

Arduino Programming Cheat Sheet

Primary source: Arduino Language Reference
<http://arduino.cc/en/Reference/>

Structure & Flow

Basic Program Structure

```
void setup() {  
  // Runs once when sketch starts  
}  
void loop() {  
  // Runs repeatedly  
}
```

Control Structures

```
if (x < 5) { ... } else { ... }  
while (x < 5) { ... }  
for (int i = 0; i < 10; i++) { ... }  
break; // Exit a loop immediately  
continue; // Go to next iteration  
switch (var) {  
  case 1:  
    ...  
    break;  
  case 2:  
    ...  
    break;  
  default:  
    ...  
}  
return x; // x must match return type  
return; // For void return type
```

Function Definitions

```
<ret. type> <name>(<params>) { ... }  
e.g. int double(int x) {return x*2;}
```

Operators

General Operators

= assignment
+ add - subtract
* multiply / divide
% modulo
== equal to != not equal to
< less than > greater than
<= less than or equal to
>= greater than or equal to
&& and || or
! not

Compound Operators

++ increment
-- decrement
+= compound addition
-= compound subtraction
*= compound multiplication
/= compound division
&= compound bitwise and
|= compound bitwise or

Bitwise Operators

& bitwise and | bitwise or
< bitwise xor ~ bitwise not
<< shift left >> shift right

Pointer Access

& reference: get a pointer
* dereference: follow a pointer

Built-in Functions

Pin Input/Output

Digital I/O - pins 0-13 A0-A5
pinMode(pin, [INPUT, OUTPUT, INPUT_PULLUP])
int digitalRead(pin)
digitalWrite(pin, [HIGH, LOW])

Analog In - pins A0-A5

int analogRead(pin)
analogReference([DEFAULT, INTERNAL, EXTERNAL])

PWM Out - pins 3 5 6 9 10 11

analogWrite(pin, value)

Advanced I/O

tone(pin, freq_Hz)
tone(pin, freq_Hz, duration_ms)
noTone(pin)
shiftOut(dataPin, clockPin, [MSBFIRST, LSBFIRST], value)
unsigned long pulseIn(pin, [HIGH, LOW])

Time

unsigned long millis() // Overflows at 50 days
unsigned long micros() // Overflows at 70 minutes
delay(msec)
delayMicroseconds(usec)

Math

min(x, y) max(x, y) abs(x)
sin(rad) cos(rad) tan(rad)
sqrt(x) pow(base, exponent)
constrain(x, minval, maxval)
map(val, fromL, fromH, toL, toH)

Random Numbers

randomSeed(seed) // long or int
long random(max) // 0 to max-1
long random(min, max)

Bits and Bytes

lowByte(x) highByte(x)
bitRead(x, bitn)
bitWrite(x, bitn, bit)
bitSet(x, bitn)
bitClear(x, bitn)
bit(bitn) // bitn: 0=LSB 7=MSB

Type Conversions

char(val) byte(val)
int(val) word(val)
long(val) float(val)

External Interrupts

attachInterrupt(interrupt, func, [LOW, CHANGE, RISING, FALLING])
detachInterrupt(interrupt)
interrupts()
noInterrupts()

Libraries

Serial - comm. with PC or via RX/TX
begin(long speed) // Up to 115200
end()

int available() // #bytes available
int read() // -1 if none available
int peek() // Read w/o removing
flush()
print(data) println(data)
write(byte) write(char * string)
write(byte * data, size)
SerialEvent() // Called if data rdy

SoftwareSerial.h - comm. on any pin

SoftwareSerial(rxPin, txPin)
begin(long speed) // Up to 115200
listen() // Only 1 can listen
isListening() // at a time.
read, peek, print, println, write
// Equivalent to Serial library

EEPROM.h - access non-volatile memory

byte read(addr)
write(addr, byte)
EEPROM[index] // Access as array

Servo.h - control servo motors

attach(pin, [min_uS, max_uS])
write(angle) // 0 to 180
writeMicroseconds(uS)
// 1000-2000; 1500 is midpoint
int read() // 0 to 180
bool attached()
detach()

Wire.h - I²C communication

begin() // Join a master
begin(addr) // Join a slave @ addr
requestFrom(address, count)
beginTransmission(addr) // Step 1
send(byte) // Step 2
send(char * string)
send(byte * data, size)
endTransmission() // Step 3
int available() // #bytes available
byte receive() // Get next byte
onReceive(handler)
onRequest(handler)

Variables, Arrays, and Data

Data Types

boolean true | false
char -128 - 127, 'a' '\$' etc..
unsigned char 0 - 255
byte 0 - 255
int -32768 - 32767
unsigned int 0 - 65535
word 0 - 65535
long -2147483648 - 2147483647
unsigned long 0 - 4294967295
float -3.4028e+38 - 3.4028e+38
double currently same as float
void i.e., no return value

Strings

```
char str1[8] =  
  {'A','r','d','u','i','n','o','\0'};  
// Includes \0 null termination  
char str2[8] =  
  {'A','r','d','u','i','n','o','\0'};  
// Compiler adds null termination  
char str3[] = "Arduino";  
char str4[8] = "Arduino";
```

Numeric Constants

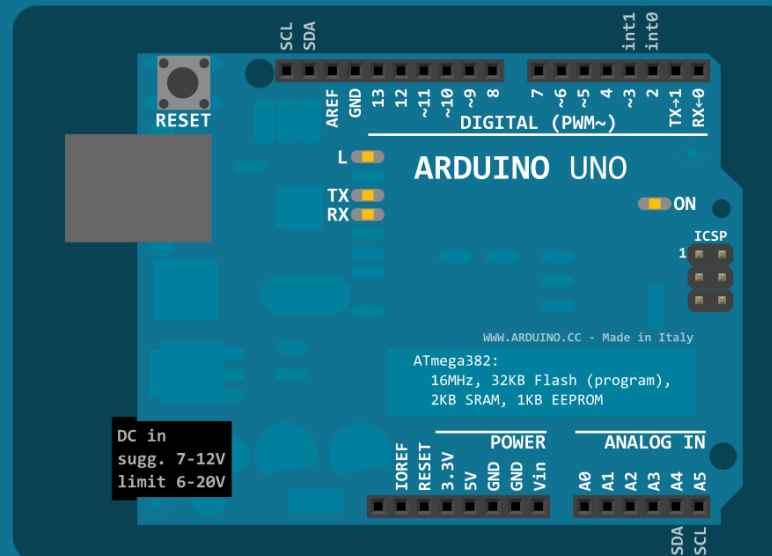
123 decimal
0b01111011 binary
0173 octal - base 8
0x7B hexadecimal - base 16
123U force unsigned
123L force long
123UL force unsigned long
123.0 force floating point
1.23e6 1.23*10⁶ = 1230000

Qualifiers

static persists between calls
volatile in RAM (nice for ISR)
const read-only
PROGMEM in flash

Arrays

```
int myPins[] = {2, 4, 8, 3, 6};  
int myInts[6]; // Array of 6 ints  
myInts[0] = 42; // Assigning first  
// index of myInts  
myInts[6] = 12; // ERROR! Indexes  
// are 0 though 5
```



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Adapted from:

- Original: Gavin Smith
- SVG version: Frederic Dufourg
- Arduino board drawing: Fritzling.org