SightScan | AMOS Project Team 2: Computer Vision for Sight Detection

Build and Deploy Documentation

SightScan | AMOS Project Team 2

INTRODUCTION

This documentation describes how to build and deploy all components of SightScan.

Make sure to follow the exact order presented in this documentation to prevent any dependency clashes between the components. The same applies to our advised hardware requirements, especially on the model training side. This documentation relies on any arbitrary Unix based operating system. We assume that the open source SightScan repository is cloned and located in your local home directory, i.e. ~/amos-pj-ws20-21-computer-vision-for-sights directory. Furthermore, being familiar with the technical documentation and especially the software architecture before advancing to the following contents is highly advised. If you simply want to launch selected components locally using Docker, please refer to the README.md files in the individual component folders.

HOW TO: BUILD AND DEPLOY

PostgreSQL Data Warehouse (DWH)

PostgreSQL is the open source, object-relational database SightScan utilizes as its central

SightScan | AMOS Project Team 2: Computer Vision for Sight Detection

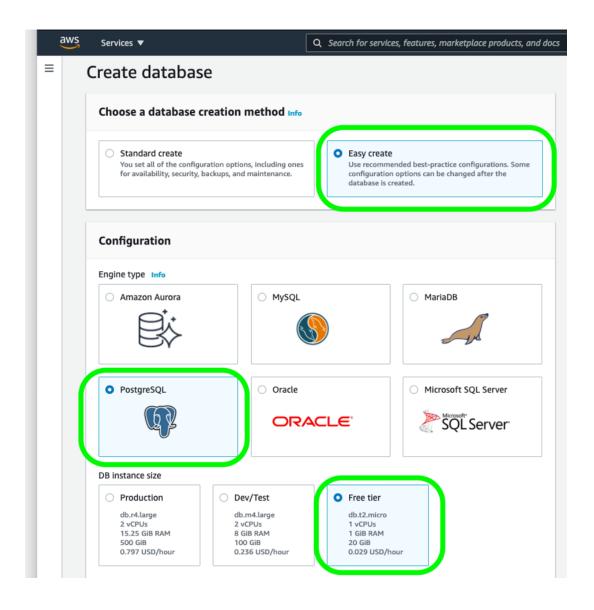
data warehouse. It is deployed on Amazon RDS (Relational Database Service) with the possibility of using the free tier for testing or development purposes.

Important Environment Variables

- PGHOST: raw host URL the DWH runs on (without http:// or https:// as a prefix)
- **PGPORT**: port the DWH is available from
- **PGDATABASE**: name of the internal database the DWH is setup with
- **PGUSER**: username for accessing the database
- **PGPASSWORD**: password for the specified user

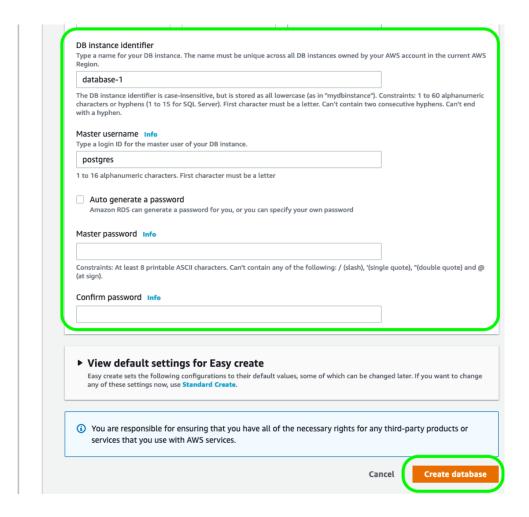
- 1. On Amazon Web Service, navigate to the Amazon RDS dashboard and click "Create database"
- **2.** Choose PostgreSQL as the database engine of choice; optionally, feel free to use the free tier configuration with limited hardware performance

SightScan | AMOS Project Team 2: Computer Vision for Sight Detection



3. Specify a database name, username, and a password for accessing the database; these parameters constitute the PGDATABASE, PGUSER, and PGPASSWORD parameters

SightScan | AMOS Project Team 2: Computer Vision for Sight Detection



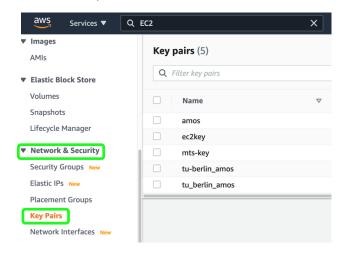
- 4. Confirm your input and create the database instance
- 5. In the settings, make sure incoming traffic from anywhere (0.0.0.0/0 and ::/0)
- 6. Execute the database_init.sql file on the newly created database instance to initialize its schema and automation mechanisms either directly in the Amazon RDS dashboard or by using an external tool of choice, e.g. DBeaver, as can be seen below:



Global SSH Key for Computing Instance Access

Since SightScan heavily relies on distributed computing instances, multiple instances must be managed. It uses Amazon Web Services (AWS) as the cloud platform of choice. In order to avoid juggling with SSH keys, we highly advise to generate a global SSH key for accessing all EC2 instances collectively. This way, key exchanges are easier on AWS, as only a single key reference needs to be replaced instead of taking care of every computing instance individually — an especially huge manual effort for large production environments. If you do not want to do this, repeat this section for every component you want to deploy, and provide the respective path to the individual SSH key in each SSH command.

 Visit the EC2 service page on AWS and navigate to the "Key Pairs" field under "Under Network & Security"

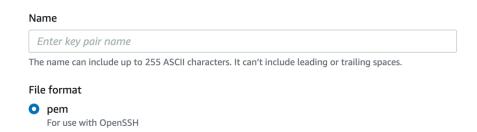


2. Click "Create key pair"



3. Create a new SSH key pair in the .pem format and using your selected name of choice; in this documentation, our global, private SSH key is persisted in the file **ec2key.pem**

SightScan | AMOS Project Team 2: Computer Vision for Sight Detection



4. Download the private SSH key so that it resides in the local Download folder of your home directory

Image Crawler (IC)

The crawler is responsible for retrieving sight images for a given city and inserting them into the data warehouse subsequently.

Important Environment Variables

- IC_URL: URL of the EC2 instance of the image crawler
- For more: see **DOS** component

Additional Command Line Arguments

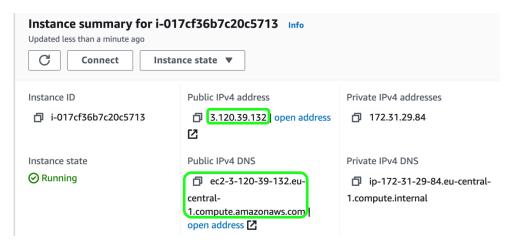
- skip: skips keywords if a downloaded directory already exists this
 is useful for caching already downloaded items or forcing redownloads; default: true
- threads: number of threads available for downloading; default: 4
- google: whether to download from google.com; default: true
- full: whether to download images in full resolution; default: false
 - Note: enabling full resolution downloads often substantially improves model performance, but comes with the expense of increased memory footprints in the data warehouse

SightScan | AMOS Project Team 2: Computer Vision for Sight Detection

- face: whether to use the included face search mode; default: false
- no_gui: whether to load images in headless mode; default: auto
 - Note: When this parameter is set to auto instead of a Boolean value, it is internally overwritten with false if the full argument is true, otherwise it is set to false
- limit: maximum images to download per identified sight; default: 0
 - Note: setting this parameter to 0 means unbounded this could theoretically lead to an unlimited number of persisted images in the data warehouse and should thus be avoided
- no_driver: whether a dedicated image crawling driver should be used; default: false
- location: name of the city to crawl sight images for
- **sights_limit**: maximum sights to support for a given city

- 1. Launch an EC2 instance for the IC component with the following basic requirements:
 - Operating system: up-to-date Linux Ubuntu
 - Computing power: at least two vCPUs
 - Random access memory: at least 8 GB
 - Disk memory: enough memory to store the downloaded sight images for a given city; we recommend 5 GB memory for small and at least 40GB for large deep learning models
 - Security group: allowing traffic from 0.0.0.0/0 and ::/0 origins for port 22 (SSH port),
 or preferably merely from the default AWS virtual private cloud (VPC) IP range
 - **Docker daemon**: configured and running
- **2.** Prepare the folder structures on the EC2 instance to deploy your code into:
 - a. Notice the target values for IC_IP (public IPv4 IP address) andIC_URL (public IPv4 DNS) on the main page of your launched instance.

SightScan | AMOS Project Team 2: Computer Vision for Sight Detection



b. Connect to the instance via SSH through your terminal of choice:

```
sudo ssh -i ~/Downloads/ec2key.pem ubuntu@<IC_IP>
```

c. On the instance, create a dedicated crawler folder to store the artifacts:

```
sudo mkdir crawler
sudo chmod 777 crawler
exit
```

3. From your local computer, upload the cache-free, clean code to the EC2 instance of the crawler:

```
sudo scp -i ~/Downloads/ec2key.pem -r ~/amos-pj-ws20-21-
computer-vision-for-sights/amos/crawler
ubuntu@<IC_URL>:~/crawler/
```

4. Reconnect to the instance via SSH and build its Docker image:

```
sudo ssh -i ~/Downloads/ec2key.pem ubuntu@<IC_IP>
cd crawler/crawler
sudo docker build . -t crawler
exit
```

5. That's it — now, executions of the constructed Docker image can be triggered from a remote DOS instance through SSH.

Model Training Service (MTS)

The model training service is responsible for training Yolov5 deep learning models for computer vision.

Important Environment Variables

- MTS_EC2_INSTANCE_ID: id assigned to the EC2 instance of the MTS
- For more: see **DMR** component

- 1. Launch an EC2 instance for the MTS component with the following basic requirements:
 - Amazon Machine Image (AMI): deep learning-specialized AMI with
 - Operating system: up-to-date Linux Ubuntu
 - Docker and Nvidia Docker pre-installed
 - CUDA and PyTorch optimization
 - Recommendation: Deep Learning Base AMI (Ubuntu 18.04) Version 32.0 (or higher)
 - Computing power: at least four vCPUs, at least Nvidia Volta GPU
 - Note: older Nvidia Tesla GPUs like the K80 are not supported by our Yolov5
 setup
 - Random access memory: at least 16 GB
 - Disk memory: persistent EBS block storage and enough memory to store the downloaded sight images for a given city, but at least 85 GB
 - **Security group**: allowing traffic from 0.0.0.0/0 and ::/0 origins for port 22 (SSH port), or preferably merely from the default AWS virtual private cloud (VPC) IP range
 - Our EC2 instance recommendation: p3.xlarge type for most cost-efficient compatibility

SightScan | AMOS Project Team 2: Computer Vision for Sight Detection

- 2. Prepare the folder structures on the EC2 instance to deploy your code into:



b. Connect to the instance via SSH through your terminal of choice:

```
sudo ssh -i ~/Downloads/ec2key.pem ubuntu@<MTS_IP>
```

c. Make sure the AWS CLI is installed to enable dynamic remote calls:

```
sudo apt-get update
sudo apt-get install awscli
```

d. On the instance, create a dedicated crawler folder to store the artifacts:

```
sudo mkdir mts
sudo chmod 777 mts
exit
```

3. From your local computer, upload the cache-free, clean code to the EC2 instance of the MTS:

```
sudo scp -i ~/Downloads/ec2key.pem -r ~/amos-pj-ws20-21-
computer-vision-for-sights/amos/mts ubuntu@<MTS_URL>:~/mts/
```

4. Upload the orchestrating bash script to the EC2 instance of the MTS:

```
sudo scp -i ~/Downloads/ec2key.pem ~/amos-pj-ws20-21-
computer-vision-for-sights/amos/mts.sh
ubuntu@<MTS_URL>:~/mts/
```

SightScan | AMOS Project Team 2: Computer Vision for Sight Detection

5. Reconnect to the instance via SSH and make the bash script executable:

```
sudo ssh -i ~/Downloads/ec2key.pem ubuntu@<MTS_IP>
cd mts
command chmod +x mts.sh
```

6. Build the Docker image for the MTS:

```
sudo ssh -i ~/Downloads/ec2key.pem ubuntu@<MTS_IP>
cd mts/yolov5
sudo docker build . -t mts
exit
```

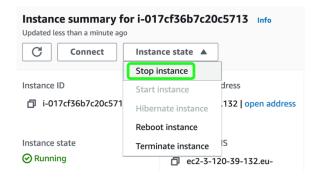
7. Stop the EC2 instance of the MTS

<u>Note 1</u>: This step is crucial since the EC2 instance of the MTS is dynamically booted and shut down for training to save costs — GPU instances are expensive. By stopping the instance initially, we allow it

to be booted by dedicated city training jobs and minimize financial expenditures.

Note 2: Terminating the instance deallocates the entire instance forever and should not be

performed at all — stopping it merely shuts it down and retains the configurations.



8. That's it — now, city training jobs can be triggered from remote services, which subsequently boots the MTS instance, performs training, and finally shuts the instance down.

Image Labelling Service (ILS)

The image labelling service communicates with the Google Vision API in order to provide labels for cities that have been lately added to SightScan.

Important Environment Variables

- ILS PORT: port the ILS runs on
 - Note: for the sake of simplicity, picking the container-internal port (8001) is advised
- MAX_GOOGLE_VISION_CALLS_PER_NEW_CITY: maximum number of requests sent to the Google Vision API for a newly supported city to restrict costs
- PGHOST, PGPORT, PGDATABASE, PGUSER, and PGPASSWORD (database parameters from above)

- 1. Launch an EC2 instance for the ILS component with the following basic requirements:
 - Operating system: up-to-date Linux Ubuntu
 - Computing power: at least two vCPU
 - Random access memory: at least 4 GB
 - Docker daemon: configured and running
 - Security group: allowing traffic from 0.0.0.0/0 and ::/0 origins for port 22 (SSH port)
 and TCP traffic on <ILS_PORT>, or preferably merely from the default AWS virtual
 private cloud (VPC) IP range
- 2. Prepare the folder structures on the EC2 instance to deploy your code into:
 - a. Notice the target values for ILS_IP (public IPv4 IP address) andILS_URL (public IPv4 DNS) on the main page of your launched instance.

SightScan | AMOS Project Team 2: Computer Vision for Sight Detection



b. Connect to the instance via SSH through your terminal of choice:

```
sudo ssh -i ~/Downloads/ec2key.pem ubuntu@<ILS IP>
```

c. On the instance, create a dedicated ILS folder to store the artifacts:

```
sudo mkdir ils
sudo chmod 777 ils
exit
```

3. From your local computer, upload the cache-free, clean code to the EC2 instance of the ILS:

```
sudo scp -i ~/Downloads/ec2key.pem -r ~/amos-pj-ws20-21-
computer-vision-for-sights/amos/image_labelling_service
ubuntu@<ILS_URL>:~/ils/
```

4. Reconnect to the instance via SSH and build its Docker image:

```
sudo ssh -i ~/Downloads/ec2key.pem ubuntu@<ILS_IP>
cd ils/image_labelling_service
sudo docker build . -t ils
```

SightScan | AMOS Project Team 2: Computer Vision for Sight Detection

5. Launch the ILS on its EC2 instance via Docker

```
sudo docker run -d
-e PGHOST=<PGHOST>
-e PGDATABASE=<PGDATABASE>
-e PGUSER=<PGUSER>
-e PGPORT=<PGPORT>
-e PGPASSWORD=<PGPASSWORD>
-e MAX_GOOGLE_VISION_CALLS_PER_NEW_CITY=
<MAX_GOOGLE_VISION_CALLS_PER_NEW_CITY>
-p <ILS_PORT>:8001
```

-it ils6. Exit the instance:

exit

Data Mart Refresher (DMR)

The data mart refresher component refreshes data warehouse contents asynchronously to expose both labelled images and trained models in dedicated data marts for faster queries. During refreshes, it identifies new cities to be labelled and triggers labelling processes. Furthermore, it detects whenever new city models are trainable, and notifies the MTS subsequently.

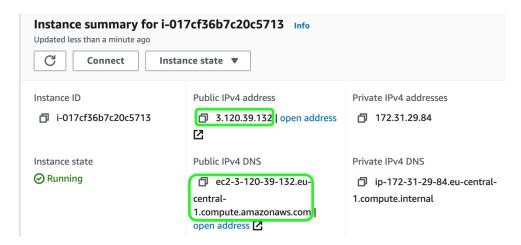
Important Environment Variables

- AWS_ACCESS_KEY_ID: Amazon Web Services key ID for the IAM role under which the
 MTS should be triggered (needs Full EC2 permission policy)
- AWS_ACCESS_KEY: corresponding key for the given key ID
- AWS_REGION: region of the AWS EC2 instances; generally: eu-central-1
- DATA_MART_REFRESH_DATA_MARTS_EVERY_SECONDS: delay between resourceintensive data mart refreshes
 - Note: typically, refreshing every hour (setting this value to 3600) is more than
 enough since users usually not count the seconds until a new model is available
- DATA_MART_ENABLE_MODEL_TRAINING_EVERY_SECONDS: delay between checking
 if a city is available for training and potentially triggering the MTS
 - Note: with the same reasoning as before, we advise setting this value to 3600 or higher; training usually takes more than an hour anyway
- DATA_MART_ENABLE_LABELLING_REQUESTS_EVERY_SECONDS: delay between emitting a batch of labelling requests to the ILS component
 - Note: the same reasoning as with the two previously mentioned parameters applies here
- ILS_PUBLIC_ENDPOINT_URL: public URL to the ILS service, including port and http prefix
- MTS_EC2_INSTANCE_ID: cf. above

SightScan | AMOS Project Team 2: Computer Vision for Sight Detection

- MTS_EPOCHS: number of epochs the MTS should train for a new city
- MIN_LABELLED_IMAGES_NEEDED_FOR_TRAINING: minimum number of required labelled images to trigger a city training job in the MTS component
- MIN_IMAGE_NUMBER_PER_LABEL: minimum number of required available images per label
 - Note: setting this parameter too high leaves more data points out of the training points, setting it too low may decrease the model performance due to highly poor class performance; consider the trade-off between data volume and data quality in your training process
- PGHOST, PGPORT, PGDATABASE, PGUSER, and PGPASSWORD (database parameters from above)

- 1. Launch an EC2 instance for the DMR with the following basic requirements:
 - Operating system: up-to-date Linux Ubuntu
 - Computing power: at least one vCPU
 - Random access memory: at least 4 GB
 - Docker daemon: configured and running
- 2. Prepare the folder structures on the EC2 instance to deploy your code into:
 - a. Notice the target values for DMR_IP (public IPv4 IP address) and
 DMR_URL (public IPv4 DNS) on the main page of your launched instance.



SightScan | AMOS Project Team 2: Computer Vision for Sight Detection

b. Connect to the instance via SSH through your terminal of choice:

```
sudo ssh -i ~/Downloads/ec2key.pem ubuntu@<DMR_IP>
```

c. On the instance, create a dedicated data mart refresher folder to store the artifacts:

```
sudo mkdir dmr
sudo chmod 777 dmr
exit
```

3. From your local computer, upload the cache-free, clean code to the EC2 instance of the DMR:

```
sudo scp -i ~/Downloads/ec2key.pem -r ~/amos-pj-ws20-21-
computer-vision-for-sights/amos/data_mart_refresher
ubuntu@<DMR_URL>:~/dmr/
```

4. Reconnect to the instance via SSH and build its Docker image:

```
sudo ssh -i ~/Downloads/ec2key.pem ubuntu@<DMR_IP>
cd dmr/data_mart_refresher
sudo docker build . -t dmr
```

SightScan | AMOS Project Team 2: Computer Vision for Sight Detection

5. Launch the DMR on its EC2 instance via Docker:

```
sudo docker run -d
-e ILS PUBLIC ENDPOINT URL=<ILS PUBLIC ENDPOINT URL>
-e MTS EC2 INSTANCE ID=<MTS EC2 INSTANCE ID>
-e AWS ACCESS KEY ID=<AWS ACCESS KEY ID>
-e AWS ACCESS KEY=<AWS_ACCESS_KEY>
-e AWS REGION=<AWS REGION>
-e MTS EPOCHS=<MTS EPOCHS>
-e DATA MART REFRESH DATA MARTS EVERY SECONDS=
<DATA MART REFRESH DATA MARTS EVERY SECONDS>
-e DATA MART ENABLE MODEL TRAINING EVERY SECONDS=
<DATA MART ENABLE MODEL TRAINING EVERY SECONDS>
-e DATA MART ENABLE LABELLING REQUESTS EVERY SECONDS=
<DATA MART ENABLE LABELLING REQUESTS EVERY SECONDS>
-e PGHOST=<PGHOST>
-e PGDATABASE=<PGDATABASE>
-e PGUSER=<PGUSER>
-e PGPORT=<PGPORT>
-e PGPASSWORD=<PGPASSWORD>
-e MIN LABELLED IMAGES NEEDED FOR TRAINING=
<MIN_LABELLED_IMAGES_NEEDED_FOR_TRAINING>
```

-e MIN IMAGE NUMBER PER LABEL=<MIN IMAGE NUMBER PER LABEL>

6. Exit the instance:

exit

-it dmr

Django Orchestration Service (DOS)

The Django orchestration service primarily functions as an abstraction layer between the client and the backend microservice ensemble. It persists client data in the data warehouse, exposes data from the latter to the client, and triggers the image crawler if needed.

Important Environment Variables

- **DOS_PORT**: the port that exposes the DOS endpoints for access by clients
- IC_URL: URL of the EC2 instance of the image crawler (cf. above)
- MAPS_KEY: Google Maps key passed to the triggered image crawler for sight name retrieval
- MAX_IMAGES_PER_SIGHT: maximum number of images the triggered image crawler should retrieve per sight
 - Note: under the hood, this parameter sets the limit command line argument of the image crawler
- MAX_SIGHTS_PER_CITY: maximum number of sights the triggered image crawler should retrieve for the city

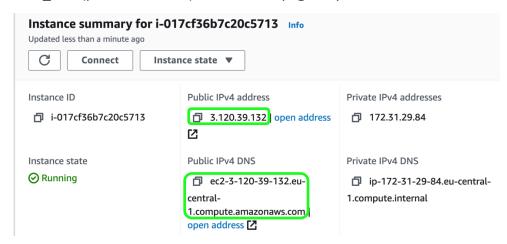
<u>Note</u>: this sets the command line argument sights_limit of the triggered image crawler

 PGHOST, PGPORT, PGDATABASE, PGUSER, and PGPASSWORD (database parameters from above)

- 1. Launch an EC2 instance for the DOS with the following basic requirements:
 - Operating system: up-to-date Linux Ubuntu
 - Computing power: at least one vCPU
 - Random access memory: at least 4 GB
 - Docker daemon: configured and running

SightScan | AMOS Project Team 2: Computer Vision for Sight Detection

- Security group: allowing traffic from 0.0.0.0/0 and ::/0 origins for port 22 (SSH port and TCP traffic on port <DOS_PORT>
- 2. Prepare the folder structures on the EC2 instance to deploy your code into:
 - a. Notice the target values for DOS_IP (public IPv4 IP address) and
 DOS_URL (public IPv4 DNS) on the main page of your launched instance.



b. Connect to the instance via SSH through your terminal of choice:

```
sudo ssh -i ~/Downloads/ec2key.pem ubuntu@<DOS IP>
```

c. On the instance, create a dedicated Django orchestrator folder to store the artifacts:

```
sudo mkdir dos
sudo chmod 777 dos
exit
```

3. From your local computer, upload the cache-free, clean code to the EC2 instance of the DOS:

```
sudo scp -i ~/Downloads/ec2key.pem -r ~/amos-pj-ws20-21-
computer-vision-for-sights/amos/django_orchestrator
ubuntu@<DOS_URL>:~/dos/
```

4. Reconnect to the instance via SSH and build its Docker image:

```
sudo ssh -i ~/Downloads/ec2key.pem ubuntu@<DMR_IP>
cd dmr/data_mart_refresher
sudo docker build . -t dmr
```

SightScan | AMOS Project Team 2: Computer Vision for Sight Detection

5. Launch the DOS on its EC2 instance via Docker:

```
sudo docker run -d
-e PGHOST=<PGHOST>
-e PGDATABASE=<PGDATABASE>
-e PGUSER=<PGUSER>
-e PGPORT=<PGPORT>
-e PGPASSWORD=<PGPASSWORD>
-e IC_URL=<IC_URL>
-e MAX_SIGHTS_PER_CITY=<MAX_SIGHTS_PER_CITY>
-e MAX_IMAGES_PER_SIGHT=<MAX_IMAGES_PER_SIGHT>
-e MAPS KEY=<MAPS KEY>
```

6. Exit the instance:

exit

Graphical User Interface

-p <**DOS PORT**>:8002 -it dos

The graphical user interface is controlled by the user — alongside communication with the DOS component, it performs typical SightScan functionalities, e.g. detecting a city's sights in a real-time webcam stream.

Important Environment Variables

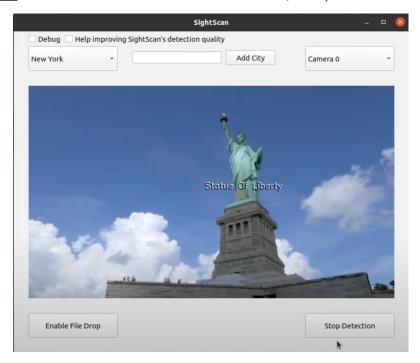
- API_ENDPOINT_URL: full base URL of the DOS component
 - Note: this parameter needs to follow the format http://<DOS_URL>:<DOS_PORT>

SightScan | AMOS Project Team 2: Computer Vision for Sight Detection

Deployment

- 1. Navigate into the folder containing the GUI
 - cd ~/amos-pj-ws20-21-computer-vision-for-sights/amos/gui
- 2. Create a file with name .env, containing only a single line:
 - API ENDPOINT URL= http://<DOS_URL>:<DOS_PORT>
- **3.** Make sure SightScan's GUI runs as expected on the client's local hardware by double-click the main.py file to launch it; alternatively, you may also double-click on the bash script located in the same folder

Note: the GUI has been tested on Windows 10, many Linux versions, and macOS



Large-Scale Production Environments

If you desire to deploy SightScan as a large-scale application, such as rolling it out for an entire country, you obviously need load balancers and many more computing resources than just one EC2 instance per component. In that case, since all components are dockerized, they can be easily deployed through Kubernetes via the Amazon Elastic Kubernetes Service (EKS) or EC2 Auto Scaling.

SightScan | AMOS Project Team 2: Computer Vision for Sight Detection

Final Words

Congratulations – at this point, the SightScan ecosystem is successfully deployed and ready to unleash its entire capabilities upon its users. Enjoy! ©