# Fishing for a good runtime starts with fusion



### Fusion

```
filterMax (xs : [Int])
= let above= filter (>0) xs
m = max xs
in (above, m)
```

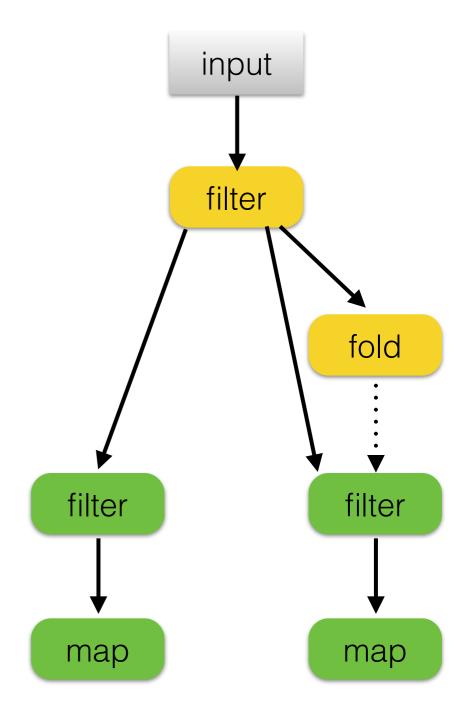
## Clustering

Paper published at FHPC'14: Fusing filters with ILP

Finds "best" clustering of graph

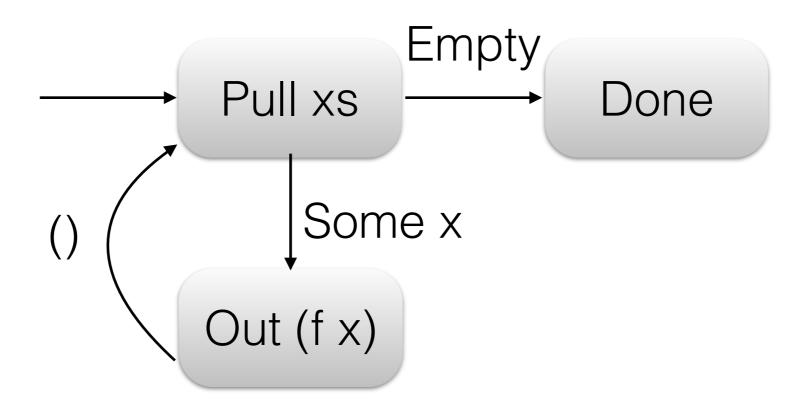
## Clustering

```
let ns = filter (>0) input
  sum = fold (+) 0
                       ns
  ls = filter (>sum)
                      ns
       = filter
              odd
                       ns
  rs
  ls'
      = map (+1)
                       Is
  rs' = map (-1)
                       rs
```

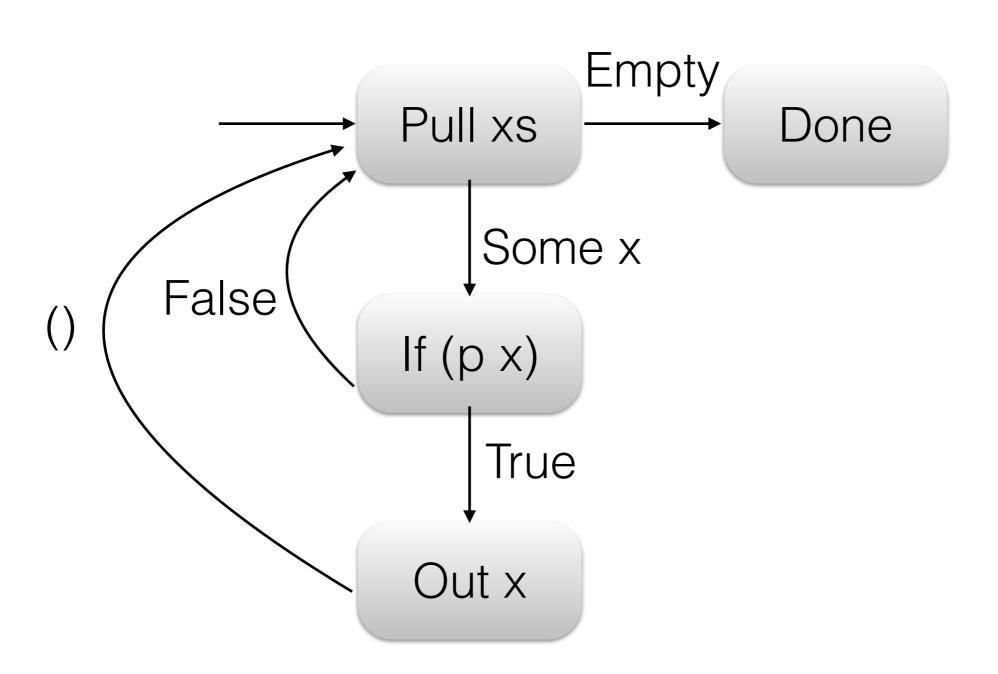




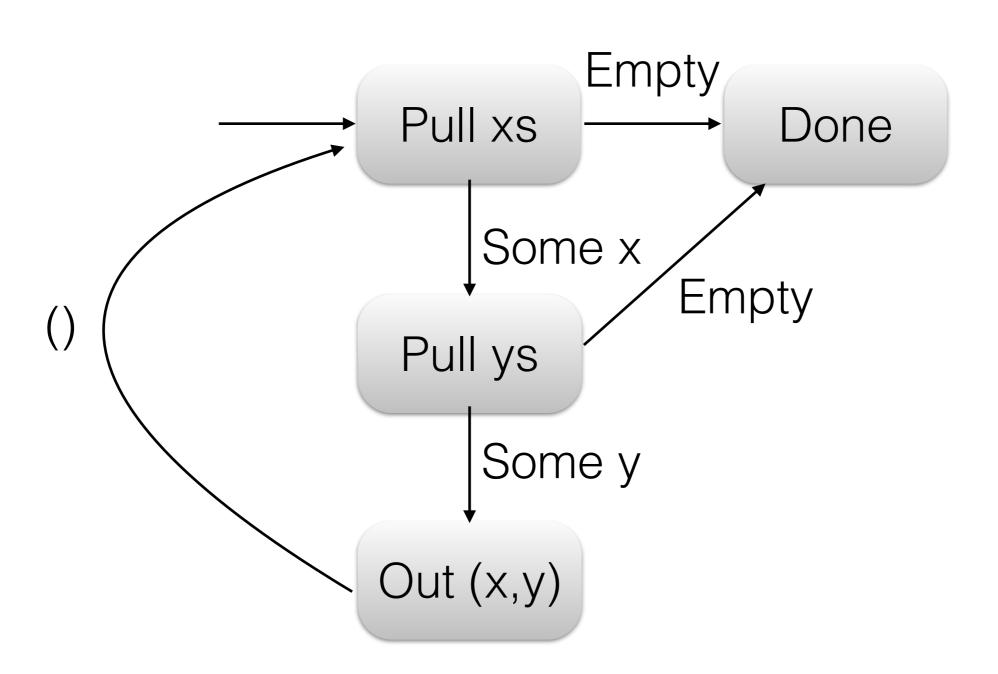
## Map f xs



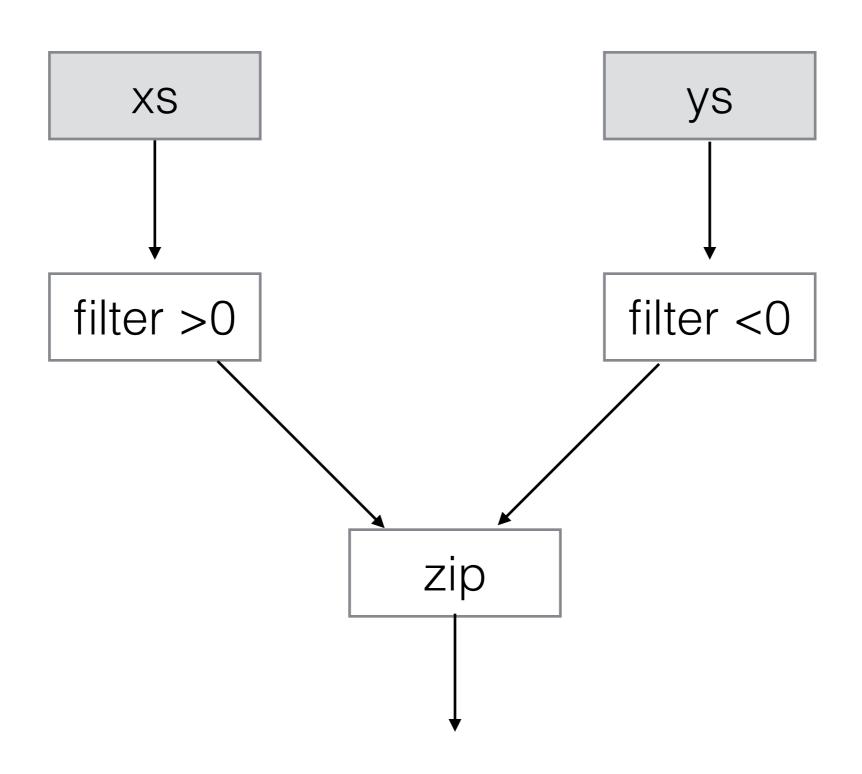
## Filter p xs



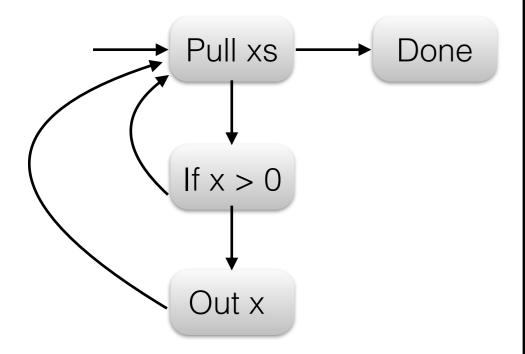
## Zip xs ys



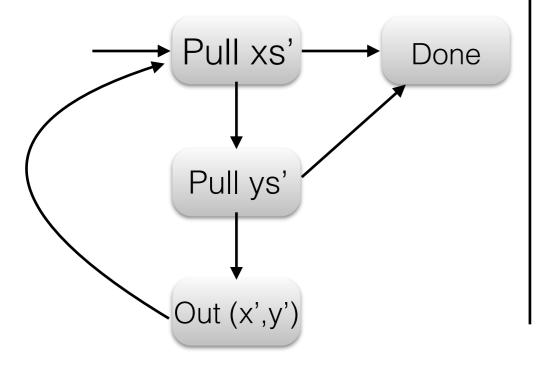
## Pairing example

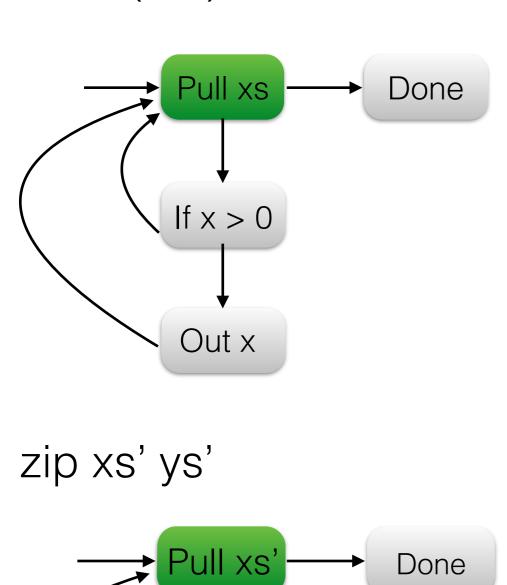


filter (>0) xs



zip xs' ys'

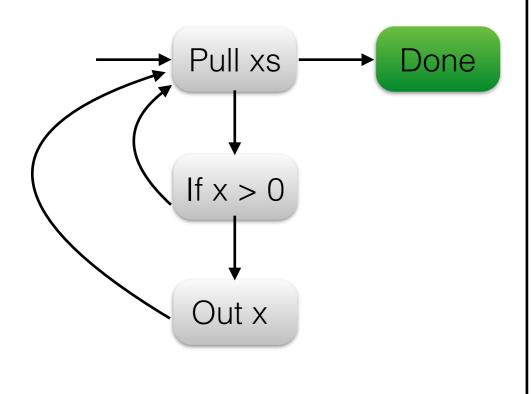




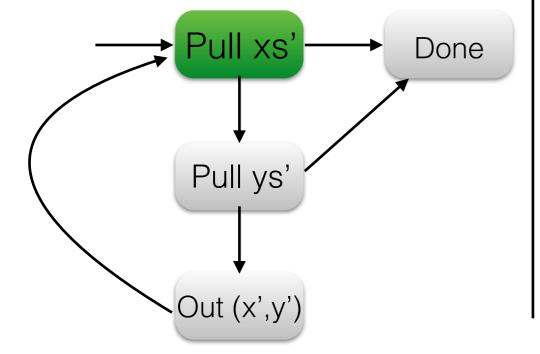
Pull ys'

Out (x',y')

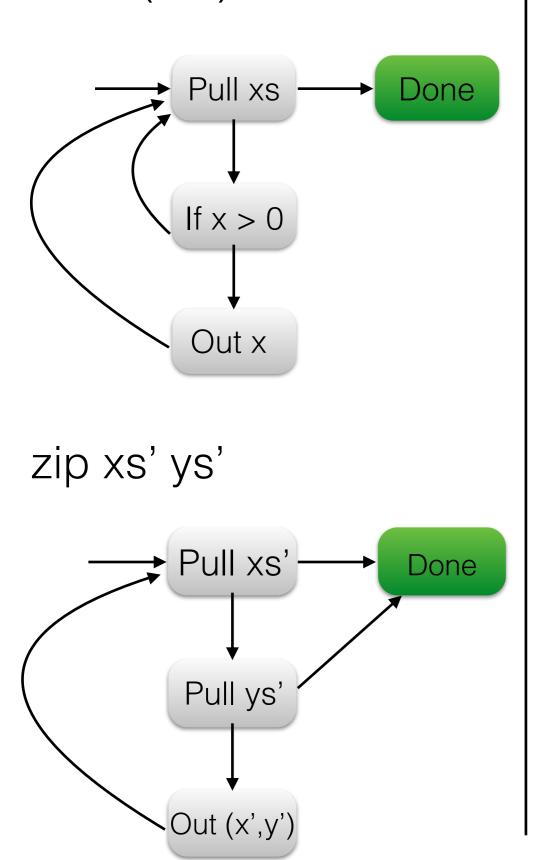
Pull xs



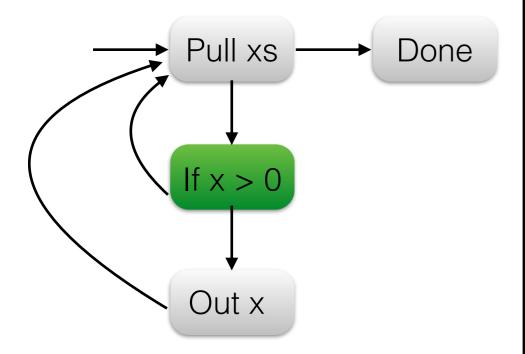
zip xs' ys'



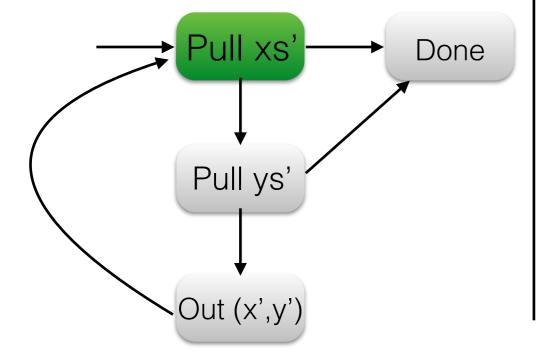
Pull xs →

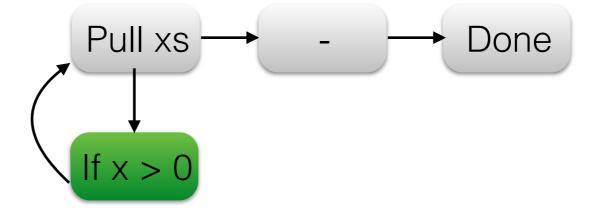


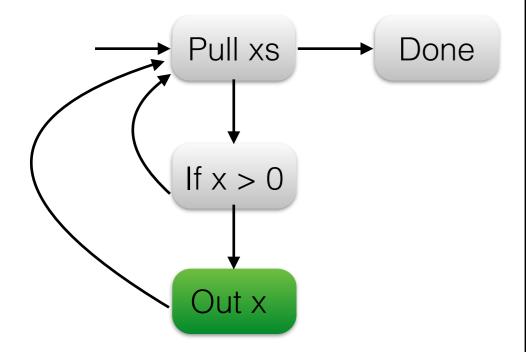




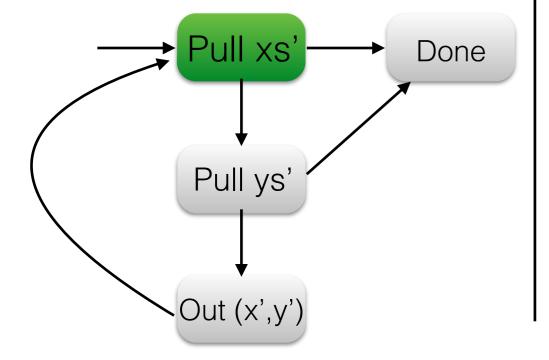
zip xs' ys'

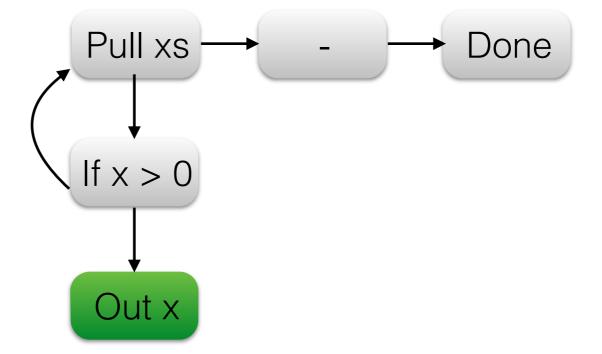


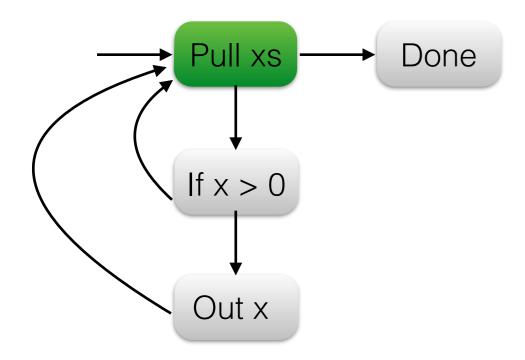




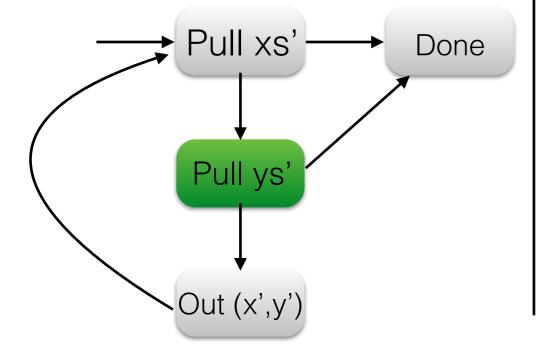
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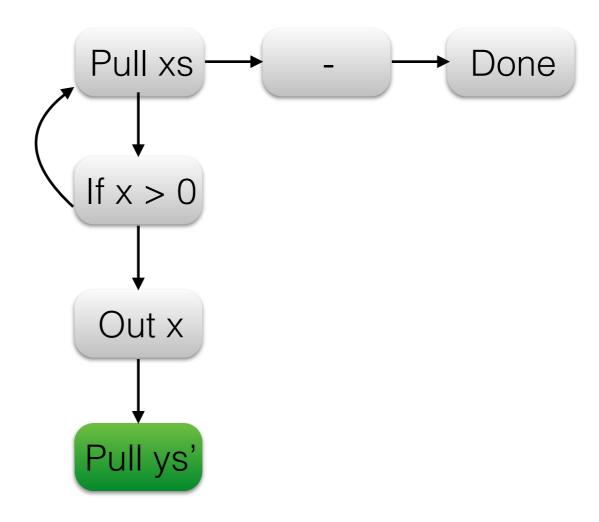


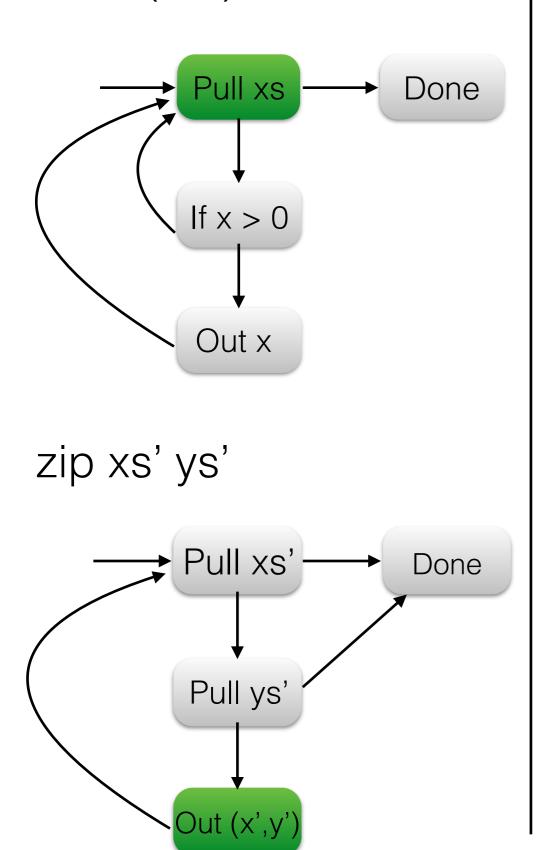


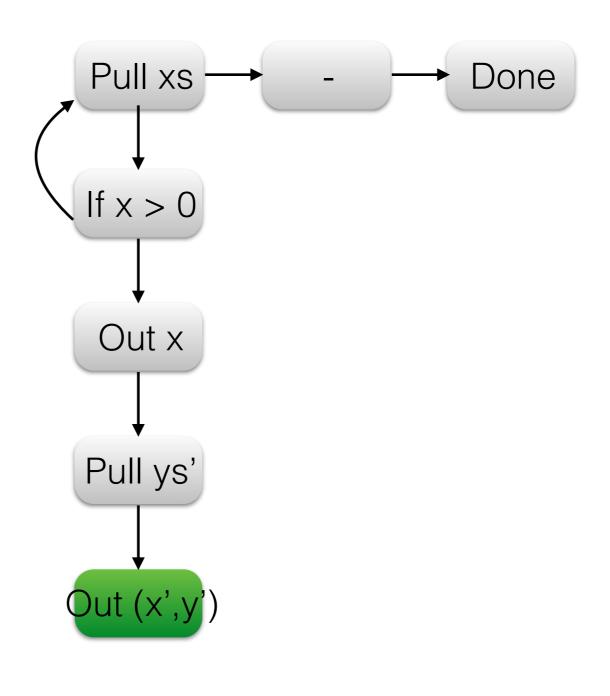


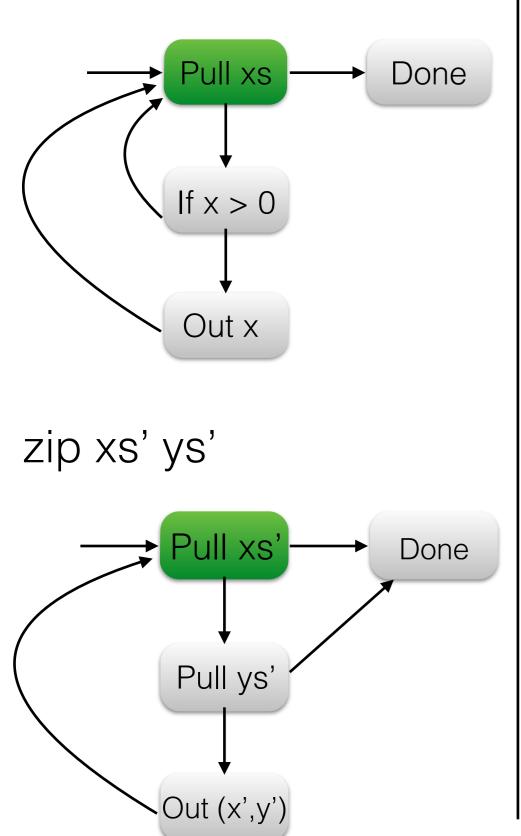
zip xs' ys'

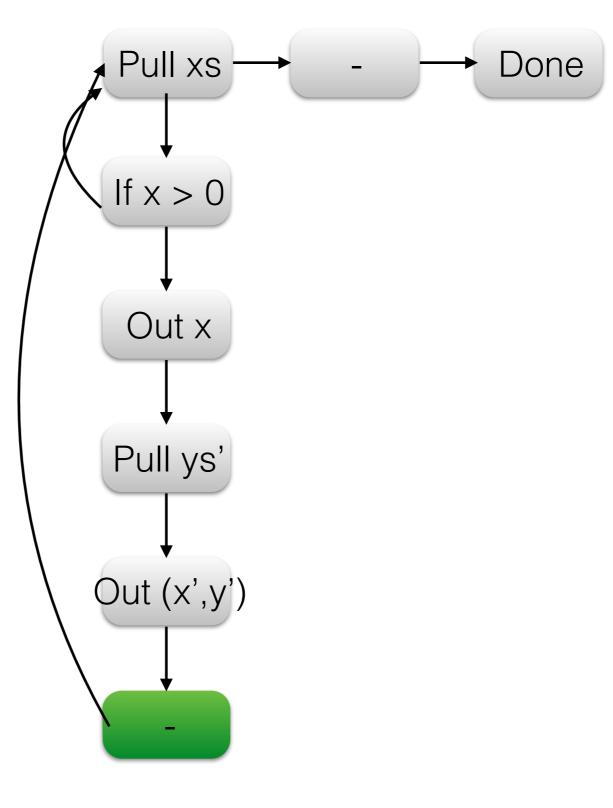


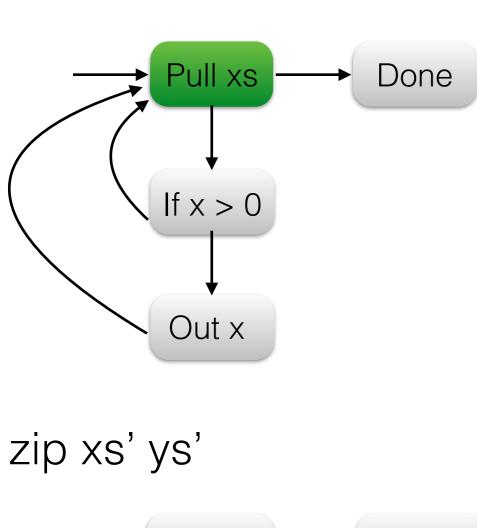


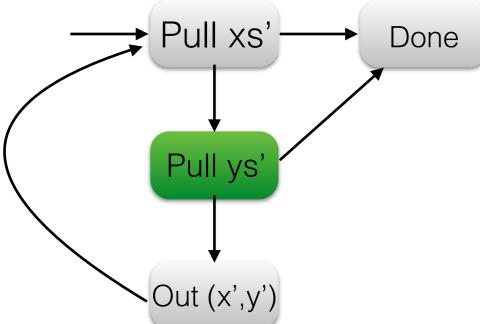


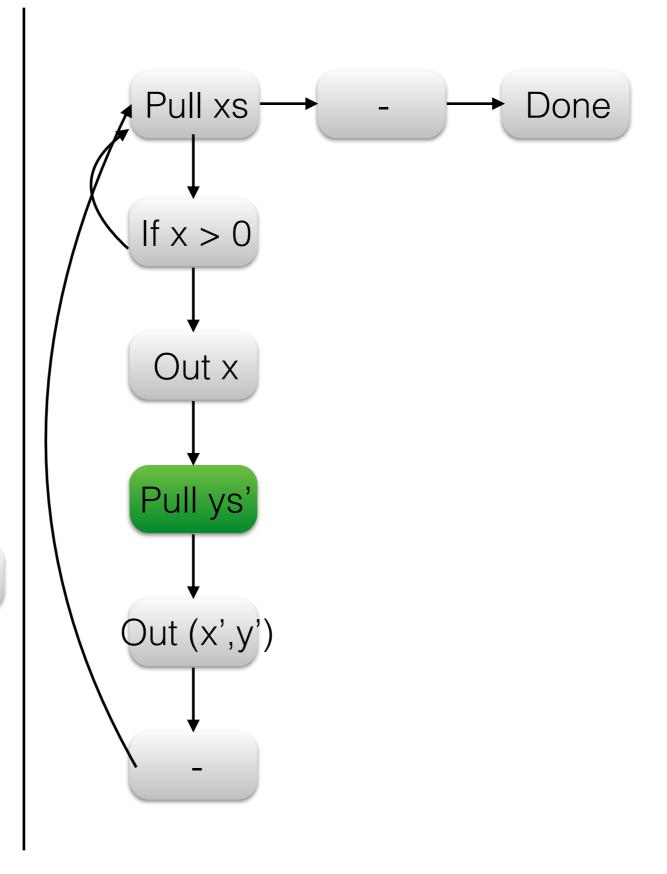


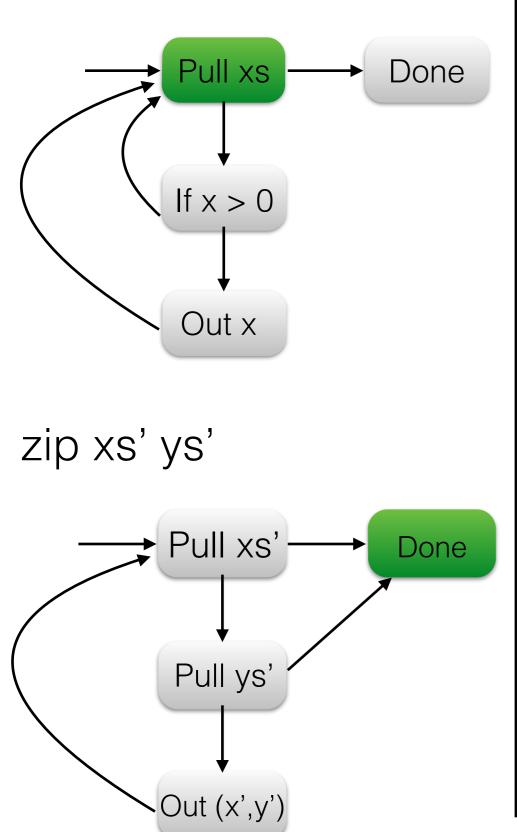


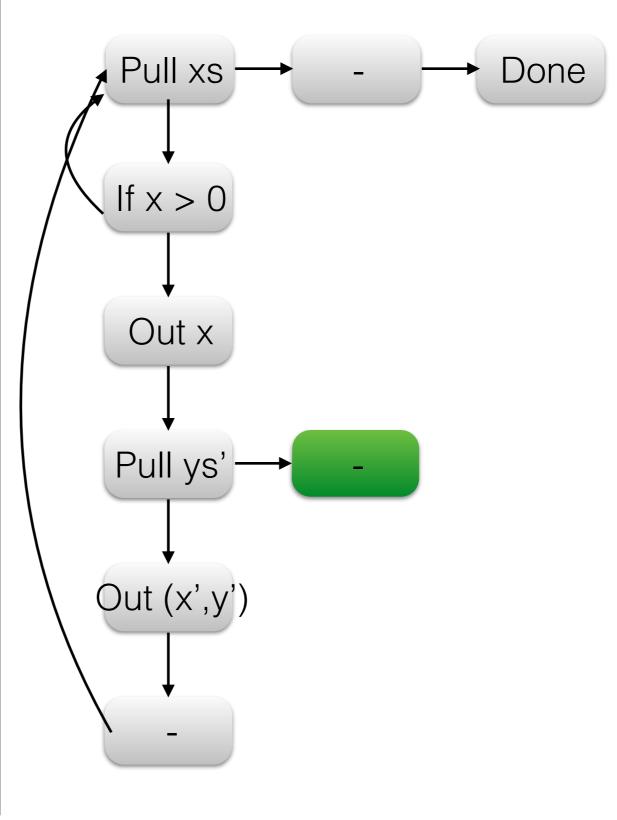


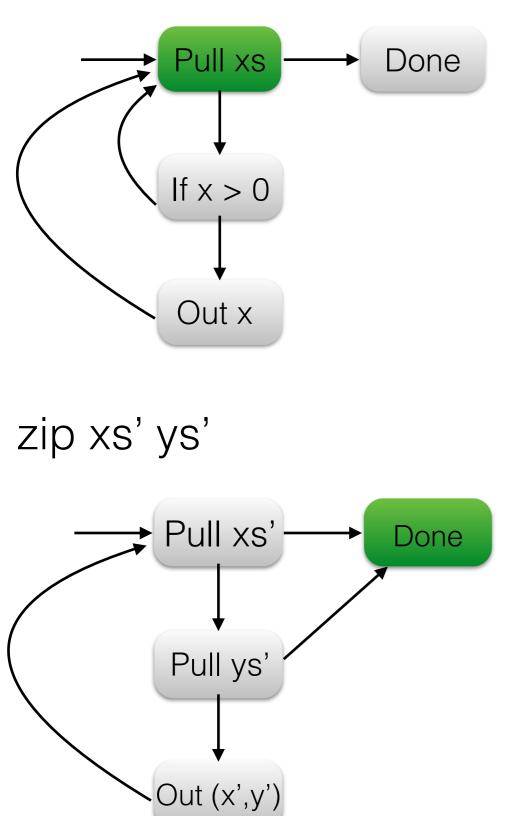


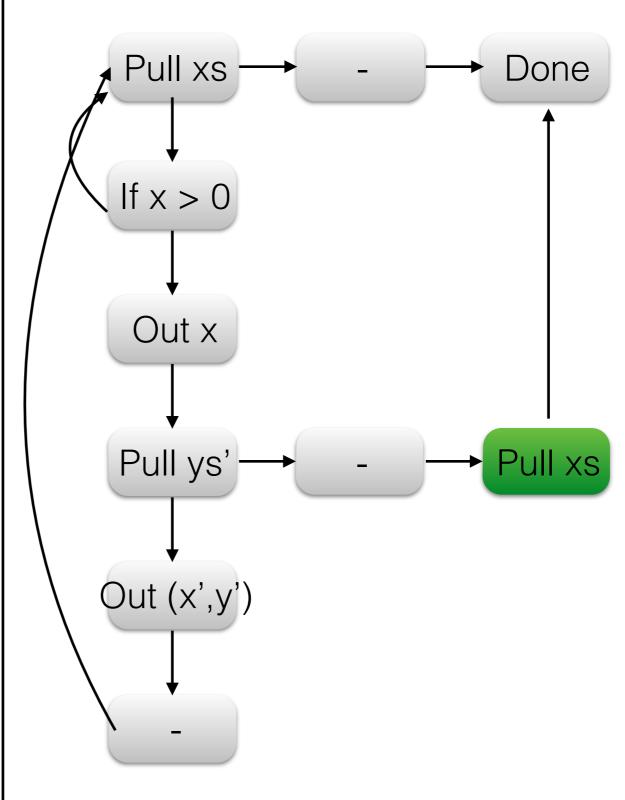


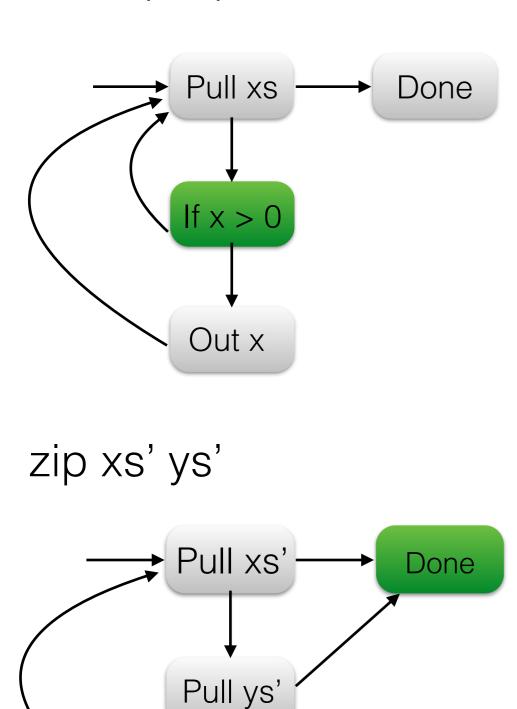




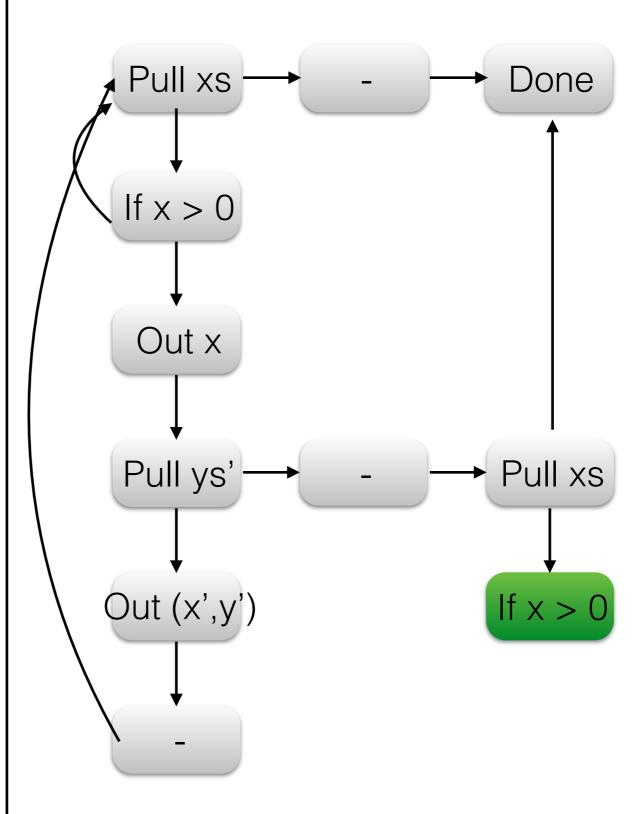


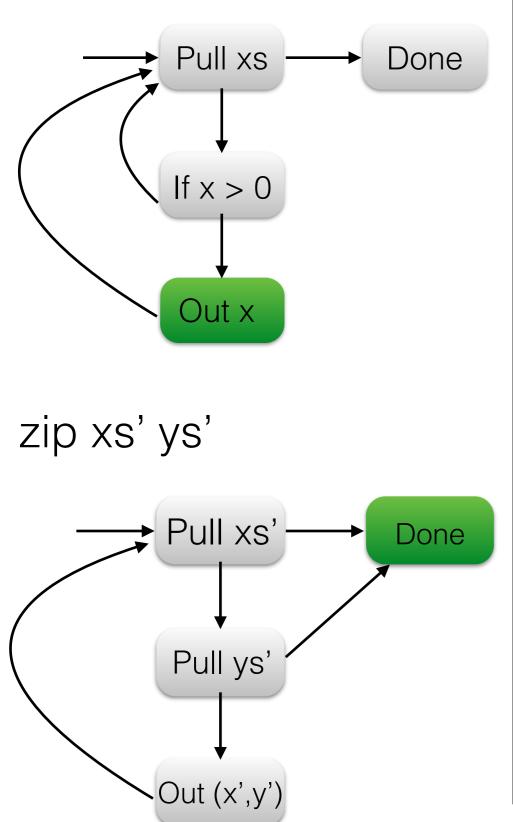


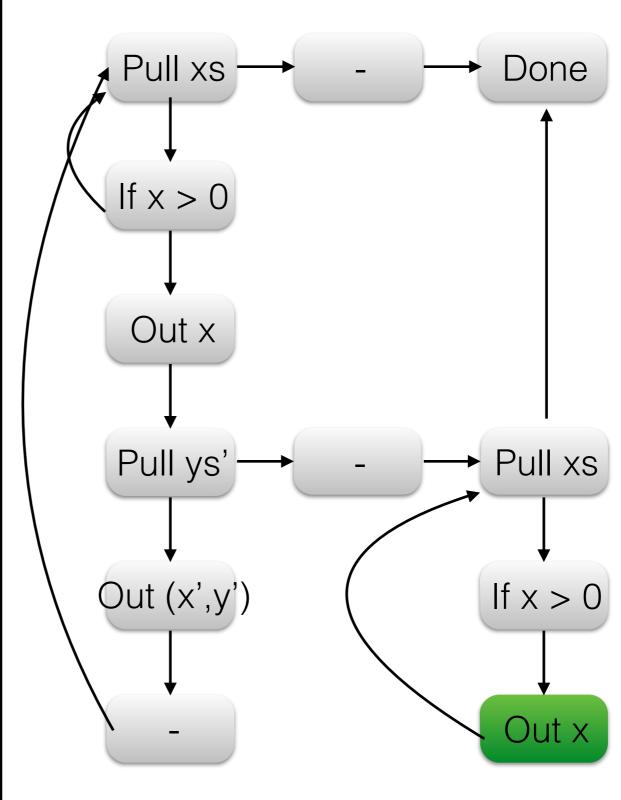


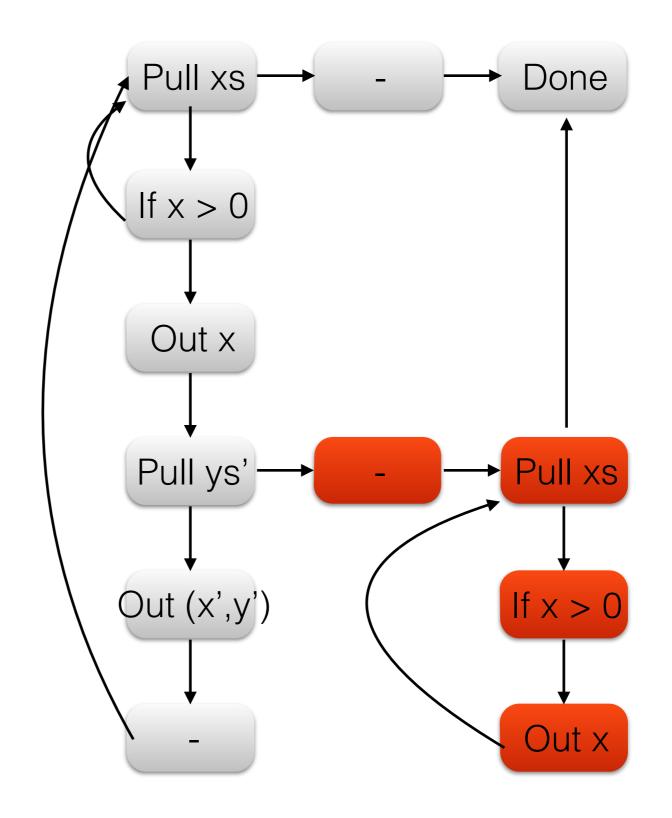


Out (x',y')

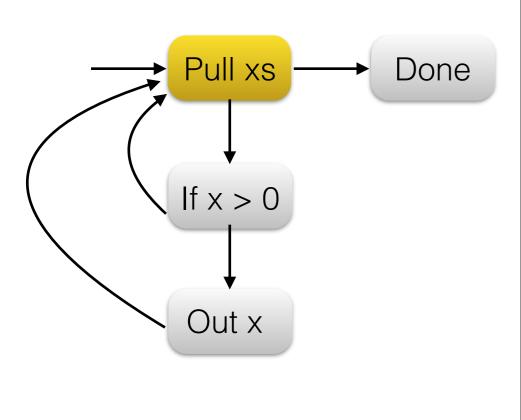




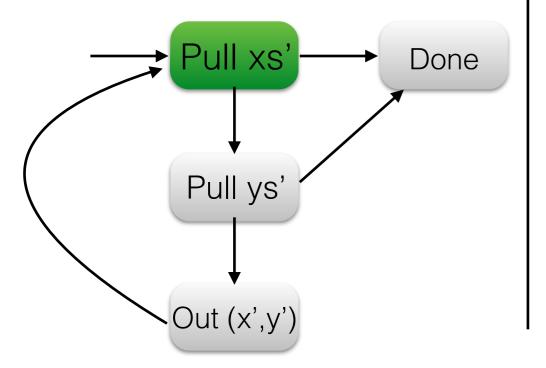


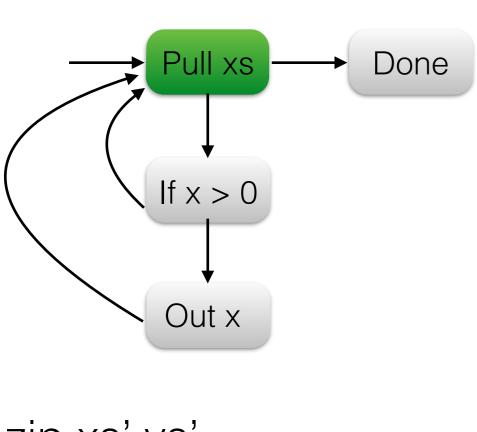


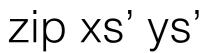
filter (>0) xs

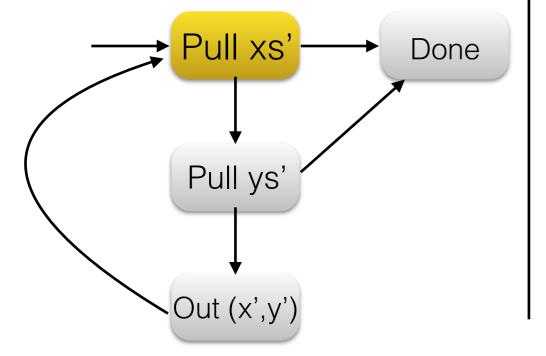


zip xs' ys'

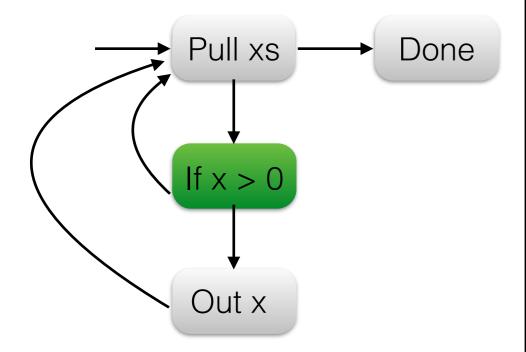




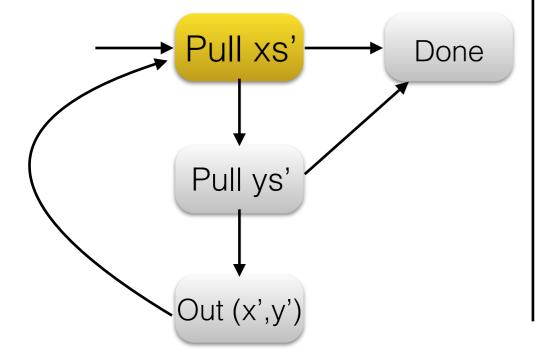


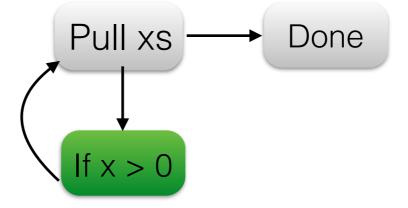


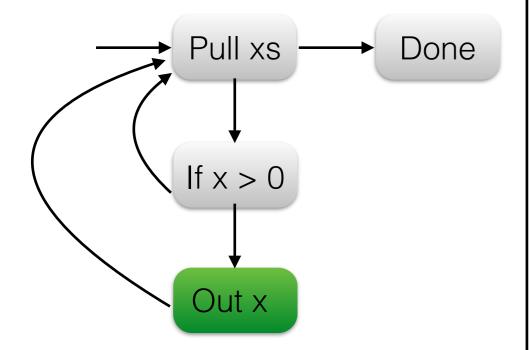
Pull xs



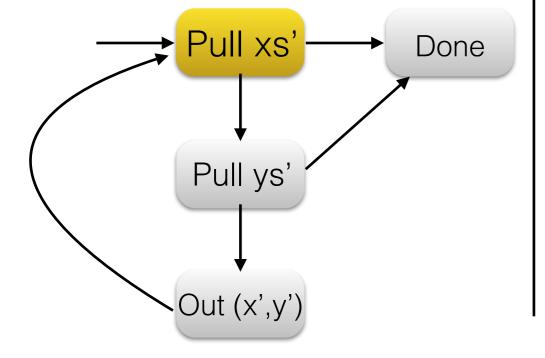
zip xs' ys'

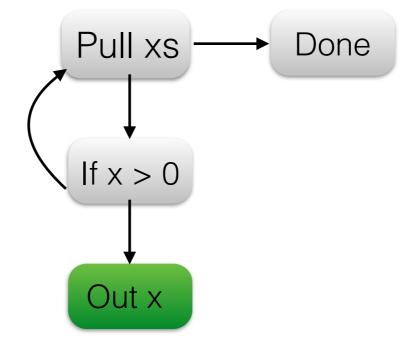


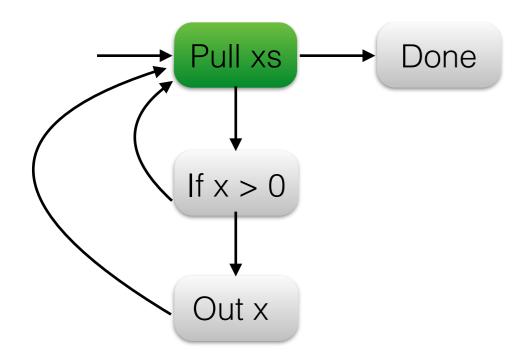




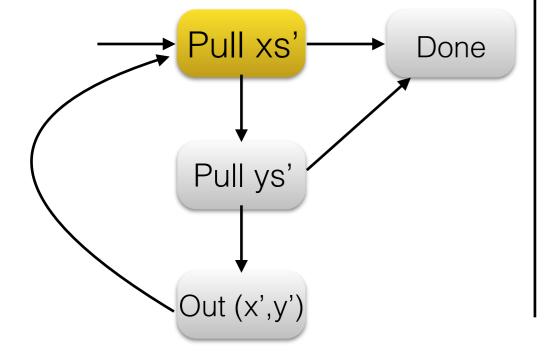
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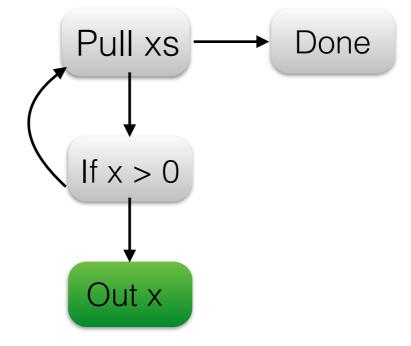


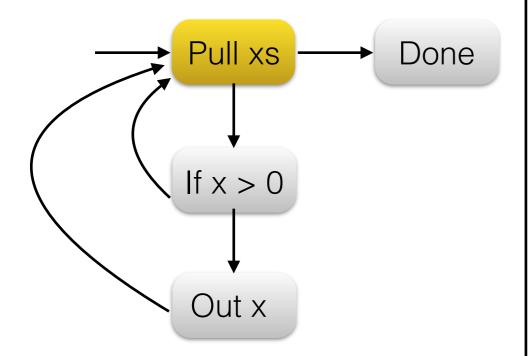




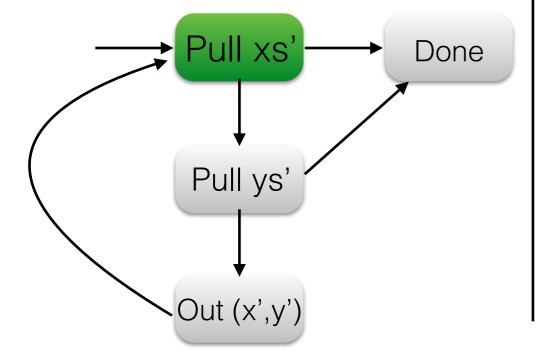
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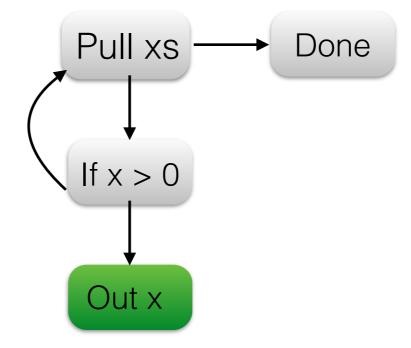


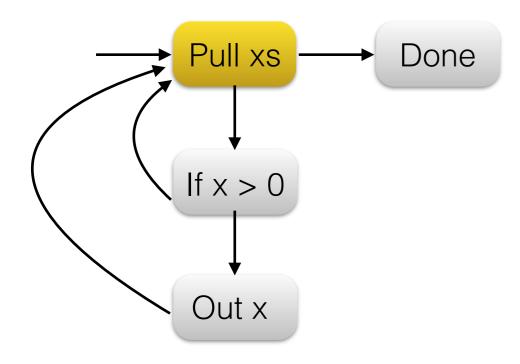




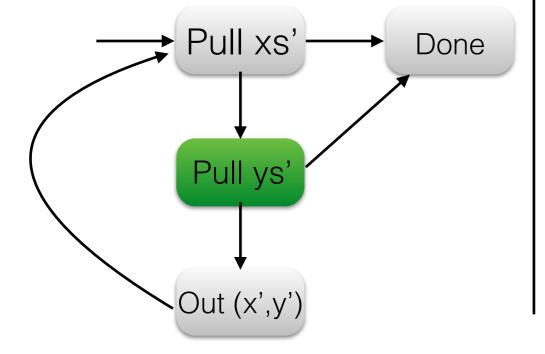
zip xs' ys'

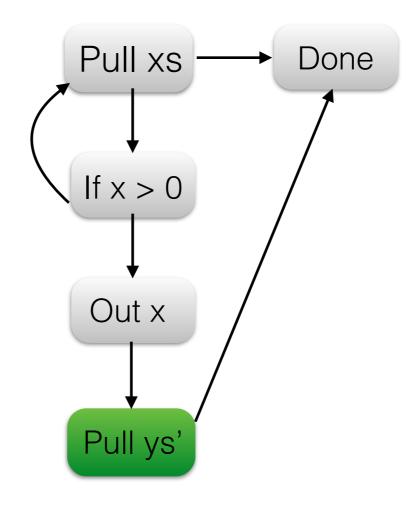


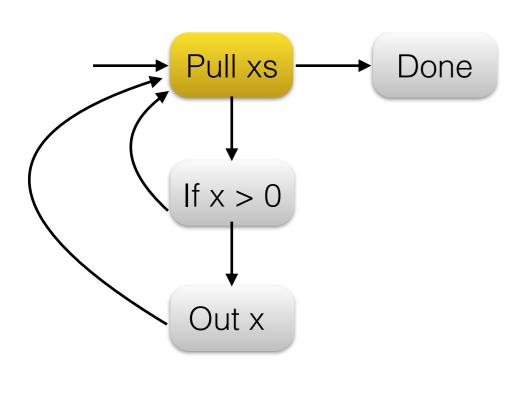




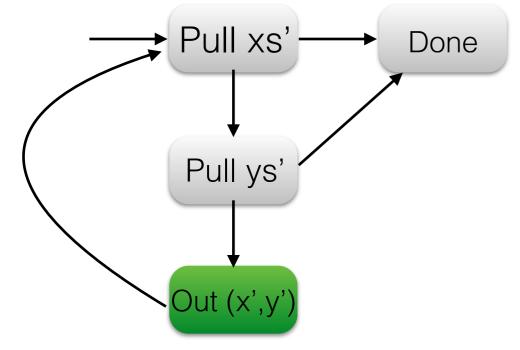
zip xs' ys'

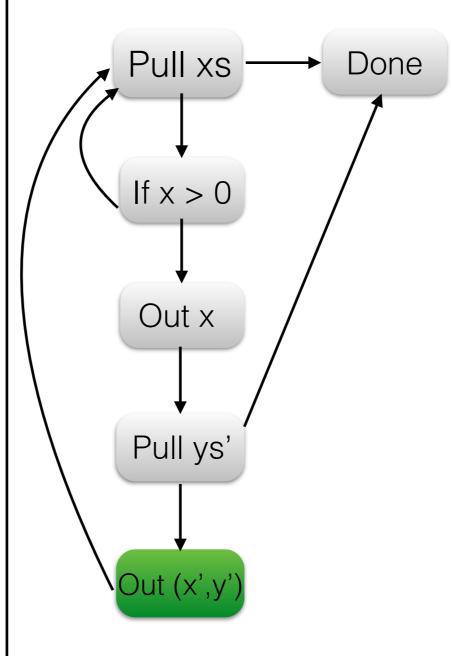


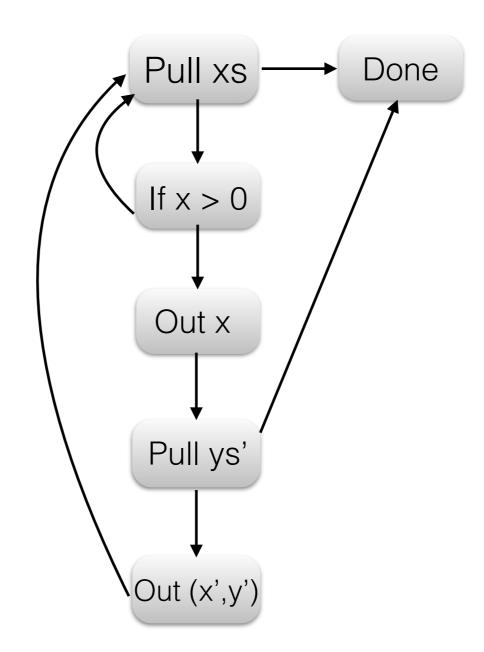




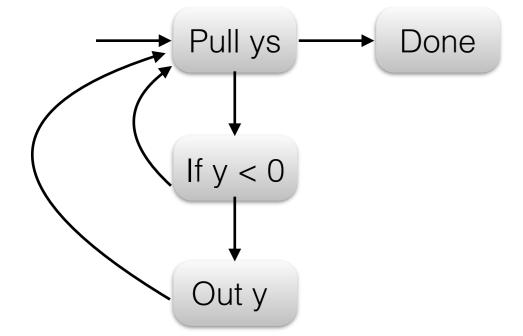
zip xs' ys'

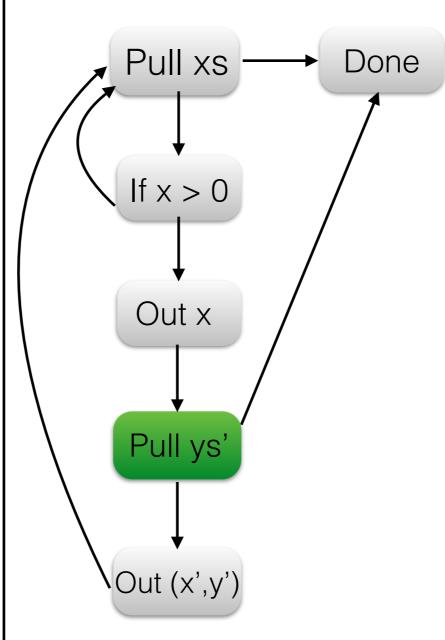




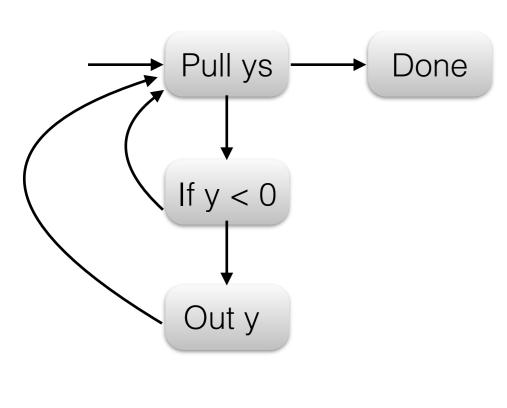


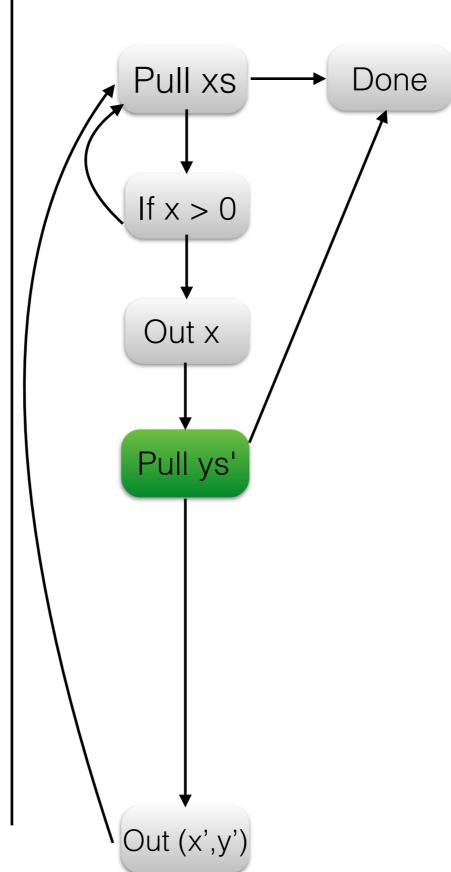
filter (<0) ys



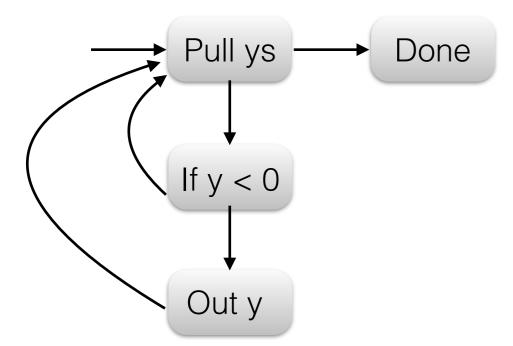


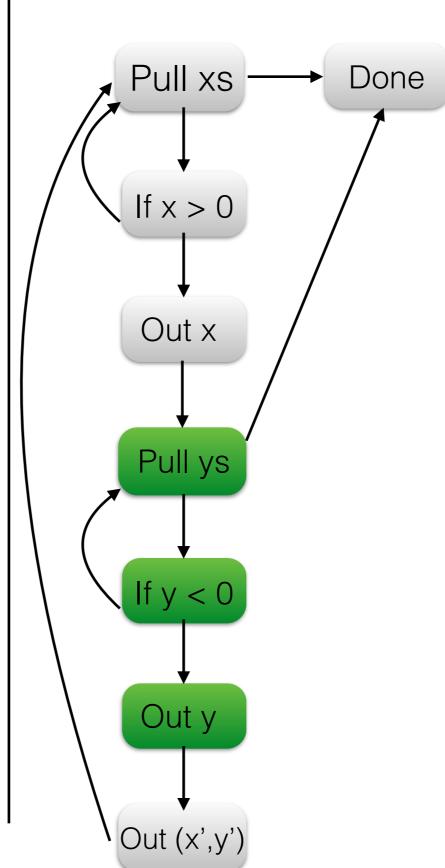
filter (<0) ys

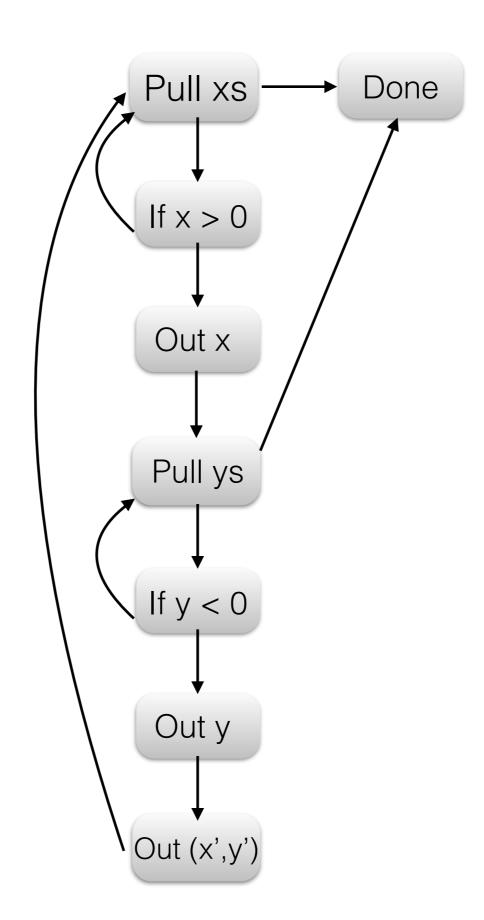




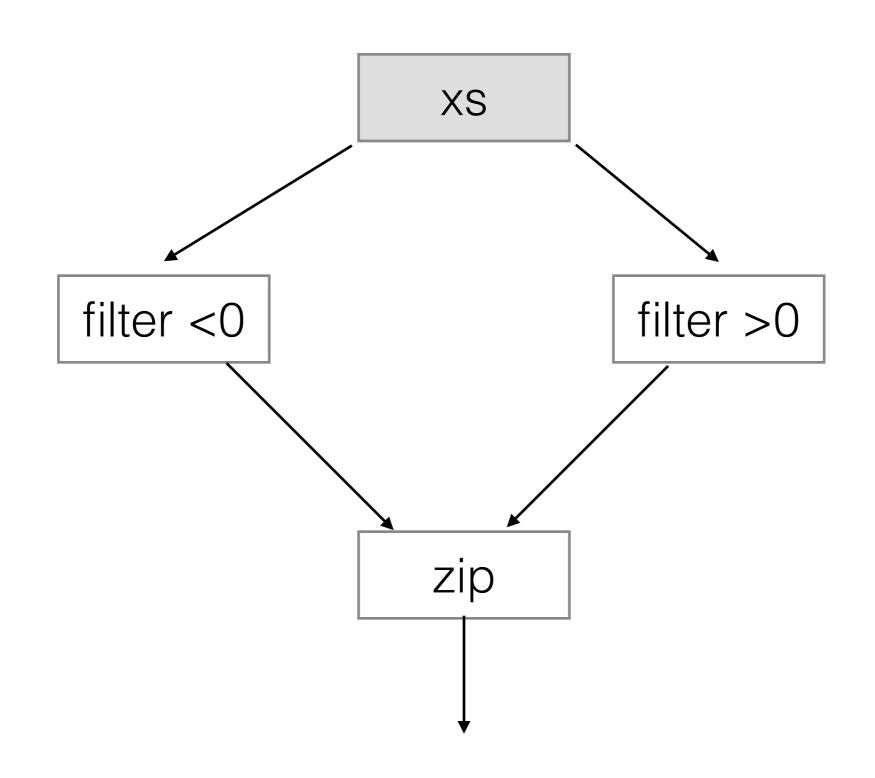
#### filter (<0) ys

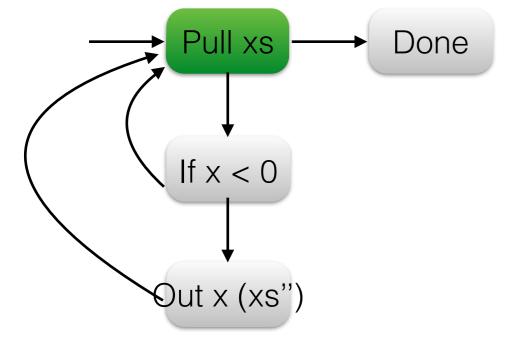


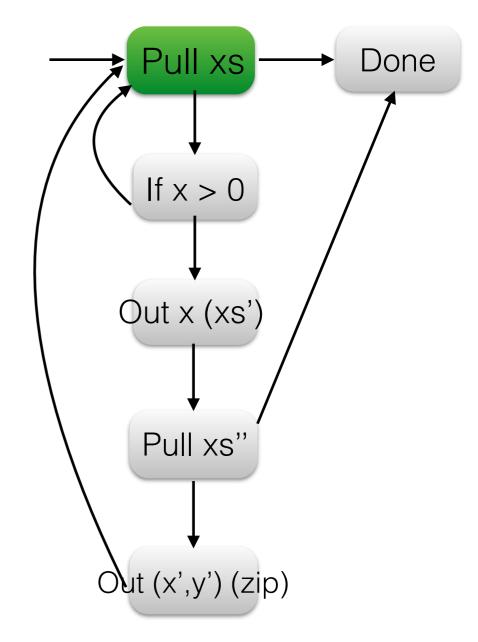


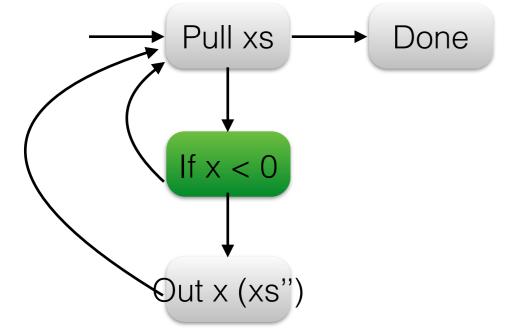


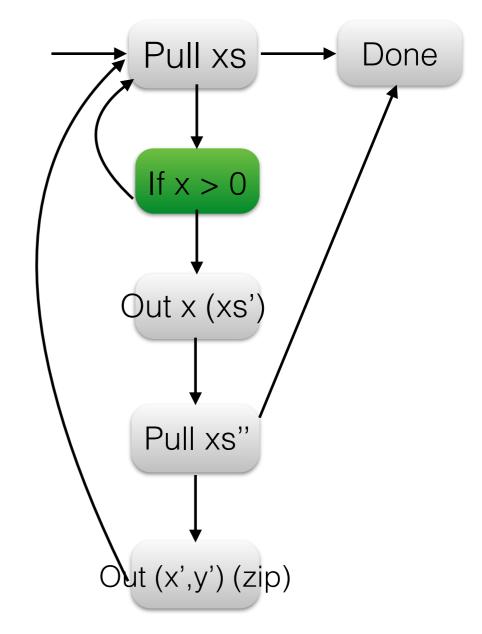
## Bad example: requires buffer

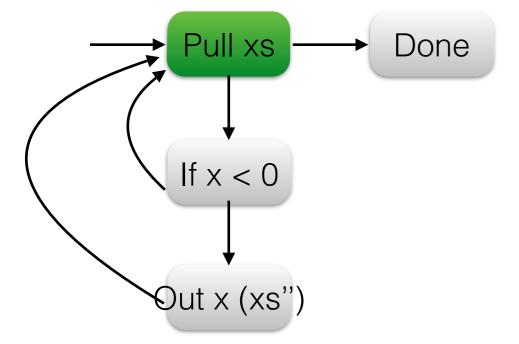


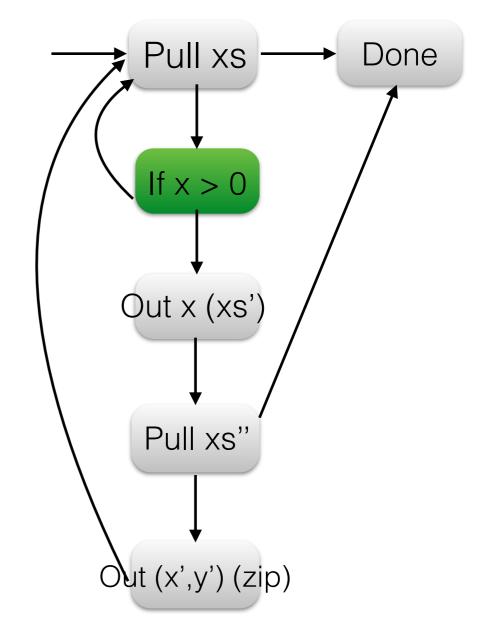


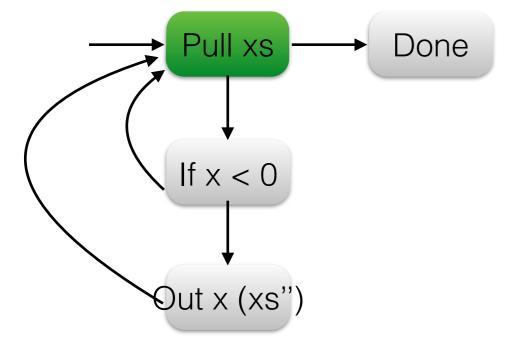


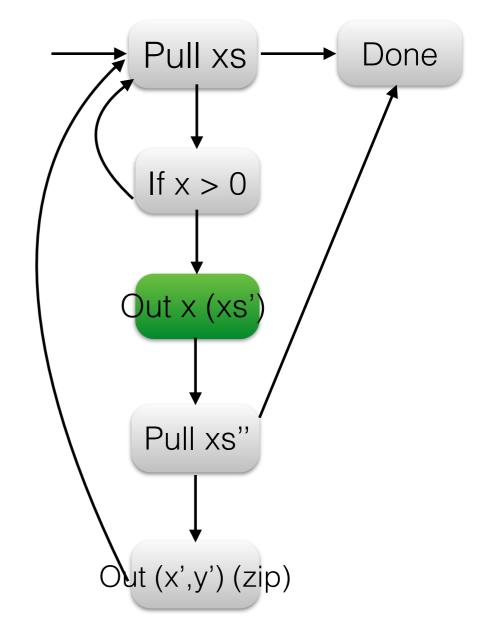


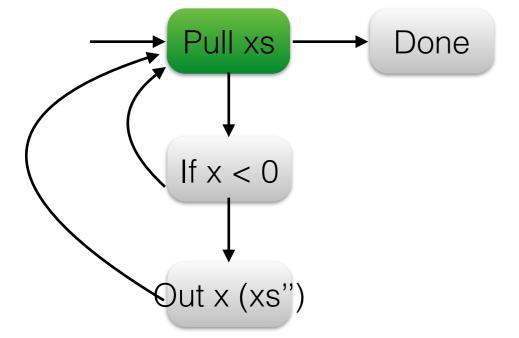


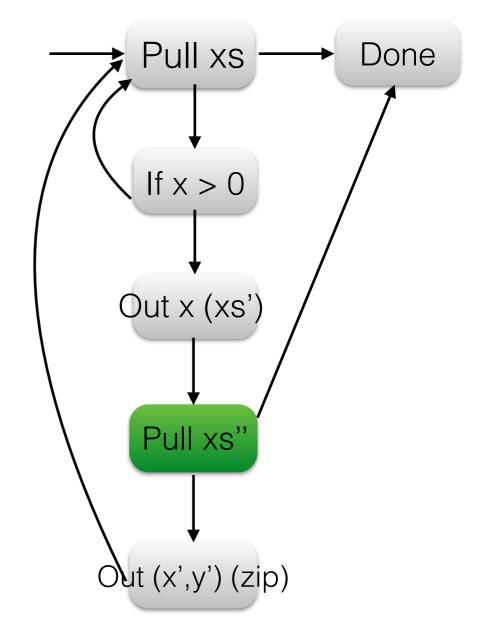




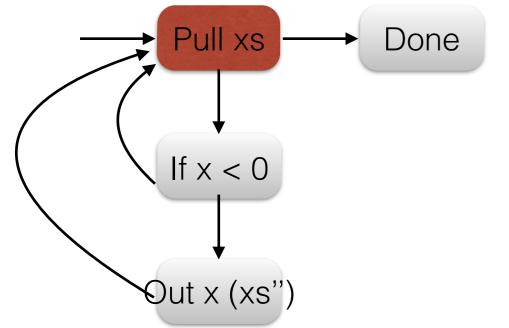




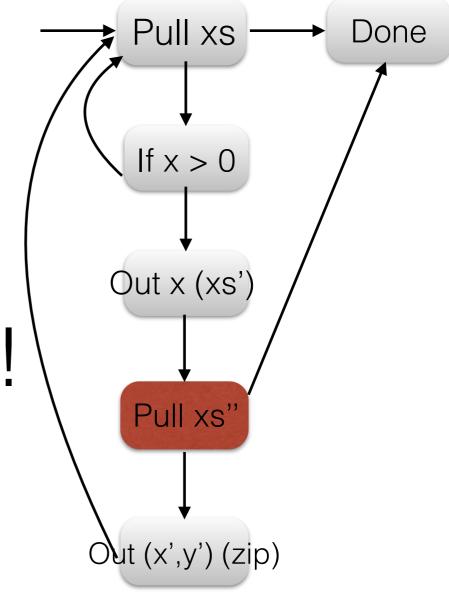




zip (filter (>0) xs) xs"



Deadlock!



## Relationships

Kahn processes

Dynamic Data flow

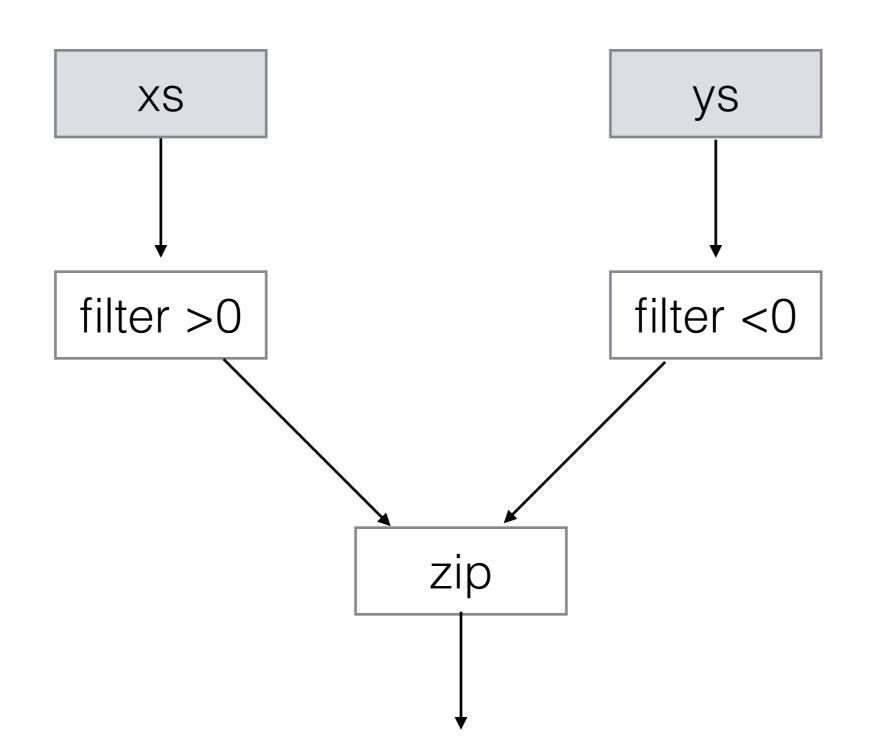
Synchronous Data flow

DFA fusion

# Next steps

## Extend to multiple machines

Order of fusion matters



# Finish writing paper

Figure 1. Invariant checking for machines

## Prove preservation & progress

 $\forall a \ b. \ a \ ok \ \land b \ ok \ \land \forall c. \ merge \ a \ b = c \implies c \ ok$ 

 $\forall a \ b. \ a \ ok \land b \ ok \land \forall c. \ merge V \ a \ b = c \implies c \ ok$ 

```
orall a\ b. \quad a\ 	ext{ok}\ \wedge\ b\ 	ext{ok} \ \wedge\ b\ 	ext{ontputs}\ a\ \cap\ 	ext{outputs}\ b=\emptyset \ \wedge\ 	ext{outputs}\ a\ \cap\ 	ext{outputs}\ b=\emptyset \ \wedge\ (\exists n.\ (\texttt{inputs}\ a\ \cap\ \texttt{outputs}\ b)\ \cup\ (\texttt{outputs}\ a\ \cap\ \texttt{inputs}\ b)=\{n\}) \ \Longrightarrow \quad \exists c.\ \texttt{mergeV}\ a\ b=c
```

### Conclusion

- Paper published since last review
- Have prototype & working on another paper