



## C interfaces to GALAHAD SHA

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# Chapter 1

## GALAHAD C package sha

### 1.1 Introduction

#### 1.1.1 Purpose

Find an approximation to a sparse Hessian using componentwise secant approximation.

Currently, only the control and inform parameters are exposed; these are provided and used by other GALAHAD packages with C interfaces.

#### 1.1.2 Authors

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C interface, additionally J. Fowkes, STFC-Rutherford Appleton Laboratory.

Julia interface, additionally A. Montoison and D. Orban, Polytechnique Montréal.

#### 1.1.3 Originally released

April 2013, C interface January 2022.



## Chapter 2

# File Index

### 2.1 File List

Here is a list of all files with brief descriptions:

<a href="#">galahad_sha.h</a>	.....	??
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## Chapter 3

# File Documentation

### 3.1 galahad\_sha.h File Reference

```
#include <stdbool.h>
#include <stdint.h>
#include "galahad_precision.h"
#include "galahad_cfunctions.h"
```

#### Data Structures

- struct [sha\\_control\\_type](#)
- struct [sha\\_inform\\_type](#)

#### 3.1.1 Data Structure Documentation

##### 3.1.1.1 struct sha\_control\_type

control derived type as a C struct

##### Data Fields

bool	f_indexing	use C or Fortran sparse matrix indexing
int	error	error and warning diagnostics occur on stream error
int	out	general output occurs on stream out
int	print_level	the level of output required. $\leq 0$ gives no output, $= 1$ gives a one-line summary for every iteration, $= 2$ gives a summary of the inner iteration for each iteration, $\geq 3$ gives increasingly verbose (debugging) output
int	approximation_algorithm	which approximation algorithm should be used? <ul style="list-style-type: none"><li>• 0 : unsymmetric (alg 2.1 in paper)</li><li>• 1 : symmetric (alg 2.2 in paper)</li><li>• 2 : composite (alg 2.3 in paper)</li><li>• 3 : composite 2 (alg 2.2/3 in paper)</li></ul>

## Data Fields

int	dense_linear_solver	which dense linear equation solver should be used? <ul style="list-style-type: none"> <li>• 1 : Gaussian elimination</li> <li>• 2 : QR factorization</li> <li>• 3 : singular-value decomposition</li> <li>• 4 : singular-value decomposition with divide-and-conquer</li> </ul>
int	max_sparse_degree	the maximum sparse degree if the combined version is used
int	extra_differences	if available use an addition extra_differences differences
bool	space_critical	if space is critical, ensure allocated arrays are no bigger than needed
bool	deallocate_error_fatal	exit if any deallocation fails
char	prefix[31]	all output lines will be prefixed by .prefix(2:LEN(TRIM(.prefix))-1) where .prefix contains the required string enclosed in quotes, e.g. "string" or 'string'

## 3.1.1.2 struct sha\_inform\_type

inform derived type as a C struct

## Data Fields

int	status	return status. See SHA_solve for details
int	alloc_status	the status of the last attempted allocation/deallocation.
int	max_degree	the maximum degree in the adgacency graph.
int	differences_needed	the number of differences that will be needed.
int	max_reduced_degree	the maximum reduced degree in the adgacency graph.
int	bad_row	a failure occured when forming the bad_row-th row (0 = no failure).
char	bad_alloc[81]	the name of the array for which an allocation/deallocation error occurred.