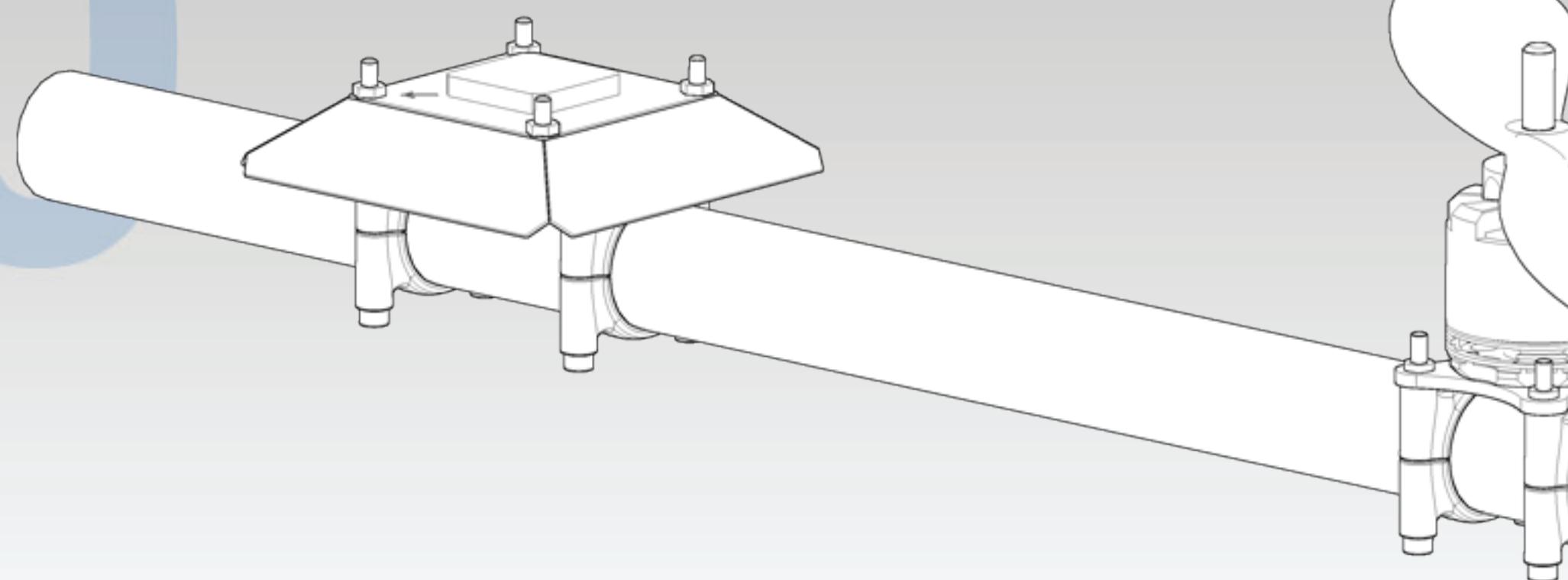
GPS6.8 Secure GPS board with nylon nuts.

9

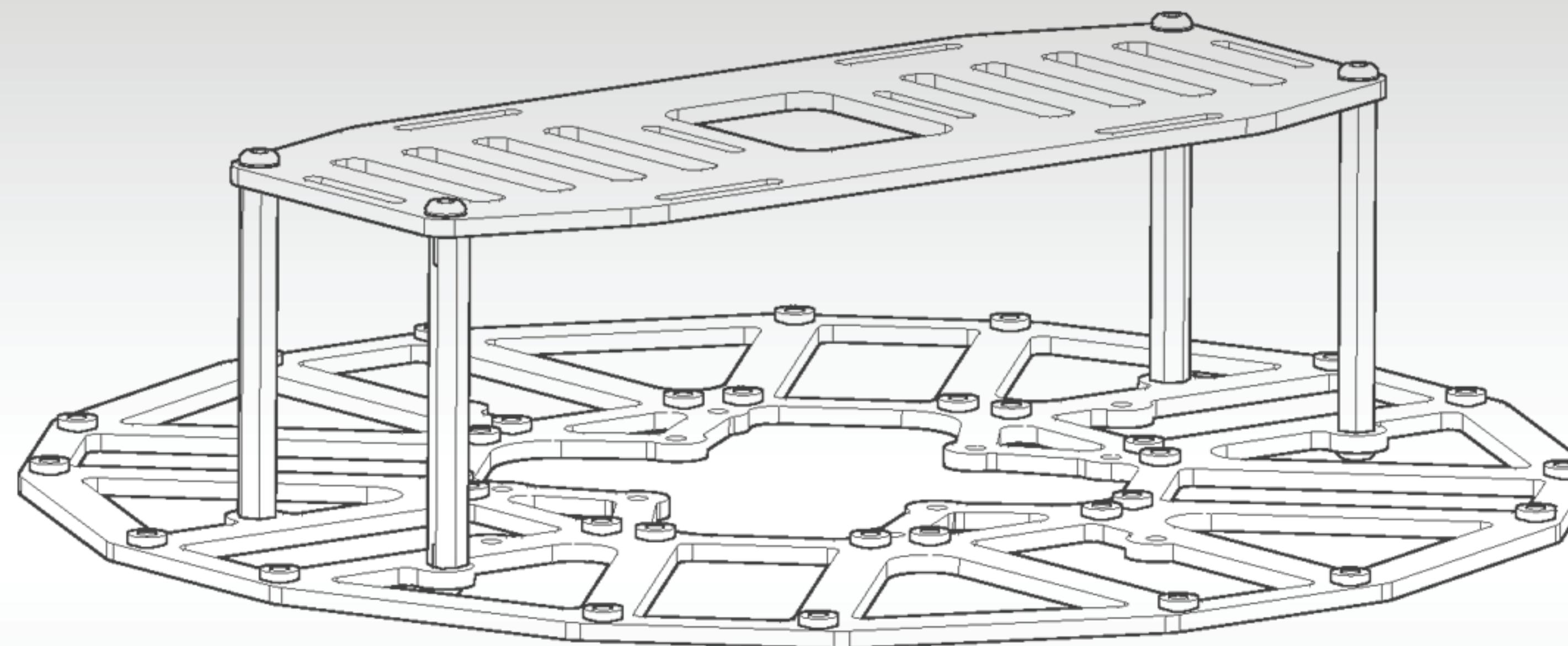


GPS6.9 GPS board and nylon nuts installed.

10



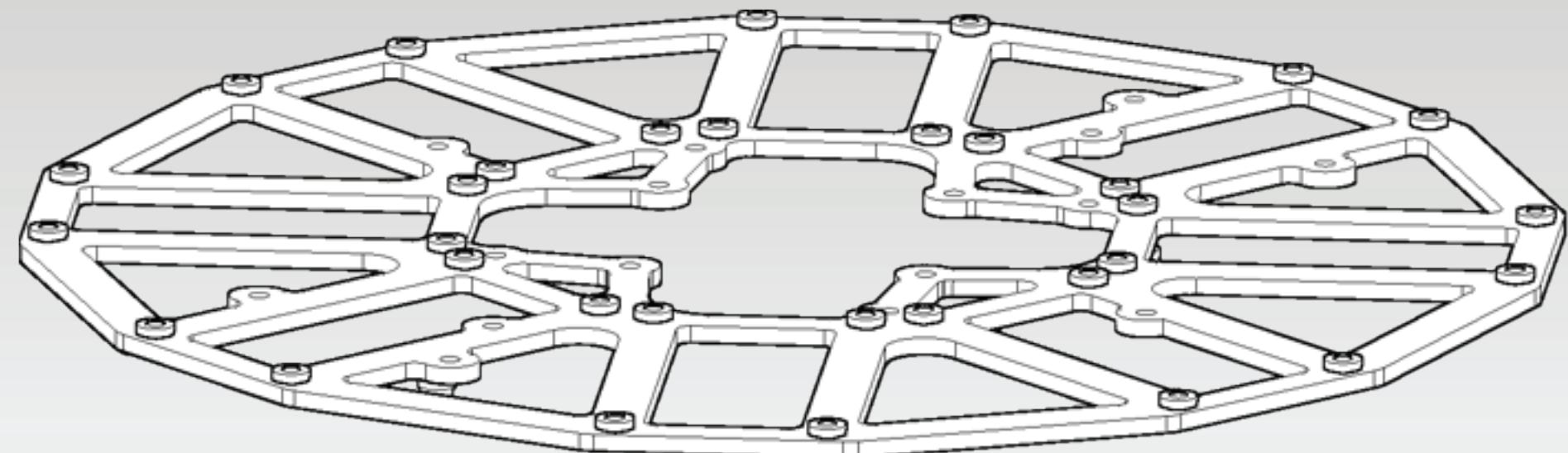
GPS6.10 Completed GPS assembly with shield.



7

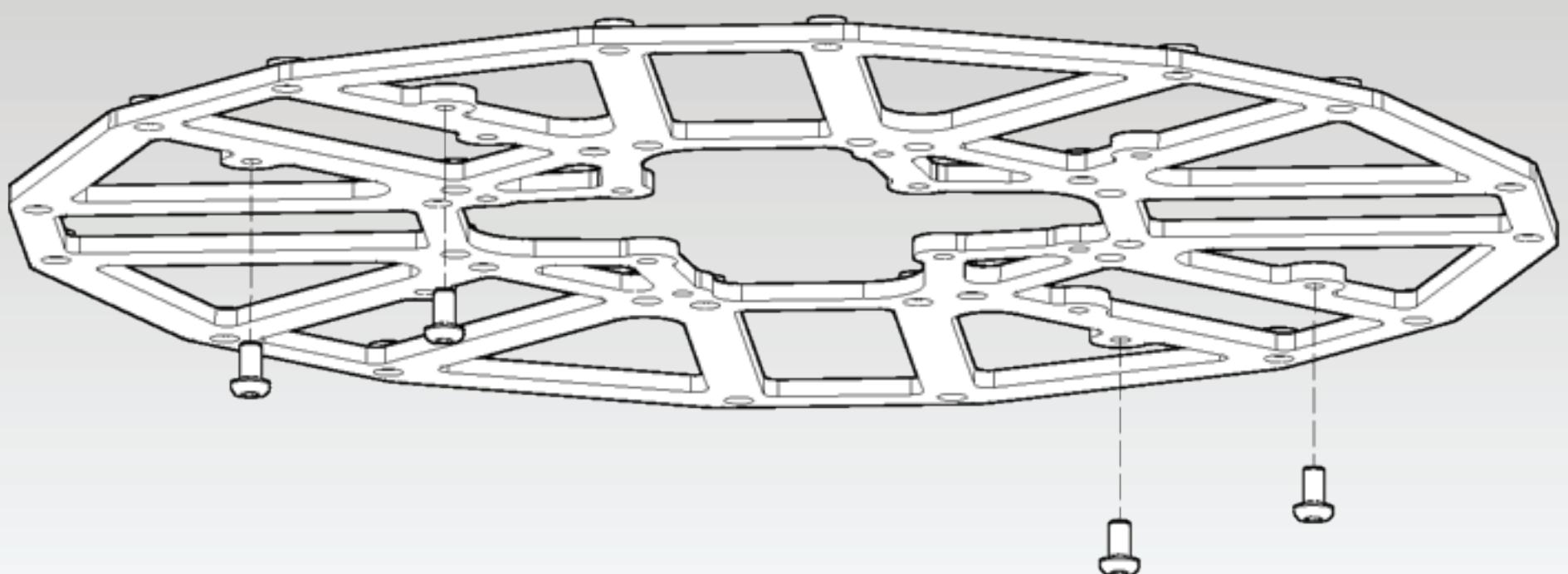
BATTERY PLATE
BP7.1 - BP7.5

1



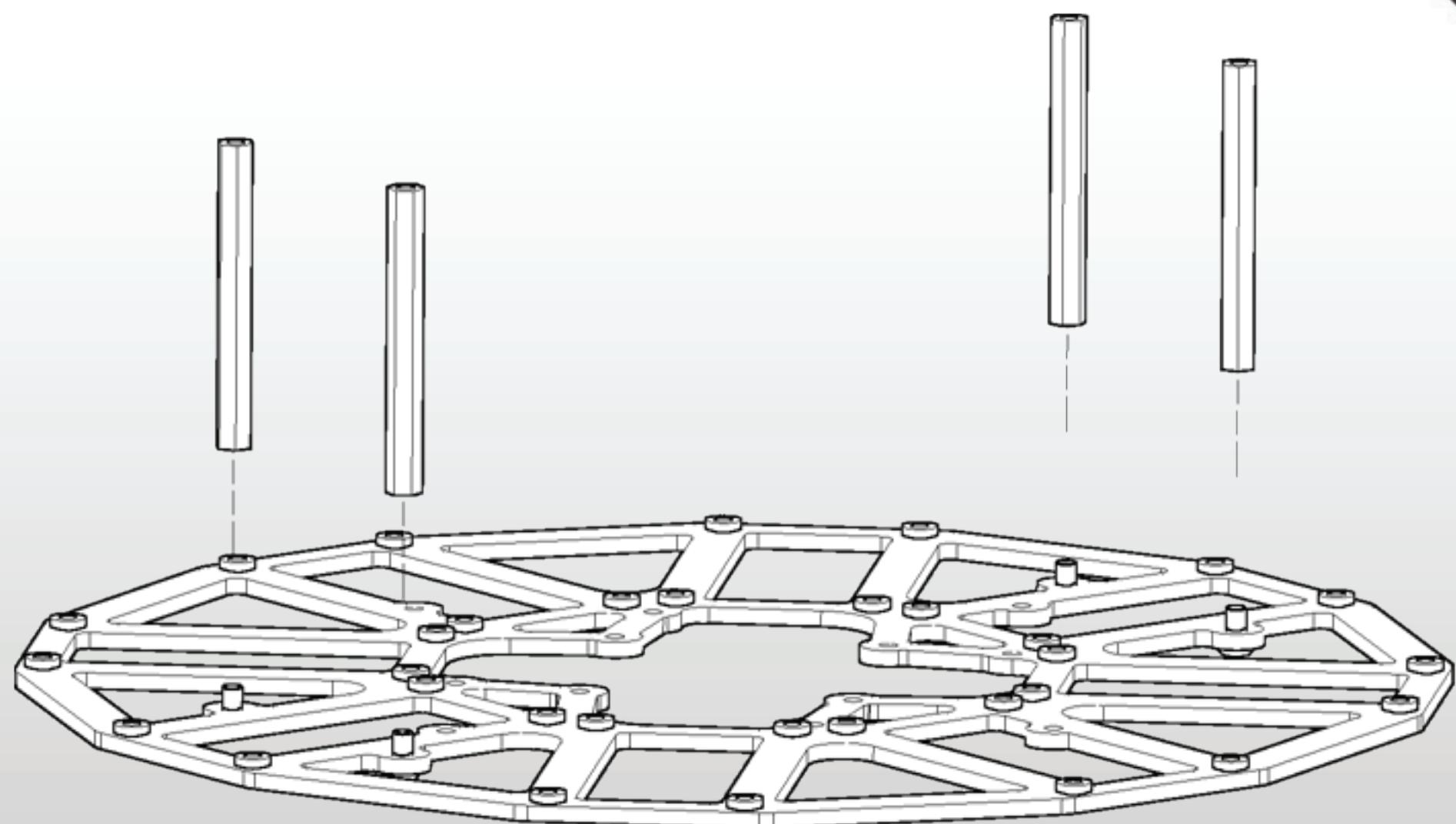
BP7.1 Now we need to install the battery tray. Note that only the top frame is shown for ease of explanation.

2



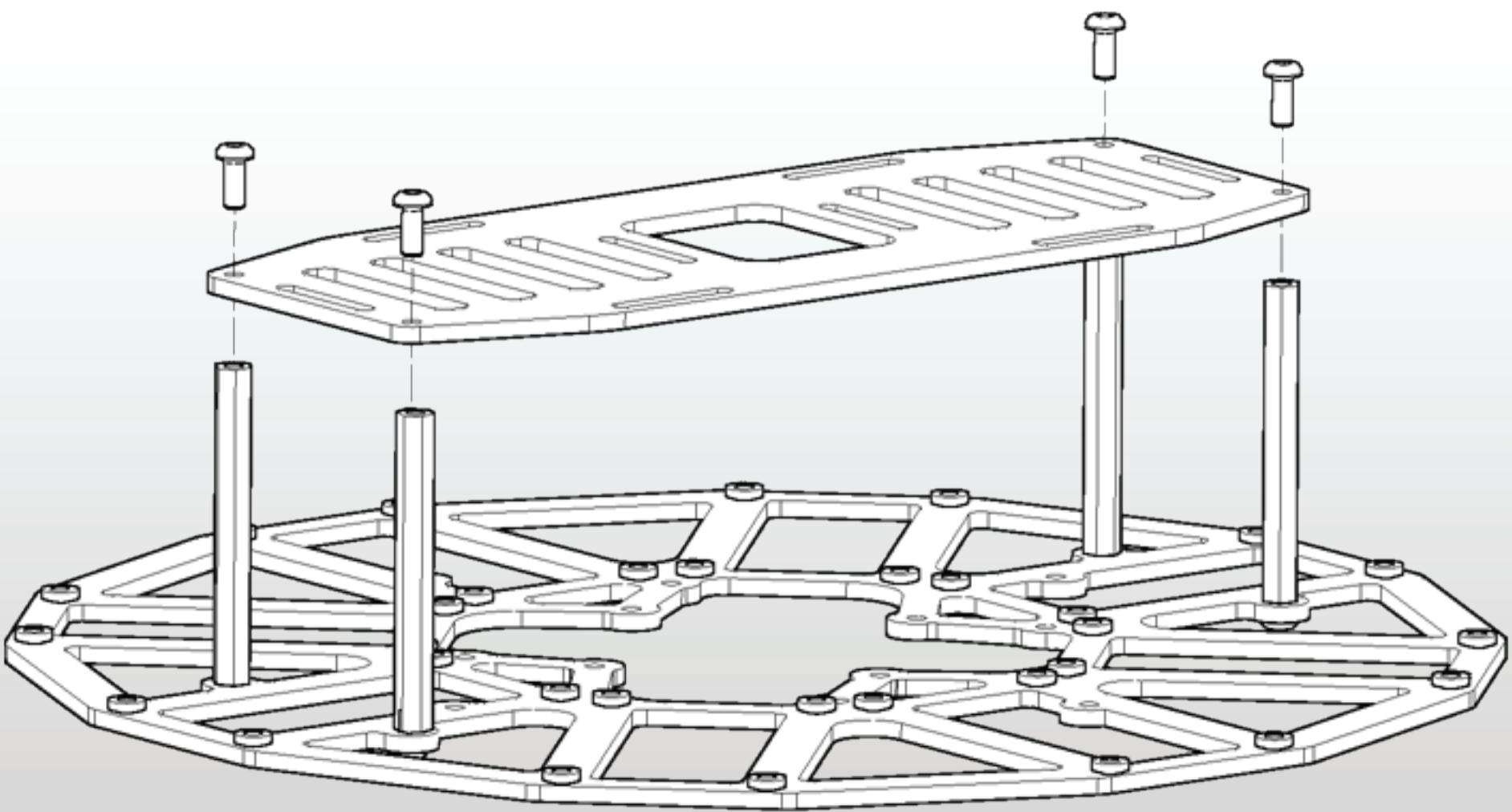
BP7.2 Insert four (4) M3x6 BHCS into the holes in the top frame plate as shown in the drawing. Note that the current view shows the bottom side of the top frame plate.

3



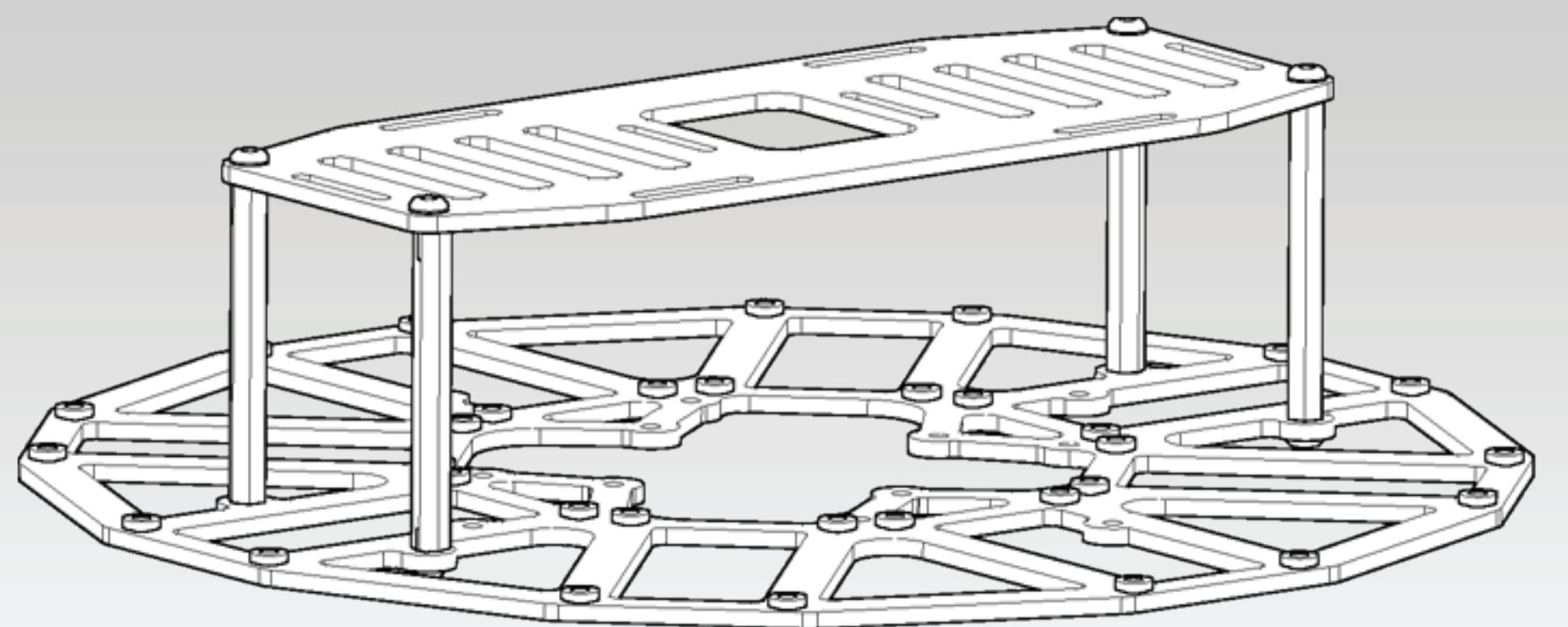
BP7.3 Thread the four (4) 50mm aluminum standoffs onto the M3x6 BHCS.

4



BP7.4 Thread four (4) M3x6 BHCS through the battery tray and into the 50mm aluminum standoffs.

5



BP7.5 Assembled battery plate.

