Georgios P. Kontoudis

Graduate Research Assistant

Department of Mechanical Engineering

Virginia Tech

One mobile: (+1) 540 449-7026

One mobile

Research interests: Robotics, Bio-Inspired Design, Mechanisms and Motion Planning.

EDUCATION

PhD, Virginia Tech, USA

2016-Present

Department of Mechanical Engineering Advisor: Prof. Tomonari Furukawa

Co-advisor: Prof. Kyriakos G. Vamvoudakis

Current GPA: 4.0/4.0

 $Course work:\ Advanced\ Experimental\ Robotics,\ Optimization\ Techniques,\ Bayesian\ Robotics,\ Cyber-Physical$

Systems & Distributed Control, Motion Planning Analysis

Diploma (MSc), National Technical University of Athens, Greece

2012-2016

School of Mechanical Engineering Advisor: Prof. Kostas J. Kyriakopoulos Co-advisor: Prof. Minas Liarokapis

Grade: $7.76/10 \ (top \ 20\%)$

BSc, Piraeus University of Applied Sciences, Greece

2005-2010

Department of Mechanical Engineering

RESEARCH EXPERIENCE

Graduate Research Assistant

May 2017 - Present

Computational Multiphysics Systems Laboratory School of Mechanical Engineering, Virginia Tech, USA

Member & Research Associate

September 2014 - Present

The OpenBionics Initiative

Research Assistant

April 2014 - March 2016

Control Systems Laboratory

School of Mechanical Engineering, National Technical University of Athens, Greece

TEACHING EXPERIENCE

Graduate Teaching Assistant

August 2016 - May 2017

School of Mechanical Engineering, Virginia Tech, USA

➤ Lectured 80 students in a senior level, control systems lab.

Fall 2016

➤ Guided 20 students in a series of 8 junior level, mechanical engineering labs.

Spring 2017

AWARDS & HONORS

NTUA Thomaideion Award

Hackaday Prize, 2^{nd} place (among 900)

Robotdalen Innovation Award, 1^{st} place

Sweden 2015

IEEE/RAS Student Travel Award (IROS)

Germany 2015

PROFESSIONAL EXPERIENCE

Senior Mechanical Engineer

Heliix Inc., Athens, Greece

> Worked on product design & development of a waste heat recovery device.

Site Supervisor

 $September\ 2013\ \hbox{-}\ August\ 2015$

Sychem S.A., Athens, Greece

> Provided guidance to industrial maintenance crew of 6 people for a desalination plant.

Mechanical Engineer

October 2010 - September 2013

Sychem S.A., Athens, Greece

➤ Monitored and commissioned desalination plants.

Aircraft Maintenance Engineer Trainee

May 2008 - January 2010

Olympic Aviation, Athens, Greece

> Performed engineering work of maintenance and modifications on aircrafts.

PUBLICATIONS

Peer-Reviewed Conference Publications

[3] George P. Kontoudis, Minas Liarokapis, Kyriakos G. Vamvoudakis, and Tomonari Furukawa, "A Bio-Inspired Actuation Design for Adaptive Robot Hands," *IEEE/RAS International Conference on Humanoid Robots* (Humanoids), Birmingham, UK, 2017. (Submitted)

[2] Kyriakos D. Tsoukalas, **George P. Kontoudis**, and Kyriakos G. Vamvoudakis, "Active-Bayesian Learning for Cooperation Connectivity in Dynamic Cyber-Physical-Human Systems," *IEEE Symposium on Adaptive Dynamic Programming and Reinforcement Learning* (ADPRL), Hawaii, USA, 2017. (To appear)

[1] George P. Kontoudis, Minas Liarokapis, Agisilaos G. Zisimatos, Christoforos I. Mavrogiannis and Kostas J. Kyriakopoulos, "Open-Source, Anthropomorphic, Underactuated Robot Hands with a Selectively Lockable Differential Mechanism: Towards Affordable Prostheses," *IEEE/RSJ International Conference on Intelligent Robots and Systems* (IROS), Hamburg, Germany, 2015.

Technical Reports

[2] George P. Kontoudis, Minas Liarokapis, Agisilaos G. Zisimatos, Christoforos I. Mavrogiannis and Kostas J. Kyriakopoulos, "How to Create Affordable, Anthropomorphic, Light-Weight Prosthetic Hands," Control Systems Lab, School of Mechanical Engineering, National Technical University of Athens, Athens, Greece, October 2015.

[1] Agisilaos G. Zisimatos, Minas Liarokapis, Christoforos I. Mavrogiannis, **George P. Kontoudis** and Kostas J. Kyriakopoulos, "How to Create Affordable, Modular, Light-Weight, Underactuated, Compliant Robot Hand," Control Systems Lab, School of Mechanical Engineering, National Technical University of Athens, Athens, Greece, January 2015.

Theses

[1] George P. Kontoudis "Design and Development of an Underactuated, Anthropomorphic Robot Hand," Diploma Thesis, National Technical University of Athens (NTUA), Athens, Greece, March 2016. (In Greek)

SKILLS

Languages: English, Greek(native)

Operating Systems: Linux, ROS, Windows

Design and Simulation Software: Solidworks, AutoCAD, ANSYS, Slic3r, ProCAST, PSpice, Cura

Programming: Pyhton, C/C++, Matlab, HTML/CSS, LATEX

Other Skills: Laser cutting, 3D printing

SERVICE ACTIVITIES

Reviewer: International Journal of Advanced Robotic Systems

March 2016 - June 2016

MEMBERSHIPS & SOCIETIES

Memberships	
IEEE - Student Member	2015 - Presen
ASME - Student Member	2016 - Presen
Societies	
IEEE - Robotics and Automation (RAS)	2015 - Presen
IEEE - Control Systems (CSS)	2017 - Presen